Exercise 8

Index No.: 190696U

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Question 1 and Question 2

```
In [ ]:
         import numpy as np
         import cv2 as cv
         import matplotlib.pyplot as plt
         temple = open(r'./templeSparseRing/templeSR_par.txt','r')
         assert temple is not None
         n = int(temple.readline())
         # Reading the information on the first image
         1 = temple.readline().split()
         im1 fn = 1[0]
         K1 = np.array([float(i) for i in l[1:10]]).reshape((3,3))
         R1 = np.array([float(i) for i in 1[10:19]]).reshape((3,3))
         t1 = np.array([float(i) for i in 1[19:22]]).reshape((3,1))
         # Reading the information on the second image
         1 = temple.readline().split()
         im2 fn = 1[0]
         K2 = np.array([float(i) for i in 1[1:10]]).reshape((3,3))
         R2 = np.array([float(i) for i in 1[10:19]]).reshape((3,3))
         t2 = np.array([float(i) for i in 1[19:22]]).reshape((3,1))
         #read 2 images and show
         im1 = cv.imread(r'./templeSparseRing/'+ im1_fn, cv.IMREAD_COLOR)
         im2 = cv.imread(r'./templeSparseRing/'+ im2_fn, cv.IMREAD_COLOR)
         assert im1 is not None
         assert im2 is not None
         #compute P1 and P2
         P1 = K1 @ np.hstack((R1,t1)) # P = K*[R|t]
         P2 = K2 @ np.hstack((R2,t2)) # P = K^*[R/t]
         print("P1 = ", P1)
         print("P2 = ", P2)
        P1 = [[ 4.80251845e+01 1.44011271e+03 -5.71648932e+02 7.53293366e+01]
         [ 1.53577034e+03 -6.41434324e+01 -1.63127843e+02 1.85810055e+02]
         [ 4.88387837e-02 -1.81568392e-01 -9.82164799e-01 6.14604846e-01]]
        P2 = [[-1.55882371e+02 1.44377186e+03 -5.42436214e+02 6.81806220e+01]
         [ 1.34928131e+03 -8.41979541e+01 -7.49443961e+02 1.99929996e+02]
         [-3.40999743e-01 -1.74474039e-01 -9.23730472e-01 6.00850565e-01]]
       Question 3
```

```
In [ ]:
    from scipy.linalg import null_space
    def skew(x):
        x = x.ravel()
        return np.array([[0,-x[2],x[1]],[x[2],0,-x[0]],[-x[1],x[0],0]])

    C = null_space(P1)
    C=C*np.sign(C[0,0])
```

```
e2 = P2 @ C
e2x = skew(e2)

F=e2x @ P2 @ np.linalg.pinv(P1)
print('F =',F)

x = np.array([130,115,1])
cv.circle(im1,(x[0],x[1]),5,(0,0,255),-1)

12 = F @ x.T

p1 = np.array([0,(12[0]*0+12[2])/12[1]]).astype(int)
p2 = np.array([500,(12[0]*500+12[2])/12[1]]).astype(int)
cv.line(im2,(p1[0],p1[1]),(p2[0],p2[1]),(255,0,0),5)

fig,ax = plt.subplots(1,2,figsize=(20,20))
ax[0].imshow(cv.cvtColor(im1,cv.COLOR_BGR2RGB))
ax[1].imshow(cv.cvtColor(im2,cv.COLOR_BGR2RGB))
```

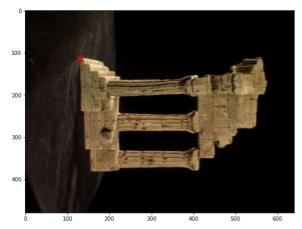
```
F = [[-2.87071497e-04 -3.96261289e-02 2.94221686e+02]

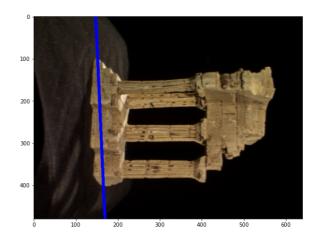
[-3.55039713e-02 1.65329260e-04 1.78860854e+01]

[-2.76702814e+02 2.12942175e+01 -9.06669374e+03]]

<matplotlib.image.AxesImage at 0x2ce387caaf0>
```

Out[]:

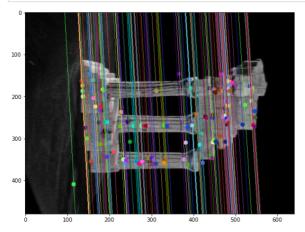


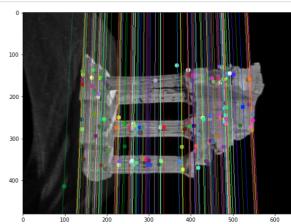


Question 4

```
In [ ]:
         img1 = cv.imread(r'./templeSparseRing/'+im1_fn,0)
         img2 = cv.imread(r'./templeSparseRing/'+im2 fn,0)
         sift = cv.SIFT_create()
         keypoint1, descriptor1 = sift.detectAndCompute(img1,None)
         keypoint2, descriptor2 = sift.detectAndCompute(img2,None)
         FLANN INDEX KDTREE = 1
         index_params = dict(algorithm = FLANN_INDEX_KDTREE, trees = 5)
         search params = dict(checks=50)
         flann = cv.FlannBasedMatcher(index params, search params)
         matches = flann.knnMatch(descriptor1,descriptor2,k=2)
         pts1 = []
         pts2 = []
         for i,(m,n) in enumerate(matches):
             if m.distance < 0.8*n.distance:</pre>
                 pts2.append(keypoint2[m.trainIdx].pt)
                 pts1.append(keypoint1[m.queryIdx].pt)
         pts1 = np.int32(pts1)
         pts2 = np.int32(pts2)
         F, mask = cv.findFundamentalMat(pts1,pts2,cv.FM LMEDS)
```

```
pts1 = pts1[mask.ravel()==1]
pts2 = pts2[mask.ravel()==1]
def drawlines(img1,img2,lines,pts1,pts2):
    r,c = img1.shape
    img1 = cv.cvtColor(img1,cv.COLOR_GRAY2BGR)
    img2 = cv.cvtColor(img2,cv.COLOR_GRAY2BGR)
    for r,pt1,pt2 in zip(lines,pts1,pts2):
        color = tuple(np.random.randint(0,255,3).tolist())
        x0,y0 = map(int, [0, -r[2]/r[1]])
        x1,y1 = map(int, [c, -(r[2]+r[0]*c)/r[1]])
        img1 = cv.line(img1, (x0,y0), (x1,y1), color,1)
        img1 = cv.circle(img1, tuple(pt1), 5, color, -1)
        img2 = cv.circle(img2, tuple(pt2), 5, color, -1)
    return img1,img2
lines1 = cv.computeCorrespondEpilines(pts2.reshape(-1,1,2), 2,F)
lines1 = lines1.reshape(-1,3)
img5,img6 = drawlines(img1,img2,lines1,pts1,pts2)
lines2 = cv.computeCorrespondEpilines(pts1.reshape(-1,1,2), 1,F)
lines2 = lines2.reshape(-1,3)
img3,img4 = drawlines(img2,img1,lines2,pts2,pts1)
plt.figure(figsize=(20,20))
plt.subplot(121),
plt.imshow(img5)
plt.subplot(122),
plt.imshow(img3)
plt.show()
```





In []: