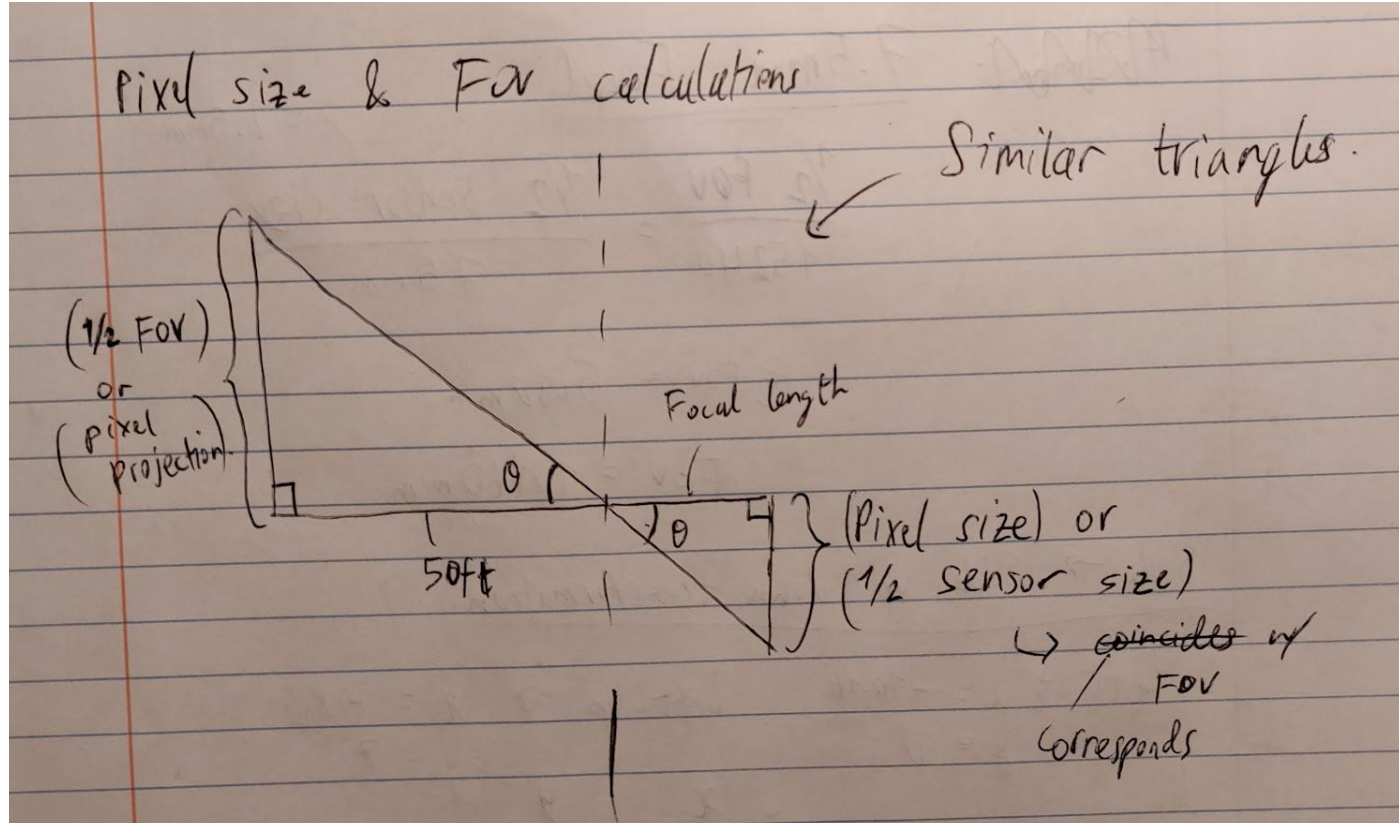


Pixel size & FOV calculations



So:

$$\text{Pixel size/Focal length} = \text{Pixel projection}/50\text{ft}$$

$$\text{sensor size/Focal length} = \text{FOV}/50\text{ft}$$

Sensor chip sizes are taken from respective manufacturer websites

DVXplorer(640x480, 7.5mm focal) 9-camera layout calculations

- FOV(mm):

Horizontal FOV/50ft = Horizontal sensor size/7.5mm

50ft = 15240mm, Horiz. sensor size = 640 * 9um = 5.76mm

Horiz. FOV = 15240*(5.76/7.5)[mm]

