

- Meeting (1.5 hours)
- Attaching the robotic arm to the robot (2 hours)
- Making adjustments on the robot to make sure it is balanced (2 hours)
- Discussing and documenting the physical and dynamical errors, and how the final design works (30 minutes)
- LDD design (2 hours)
- Meeting (30 minutes)
- new claw design (30 minutes)