



Figure 8: Final Functioning Prototype of the CDT MixMaster 8000

Full Arduino Code:

```
#include "Adafruit_GFX.h"
#include "Adafruit_ILI9341.h"

//using pins 40 - 45 for LCD
#define TFT_CS 40
#define TFT_RST 41
#define TFT_DC 42
#define TFT_MOSI 43
```

```

#define TFT_CLK 44
#define TFT_MISO 45

#define ROWS 7
#define COLS 8

// MIDI serial definitions
#define NOTE_ON_CMD 0x90
#define NOTE_OFF_CMD 0x80
#define NOTE_VELOCITY 0x7F // any value 0-127

// MIDI baud rate
#define SERIAL_RATE 31250

// Maximum number of keys that can be played at once
#define MAX_KEYS_PLAYED 12

// Number of samples in sine wave. Highly recommend using a power of 2.
#define SAMPLES 4096

//-----MIDI-----
// column pins
const int col1Pin = 29;
const int col2Pin = 30;
const int col3Pin = 31;
const int col4Pin = 32;
const int col5Pin = 33;
const int col6Pin = 34;
const int col7Pin = 35;
const int col8Pin = 36;
const int colPins[COLS] =

```

```

{
    col1Pin,
    col2Pin,
    col3Pin,
    col4Pin,
    col5Pin,
    col6Pin,
    col7Pin,
    col8Pin
};

// row pins
const int row1Pin = 22;
const int row2Pin = 23;
const int row3Pin = 24;
const int row4Pin = 25;
const int row5Pin = 26;
const int row6Pin = 27;
const int row7Pin = 28;
const int rowPins[ROWS] =
{
    row1Pin,
    row2Pin,
    row3Pin,
    row4Pin,
    row5Pin,
    row6Pin,
    row7Pin
};

boolean keyPressed[ROWS][COLS];
uint8_t keyToMidiMap[ROWS][COLS];

```

```

//-----BLUETOOTH-----
//SoftwareSerial BT(46, 47); // RX, TX --> can be any digital pins
volatile char command; // data from HC-06 Bluetooth device

//-----LCD-----
Adafruit_ILI9341 tft = Adafruit_ILI9341(TFT_CS, TFT_DC, TFT_MOSI, TFT_CLK,
TFT_RST, TFT_MISO);
int tracker1;
int tracker2;
int tracker3;
int tracker4;
int tracker5;

//-----INDEPENDENT-----
//const int speaker = 37;
//int timer;

double frequencyChart[] =
{
    32.70, 34.65, 36.71, 38.89, 41.20, 43.65, 46.25, 49.00,
    51.91, 55.00, 58.27, 61.74, 65.41, 69.30, 73.42, 77.78,
    82.41, 87.31, 92.50, 98.00, 103.83, 110.00, 116.54, 123.47,
    130.81, 138.59, 146.83, 155.56, 164.81, 174.61, 185.00, 196.00,
    207.65, 220.0, 223.08, 246.94, 261.63, 277.18, 293.66, 311.13, 329.63,
    349.23, 369.99, 392.00, 415.30, 440.00, 466.16, 493.88, 523.25, 554.37,
    587.33, 622.25, 659.25, 698.46,
};
byte storedWave[SAMPLES]; // Stored waveform

unsigned long t = 0; // Counter used to iterate through the waveform
int buf; // Buffer for the next value to load into the DAC.

```

```
unsigned int count; // Count of the loop. Used to limit the number of
function calls per loop.
```

```
void setup() {
    count = 0;

    //setting up LCD
    tracker1 = 0;
    tracker2 = 0;
    tracker3 = 0;
    tracker4 = 0;
    tracker5 = 0;

    tft.begin();
    tft.setRotation(3); // rotate screen orientation
    tft.fillScreen(ILI9341_BLACK);
    tft.setCursor(0, 0);
    tft.setTextColor(ILI9341_GREEN);
    tft.setTextSize(3);
    tft.println("WELCOME TO...");
    delay(2000);
    tft.setTextColor(ILI9341_RED);
    tft.setTextSize(4);
    tft.println();
    tft.println("The CDT");
    tft.println("MixMaster");
    tft.println("8000!!!");
    delay(3500); // display this message for a bit
    tft.fillScreen(ILI9341_BLACK);
    tft.setCursor(0, 0);
    tft.setTextColor(ILI9341_GREEN);
    tft.setTextSize(3);
    tft.println("OPERATING MODE:");
}
```

```

// boolean matrix that checks for keys pressed
for (int i = 0; i < COLS; ++i) {
    for (int j = 0; j < ROWS; ++j) {
        keyPressed[j][i] = false;
    }
}