= 11704mm = 11.70m = 38.39ft

Vertical FOV/50ft = Vertical sensor size/7.5mm

50ft = 15240mm, Vert. sensor size = 480 * 9um = 4.32mm

Vert. FOV = 15240*(4.32/7.5)[mm]

= 8778mm = 8.78m = 28.81ft

- Pixel projection(mm):

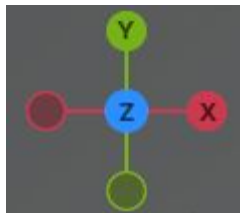
Pixel proj/50ft = Pixel size/7.5mm

For DVXplorer, Pixel size is 9um(from Inivation website specs)

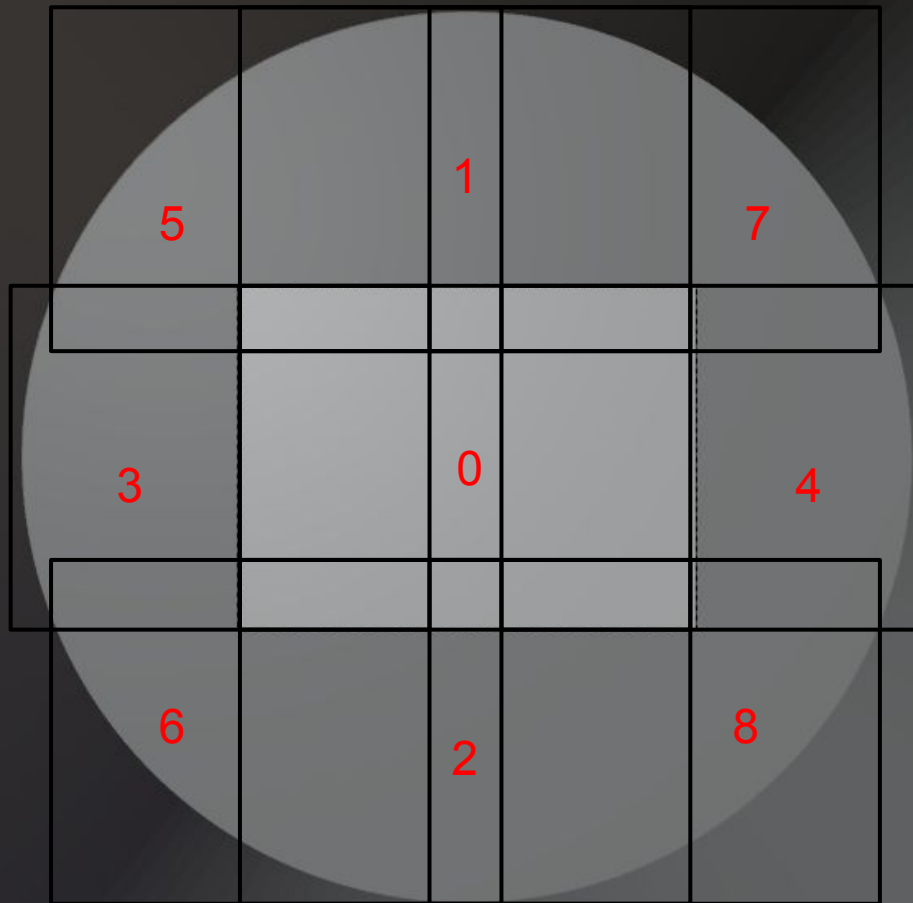
Pixel proj = 15240*(9e-3/7.5)[mm]

= 18.29mm

(The width of a single pixel projected 50ft to the bottom of the tank is 18.29mm)



DVXplorer
(640x480)
7.5mm focal
9-camera
layout



Coordinate layout(ft)

0: $x = 0, y = 0$

1: $x = 0, y = 23.0$

2: $x = 0, y = -23.0$

3: $x = -18.37, y = 0$

4: $x = 18.37, y = 0$

5: $x = -18.37, y = 23$

6: $x = -18.37, y = -23$

7: $x = 18.37, y = 23$

8: $x = 18.37, y = -23$

Note: Cameras 5 and 7,
& 6 and 8 overlap;
Cameras 3 and 4 do
NOT overlap.

