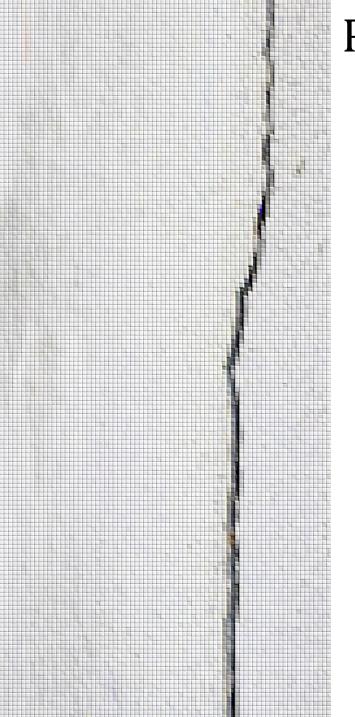
Crack Detection in Concrete surfaces



Problem Statement

Build a **classifier model** that can **reliably and accurately detect cracks** in typical **concrete surfaces**

Why?

'Tragedy waiting to happen': Italian bridge that collapsed had been riddled with structural problems for decades

Genoa's Morandi motorway bridge had required constant maintenance for cracks and other woes, as a result of 'failed' construction techniques employed in the 1960s

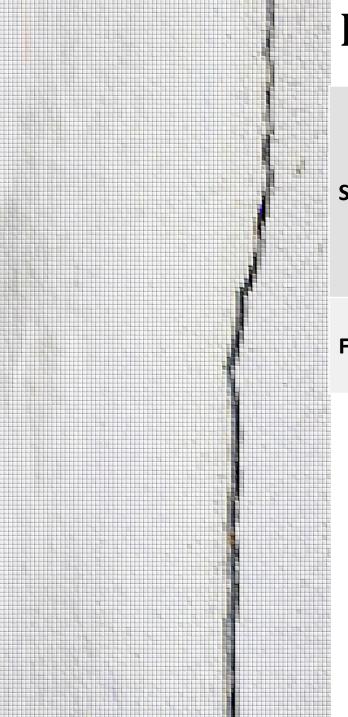




Why?



Downtown line is 44 km long



Dataset

https://data.mendeley.com/datasets/5y9wdsg2zt/2

Source

2018 – Özgenel, Ç.F., Gönenç Sorguç, A. "Performance Comparison of Pretrained Convolutional Neural Networks on Crack Detection in Buildings", ISARC 2018, Berlin.

Lei Zhang, Fan Yang, Yimin Daniel Zhang, and Y. J. Z., Zhang, L., Yang, F., Zhang, Y. D., & Zhu, Y. J. (2016). Road Crack Detection Using Deep Convolutional Neural Network. In 2016 IEEE International Conference on Image Processing (ICIP). http://doi.org/10.1109/ICIP.2016.7533052

Format

RGB Images of size 227 x 227 concrete surfaces:

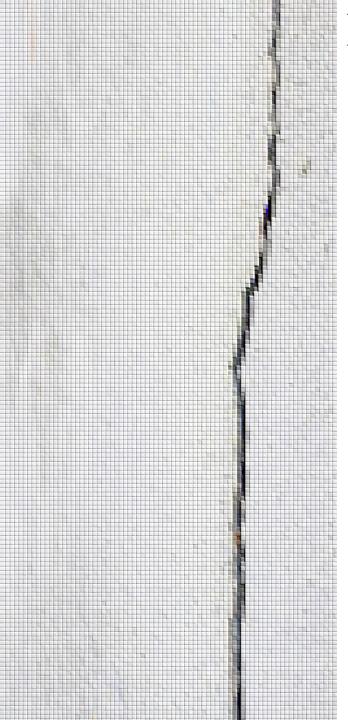
- 20,000 positive class images (surfaces with cracks)
- 20,000 **negative class** images (surfaces **without cracks**)

Class 0 (Negative class)



Class 1 (Positive class)