```

```

// maps correct MIDI notes to each key
int note = 0x24; //c2 = note 36
for (int i = 0; i < ROWS ; ++i) {
    for (int j = 0; j < COLS; ++j) {
        keyToMidiMap[i][j] = note;
        note++;
    }
}

```

```

// pin mode setup

```

```

pinMode(col1Pin, OUTPUT);
pinMode(col2Pin, OUTPUT);
pinMode(col3Pin, OUTPUT);
pinMode(col4Pin, OUTPUT);
pinMode(col5Pin, OUTPUT);
pinMode(col6Pin, OUTPUT);
pinMode(col7Pin, OUTPUT);
pinMode(col8Pin, OUTPUT);

```

```

//pinMode(speaker, OUTPUT);

```

```

pinMode(row1Pin, INPUT);
pinMode(row2Pin, INPUT);
pinMode(row3Pin, INPUT);

```

```

pinMode(row4Pin, INPUT);
pinMode(row5Pin, INPUT);
pinMode(row6Pin, INPUT);
pinMode(row7Pin, INPUT);

Serial.begin(2000000);
Serial1.begin(SERIAL_RATE);

// The HC-06 defaults to 9600 according to the datasheet.
Serial3.begin(9600);
command = '0';

// DAC Pins. PORT D.
pinMode(10, OUTPUT);
pinMode(11, OUTPUT);
pinMode(12, OUTPUT);
pinMode(13, OUTPUT);
pinMode(50, OUTPUT);
pinMode(51, OUTPUT);
pinMode(52, OUTPUT);
pinMode(53, OUTPUT);
// Setup interrupts for signal output to DAC.
cli();//stop interrupts

//set timer2 interrupt at 40kHz
TCCR2A = 0;// set entire TCCR2A register to 0
TCCR2B = 0;// same for TCCR2B
TCNT2 = 0;//initialize counter value to 0
// set compare match register for 40khz increments
OCR2A = 49;//(84*10000) / ((8*10)-1)
// turn on CTC mode
TCCR2A |= (1 << WGM21);
// Set CS21 bit for 8 prescaler

```

```

TCCR2B |= (1 << CS21);
// enable timer compare interrupt
TIMSK2 |= (1 << OCIE2A);
sei();//allow interrupts

// Adjust frequencies to proper values
// 10 is used based on the 4000 samples of the array
// 2 is used to increase the notes by 1 octave
for (int j = 0; j < 54; j++) {
    frequencyChart[j] = (frequencyChart[j] / 10.0) * 2;
}

// Initialize the stored wave to a sine wave.
//generateSine();
}

// Smallest possible implementation of scanKeys(), smallest being time
increment
int bigRowCtr = 0;
int bigColCtr = 0;
int bigRowValue[ROWS];
void scanKeys() {
    digitalWrite(colPins[bigColCtr], HIGH);

    bigRowValue[bigRowCtr] = digitalRead(rowPins[bigRowCtr]);

    if (bigRowValue[bigRowCtr] != 0 && !keyPressed[bigRowCtr][bigColCtr]) {
        keyPressed[bigRowCtr][bigColCtr] = true;
    }
    if (bigRowValue[bigRowCtr] == 0 && keyPressed[bigRowCtr][bigColCtr]) {
        keyPressed[bigRowCtr][bigColCtr] = false;
    }
    digitalWrite(colPins[bigColCtr], LOW);
}