IMX636(1280x720, 6.0mm focal) 5-camera layout calculations

- FOV(mm):

Horizontal FOV/50ft = Horizontal sensor size/6.0mm

50ft = 15240mm, Horiz. sensor size = $1280 * 4.86\mu\text{m} = 6.2\text{mm}$

Horiz. FOV = $15240 * (6.2/6.0)[\text{mm}]$

= 15748mm = 15.75m = 51.67ft

Vertical FOV/50ft = Vertical sensor size/6.0mm

Vert. sensor size = $720 * 4.86\mu\text{m} = 3.5\text{mm}$

Vert. FOV = $15240 * (3.5/6.0)[\text{mm}]$

= 8890mm = 8.89m = 29.17ft

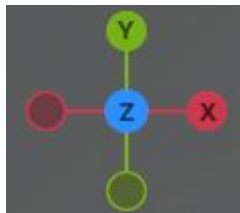
- Pixel projection(mm):

Pixel proj/50ft = Pixel size/6.0mm

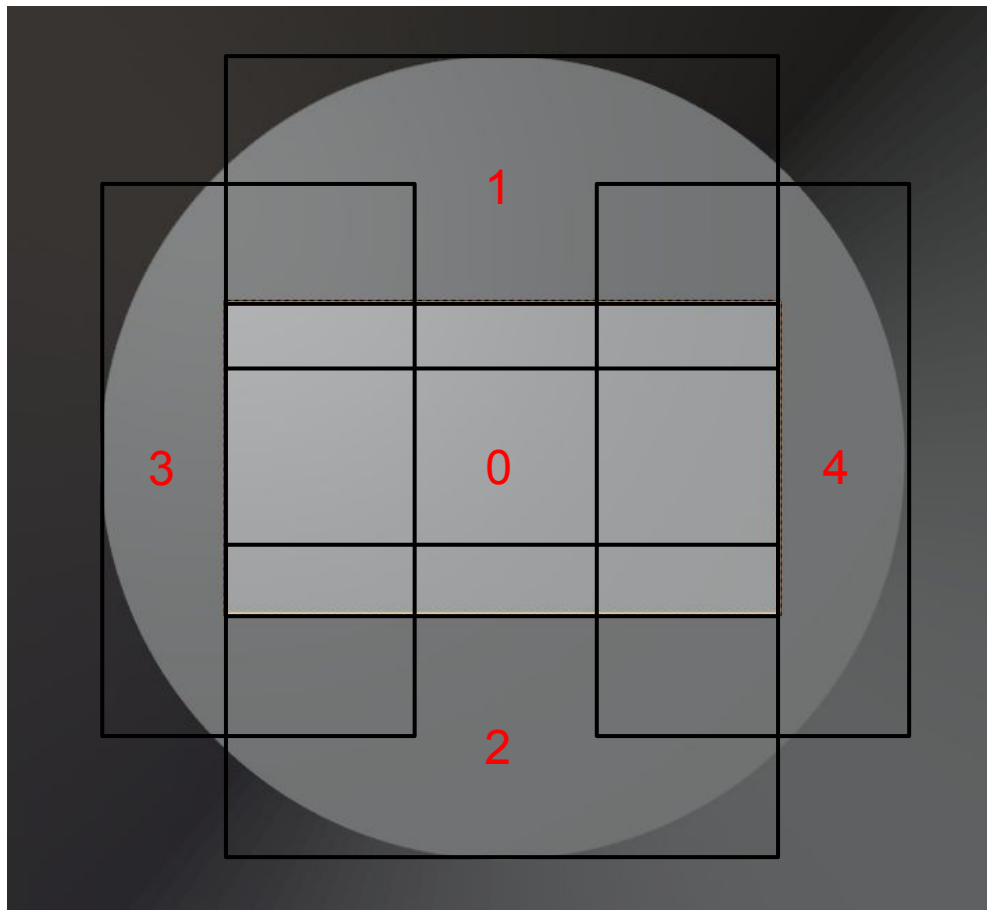
For IMX636, Pixel size is $4.86\mu\text{m}$ (from Prophesee website specs)

Pixel proj = $15240 * (4.86e-3/6.0)[\text{mm}]$

= 12.34mm



IMX636
(1280x720)
6mm focal
5-camera
layout



Coordinate layout(ft)

0: $x = 0, y = 0$

1: $x = 0, y = 23.3$

2: $x = 0, y = -23.3$

3: $x = -23.3, y = 0$

4: $x = 23.3, y = 0$

GENX320(320x320, 4mm focal) 9-camera layout calculations

- FOV(mm):

$\text{FOV}/50\text{ft} = \text{Sensor size}/4.0\text{mm}$

$50\text{ft} = 15240\text{mm}$, sensor size = $320 * 6.3\mu\text{m} = 2.02\text{mm}$

