

Pulse

Scanned by CamScanner

Y(+) >0

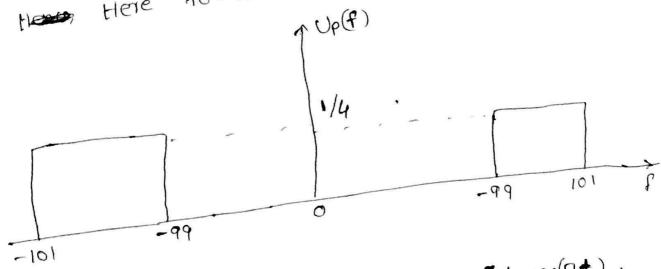
Xf

Question: 2. A and 2. B.

Criven Up(t)=a(t) cos(20011t), where a(t)=sinc(2t).

$$a(t)$$
, $(os(e)(f)) \rightarrow f(f-fo) + f(f+fo)$.

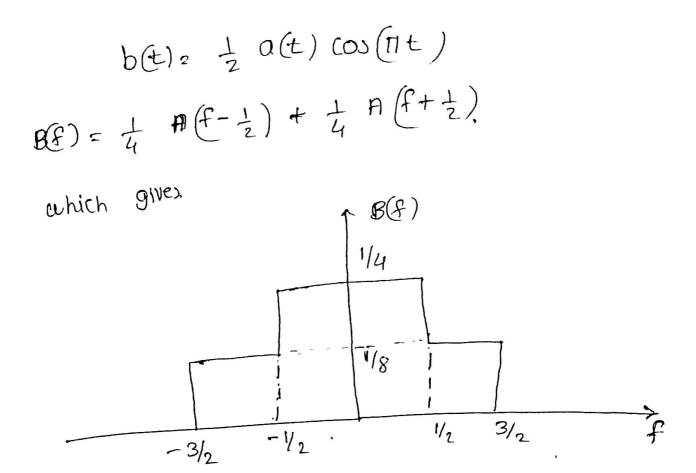
Up(f) is given by. Here fo=100 Hz. Hence



not be present asker low pass firming the signou

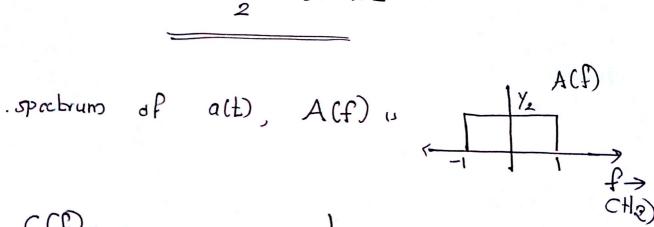
up(t) cos (19911t) = \frac{1}{2} a(t) (o) (399 11t) + \frac{1}{2} a(t) cos (19911t)

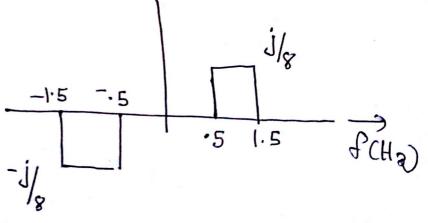
Thus after Low pass filtering we have.



1 LP filtered to get cct

So





note that CCF) is complex valued

Communication Systems; Tutorial 3

2.d; solution

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after low pass filtering, we have

$$a(t) = 0.5u_p(t)cos(\pi t)$$

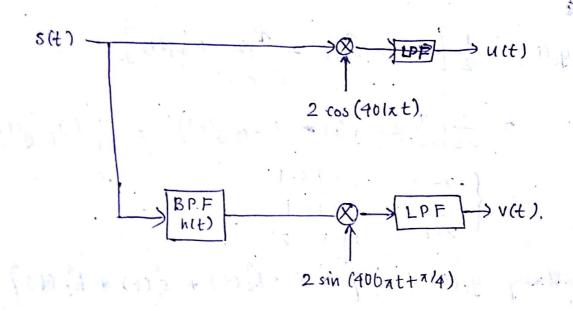
 $b(t) = -0.5u_p(t)sin(\pi t)$

now multiply with $cos(\pi t)$ and $sin(\pi t)$ respectively and subtract to get

$$a(t)cos(\pi t) - b(t)sin(\pi t) = 0.5u_p(t)cos^2(\pi t) + 0.5u_p(t)sin^2(\pi t)$$