Data preprocessing

Import image data as array

```
In [10]: M 1 im.shape Out[10]: (227, 227)
```

Shuffle data and divide to train & test sets (0.75 train, 0.25 test)

```
# Shuffle the data
random.shuffle(data)

# Split data into train and test set
train = data[0:int(len(data)*0.75)]
test = data[int((len(data)*0.75)): ]
```

Check len of train and test
print(len(train))
print(len(test))

30000 10000

Save data in h5py format

Model Construction - Deep Learning

Convolutional Neural Network – Model 1

```
model1 = Sequential()
model1.add(Conv2D(filters=8,
                 kernel size=3,
                 activation='relu',
                 input shape=(227, 227, 1)))
model1.add(MaxPooling2D(pool_size = (2,2)))
model1.add(Dropout(0.5))
model1.add(Conv2D(16, 3, activation='relu'))
model1.add(MaxPooling2D(pool size = (2,2)))
model1.add(Dropout(0.5))
model1.add(Flatten())
model1.add(Dense(230, activation='relu'))
model1.add(Dense(1, activation='sigmoid'))
```

```
model1.summary()
Model: "sequential 1"
Layer (type)
                              Output Shape
                                                         Param #
conv2d 1 (Conv2D)
                              (None, 225, 225, 8)
                                                         80
max pooling2d 1 (MaxPooling2 (None, 112, 112, 8)
                                                         0
dropout 1 (Dropout)
                              (None, 112, 112, 8)
                                                         0
conv2d 2 (Conv2D)
                              (None, 110, 110, 16)
                                                         1168
max pooling2d 2 (MaxPooling2 (None, 55, 55, 16)
                                                         0
dropout 2 (Dropout)
                              (None, 55, 55, 16)
                                                         0
flatten 1 (Flatten)
                              (None, 48400)
                                                         0
dense 1 (Dense)
                              (None, 230)
                                                         11132230
dense 2 (Dense)
                              (None, 1)
                                                         231
```

Total params: 11,133,709
Trainable params: 11,133,709
Non-trainable params: 0

Model Construction - Deep Learning

Convolutional Neural Network – Model 2

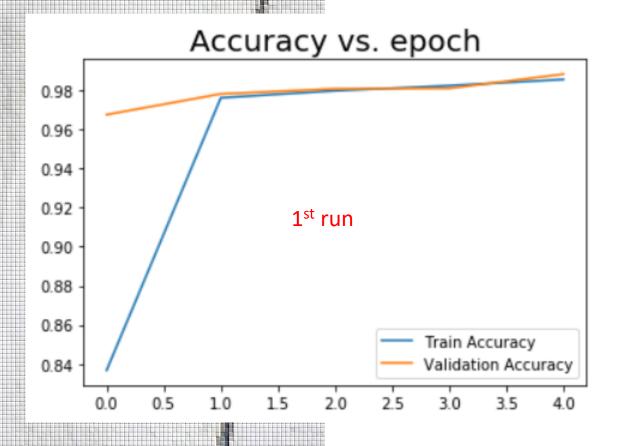
```
# Double no. of filters from model 1
   # No dropout
   model2 = Sequential()
   model2.add(Conv2D(filters=16,
                     kernel size=3,
                     activation='relu',
                     input_shape=(227, 227, 1)))
   model2.add(MaxPooling2D(pool size = (2,2)))
10
   model2.add(Conv2D(32, 3, activation='relu'))
   model2.add(MaxPooling2D(pool size = (2,2)))
13
   model2.add(Flatten())
   model2.add(Dense(230, activation='relu'))
16
   model2.add(Dense(1, activation='sigmoid'))
```

