

Active/Passive Policies

Chase R. Abram

Kenneth C. Griffin Department of Economics
University of Chicago

May 20, 2021

Genesis

- (Sometimes wrong) intuition: FP and MP control macroeconomy. One gets to be active/first mover/free and the other must be passive/second mover/constrained
- (Leeper, 1991) formalized this idea theoretically in an *extremely narrow* policy space
- Leeper identifies 4 policy regions: “standard” AM/PF, “FTPL” PM/AF, underdetermined PM/PF, overdetermined AM/AF
- Can we identify regimes (test/reject FTPL!)?
- Can we study [policy regime-switching](#)?

Towards Formalization

- Consider policies $(M_1, F_1), (M_2, F_1), (M_3, F_1) \in \mathcal{P}$, where \mathcal{P} is a policy space, such that
 - $(M_1, F_1) \Rightarrow$ underdetermined eq.
 - $(M_2, F_1) \Rightarrow$ uniquely determined eq.
 - $(M_3, F_1) \Rightarrow$ overdetermined eq.
- Is FP F_1 active or passive?
- (This hypothetical \mathcal{P} exists.)
- Can *only* make active/passive statements if we restrict policy space \mathcal{P}
- Statements such as “Policy X by authority Y is active” must nest assumptions about what policies are allowed

General System

- System (Ben's continuous NK + debt valuation)

$$\dot{\pi} = \rho\pi - \kappa x$$

$$\dot{x} = i - \pi - \rho$$

$$\dot{b} = (i - \pi)b - s$$

$$b(0) = \lim_{T \rightarrow \infty} b(T) = \bar{b}$$

$$\lim_{T \rightarrow \infty} x(T) = \bar{x}$$

- Policies

$$i = M(\pi, x, b)$$

$$s = F(\pi, x, b)$$

Dual Taylor

- Restrict

$$\mathcal{P} = \{(M, F) \mid M(\pi, x, b) = \bar{\rho} + \phi\pi, \\ F(\pi, x, b) = \bar{s} + \gamma b, \phi, \gamma \in \mathbb{R}, \bar{s} = (\bar{\rho} - \gamma)\bar{b}\}$$

- System is then

$$\dot{\pi} = \rho\pi - \kappa x$$

$$\dot{x} = (\phi - 1)\pi + \bar{\rho} - \rho$$

$$\dot{b} = (\bar{\rho} - \gamma)(b - \bar{b}) + (\phi - 1)\pi b$$

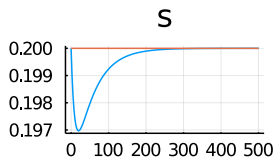
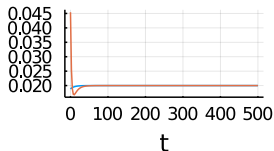
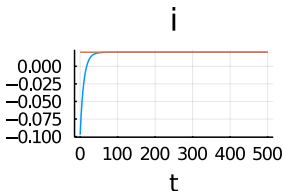
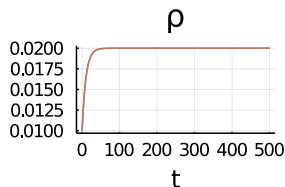
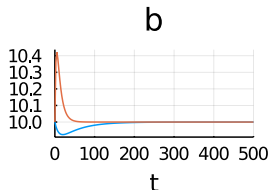
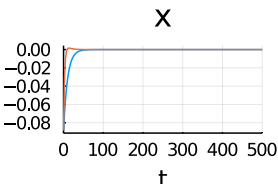
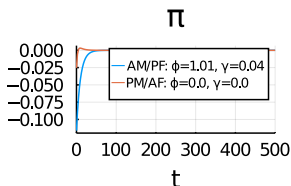
$$b(0) = \lim_{T \rightarrow \infty} b(T) = \bar{b}$$

$$\lim_{T \rightarrow \infty} x(T) = \bar{x}$$

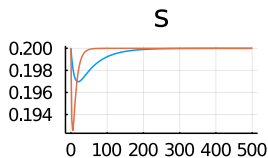
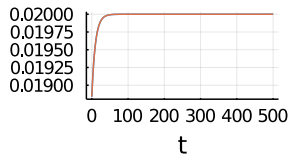
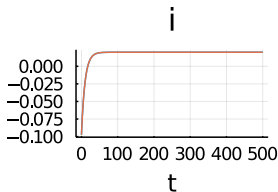
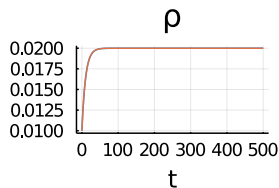
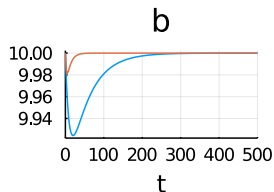
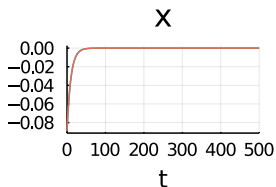
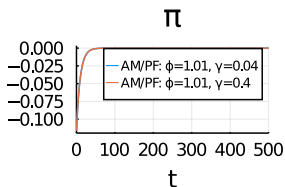
Dual Taylor Results

- Can make active/passive statements in dual Taylor policy space, in particular
 - FP is active when $\phi > 1$
 - MP is active when $\gamma < \rho$
- For a given $\phi > 1$, *any* $\gamma > \rho$ generates the same IRFs for π, x, i, r
 - Proof idea: Check that paths remain consistent
 - Contrapositive: Proof breaks down in PM/AF

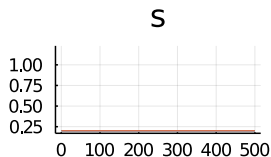
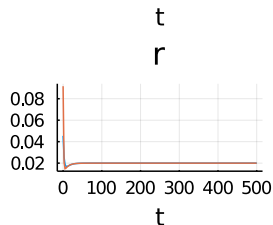
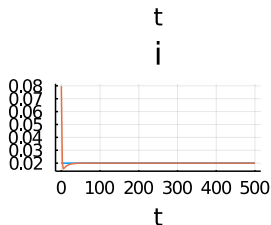
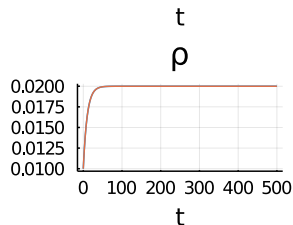
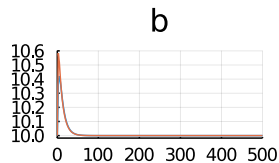
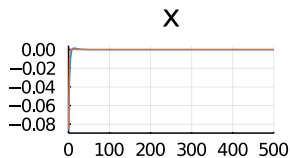
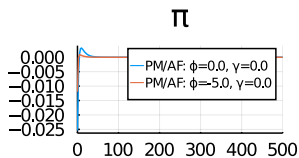
Two Determinate Regimes



Invariance Result



Non-Invariance Result



Observational Equivalence Banished?

- No, we cheated
- Identification in this world:
 - Restrictive policy space (2D)
 - Static policies
 - No stochastics (probably less relevant)
- Consider opening up the policy space with * notation: different coefficients for “off-equilibrium threats” ...
- ...Good luck identifying, even in this bananas-simple framework (see Chapter 22)
- Choice: identification with strong assumptions or no identification, no FTPL test

Leeper, Eric (1991). “Equilibria under ‘active’ and ‘passive’ monetary and fiscal policies”. In: *Journal of Monetary Economics* 27.1, pp. 129–147.