$\text{FOV} = 15240 * (2.02/4.0)[\text{mm}]$

= 7696mm = 7.70m = 25.26ft

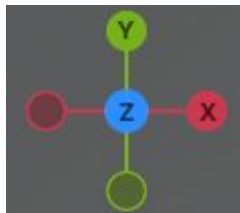
- Pixel projection(mm):

$\text{Pixel proj}/50\text{ft} = \text{Pixel size}/4.0\text{mm}$

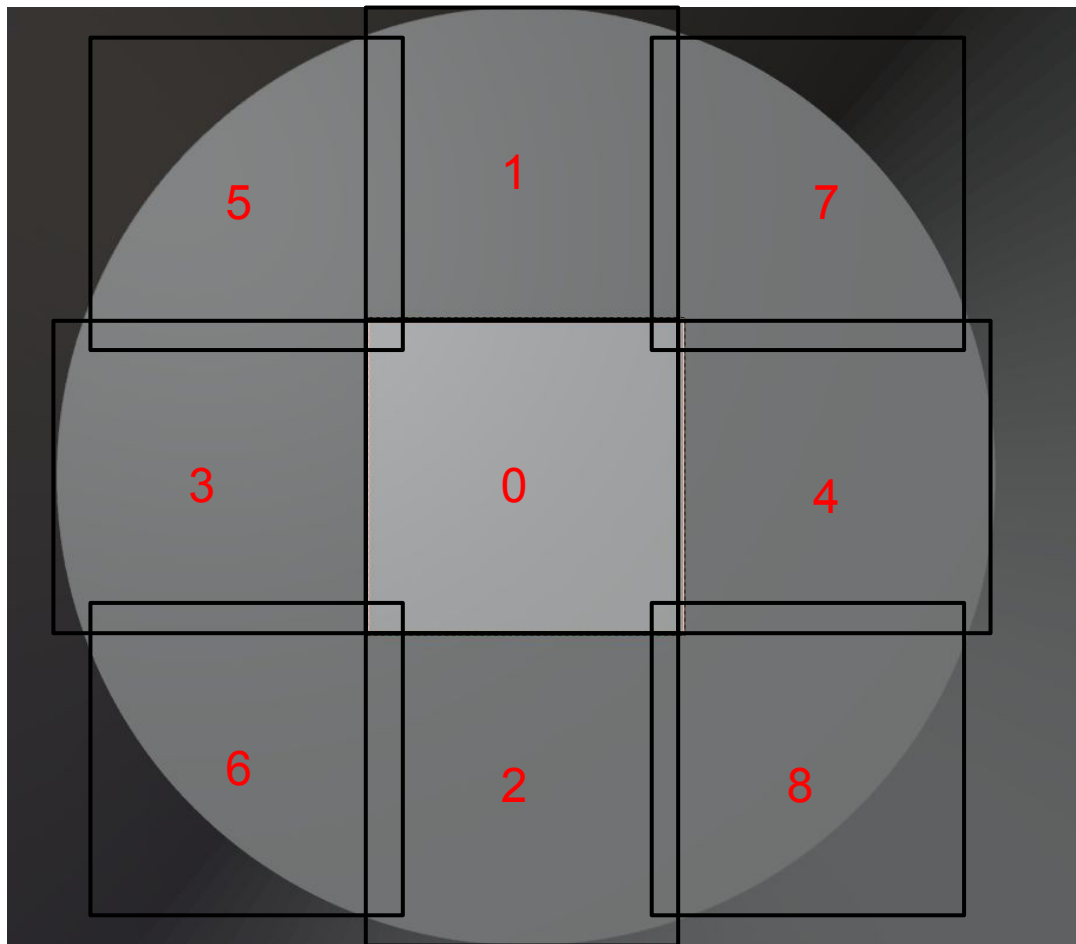
For GENX320, Pixel size is $6.3\mu\text{m}$ (from Prophesee website specs)

$\text{Pixel proj} = 15240 * (6.3\text{e-}3/4.0)[\text{mm}]$

= 24.00mm



GENX320
(320x320)
4mm focal
9-camera
layout



Coordinate layout(ft)

0: $x = 0, y = 0$

1: $x = 0, y = 25.3$

2: $x = 0, y = -25.3$

3: $x = -25.3, y = 0$

4: $x = 25.3, y = 0$

5: $x = -22.5, y = 23.0$

6: $x = -22.5, y = -23.0$

7: $x = 22.5, y = 23.0$

8: $x = 22.5, y = -23.0$

IMX636(1280x720, 4.1mm focal) 2-camera layout calculations

- FOV(mm):

