Deshpande_Charudatta_Linear_Algebra

January 21, 2018

1 Linear algebra

This is a voluntary problem set that helps you to learn linear algebra (and the related numpy commands.) Consult Greene "Econometric Analysis" Appendix A when solving these problems. If handed in (and solved correctly ;-), it gives you 5 credits.

```
### Student Name - Charudatta Deshpande
     ###
                                            ###
     ### Collaborators - Ram Ganesan, Charles Hemstreet, Mehdi Muntazir ###
     ###
     ### Import required libraries.
     ###
     import numpy as np
     import scipy as sp
     from scipy import linalg
     import pandas as pd
     import math as mt
     from numpy.linalg import matrix_rank
```

1.1 1 Matrix multiplication

- create the following matrices: a = [1 2 3 4], b = [5 6 7 8]' (note: b includes the transposition sign)
- compute the following matrix products $a \cdot b$ and $a' \cdot b'$

```
c = np.dot(a,b)
         print('ab is equal to : ', c)
         # Calculate the dot product ab
         a_dash = a.transpose()
         b_dash = b.transpose()
         d = np.dot(a_dash,b_dash)
         print('ab is equal to : \n', d)
[[1 2 3 4]]
[[5]
 [6]
 [7]
 [8]]
ab is equal to : [[70]]
ab is equal to :
[[ 5 6 7 8]
 [10 12 14 16]
 [15 18 21 24]
 [20 24 28 32]]
```

1.2 2 Linear (in)dependence

Consider three vectors: $a = [1 \ 2 \ 3 \ 4], b = [5 \ 6 \ 7 \ 8]$ and $c = [9 \ 10 \ 11 \ 12]$

• are these vectors linearly independent? Calculate the rank, a related determinant, and show how they are related/unrelated

```
In [63]: #
    # Input the matrices.
#
# This is about determinant.
# If the matrices can be described in terms of each other, they are dependent.
# else they are independent.
# Create a single matrix out of 3 vectors. Calculate rank.
# If rank is greater than 3 (number of rows), these vectors are independent.
#
a = np.matrix([[1,2,3,4]])
b = np.matrix([[5,6,7,8]])
c = np.matrix([[9,10,11,12]])
X = np.row_stack([a, b, c])
print(X)
#
# Method 1 to calculate rank
#
print('Matrix X rank is: ', matrix_rank(X))
```

```
# Method 2 to calculate rank
        TOLERANCE = 1e-14
        U, s, V = np.linalg.svd(X)
        print(s)
        print('Matrix X rank using second methos is: ', np.sum(s > TOLERANCE))
[[1 2 3 4]
 [5 6 7 8]
 [ 9 10 11 12]]
Matrix X rank is: 2
[ 2.54368356e+01 1.72261225e+00
                                    4.20733283e-16]
Matrix X rank using second methos is: 2
In [64]: ## Explanation of Q 2.
         ## The rank is 2 and number of rows are 3.
         ## The number of rows is greater than the rank, so these vectors are
         ## not independent (are dependent).
         ## This means that one vector can be defined as a linear combination of the
         ## other two vectors.
```

1.3 3 Find the inverses of the following matrices:

```
A = [ 1 2 3 4 5 6 7 8 -1 10 11 12 13 14 15 17 ],
B = [ 1 0 0 0 4 0 0 0 16]
and
C = [ 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 17 ]
```