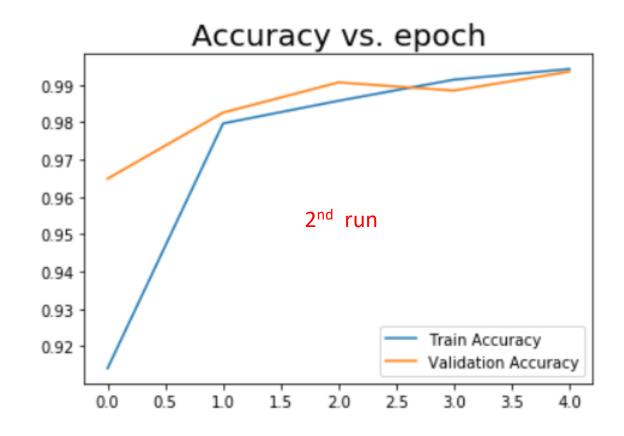
Model: "sequential_1"			
Layer (type)	Output	Shape	Param #
conv2d_1 (Conv2D)	(None,	225, 225, 16)	160
max_pooling2d_1 (MaxPooling2	(None,	112, 112, 16)	0
conv2d_2 (Conv2D)	(None,	110, 110, 32)	4640
max_pooling2d_2 (MaxPooling2	(None,	55, 55, 32)	0
flatten_1 (Flatten)	(None,	96800)	0
dense_1 (Dense)	(None,	230)	22264236
dense 2 (Dense)	(None,	1)	231

Total params: 22,269,261 Trainable params: 22,269,261 Non-trainable params: 0

Model Construction - Deep Learning

Convolutional Neural Network – Model 2

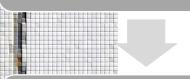




Pre-processing

Fast Fourier Transform (FFT) on image array

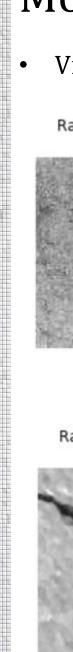
Calculate **Azimuthal average** of **Magnitude Spectrum**



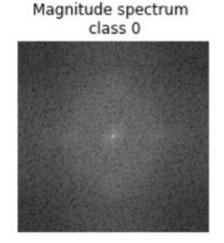
Obtain 1D amplitude spectrum

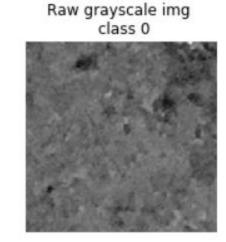
```
# Define function to apply Direct Fourier Transfrom on image array
2 def dff img(img array, filename):
       psd1D array = np.empty([img array.shape[0], 158])
       for i, img in enumerate(img array):
           # use numpy library to apply fourier transform
           f = np.fft.fft2(img.reshape(227,227))
           # shift areas of low frequency (by default at the top left corner) to the center
           # areas of low frequency indicate that
           fshift = np.fft.fftshift(f)
           magnitude spectrum = 20*np.log(np.abs(fshift))
           # Calc the 1D amplitude spectrum from the magnitude spectrum
           # This converts the image data into a single row of numbers, making modelling with ML possible
           psd1D = radialProfile.azimuthalAverage(magnitude spectrum)
13
           psd1D array[i,:] = psd1D
14
15
       # Code below was to play around with high pass filtering - not used
16
       #rows, cols = imq.shape
       #crow, ccol = rows/2, cols/2
       #fshift[crow-30:crow+30, ccol-30:ccol+30] = 0
       #f ishift = np.fft.ifftshift(fshift)
       #img back = np.fft.ifft2(f ishift)
       #X train dft.append(img back)
22
23
       pd.DataFrame(psd1D array).to csv(f'../dataset/{filename}.csv', index=False)
24
```

