Summer School in Quantitative Fisheries Stock Assessment

Day 2: Biomass dynamic models

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Unlimited population growth

Limited population growth

Fishing

Estimation

Important points

Summary

Outline

Unlimited population growth

Limited population growth

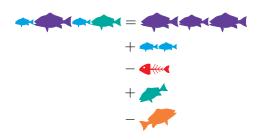
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Demographic variables



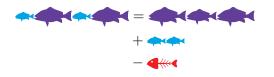
$$N_{t+1} = N_t + B_t - D_t + I_t - E_t$$

where

- N_t is the population number at time t
- *B_t* is the number of births
- D_t is the number of deaths
- It is the number immigrating
- *E_t* is the number emigrating



Closed population assumption



$$N_{t+1} = N_t + B_t - D_t + \mathcal{Y}_{\xi} - \mathcal{Y}_{\xi}$$

Birth and death rates

Define constant per-capita rates of:

birth

$$b = \frac{}{}$$

death

$$d = \frac{}{}$$

Population growth

Can now write

$$N_{t+1} = N_t + bN_t - dN_t$$

= $N_t + (b - d)N_t$

Define constant per-capita population growth rate

$$r = (b - d)$$

So

$$N_{t+1} = N_t + rN_t$$
$$= (1+r)N_t$$

Population growth

Here

$$b = \frac{2}{3}$$

$$d = \frac{4}{3}$$

$$r = (b - d) = \frac{2}{3} - \frac{1}{3} = \frac{1}{3}$$

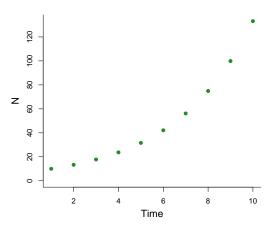
Population growth

$$\begin{array}{lcl} N_{1} & = & N_{0} \left(1 + \frac{1}{3} \right) \\ N_{2} & = & N_{1} \left(1 + \frac{1}{3} \right) = N_{0} \left(1 + \frac{1}{3} \right) \times \left(1 + \frac{1}{3} \right) \\ N_{3} & = & N_{2} \left(1 + \frac{1}{3} \right) = N_{0} \left(1 + \frac{1}{3} \right) \times \left(1 + \frac{1}{3} \right) \times \left(1 + \frac{1}{3} \right) \\ \vdots & \vdots & \vdots \\ N_{t} & = & N_{0} \left(1 + \frac{1}{3} \right)^{t} \end{array}$$

Geometric population growth

$$N_t = N_0 \left(1 + r\right)^t$$

Geometric population growth



"Population, when unchecked, increases in a geometrical ratio".

Geometric population growth

Populations will be limited though through competition for limited:

- Food
- Space
- Light
- . . .

Need to include effect of competition on the population growth rate, i.e., density dependence

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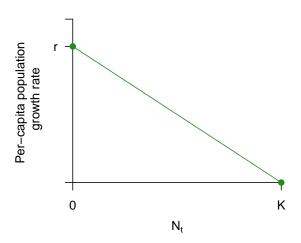
Important points

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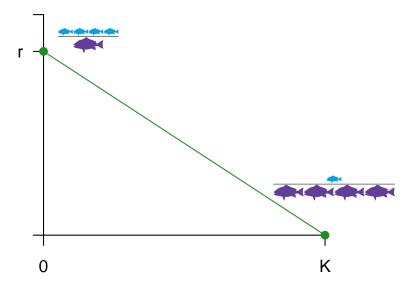
For geometric population growth:

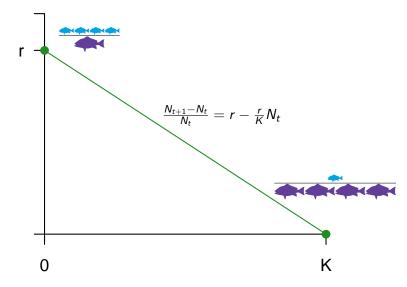
$$\begin{array}{rcl}
N_{t+1} & = & N_t + rN_t \\
\frac{N_{t+1} - N_t}{N_t} & = & r
\end{array}$$

Now let the per-capita growth rate be a decreasing function of population size, i.e., not constant



Increase in per-capita rate of population growth <u>compensates</u> for reduced population size





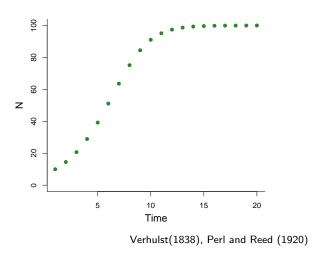
$$\frac{N_{t+1} - N_t}{N_t} = r - \frac{r}{K} N_t$$

$$N_{t+1} = N_t + rN_t \left(1 - \frac{N_t}{K}\right)$$

- Termed the discrete logistic population model
- Cornerstone of initial theory of compensation
- Often used in stock assessment of harvested populations
- Note N_t not disaggregated by age

