## Math 206A Probability: Chapter 5 Markov Chains: written by Rick Durrett

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Chapter 5.1 Examples

Cahpter 5.2 Construction, Markov Properties

**THeorem 5.2.1**  $X_n$  is a Markov chain (with respect to  $\mathcal{F}_n = \sigma(X_0, X_1, ..., X_n)$ ) with transition probability p. That is,

$$P_{\mu}(X_{n+1} \in B | \mathcal{F}_n) = p(X_n, B)$$

**Theorem 5.2.2 Monotone class theorem** Let A be a  $\pi$  – system that contains  $\Omega$  and let  $\mathcal{H}$  be a collection of real valued functions that satisfies:

- (i) If  $A \in \mathcal{A}$  then  $1_A \in \mathcal{H}$
- (ii) If  $f,g \in \mathcal{H}$  then f + g, and  $cf \in \mathcal{H}$  for any real number c.
- (iii) If  $f_n \in \mathcal{H}$  are nonnegative and increase to a bounded function f then  $f \in \mathcal{H}$ Then  $\mathcal{H}$  contains all bounded functions measurable with respect to  $\sigma(\mathcal{A})$ .

**Theorem 5.2.3 The Markov property** Let  $Y : \Omega_o \to R$  be bounded and measurable

$$E_{\mu}(Y \circ \theta_m | \mathcal{F}_m) = Ex_m Y$$

Theorem 5.2.4 Chapman-Kolmogorov equation

$$P_x(X_{m+n} = z) = \sum_{y} P_x(X_m = y) P_y(X_n = z)$$

**Theorem 5.2.5 Strong Markov property** Suppose that for each  $n, Y_n$ :  $\Omega_0 \to R$  is measurable and  $|Y_n| \le M$  for all n. Then

$$E_{\mu}(Y_n \circ \theta_N | \mathcal{F}_N) = Ex_N Y_N \text{ on } \{N < \infty\}$$

where the right hand side is  $\varphi(x,n)=E_xY_n$  evaluated at  $x=X_N, n=N$ Theorem 5.2.6  $P_x(T_y^k<\infty)=p_{xy}p_{yy}^{k-1}$  Intuitively in order to make k visits to y, we first have to go from x to y and then return k - 1 times to y.

**Theorem 5.2.7 Reflection principle**  $\xi_1, \xi_2, ...$  be independent and identically distributed with a distribution that is symmetric about 0. Let  $S_n =$  $\xi_1 + \dots + \xi_n$  If a > 0 then

$$P(sup_{m \le n} S_m \ge a) \le 2P(S_n \ge a)$$

## Chapter 5.3 Recurrence and Transience

**Theorem 5.3.1** y is recurrent if and only if  $E_y N(y) = \infty$ 

**Theorem 5.3.2** If x is recurrent and  $p_{xy} > 0$  then y is recurrent and  $p_{yx} = 1$ 

**Theorem 5.3.3** Let C be a finite closed set. Then C contains a recurrent state. If C is irreducible then all states in C are recurrent.

Theorem 5.3.5 Decomposition Theorem Let  $R = \{x : p_{xx} = 1\}$  be the recurrent states of a Markov chain. R can be written as  $\bigcup_i R_i$ , where each  $R_i$  is closed and irreducible.

**Theorem 5.3.8** Suppose S is irreducible and  $\varphi \geq 0$  with  $E_x \varphi(X_i) \leq \varphi(x)$  for  $x \notin F$ , a finite set, and  $\varphi(x) \to \infty$  as  $x \to \infty$  i.e.  $\{x : \varphi(x) \leq M\}$  is finite for any  $M < \infty$ , then the chain is recurrent.

**Theorem 5.3.10** If a < x < b then

$$P_x(T_a < T_b) = \frac{\varphi(b) - \varphi(x)}{\varphi(b) - \varphi(a)} \qquad P_X(T_b < T_a) = \frac{\varphi(x) - \varphi(a)}{\varphi(b) - \varphi(a)}$$

**Theorem 5.3.11** 0 is recurrent if and only if  $\varphi(M) \to \infty$  as  $M \to \infty$  i.e.,

$$\varphi(\infty) = \sum_{m=0}^{\infty} \prod_{j=1}^{m} \frac{q_j}{p_j} = \infty$$

If  $\varphi(\infty) < \infty$  then  $P_x(T_0 = \infty) = \varphi(x)/\varphi(\infty)$ 

Chapter 5.4 Recurrence of Random Walks

**Theorem 5.4.1** The set V of recurrent values is either  $\emptyset$  or a closed subgroup of  $\mathbb{R}^d$ . In the second case V = U, the set of possible values.