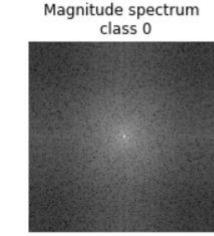
Visualization of Magnitude Spectrum

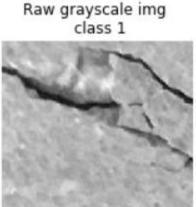


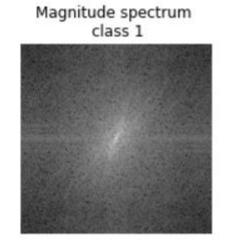
Raw grayscale img class 0

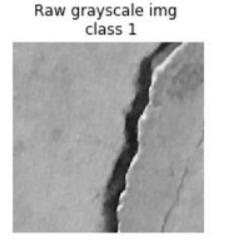


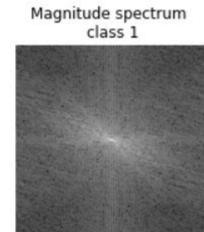




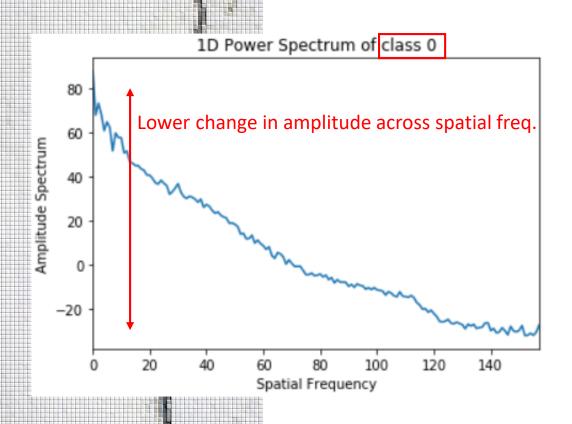


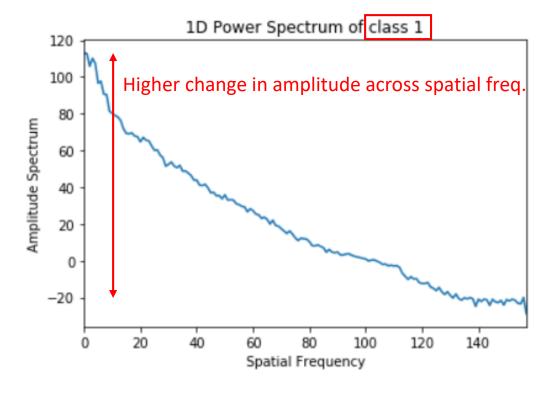






Visualization of 1D Amplitude spectrum





Evaluation of metrics

Model	Accuracy	F1-score	Recall	Specificity	Precision
Logistic Regression	0.969	0.969	0.972	0.972	0.967
Random Forest	0.976	0.976	0.976	0.976	0.976
AdaBoost	0.969	0.969	0.967	0.971	0.971
XGBoost	0.971	0.971	0.969	0.974	0.974
KNN	0.974	0.974	0.974	0.975	0.975
SVM	0.952	0.954	0.987	0.917	0.923

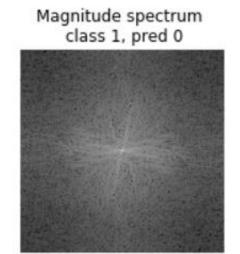
AdaBoost classifier:

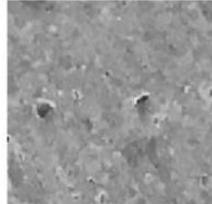
Model Evaluation – Machine Learning

Misclassified images

Random Forest classifier:

Raw grayscale img class 1

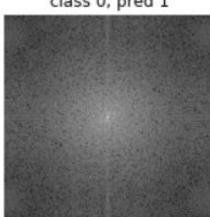




Raw grayscale img

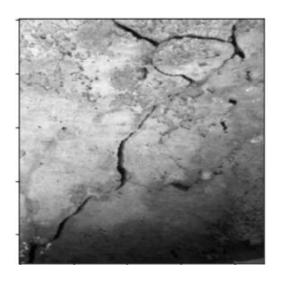
class 0

Magnitude spectrum class 0, pred 1



Models Performance

Testing on unseen images – Positive Class



```
prediction = cnn_model2.predict_proba(img)
prediction[0][0]
```

0.9999999

```
prediction = cnn_model2.predict_proba(img)
prediction[0][0]
```

0.0010422585

```
logreg pkl = joblib.load('../model/logreg.pkl')
logreg_pkl predict_proba(img_dff)[0][1]
```