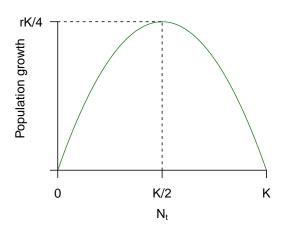
Limited population growth

Logistic model



Overall population growth rate

Population growth (per-capita \times population size) has an optimum



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Russell (1931)

Russell's Fishery equation:

$$S_2 = S_1 + (R + G) - (M + F)$$

where

- S is the stock size
- R is recruitment of new individuals
- G is somatic growth
- M is natural mortality
- F is fishing mortality

Russell (1931)

Can cast in terms of our simple population model

$$B_{t+1} = B_t + R_t - D_t - C_t$$

where here

- B_t is now the biomass of the population (numbers times mass)
- R_t is the biomass of new recruits
- D_t is the biomass dying naturally
- C_t is mass caught (catch)

Graham-Schaefer biomass dynamic model

Difference (non-continuous) version

$$B_{t+1} = B_t + rB_t \left(1 - \frac{B_t}{K} \right) - C_t$$

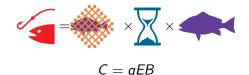
Often called just the Schaefer model. Widely-used model in fisheries assessment

Note

The Schaefer biomass dynamic model can be derived simply from a linear decrease in the per-capita growth rate over abundance with catch subtracted.

A first catch equation

Catch can be modelled as:



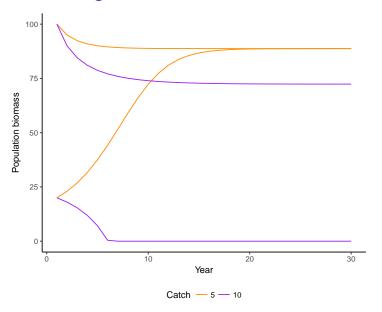
Where

- C is the catch
- q is catchability, defined as the proportion of the population removed per unit effort
- E is effort (e.g., fishing days, kW days, hooks)

What is a sustainable catch?

Q: For a given r and K parameters what values of catch are sustainable?

Catch and starting biomass



Catch and starting biomass

Note

Sustainability of a given catch depends on what level of biomass you start from.

Better to work with a rate of removal of the population

Fishing mortality

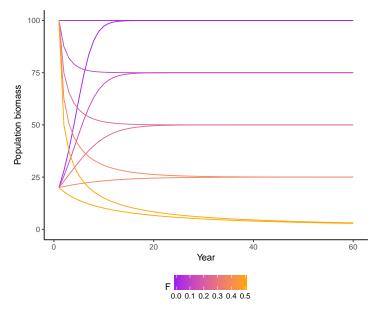
Note

Catchability and effort are often combined into the fishing mortality

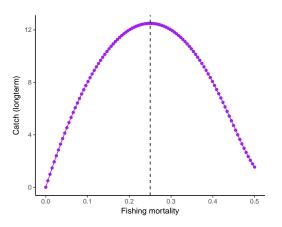
$$F = qE$$

which is usually expressed as an instantaneous rate but used here to denote the proportion of the population removed by fishing each year (often termed the harvest rate, sometimes denoted u).

What is a sustainable rate of fishing mortality?



Try different values for the harvest rate



- $F_{MSY} = \frac{r}{2}$ in the Schaefer model
- K/2 termed B_{MSY} long-term biomass obtained if fishing at $F_{MSY}=r/2$

More on reference points later . . .



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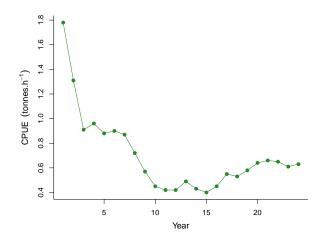
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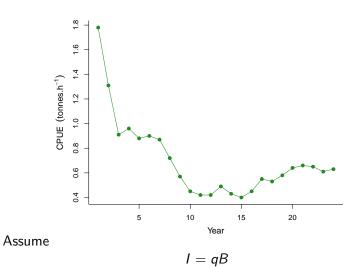
Need to estimate the parameters of the biomass dynamic model from:

- Biomass index *I*, e.g.
 - Survey index
 - Standardised CPUE index
- Catch C

Biomass index



Biomass index



Index is proportional to biomass

Predicting the biomass index

Say we guessed the parameters, we would predict the index values via

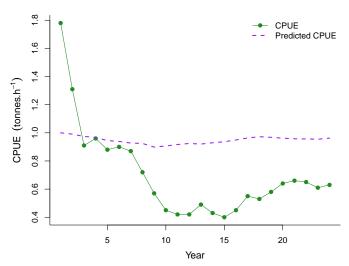
$$egin{aligned} \hat{eta}_{t=1} &= \hat{eta}_0 \ \hat{eta}_{t+1} &= \hat{eta}_t + \hat{r}\hat{eta}_t \left(1 - rac{\hat{eta}_t}{\hat{\mathcal{K}}}
ight) - C_t \ \hat{eta}_t &= \hat{q}\hat{eta}_t \end{aligned}$$