Horizontal FOV/50ft = Horizontal sensor size/4.1mm

50ft = 15240mm, Horiz. sensor size = $1280 * 4.86\mu\text{m} = 6.2\text{mm}$

Horiz. FOV = $15240 * (6.2/4.1)[\text{mm}]$

= 23046mm = 23.05m = 75.62ft

Vertical FOV/50ft = Vertical sensor size/4.1mm

Vert. sensor size = $720 * 4.86\mu\text{m} = 3.5\text{mm}$

Vert. FOV = $15240 * (3.5/4.1)[\text{mm}]$

= 13009mm = 13.01m = 42.68ft

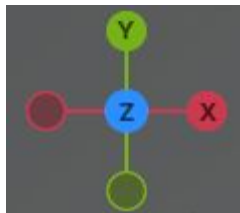
- Pixel projection(mm):

Pixel proj/50ft = Pixel size/4.1mm

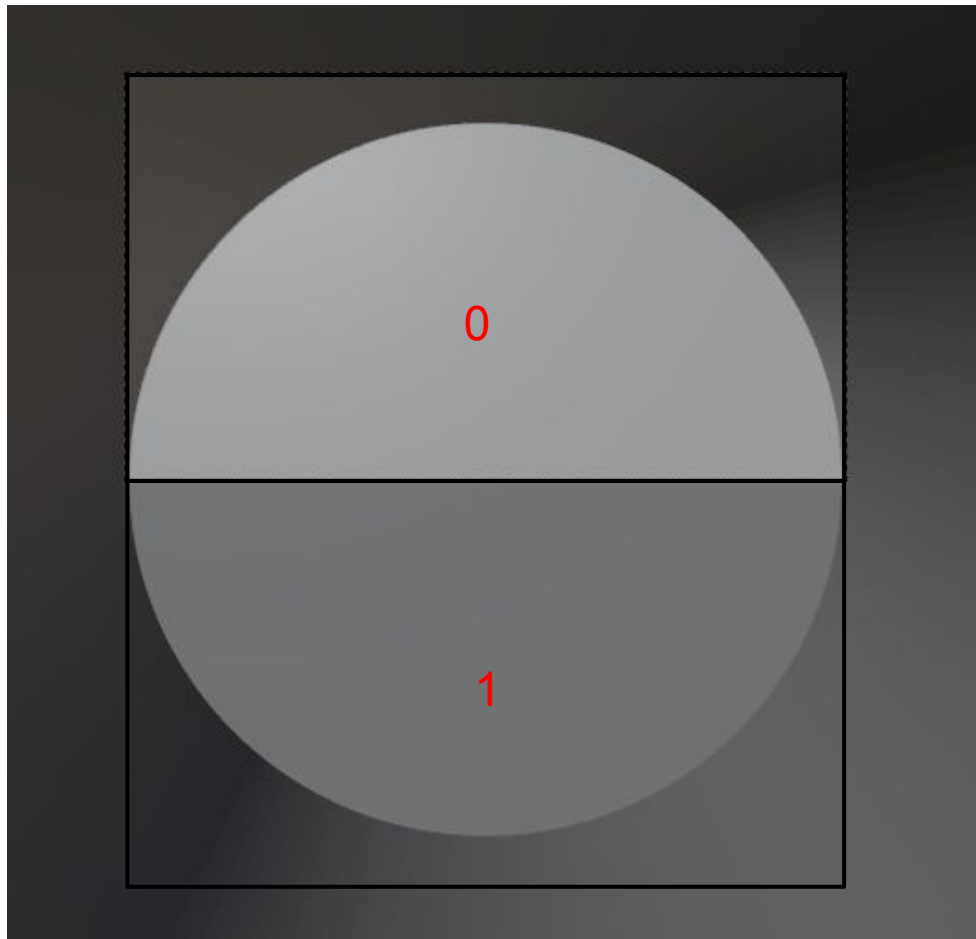
For IMX636, Pixel size is $4.86\mu\text{m}$ (from Prophesee website specs)

Pixel proj = $15240 * (4.86e-3/4.1)[\text{mm}]$

= 18.06mm



IMX636
(1280x720)
4.1mm focal
2-camera
layout



Coordinate layout(ft)

0: $x = 0, y = 21.34$

1: $x = 0, y = -21.34$

DVXplorer Lite(320x240, 7.5mm focal) 9-camera layout calculations

- FOV(mm):