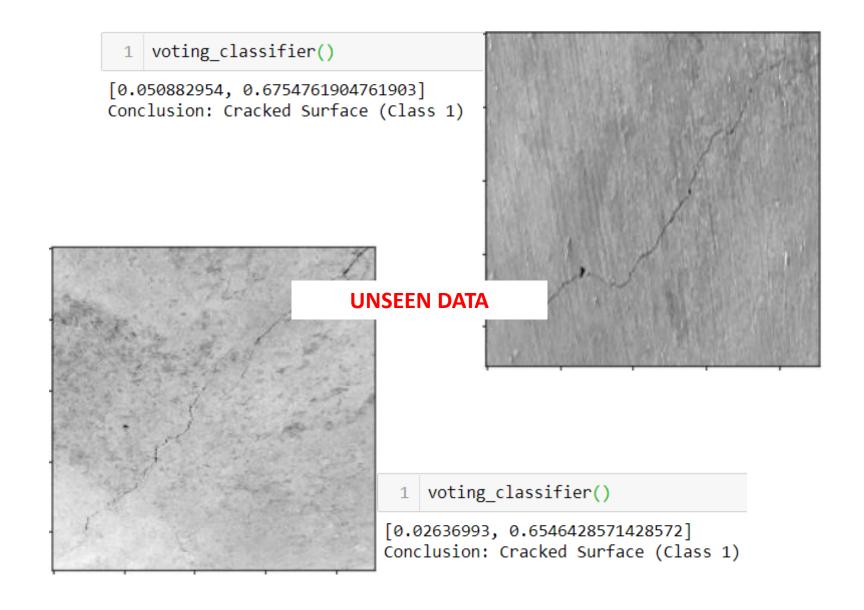
0.9645558888529413

Meta classifier

Voting Classifier

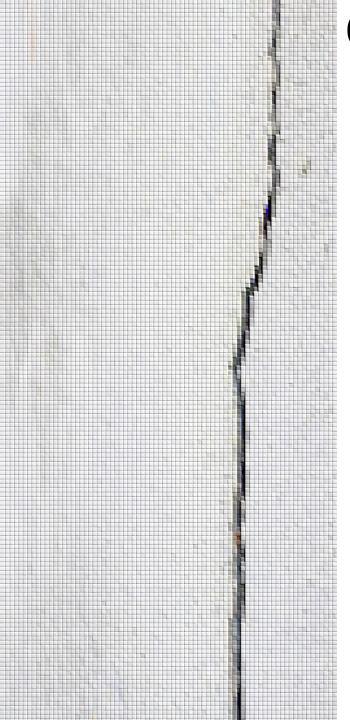
```
def voting classifier(cnn model = [cnn model2].
                          ml_models = [rf_model]): #[logreg_model, rf_model, ada_model, xgb_model, knn_model, svm_model]):
        pred probas = []
                                     2 models total
        preds = None
        pred = None
        for model in cnn model:
            pred probas.append(model.predict proba(img)[0][0])
        for model in ml models:
            pred probas.append(model.predict proba(img dff)[0][1])
10
11
        print(pred probas)
        preds = [1 if proba >= 0.5 else 0 for proba in pred probas]
13
        #print(preds)
14
        if (sum(preds) >= 1) & (pred_probas[0] > 0.02):
15
16
            #print(f"{sum(preds)} out of {len(preds)} models: Surface has a crack.")
            print("Conclusion: Cracked Surface (Class 1)")
18
        else:
19
            pred = 0
20
            #print(f"{sum(preds)} out of {len(preds)} models: Surface has a crack.")
21
            print("Conclusion: Non cracked surface (Class 0)")
22
23
        return pred
24
25
```

Voting Classifier – Class 1



Voting Classifier – Class 0





Conclusion & Summary

CNN model	Machine Learning Models
Good at differentiating craters/bumps on surface from actual cracks	Bad at this
Bad at detecting narrow/small cracks	Good at this

• Meta classifier (voting classifier) used to increase reliability

Limitations

- Generally, 2 scenarios that caused misclassification:
 - Thin, narrow cracks
 - Surfaces with a lot of small craters
- Cracks are only 1 type of defect

Future work

Extend to other types of defect