Note

This is an observation error approach

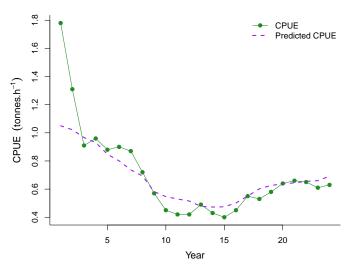
Predicting the biomass index

Say we guessed $\hat{r} = 0.5, \ \hat{K} = 10,000, \hat{B}_0 = 10,000, \ \hat{q} = 0.0001$



Another guess

Say we guessed $\hat{r} = 0.3$, $\hat{K} = 3,500$, $\hat{B}_0 = 3,500$, $\hat{q} = 0.0003$



Estimation

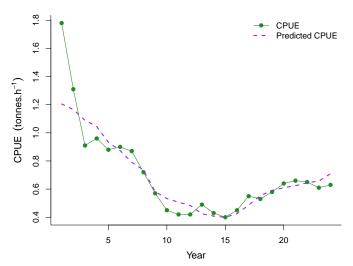
Like to do better than guess, so we estimate Define the likelihood

$$L(r, K, B_0, q, \sigma | \mathbf{I}) = \prod_{t=1}^{T} N(\ln(I_t) - \ln(\hat{I}_t), \sigma^2)$$

which we maximise with respect to the parameters to obtain the maximum likelihood estimates

Maximum likelihood estimates: observation error

$$\hat{r} = 0.37, \ \hat{K} = \hat{B}_0 = 2,823, \ \hat{q} = 0.00042, \ \hat{\sigma} = 0.125$$



Process error approach

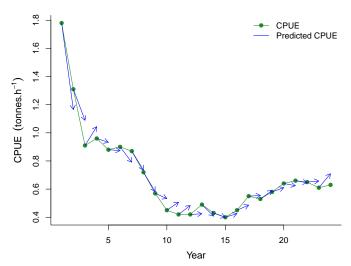
Rather than predict all the way through, a process error only model assumes the observations are perfect and the only error is in the biomass dynamic model

Note

A process error only approach assumes only source of error is in the biomass dynamics, not the observations.

Maximum likelihood estimates: process error

$$\hat{r} = 0.31, \ \hat{K} = \hat{B}_0 = 3,577, \ \hat{q} = 0.00025, \ \hat{\sigma} = 0.1$$



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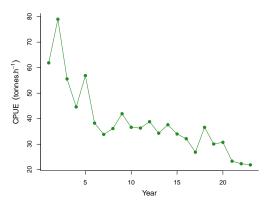
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Contrast

Need historical variation in stock size and fishing pressure to properly estimate the parameters of the biomass dynamic model. Beware of one-way trip data like this

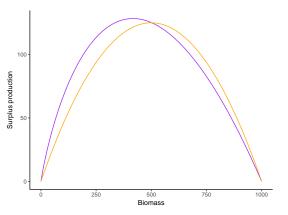


- r estimation requires points at low stock size and low effort
- K estimation requires high stock sizes and low effort
- Ideally there would be variation in both



Alternative forms

A common alternative form is the Pella-Tomlinson model



Model — Pella-Tomlinson — Schaefer

$$B_{t+1} = B_t + \frac{r}{n}B_t\left(1 - \left(\frac{B_t}{K}\right)^n\right) - C_t$$

State space formulation

Recently, much interest in estimation including \underline{both} observation and process error (spict)

Process equation:
$$B_{t+1} = \left(B_t + rB_t\left(1 - \frac{B_t}{K}\right) - C_t\right)e^{\eta_t}$$

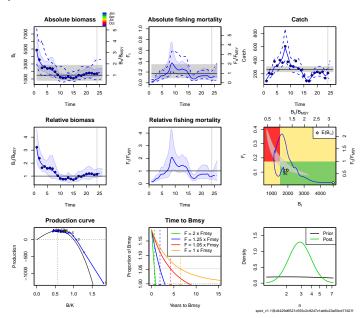
Observation equation: $I_t = qB_te^{\varepsilon_t}$

where η_t are process errors on biomass $(\eta_t \sim N(0, \sigma_b))$ and ε_t are measurement errors $(\varepsilon_t \sim N(0, \sigma_i))$.

Note

spict also includes a process and measurement equation for catches. A rich output but care needed in terms of the number of parameters estimated and given data quality. Make sure to check parameter correlation and diagnostics.

State space formulation



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- Reference points straightforward to obtain from a good fit
- Advanced models provide options for multiple indices, sources of error, asymmetric production
- Critical evaluation of the assessment fit and diagnostics very important with aggregate biomass dynamic models



References

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Meyer, R., and Millar, R. B. (1999). BUGS in Bayesian stock assessments. Canadian Journal of Fisheries and Aquatic Sciences, 56(6), 1078-1087.

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