```



```

bigRowCtr++;
if (bigRowCtr >= ROWS) {
    bigRowCtr = 0;
    bigColCtr++;
    if (bigColCtr >= COLS) {
        bigColCtr = 0;
    }
}
}

void noteOn(int row, int col) {
    Serial1.write(NOTE_ON_CMD);
    Serial1.write(keyToMidiMap[row][col]);
    Serial1.write(NOTE_VELOCITY);
}

void noteOff(int row, int col) {
    Serial1.write(NOTE_OFF_CMD);
    Serial1.write(keyToMidiMap[row][col]);
    Serial1.write(NOTE_VELOCITY);
}

void drawRects() {
    /*
    for (int j = 80; j < 120; j += 20) {
        for (int i = 0; i < 320; i += 20) {
            tft.fillRect(i, j, 20, 20, ILI9341_BLACK);
        }
    }
    */
    tft.fillRect(55, 80, 265, 40, ILI9341_BLACK);
}

```

```

void sineWave() {
    if (tracker1 == 0) {
        generateSine();
        if (tracker2 == 1) {
            tft.fillRect(0, 30, 320, 90, ILI9341_BLACK);
        } else {
            drawRects();
        }
        tft.setCursor(0, 40);
        tft.setTextSize(3);
        tft.setTextColor(ILI9341_RED);
        tft.println("Normal Keyboard");
        tft.println();
        tft.println("--> Sine Wave");

    }
    tracker1 = 1;
    tracker2 = 0;
    tracker3 = 0;
    tracker4 = 0;
    tracker5 = 0;

    incrementedScan();
    buf = loadBuffer();

}

void squareWave () {
    if (tracker3 == 0) {
        generateSquare();
        if (tracker2 == 1) {
            tft.fillRect(0, 30, 320, 90, ILI9341_BLACK);
        } else {

```

```

        drawRects();
    }
    tft.setCursor(0, 40);
    tft.setTextSize(3);
    tft.setTextColor(ILI9341_RED);
    tft.println("Normal Keyboard");
    tft.println();
    tft.println("--> Square Wave");

}

tracker1 = 0;
tracker2 = 0;
tracker3 = 1;
tracker4 = 0;
tracker5 = 0;

incrementedScan();
buf = loadBuffer();
}

void sawtoothWave () {
    if (tracker4 == 0) {
        generateSawtooth();
        if (tracker2 == 1) {
            tft.fillRect(0, 30, 320, 90, ILI9341_BLACK);
        } else {
            drawRects();
        }
        tft.setCursor(0, 40);
        tft.setTextSize(3);
        tft.setTextColor(ILI9341_RED);
        tft.println("Normal Keyboard");
        tft.println();
    }
}

```

```

        tft.println("--> Sawtooth Wave");

    }

    tracker1 = 0;
    tracker2 = 0;
    tracker3 = 0;
    tracker4 = 1;
    tracker5 = 0;

    incrementedScan();
    buf = loadBuffer();
}

void triangleWave () {
    if (tracker5 == 0) {
        generateTriangle();
        if (tracker2 == 1) {
            tft.fillRect(0, 30, 320, 90, ILI9341_BLACK);
        } else {
            drawRects();
        }
        tft.setCursor(0, 40);
        tft.setTextSize(3);
        tft.setTextColor(ILI9341_RED);
        tft.println("Normal Keyboard");
        tft.println();
        tft.println("--> Triangle Wave");

    }

    tracker1 = 0;
    tracker2 = 0;
    tracker3 = 0;
    tracker4 = 0;

```

```

    tracker5 = 1;

    incrementedScan();
    buf = loadBuffer();
}

void MIDIOp() {
    if (tracker2 == 0) {
        tft.fillRect(0, 30, 320, 90, ILI9341_BLACK);
        tft.setCursor(0, 40);
        tft.setTextSize(3);
        tft.setTextColor(ILI9341_RED);
        tft.println("MIDI");
        tft.println();
        tft.println("Keyboard");
    }
    tracker2 = 1;
    tracker1 = 0;
    tracker3 = 0;
    tracker4 = 0;
    tracker5 = 0;

    for (int colCtr = 0; colCtr < COLS; ++colCtr) {
        digitalWrite(colPins[colCtr], HIGH);

        int rowValue[ROWS]; // moved this to inside the loop

        // get the row values of the scanned columns
        rowValue[0] = digitalRead(row1Pin);
        rowValue[1] = digitalRead(row2Pin);
        rowValue[2] = digitalRead(row3Pin);
        rowValue[3] = digitalRead(row4Pin);
        rowValue[4] = digitalRead(row5Pin);
    }
}

