CART, KNN, Naive Bayes

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```
knitr::opts_chunk$set(eval = FALSE)
library(tidyverse)
## Registered S3 methods overwritten by 'ggplot2':
    method
                 from
##
    [.quosures
                  rlang
    c.quosures
                 rlang
    print.quosures rlang
## Registered S3 method overwritten by 'rvest':
    {\tt method}
                     from
##
    read_xml.response xml2
## -- Attaching packages -----
                   v purrr 0.3.2
## v ggplot2 3.1.1
## v tibble 2.1.1
                     v dplyr 0.8.0.1
          0.8.3
## v tidyr
                     v stringr 1.4.0
## v readr
           1.3.1
                       v forcats 0.4.0
## -- Conflicts ------
## x dplyr::filter() masks stats::filter()
## x dplyr::lag()
                   masks stats::lag()
library(caret)
## Loading required package: lattice
## Attaching package: 'caret'
## The following object is masked from 'package:purrr':
##
##
      lift
library(pROC)
## Type 'citation("pROC")' for a citation.
##
## Attaching package: 'pROC'
## The following objects are masked from 'package:stats':
##
      cov, smooth, var
##
library(RANN)
library(rpart)
library(rpart.plot)
```

Data loading and train

KNN

Resampled AUC: 0.764509

Performance on test data:

Classification Tree

```
set.seed(14)
```

```
rpart_fit <- train(x = cog_train[3:10],</pre>
                   y = cog_train$cdr,
                   method = "rpart",
                   tuneGrid = data.frame(cp = exp(seq(-12, -3, length = 100))),
                   trControl = ctrl1)
ggplot(rpart_fit, highlight = TRUE) + theme_minimal()
cp_optimal <- rpart_fit$results %>% as.tibble() %>%
 mutate(ROC_onesd = ROC - ROCSD) %>%
 select(cp, ROC, ROC_onesd) %>%
  filter(cp >= cp[which.max(ROC)],
         ROC >= ROC_onesd[which.max(ROC)]) %>%
  summarize(cp_maxROC = min(cp),
            cp_1se = max(cp)
tree_min <- prune(rpart_fit$finalModel, cp = cp_optimal$cp_maxROC)</pre>
tree_1se <- prune(rpart_fit$finalModel, cp = cp_optimal$cp_1se)
rpart.plot(tree_1se, box.palette = "GnPu", branch.lty = 3, shadow.col = "gray", nn = TRUE)
```

Naive Bayes

```
set.seed(1)
# 3 tuning parameters
nbGrid <- expand.grid(usekernel = c(FALSE, TRUE), # FALSE means use Gaussian; TRUE means non-parametric
                      fL = 1, # rLaplace smoother. Handles density of points that fall lutside of the o
                      adjust = seq(0,10,by = 1)) # constrols smoothness of density estimate; large mean
model.nb <- train(x = cog_train[3:10],</pre>
                  y = cog_train$cdr,
                  method = "nb", # specifies bandwidth of kernel estimate
                  tuneGrid = nbGrid,
                  metric = "ROC".
                  trControl = ctrl1)
plot(model.nb)
model.nb$results[which.max(model.nb$results$ROC), ]
saveRDS(knn_fit, "./data/knn.RDS")
saveRDS(model.nb, "./data/nb.RDS")
saveRDS(rpart_fit, "./data/cart.RDS")
```