= $0.5u_p(t)$

$$S(t) = \frac{I(t)}{(-1,1)} \cos(400 \pi t).$$



Gas
$$u(t) = LPF \left\{ s(t) - 2\cos(401nt) \right\}$$

$$= LPF \left\{ I_{[-1,1]}(t) \cos 400nt \cdot 2 \cos(401nt) \right\}$$

$$= LPF \left\{ I_{[-1,1]}(t) \left(\cos nt + \cos 801nt \right) \right\}$$

$$= I_{[-1,1]}(t) \cos nt$$

(3b)
$$h(t) = I_{(0,1)}(t) \sin (400\pi t + \frac{\pi}{4})$$

 $S(t) = I_{(-1,1)}(t) \cos 400\pi t$
 $= \int_{c}^{c} I_{(-1,1)}(t) \int_{c}^{c} I_{(-1$

$$k_{c}^{A}(t) = \frac{1}{\sqrt{2}} \cdot \frac{1}{\sqrt{2}} I_{(k)} = \frac{1}{2} I_{(k)}(t),$$
where the set $y_{c}(t) = \frac{1}{\sqrt{2}} \left[\frac{1}{\sqrt{2}} I_{(k)}(t) + \frac{1}{\sqrt{2}} I_{(k)}(t) + \frac{1}{\sqrt{2}} I_{(k)}(t) \right],$

$$= \frac{1}{\sqrt{2}} \left(\frac{1}{\sqrt{2}} I_{(k)}(t) + \frac{1}{2} I_{(k)}(t) \right) = \frac{1}{4} \left(I_{(k)}(t) + I_{(k)}(t) \right)$$

$$= \begin{cases} -2 - t & -2 \le t \le -1 \\ -1 & -1 \le t \le 1 \end{cases}$$

$$= \frac{1}{2} \left[\frac{1}{2} I_{(k)}(t) + \frac{1}{2} I_{(k)}(t) \right] = y_{c}(t).$$
Where the set $y_{c}(t) = \frac{1}{\sqrt{2}} \left[\frac{1}{\sqrt{2}} I_{(k)}(t) + \frac{1}{\sqrt{2}} I_{(k)}(t) \right]$

$$= \frac{1}{4} \left[\frac{1}{2} I_{(k)}(t) + \frac{1}{2} I_{(k)}(t) \right] = y_{c}(t).$$

$$\hat{y}(t) = y_{c}(t) + \frac{1}{2} y_{c}(t)$$

$$y(t) = Re \left[\sqrt{2} \int_{0}^{4} I_{(k)}(t) e^{-\frac{1}{2} I_{(k)}(t)} + \frac{1}{2} I_{(k)}(t) \right]$$

$$= Re \left[\sqrt{2} \int_{0}^{4} I_{(k)}(t) e^{-\frac{1}{2} I_{(k)}(t)} + \frac{1}{2} I_{(k)}(t) \right]$$

$$= V^{2} \int_{0}^{4} I_{(k)}(t) \left(\frac{1}{\sqrt{2}} I_{(k)}(t) \right)$$

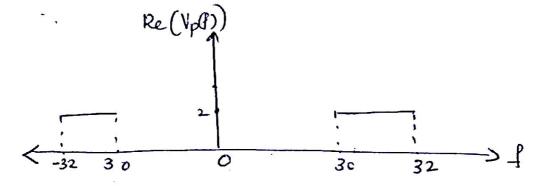
$$= \left(y_{c}(t) + \frac{1}{2} y_{c}(t) \right) \left(I_{(k)}(t) - \frac{1}{2} \right).$$

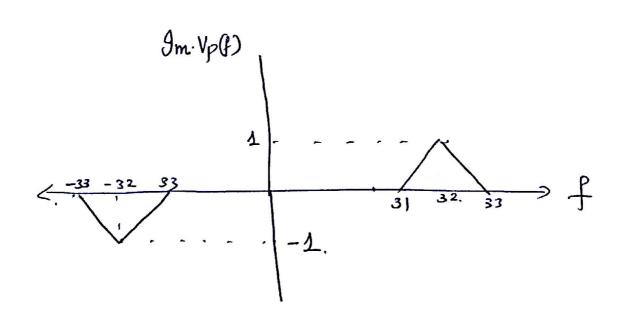
$$Now LPF(t) = -\frac{1}{2} I_{(k)} \left\{ g'(t) \right\}$$

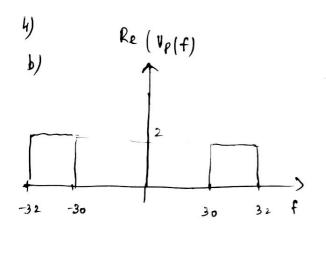


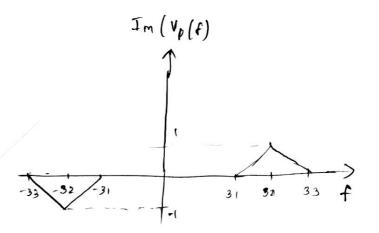
Since $V_p(t)$ is real valued slg $V_p(f) = V_p^*(f)$











After passing though LPF,

we get, X(f) as,