```

```

    rowValue[5] = digitalRead(row6Pin);
    rowValue[6] = digitalRead(row7Pin);

    // process keys pressed
    for(int rowCtr=0; rowCtr < ROWS; ++rowCtr) {
        if (rowValue[rowCtr] != 0 && !keyPressed[rowCtr][colCtr]) {
            keyPressed[rowCtr][colCtr] = true;
            noteOn(rowCtr,colCtr);
        } else if (rowValue[rowCtr] == 0 && keyPressed[rowCtr][colCtr]) {
            keyPressed[rowCtr][colCtr] = false;
            noteOff(rowCtr,colCtr);
        }
    }
    digitalWrite(colPins[colCtr], LOW);
}
}

// Returns the correct value to load into the buffer
int loadBuffer() {
    unsigned int result = 0;
    unsigned int num = 0;
    unsigned int pos = t;
    double freq = 40;
    unsigned int leftshift = 0;
    unsigned int rightshift = 0;

    for (int i = 0; i < COLS; ++i) {
        for (int j = 0; j < ROWS; ++j) {
            if (keyPressed[j][i]) {
                //freq = frequencyChart[(i*8) + j];
                freq = frequencyChart[i + (j*8)];
                /*
                leftshift = analogRead(0);

```

```

    rightshift = analogRead(1);

    Serial.print("leftshift: ");
    Serial.println(leftshift);
    Serial.print("rightshift: ");
    Serial.print(rightshift);

    if (leftshift > 350 && leftshift < 610) {
        freq = freq / ((0.0125 * (double) leftshift) + 1);
    } else if (rightshift > 350 && rightshift < 610) {
        freq = freq * ((0.0125 * (double) rightshift) + 1);
    }
    */
    //Serial.println((i*8) + j);
    //Serial.print("leftshift: ");
    //Serial.println(leftshift);
    //Serial.print("rightshift: ");
    //Serial.print(rightshift);

    pos = freq * t;
    pos = pos & 0xFFF;

    result += storedWave[pos]; //library here
    num++;
}
}

// Normalize the wave. Consider optimizing. Division is very expensive.
if (num) {
    //result = result >> 3;
    result = result / num;
}

```

```

    return result;
}

// Generate sine wave and place values in storedWave
void generateSine() {
    // Generate sine signals
    for (int i = 0; i < SAMPLES; i++) {
        storedWave[i] = 127 + (127 * sin((6.28*i)/SAMPLES));
        //Serial.println(storedWave[i]);
    }
}

// Generate sawtooth wave and place values in storedWave
void generateSawtooth() {
    for (int i = 0; i < SAMPLES; i++) {
        storedWave[i] = (i * 256) / SAMPLES;
    }
}

// Generate square wave and place values in storedWave
void generateSquare() {
    for (int i = 0; i < SAMPLES; i++) {
        if (i < (SAMPLES / 2)) {
            storedWave[i] = 255;
        } else {
            storedWave[i] = 0;
        }
    }
}

// Generate triangle wave and place values in storedWave
void generateTriangle() {
    for (int i = 0; i < SAMPLES; i++) {

```



```

        if (i < (SAMPLES/2)) {
            storedWave[i] = (i * 256 * 2) / SAMPLES;
        } else {
            storedWave[i] = 255 - (((i - (SAMPLES / 2)) * 256 * 2) / SAMPLES);
        }
    }
}

void incrementedScan() {
    // Scan the keys once every 10 loops
    count++;
    if (count >= 10) {
        count = 0;
    }
    if (!count) {
        scanKeys();
    }
}

void loop() {

    if (Serial3.available()) { // if there is bluetooth data, update command
        while(Serial3.available()) { // While there is more to be read, keep
reading.
            command = Serial3.read();
        }
    }
    if (command == 'm') { //MIDI OPERATION
        MIDIOp();
    } else if (command == 'i') { //INDEPENDENT OPERATION
        sineWave();
    } else if (command == 'q') {
        squareWave();
    }
}