• Check the results by left- and right multiplication of the inverse. Explain.

```
print('A.A_inverse is equal to : \n', np.dot(A, A_inverse))
        print('A_inverse.A is equal to : \n', np.dot(A_inverse, A))
        print('B.B_inverse is equal to : \n', np.dot(B, B_inverse))
        print('B inverse.B is equal to : \n', np.dot(B inverse, B))
        print('C.C_inverse is equal to : \n', np.dot(C, C_inverse))
        print('C inverse.C is equal to : \n', np.dot(C inverse, C))
A inverse is equal to :
 [[ -1.0000000e-01
                     2.00000000e-01 -1.0000000e-01
                                                     2.73285668e-16]
 [ 4.50000000e-01 -2.65000000e+00
                                    2.0000000e-01
                                                    1.00000000e+00]
 [ -2.6000000e+00
                    5.70000000e+00 -1.00000000e-01 -2.00000000e+00]
 [ 2.00000000e+00 -3.00000000e+00 -7.40148683e-17
                                                    1.00000000e+00]]
B inverse is equal to:
 [[ 1.
           0.
                   0.
 [ 0.
          0.25
                  0.
                       1
 [ 0.
          0.
                  0.0625]]
C inverse is equal to :
 [[ -1.54070514e+15
                     3.08141027e+15 -1.54070514e+15 -4.70000000e-01]
 [ 3.08141027e+15 -6.16282054e+15
                                    3.08141027e+15
                                                    1.9400000e+00]
 「 -1.54070514e+15
                    3.08141027e+15 -1.54070514e+15
                                                  -2.47000000e+001
 1.15789474e+00 -1.31578947e+00 -8.42105263e-01
                                                    1.0000000e+00]]
A.A inverse is equal to :
 [[ 1.0000000e+00
                    0.00000000e+00
                                     0.0000000e+00
                                                     0.0000000e+00]
 [ 0.0000000e+00
                                    0.0000000e+00
                                                    0.0000000e+001
                    1.0000000e+00
 [ 0.0000000e+00
                    7.10542736e-15
                                    1.0000000e+00
                                                   -3.55271368e-15]
 [ 0.0000000e+00
                                                    1.0000000e+00]]
                    0.0000000e+00
                                    0.0000000e+00
A_inverse.A is equal to :
                                                     2.22044605e-15]
 [[ 1.0000000e+00
                     1.77635684e-15
                                     1.77635684e-15
 [ -1.77635684e-15
                    1.00000000e+00 -1.77635684e-15 -2.66453526e-15]
 [ 1.33226763e-15
                    8.88178420e-16
                                    1.00000000e+00
                                                    1.77635684e-15]
 [ 4.44089210e-16
                    1.77635684e-15
                                    1.77635684e-15
                                                    1.00000000e+00]]
B.B_inverse is equal to :
 [[ 1. 0. 0.]
 [ 0. 1. 0.]
 [ 0. 0. 1.]]
B_inverse.B is equal to :
 [[ 1. 0. 0.]
 [ 0. 1. 0.]
 [ 0. 0. 1.]]
C.C inverse is equal to :
 [[ 1.
         0.
              1.
                   0.1
 Γ-4.
        0. -4.
                  0.1
 Γ-4.
             0.
                  0.1
        8.
 [ 0. 16.
             0.
                  1.]]
C_inverse.C is equal to :
 [[ 8.0000000e+00
                    8.0000000e+00
                                     8.0000000e+00
                                                     1.20000000e+01]
```

```
[ -8.88178420e-16 -1.77635684e-15 -1.77635684e-15 1.00000000e+00]]

In [66]: ## Explanation of Q 3.

## Dot product of a matrix and its inverse should be an identity matrix irrespective ## of the order of the multiplication.

## For A, A.A_inverse and A_inverse.A are very close to being an identity matrix.

## However, the identity matrices are not perfect.

## For B, B.B_inverse and B_inverse.B are perfect identity matrices.

## For C, C.C_inverse and C_inverse.C are not identity matrices.

## This indicates that C is not an invertible matrix.
```

8.0000000e+001

1.4 4 Characteristic roots

• Find the roots (eigenvalues) of the matrices A, B, C above.

[4.0000000e+00 4.0000000e+00 8.0000000e+00

- Calculate the condition numbers of these matrices in two ways: the default numpy way, and in this way as it is explained in Greene (2003, page 829)
- Explain the results

```
In [67]: #
         #Calculate eigenvalues for A, B and C.
         eigvals_A = np.linalg.eigvals(A)
         eigvals_B = np.linalg.eigvals(B)
         eigvals_C = np.linalg.eigvals(C)
         eigvals_A = np.absolute(eigvals_A)
         eigvals_B = np.absolute(eigvals_B)
         eigvals_C = np.absolute(eigvals_C)
         print('eigenvalues for A: \n', eigvals_A)
         print('eigenvalues for B: \n', eigvals_B)
         print('eigenvalues for C: \n', eigvals_C)
         #Calculate condition numbers for A, B and C - the default numpy way.
         print('condition number for A using Numpy method: \n', np.linalg.cond(A))
         print('condition number for B using Numpy method: \n', np.linalg.cond(B))
         print('condition number for C using Numpy method: \n', np.linalg.cond(C))
         #Calculate condition numbers for A, B and C - as explained in Greene (2003, page 829)
         condition_number_A = np.sqrt(eigvals_A.max() / eigvals_A.min())
         print('condition number for A using Greene method: \n', condition number A)
         condition_number_B = np.sqrt(eigvals_B.max() / eigvals_B.min())
         print('condition number for A using Greene method: \n', condition number B)
         condition_number_C = np.sqrt(eigvals_C.max() / eigvals_C.min())
```

print('condition number for A using Greene method: \n', condition_number_C)

```
eigenvalues for A:
 [ 35.83449756
                1.34371891 1.6853005 0.49291597]
eigenvalues for B:
 [ 1.
        4. 16.]
eigenvalues for C:
 [ 3.66727818e+01
                    2.00000000e+00
                                      2.08470091e-15 3.27218155e-01]
condition number for A using Numpy method:
299.050204082
condition number for B using Numpy method:
condition number for C using Numpy method:
7.60469682786e+16
condition number for A using Greene method:
8.5263707646
condition number for A using Greene method:
condition number for A using Greene method:
132632528.659
In [68]: # Explanation of Q 4 -
         # The condition numbers using Numpy method and Greene method
         # do not match. This could be mostly due to an error I made in the
         # calculation of Eigenvalues, or use of an incorrect option in
         # calculation of condition numbers using Greene method.
         # I understood how the Greene method is used, however I was getting
         # negative eigenvalues, and using those in square root function was
         # returning an invalid calculation. So I had to use absolute values
         # and I believe I missed something there that is giving me wrong
         # condition numbers using Greene method.
```