**Theorem 5.4.3** For any random walk, the following are equivalent: (i)  $P(\mathcal{T}_1 < \infty) = 1$ , (ii)  $P(S_m = 0 \text{ i.o.}) = 1$  and (iii)  $\sum_{m=0}^{\infty} P(S_m = 0) = \infty$ 

**Theorem 5.4.4** Simple random walk is recurrent in  $d \le 2$  and transient in d > 3

**Lemma 5.4.5** If  $\sum_{n=1}^{\infty} P(||S_n|| < \epsilon) < \infty$  then  $P(||S_n|| < \epsilon$  i.o.) = 0. If  $\sum_{n=1}^{\infty} P(||S_n|| < \epsilon) = \infty$  then  $P(||S_n|| < 2\epsilon$  i.o.) = 1.

**Lemma 5.4.6** Let m be an integer  $\geq 2$ 

$$\sum_{n=0}^{\infty} P(||S_n|| < m\epsilon) \le (2m)^d \sum_{n=0}^{\infty} P(||S_n|| < \epsilon)$$

**Theorem 5.4.7** The convergence (resp. divergence) of  $\sum_n P(||S_n|| < \epsilon)$  for a single value of  $\epsilon > 0$  is sufficient for transience (resp. recurrence).

Theorem 5.4.8 Chung Fuchs theorem Suppose d=1. If the weak law of large numbers holds in the form  $S_n/n \to 0$  in probability, then  $S_n$  is recurrent.

**Theorem 5.4.9** If  $S_n$  is a random walk in  $R^2$  and  $S_n/n^{1/2} \Rightarrow$  a nondegenerate normal distribution then  $S_n$  is recurrent.

**Theorem 5.4.10** Let  $\delta > 0.S_n$  is recurrent if and only if

$$\int_{(-\delta,\delta)^d} Re \frac{1}{1-\varphi(y)} dy = \infty$$

**Theorem 5.4.11** Let  $\delta > 0S_n$  is recurrent if and only if

$$\sup_{r<1} \int_{(-\delta,\delta)^d} Re \frac{1}{1-\varphi(y)} dy = \infty$$

**Lemma 5.4.12 Parseval relation** Let  $\mu$  and v be probability measures on  $R^d$  with ch.f.'s  $\varphi$  and  $\psi$ 

$$\int \psi(t)\mu(dt) = \int \varphi(x)v(dx)$$

**lemma 5.4.13** If  $|x| \le \pi/3$  then  $1 - \cos x \ge x^2/4$ 

Theorem 5.4.14 No truly three dimensional random walk is recurrent.

Chapter 5.5 Stationary Measures

**Theorem 5.5.5** Let  $\mu$  be a stationary measure and suppose  $X_0$  has "distribution"  $\mu$ . Then  $Y_m = X_{n-m}, 0 \le m \le n$  is a Markov chain with initial measure  $\mu$  and transition probability

$$q(x, y) = \mu(y)p(y, x)/\mu(x)$$

q is called the dual transition probability. If  $\mu$  is a reversible measure then q = p.

**Theorem 5.5.6 Kolmogorov's cycle condition** Suppose p is irreducible. A necessary and sufficient condition for the existence of a reversible measure is that (i) p(x,y) > 0 implies p(y,x) > 0 and (ii) for any loop  $x_0, x_1, ..., x_n = x_0$  with  $\prod_{1 \le i \le n} p(x_i, x_{i-1}) > 0$ 

$$\prod_{i=1}^{n} \frac{p(x_{i-1}, x_i)}{p(x_i, x_{i-1})} = 1$$

**Theorem 5.5.7** Let x be a recurrent state and let  $T = \inf\{n \ge 1 : X_n = x\}$ . Then

$$\mu_x(y) = E_x(\sum_{n=0}^{T-1} 1_{\{X_n = y\}}) = \sum_{n=0}^{\infty} P_x(X_n = y, T > n)$$

defines a stationary measure.

**Theorem 5.5.9** if p is irreducible and recurrent (i.e. all states are) then the stationary measure is unique up to constant multiples.

**Theorem 5.5.10** If there is a stationary distribution then all states that have  $\pi(y) > 0$  are recurrent.

**Theorem 5.5.11** if p is irreducible and has stationary distribution  $\pi$ , then

$$\pi(x) = 1/E_x T_x$$

**Theorem 5.5.12** If p is irreducible then the following are equivalent

- (i) Some x is positive recurrent
- (ii) There is a stationary distribution
- (iii) All states are positive recurrent

This result shows that being positive recurrent is a class property. If it holds for one state in an irreducible set, then it is true for all.