```

```

    } else if (command == 'a') {
        sawtoothWave();
    } else if (command == 't') {
        triangleWave();
    } else {
        sineWave();
    }
}

// Interrupt code for timer 2
ISR(TIMER2_COMPA_vect){
    PORTB = buf;
    t++;
}

#include <SoftwareSerial.h> //bluetooth header
#include "Adafruit_GFX.h"
#include "Adafruit_ILI9341.h"

//using pins 40 - 45 for LCD
#define TFT_CS 40
#define TFT_RST 41
#define TFT_DC 42
#define TFT_MOSI 43
#define TFT_CLK 44
#define TFT_MISO 45

#define ROWS 7
#define COLS 8

// MIDI serial definitions
#define NOTE_ON_CMD 0x90
#define NOTE_OFF_CMD 0x80
#define NOTE_VELOCITY 0x7F // any value 0-127

```

```

// MIDI baud rate
#define SERIAL_RATE 31250

// Maximum number of keys that can be played at once
#define MAX_KEYS_PLAYED 12

// Number of samples in sine wave. Highly recommend using a power of 2.
#define SAMPLES 4096

//-----MIDI-----
// column pins
const int col1Pin = 29;
const int col2Pin = 30;
const int col3Pin = 31;
const int col4Pin = 32;
const int col5Pin = 33;
const int col6Pin = 34;
const int col7Pin = 35;
const int col8Pin = 36;
const int colPins[COLS] =
{
    col1Pin,
    col2Pin,
    col3Pin,
    col4Pin,
    col5Pin,
    col6Pin,
    col7Pin,
    col8Pin
};

```

```

// row pins
const int row1Pin = 22;
const int row2Pin = 23;
const int row3Pin = 24;
const int row4Pin = 25;
const int row5Pin = 26;
const int row6Pin = 27;
const int row7Pin = 28;
const int rowPins[ROWS] =
{
    row1Pin,
    row2Pin,
    row3Pin,
    row4Pin,
    row5Pin,
    row6Pin,
    row7Pin
};

boolean keyPressed[ROWS][COLS];
uint8_t keyToMidiMap[ROWS][COLS];

//-----BLUETOOTH-----
//SoftwareSerial BT(46, 47); // RX, TX --> can be any digital pins
volatile char command; // data from HC-06 Bluetooth device

//-----LCD-----
Adafruit_ILI9341 tft = Adafruit_ILI9341(TFT_CS, TFT_DC, TFT_MOSI, TFT_CLK,
TFT_RST, TFT_MISO);
int tracker1;
int tracker2;

```

```

int tracker3;
int tracker4;
int tracker5;

//-----INDEPENDENT-----

//const int speaker = 37;
//int timer;

double frequencyChart[] =
{
    32.70, 34.65, 36.71, 38.89, 41.20, 43.65, 46.25, 49.00,
    51.91, 55.00, 58.27, 61.74, 65.41, 69.30, 73.42, 77.78,
    82.41, 87.31, 92.50, 98.00, 103.83, 110.00, 116.54, 123.47,
    130.81, 138.59, 146.83, 155.56, 164.81, 174.61, 185.00, 196.00,
    207.65, 220.0, 223.08, 246.94, 261.63, 277.18, 293.66, 311.13, 329.63,
    349.23, 369.99, 392.00, 415.30, 440.00, 466.16, 493.88, 523.25, 554.37,
    587.33, 622.25, 659.25, 698.46,
};

byte storedWave[SAMPLES]; // Stored waveform

unsigned long t = 0; // Counter used to iterate through the waveform
int buf; // Buffer for the next value to load into the DAC.
unsigned int count; // Count of the loop. Used to limit the number of
function calls per loop.

void setup() {
    count = 0;

    //setting up LCD
    tracker1 = 0;
    tracker2 = 0;
    tracker3 = 0;

```

```

tracker4 = 0;
tracker5 = 0;

tft.begin();
tft.setRotation(3); // rotate screen orientation
tft.fillScreen(ILI9341_BLACK);
tft.setCursor(0, 0);
tft.setTextColor(ILI9341_GREEN);
tft.setTextSize(3);
tft.println("WELCOME TO...");
delay(2000);
tft.setTextColor(ILI9341_RED);
tft.setTextSize(4);
tft.println();
tft.println("The CDT");
tft.println("MixMaster");
tft.println("8000!!!");
delay(3500); // display this message for a bit
tft.fillScreen(ILI9341_BLACK);
tft.setCursor(0, 0);
tft.setTextColor(ILI9341_GREEN);
tft.setTextSize(3);
tft.println("OPERATING MODE:");

// boolean matrix that checks for keys pressed
for (int i = 0; i < COLS; ++i) {
    for (int j = 0; j < ROWS; ++j) {
        keyPressed[j][i] = false;
    }
}

// maps correct MIDI notes to each key
int note = 0x24; //c2 = note 36

