```
pu
  The user factors (only exists if fit() has been called)
   Type
      numpy array of size (n_users, n_factors)
qi
  The item factors (only exists if | fit() | has been called)
   Type
      numpy array of size (n_items, n_factors)
bu
  The user biases (only exists if fit() has been called)
   Type
      numpy array of size (n_users)
bi
  The item biases (only exists if fit() has been called)
   Type
      numpy array of size (n_items)
```

class surprise.prediction_algorithms.matrix_factorization.SVDpp(n_factors=20, n_epochs=20, init_mean=0, init_std_dev=0.1, lr_all=0.007, reg_all=0.02, lr_bu=None, lr_bi=None, lr_pu=None, lr_qi=None, reg_bu=None, reg_bi=None, reg_pu=None, reg_qi=None, reg_yj=None, random_state=None, verbose=False, cache_ratings=False)

Bases: AlgoBase

The SVD++ algorithm, an extension of svo taking into account implicit ratings.

The prediction \hat{r}_{ui} is set as:

$$\hat{r}_{ui} = \mu + b_u + b_i + q_i^T \left(p_u + |I_u|^{-rac{1}{2}} \sum_{j \in I_u} y_j
ight)$$

Where the y_j terms are a new set of item factors that capture implicit ratings. Here, an implicit rating describes the fact that a user u rated an item j, regardless of the rating value.

If user u is unknown, then the bias b_u and the factors p_u are assumed to be zero. The same applies for item i with b_i , q_i and y_i .

For details, see section 4 of [Kor08]. See also [RRSK10], section 5.3.1.

Just as for svo, the parameters are learned using a SGD on the regularized squared error objective.

Baselines are initialized to <a>o. User and item factors are randomly initialized according to a normal distribution, which can be tuned using the <a>init_mean and <a>init_std_dev parameters.

You have control over the learning rate γ and the regularization term λ . Both can be different for each kind of parameter (see below). By default, learning rates are set to 0.005 and regularization terms are set to 0.002.

Parameters

```
n_factors - The number of factors. Default is 20.
```

n_epochs – The number of iteration of the SGD procedure. Default is **20**.

cache_ratings – Whether or not to cache ratings during *fit()*. This should speed-up the training, and has a higher memory footprint. Default is False.

init_mean - The mean of the normal distribution for factor vectors initialization.Default is •.

init_std_dev - The standard deviation of the normal distribution for factor vectors initialization. Default is 0.1.

Ir_all – The learning rate for all parameters. Default is **0.007**.

reg_all - The regularization term for all parameters. Default is 0.02.

 ${
m lr_bu}$ – The learning rate for b_u . Takes precedence over ${
m lr_all}$ if set. Default is ${
m None}$.

 Ir_bi – The learning rate for b_i . Takes precedence over Ir_all if set. Default is None.

 Ir_pu – The learning rate for p_u . Takes precedence over lr_all if set. Default is ll_n .

 Ir_qi – The learning rate for q_i . Takes precedence over $1r_{all}$ if set. Default is none.

 $m lr_yj$ – The learning rate for y_j . Takes precedence over $m lr_all$ if set. Default is m None .

 ${f reg_bu}$ – The regularization term for b_u . Takes precedence over ${f reg_all}$ if set. Default is ${f None}$.

 ${f reg_bi}$ – The regularization term for b_i . Takes precedence over ${f reg_all}$ if set. Default is ${f None}$.

 ${f reg_pu}$ – The regularization term for p_u . Takes precedence over ${f reg_all}$ if set. Default is ${f None}$.

 ${f reg_qi}$ – The regularization term for q_i . Takes precedence over ${f reg_all}$ if set. Default is ${f None}$.

 $\operatorname{reg_yj}$ – The regularization term for y_j . Takes precedence over $\operatorname{reg_all}$ if set. Default is None .

```
random_state (int, RandomState instance from numpy, or None ) - Determines the
  RNG that will be used for initialization. If int, random_state will be used as a seed for a
  new RNG. This is useful to get the same initialization over multiple calls to fit(). If
  RandomState instance, this same instance is used as RNG. If None, the current RNG
  from numpy is used. Default is None.
  verbose - If True, prints the current epoch. Default is False.
pu
  The user factors (only exists if | fit() | has been called)
   Type
     numpy array of size (n_users, n_factors)
qi
  The item factors (only exists if fit() has been called)
   Type
     numpy array of size (n_items, n_factors)
уj
  The (implicit) item factors (only exists if fit() has been called)
   Type
      numpy array of size (n_items, n_factors)
bu
  The user biases (only exists if fit() has been called)
   Type
     numpy array of size (n_users)
bi
  The item biases (only exists if fit() has been called)
   Type
     numpy array of size (n_items)
```

class surprise.prediction_algorithms.matrix_factorization.NMF(n_factors=15, n_epochs=50, biased=False, reg_pu=0.06, reg_qi=0.06, reg_bu=0.02, reg_bi=0.02, lr_bu=0.005, lr_bi=0.005, init_low=0, init_high=1, random_state=None, verbose=False)