**Theorem 5.5.15** If p is irreducible and has a stationary distribution  $\pi$  then any other stationary measure is a multiple of  $\pi$ 

Chapter 5.6 Asymptotic behavior

**Theorem 5.6.1** Suppose y is recurrent. For any  $x \in S$ , as  $n \to \infty$ 

$$\frac{N_n(y)}{n} \to \frac{1}{E_y T_y} 1_{\{T_y < \infty\}} \qquad P_x - a.s.$$

Here  $1/\infty = 0$ 

**lemma 5.6.4** If  $p_{xy} > 0$  then  $d_y = d_x$ 

**Lemma 5.6.5** If  $d_x = 1$  then  $p^m(x, x) > 0$  for  $m \ge m_0$ 

**Theorem 5.6.6 Convergence theorem** Suppose p is irreducible aperiodic (i.e. all states have  $d_x = 1$ ), and has stationary distribution  $\pi$ . Then, as  $n \to \infty, p^n(x, y) \to \pi(y)$ 

Chapter 5.7 Periodicity, Tail  $\sigma - field^*$  Lemma 5.7.1 Suppose p is irreducible, recurrent, and all states have period d. Fix  $x \in S$ , and for each  $y \in S$ , let  $K_y = \{n \ge 1 : p^n(x,y) > 0\}$  (i) There is an  $r_y \in \{0,1,..,d-1\}$  so that if  $n \in K_y$  then  $n = r_y \mod d$ , i.e. the difference  $n - r_y$  is a multiple of d. (ii) Let  $S_r = \{y : r_y = r\}$  for  $0 \le r < d$ . If  $y \in S_i, z \in S_j$  and  $p^n(y,z) > 0$ , then  $n = (j-i) \mod d$ . (iii)  $S_0, S_1, ..., S_{d-1}$  are irreducible classes for  $p^d$ , and all states have period 1.

Theorem 5.7.2 Convergence theorem, periodic case Suppose p is irreducible, has a stationary distribution  $\pi$ , and all states have period d. Let  $x \in S$  and let  $S_0, S_1, ..., S_{d-1}$  be the cyclic decomposition of the state space with  $x \in S_0$  If  $y \in S_r$  then

$$\lim_{m\to\infty} p^{md+r}(x,y) = \pi(y)d$$

**Theorem 5.7.3** Suppose p is irreducible, recurrent, and all states have period d,  $\mathcal{T} = \sigma(\{X_0 \in S_r\} : 0 \le r < d)$ 

**Theorem 5.7.4** Suppose  $X_0$  has initial distribution  $\mu$ . The equations

$$h(X_n, n) = E_{\mu}(Z|\mathcal{F}_n)$$
 and  $Z = \lim_{n \to \infty} h(X_n, n)$ 

set up a 1-1 correspondence between bounded  $Z \in \mathcal{T}$  and bounded space-time harmonic functions, i.e. bounded  $h: Sx\{0,1,\ldots\} \to R$ , so that  $h(X_n,n)$  is a martingale.

Theorem 5.7.6 For d-dimensional simple random walk

$$\mathcal{T} = \sigma(\{X_0 \in L_i\}, i = 0, 1)$$

Chapter 5.8 General State Space\*

**Lemma 5.8.4**  $v\bar{p} = \bar{p}$  and  $\bar{p}v = p$ .

**Lemma 5.8.5** Let  $Y_n$  be an inhomogeneous Markov chain with  $p_{2k} = v$  and  $p_{2k+1} = \bar{p}$ . Then  $\bar{X}_n = Y_{2n}$  is a Markov chian with transition probability  $\bar{p}$  and  $X_n = Y_{2n+1}$  is a Markov chain with transition probability p.

**Lemma 5.8.6** If  $\mu$  is a probability measure on  $(S, \mathcal{S})$  then

$$E_{\mu}f(X_n) = E_{\mu}\bar{f}(\bar{X}_n)$$

Chapter 5.8.1 Recurrence and Transience

**Theorem 5.8.8** Let  $\lambda(C) = \sum_{n=1}^{\infty} 2^{-n} p^{-n}(\alpha, C)$ . In the recurrent case if  $\lambda(C) > 0$  then  $P_{\alpha}(\bar{X}_n \in C \text{ i.o.}) = 1$ . For  $\lambda - a.e.x, P_x(R < \infty) = 1$ 

Chapter 5.8.2 Stationary Measures

**Theorem 5.8.9** in the recurrent case, there is a  $\sigma-finite$  stationary measure  $\bar{\mu}<<\lambda$ 

**Lemma 5.8.10** If v is a  $\sigma-finite$  stationary measure for p, then  $v(A)<\infty$  and  $\bar{v}=v\bar{p}$  is a stationary measure for  $\bar{p}$  with  $\bar{v}(\alpha)<\infty$ 

**Theorem 5.8.11** Suppose p is recurrent. If v is a  $\sigma$  – finite stationary measure then  $v = \bar{v}(\alpha)\mu$ , where  $\mu$  is the measure constructed in the proof of theorem 5.8.9.

**Theorem 5.8.12** Let  $X_n$  be an aperiodic recurrent Harris chain with stationary distribution  $\pi$ . If  $P_x(R < \infty) = 1$  then as  $n \to \infty$ 

$$||p^n(x,\cdot) - \pi(\cdot)|| \to 0$$

## Chapter 5.8.4 G1/G/1 queue

**Lemma 5.8.13** Suppose  $X, Y \ge 0$  are independent and  $P(X > x) = e^{-\lambda x}$ . Show that  $P(X - Y > x) = ae^{-\lambda x}$ . Show that  $P(X - Y > x) = ae^{-\lambda x}$ , where a = P(X - Y > 0).