```

```

for (int i = 0; i < ROWS ; ++i) {
    for (int j = 0; j < COLS; ++j) {
        keyToMidiMap[i][j] = note;
        note++;
    }
}

// pin mode setup

pinMode(col1Pin, OUTPUT);
pinMode(col2Pin, OUTPUT);
pinMode(col3Pin, OUTPUT);
pinMode(col4Pin, OUTPUT);
pinMode(col5Pin, OUTPUT);
pinMode(col6Pin, OUTPUT);
pinMode(col7Pin, OUTPUT);
pinMode(col8Pin, OUTPUT);

//pinMode(speaker, OUTPUT);

pinMode(row1Pin, INPUT);
pinMode(row2Pin, INPUT);
pinMode(row3Pin, INPUT);
pinMode(row4Pin, INPUT);
pinMode(row5Pin, INPUT);
pinMode(row6Pin, INPUT);
pinMode(row7Pin, INPUT);

Serial.begin(2000000);
Serial1.begin(SERIAL_RATE);

// The HC-06 defaults to 9600 according to the datasheet.
Serial3.begin(9600);

```

```

command = '0';

// DAC Pins. PORT D.
pinMode(10, OUTPUT);
pinMode(11, OUTPUT);
pinMode(12, OUTPUT);
pinMode(13, OUTPUT);
pinMode(50, OUTPUT);
pinMode(51, OUTPUT);
pinMode(52, OUTPUT);
pinMode(53, OUTPUT);
// Setup interrupts for signal output to DAC.
cli();//stop interrupts

//set timer2 interrupt at 40kHz
TCCR2A = 0;// set entire TCCR2A register to 0
TCCR2B = 0;// same for TCCR2B
TCNT2 = 0;//initialize counter value to 0
// set compare match register for 40khz increments
OCR2A = 49;//(84*10000) / ((8*10)-1)
// turn on CTC mode
TCCR2A |= (1 << WGM21);
// Set CS21 bit for 8 prescaler
TCCR2B |= (1 << CS21);
// enable timer compare interrupt
TIMSK2 |= (1 << OCIE2A);
sei();//allow interrupts

// Adjust frequencies to proper values
// 10 is used based on the 4000 samples of the array
// 2 is used to increase the notes by 1 octave
for (int j = 0; j < 54; j++) {
    frequencyChart[j] = (frequencyChart[j] / 10.0) * 2;
}

```



```

    }

    // Initialize the stored wave to a sine wave.
    //generateSine();
}

// Smallest possible implementation of scanKeys(), smallest being time
increment
int bigRowCtr = 0;
int bigColCtr = 0;
int bigRowValue[ROWS];
void scanKeys() {
    digitalWrite(colPins[bigColCtr], HIGH);

    bigRowValue[bigRowCtr] = digitalRead(rowPins[bigRowCtr]);

    if (bigRowValue[bigRowCtr] != 0 && !keyPressed[bigRowCtr][bigColCtr]) {
        keyPressed[bigRowCtr][bigColCtr] = true;
    }
    if (bigRowValue[bigRowCtr] == 0 && keyPressed[bigRowCtr][bigColCtr]) {
        keyPressed[bigRowCtr][bigColCtr] = false;
    }
    digitalWrite(colPins[bigColCtr], LOW);
    bigRowCtr++;
    if (bigRowCtr >= ROWS) {
        bigRowCtr = 0;
        bigColCtr++;
        if (bigColCtr >= COLS) {
            bigColCtr = 0;
        }
    }
}
}