Horizontal FOV/50ft = Horizontal sensor size/7.5mm

50ft = 15240mm, Horiz. sensor size = $320 * 18\mu\text{m} = 5.76\text{mm}$

Horiz. FOV = $15240 * (5.76/7.5)[\text{mm}]$

= 11704mm = 11.70m = 38.39ft

Vertical FOV/50ft = Vertical sensor size/7.5mm

50ft = 15240mm, Vert. sensor size = $240 * 18\mu\text{m} = 4.32\text{mm}$

Horiz. FOV = $15240 * (4.32/7.5)[\text{mm}]$

= 8778mm = 8.78m = 28.81ft

- Pixel projection(mm):

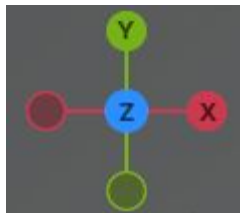
Pixel proj/50ft = Pixel size/7.5mm

For DVXplorer, Pixel size is 18um(from Inivation website specs)

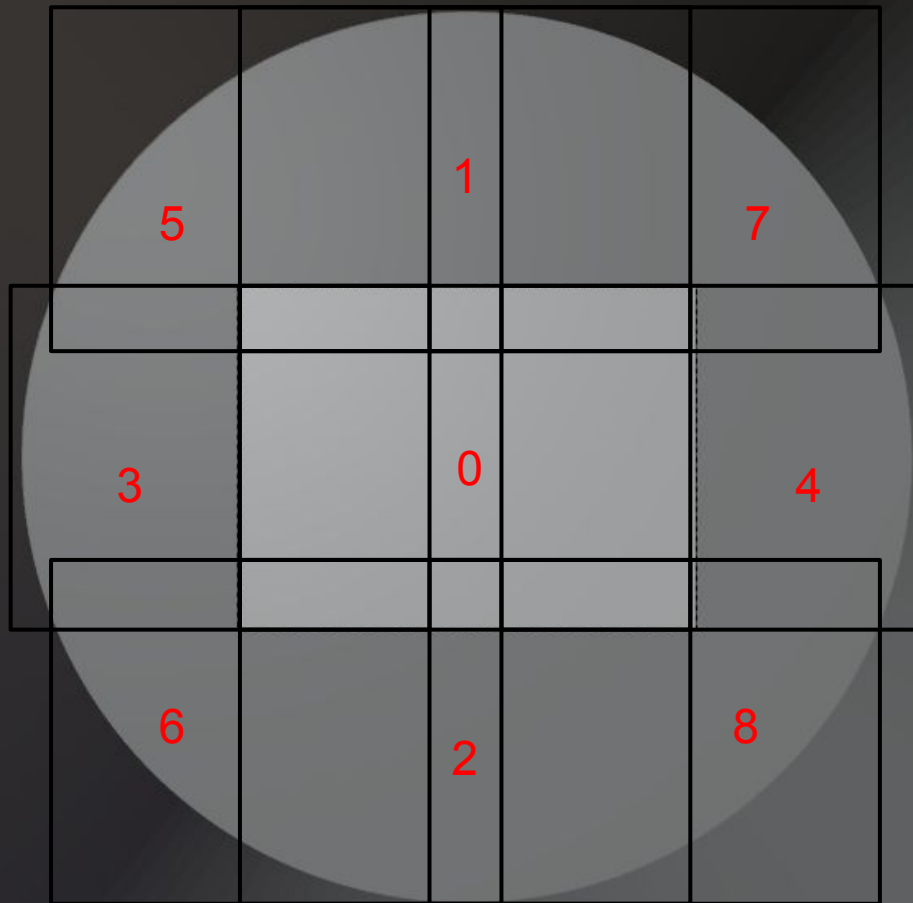
Pixel proj = $15240 * (18e-3/7.5)[\text{mm}]$

= 36.58mm

(Same FOV as Regular DVXplorer, 2x pixel projection size)



DVXplorer Lite
(320x240)
7.5mm focal
9-camera
layout



Coordinate layout(ft)

0: $x = 0, y = 0$

1: $x = 0, y = 23.0$

2: $x = 0, y = -23.0$

3: $x = -18.37, y = 0$

4: $x = 18.37, y = 0$

5: $x = -18.37, y = 23$

6: $x = -18.37, y = -23$

7: $x = 18.37, y = 23$

8: $x = 18.37, y = -23$

Note: Cameras 5 and 7,
& 6 and 8 overlap;
Cameras 3 and 4 do
NOT overlap.