```

```

void noteOn(int row, int col) {
    Serial1.write(NOTE_ON_CMD);
    Serial1.write(keyToMidiMap[row][col]);
    Serial1.write(NOTE_VELOCITY);
}

void noteOff(int row, int col) {
    Serial1.write(NOTE_OFF_CMD);
    Serial1.write(keyToMidiMap[row][col]);
    Serial1.write(NOTE_VELOCITY);
}

void drawRects() {
    /*
    for (int j = 80; j < 120; j += 20) {
        for (int i = 0; i < 320; i += 20) {
            tft.fillRect(i, j, 20, 20, ILI9341_BLACK);
        }
    }
    */
    tft.fillRect(55, 80, 265, 40, ILI9341_BLACK);
}

void sineWave() {
    if (tracker1 == 0) {
        generateSine();
        if (tracker2 == 1) {
            tft.fillRect(0, 30, 320, 90, ILI9341_BLACK);
        } else {
            drawRects();
        }
        tft.setCursor(0, 40);
        tft.setTextSize(3);
    }
}

```

```

        tft.setTextColor(ILI9341_RED);
        tft.println("Normal Keyboard");
        tft.println();
        tft.println("--> Sine Wave");

    }

    tracker1 = 1;
    tracker2 = 0;
    tracker3 = 0;
    tracker4 = 0;
    tracker5 = 0;

    incrementedScan();
    buf = loadBuffer();

}

void squareWave () {
    if (tracker3 == 0) {
        generateSquare();
        if (tracker2 == 1) {
            tft.fillRect(0, 30, 320, 90, ILI9341_BLACK);
        } else {
            drawRects();
        }
        tft.setCursor(0, 40);
        tft.setTextSize(3);
        tft.setTextColor(ILI9341_RED);
        tft.println("Normal Keyboard");
        tft.println();
        tft.println("--> Square Wave");
    }
}

```

```

    tracker1 = 0;
    tracker2 = 0;
    tracker3 = 1;
    tracker4 = 0;
    tracker5 = 0;

    incrementedScan();
    buf = loadBuffer();
}

void sawtoothWave () {
    if (tracker4 == 0) {
        generateSawtooth();
        if (tracker2 == 1) {
            tft.fillRect(0, 30, 320, 90, ILI9341_BLACK);
        } else {
            drawRects();
        }
        tft.setCursor(0, 40);
        tft.setTextSize(3);
        tft.setTextColor(ILI9341_RED);
        tft.println("Normal Keyboard");
        tft.println();
        tft.println("--> Sawtooth Wave");
    }

    tracker1 = 0;
    tracker2 = 0;
    tracker3 = 0;
    tracker4 = 1;
    tracker5 = 0;

    incrementedScan();

```

```

    buf = loadBuffer();
}

void triangleWave () {
    if (tracker5 == 0) {
        generateTriangle();
        if (tracker2 == 1) {
            tft.fillRect(0, 30, 320, 90, ILI9341_BLACK);
        } else {
            drawRects();
        }
        tft.setCursor(0, 40);
        tft.setTextSize(3);
        tft.setTextColor(ILI9341_RED);
        tft.println("Normal Keyboard");
        tft.println();
        tft.println("--> Triangle Wave");
    }

    tracker1 = 0;
    tracker2 = 0;
    tracker3 = 0;
    tracker4 = 0;
    tracker5 = 1;

    incrementedScan();
    buf = loadBuffer();
}

void MIDIOp() {
    if (tracker2 == 0) {
        tft.fillRect(0, 30, 320, 90, ILI9341_BLACK);
        tft.setCursor(0, 40);
    }
}

```

```

    tft.setTextSize(3);
    tft.setTextColor(ILI9341_RED);
    tft.println("MIDI");
    tft.println();
    tft.println("Keyboard");
}

tracker2 = 1;
tracker1 = 0;
tracker3 = 0;
tracker4 = 0;
tracker5 = 0;

for (int colCtr = 0; colCtr < COLS; ++colCtr) {
    digitalWrite(colPins[colCtr], HIGH);

    int rowValue[ROWS]; // moved this to inside the loop

    // get the row values of the scanned columns
    rowValue[0] = digitalRead(row1Pin);
    rowValue[1] = digitalRead(row2Pin);
    rowValue[2] = digitalRead(row3Pin);
    rowValue[3] = digitalRead(row4Pin);
    rowValue[4] = digitalRead(row5Pin);
    rowValue[5] = digitalRead(row6Pin);
    rowValue[6] = digitalRead(row7Pin);

    // process keys pressed
    for(int rowCtr=0; rowCtr < ROWS; ++rowCtr) {
        if (rowValue[rowCtr] != 0 && !keyPressed[rowCtr][colCtr]) {
            keyPressed[rowCtr][colCtr] = true;
            noteOn(rowCtr,colCtr);
        } else if (rowValue[rowCtr] == 0 && keyPressed[rowCtr][colCtr]) {
            keyPressed[rowCtr][colCtr] = false;

```

```

        noteOff(rowCtr,colCtr);
    }
}
digitalWrite(colPins[colCtr], LOW);
}
}

// Returns the correct value to load into the buffer
int loadBuffer() {
    unsigned int result = 0;
    unsigned int num = 0;
    unsigned int pos = t;
    double freq = 40;
    unsigned int leftshift = 0;
    unsigned int rightshift = 0;

    for (int i = 0; i < COLS; ++i) {
        for (int j = 0; j < ROWS; ++j) {
            if (keyPressed[j][i]) {
                //freq = frequencyChart[(i*8) + j];
                freq = frequencyChart[i + (j*8)];
                /*
                leftshift = analogRead(0);
                rightshift = analogRead(1);

                Serial.print("leftshift: ");
                Serial.println(leftshift);
                Serial.print("rightshift: ");
                Serial.print(rightshift);

                if (leftshift > 350 && leftshift < 610) {
                    freq = freq / ((0.0125 * (double) leftshift) + 1);
                } else if (rightshift > 350 && rightshift < 610) {

```

```

        freq = freq * ((0.0125 * (double) rightshift) + 1);
    }
    */
    //Serial.println((i*8) + j);
    //Serial.print("leftshift: ");
    //Serial.println(leftshift);
    //Serial.print("rightshift: ");
    //Serial.print(rightshift);

    pos = freq * t;
    pos = pos & 0xFF;

    result += storedWave[pos]; //library here
    num++;
}
}

// Normalize the wave. Consider optimizing. Division is very expensive.
if (num) {
    //result = result >> 3;
    result = result / num;
}
return result;
}

// Generate sine wave and place values in storedWave
void generateSine() {
    // Generate sine signals
    for (int i = 0; i < SAMPLES; i++) {
        storedWave[i] = 127 + (127 * sin((6.28*i)/SAMPLES));
        //Serial.println(storedWave[i]);
    }
}

```



```

}

// Generate sawtooth wave and place values in storedWave
void generateSawtooth() {
    for (int i = 0; i < SAMPLES; i++) {
        storedWave[i] = (i * 256) / SAMPLES;
    }
}

// Generate square wave and place values in storedWave
void generateSquare() {
    for (int i = 0; i < SAMPLES; i++) {
        if (i < (SAMPLES / 2)) {
            storedWave[i] = 255;
        } else {
            storedWave[i] = 0;
        }
    }
}

// Generate triangle wave and place values in storedWave
void generateTriangle() {
    for (int i = 0; i < SAMPLES; i++) {
        if (i < (SAMPLES/2)) {
            storedWave[i] = (i * 256 * 2) / SAMPLES;
        } else {
            storedWave[i] = 255 - (((i - (SAMPLES / 2)) * 256 * 2) / SAMPLES);
        }
    }
}

void incrementedScan() {
    // Scan the keys once every 10 loops

```

```

    count++;
    if (count >= 10) {
        count = 0;
    }
    if (!count) {
        scanKeys();
    }
}

void loop() {

    if (Serial3.available()) { // if there is bluetooth data, update command
        while(Serial3.available()) { // While there is more to be read, keep
reading.
            command = Serial3.read();
        }
    }
    if (command == 'm') { //MIDI OPERATION
        MIDIOp();
    } else if (command == 'i') { //INDEPENDENT OPERATION
        sineWave();
    } else if (command == 'q') {
        squareWave();
    } else if (command == 'a') {
        sawtoothWave();
    } else if (command == 't') {
        triangleWave();
    } else {
        sineWave();
    }
}

```

```
// Interrupt code for timer 2
ISR(TIMER2_COMPA_vect){
    PORTB = buf;
    t++;
}
```