

Assignment - II.

Q.

$$A = \begin{bmatrix} -2 & -5 & 8 & 0 & -12 \\ 1 & 3 & -5 & 1 & 5 \\ 3 & 11 & -19 & 7 & 1 \\ 1 & 7 & -13 & 5 & -3 \end{bmatrix}$$

$$A = [a_1 \quad a_2 \quad a_3 \quad a_4 \quad a_5]$$

$a_1 \quad a_2 \rightarrow$ independent (obvious)

$$a_1 - 2a_2 = a_3$$

$a_1 \quad a_2 \quad a_4 \rightarrow$ independent. (verified).

$$a_1 + 3a_2 - 5a_4 = a_5$$

$$\therefore \text{Rank}(A) = 3$$

in fundamental theorem of linear algebra

~~rank~~

$$\text{rank}(A) + \text{nullity}(A) = \text{no. of columns.}$$

$$3 + \text{nullity} = 5$$

$$\therefore \text{nullity}(A) = 2 //$$

$$4. \quad \begin{aligned} \dot{x} &= Ax + Bu \\ y &= Cx + Du \end{aligned}$$

$$L_1 = [B \quad AB \quad \dots \quad A^{n-1}B]$$

$$\theta_1 = \begin{bmatrix} C \\ CA \\ \vdots \\ CA^{n-1} \end{bmatrix}$$

$$\dot{w} = -A^T w + C^T u$$

$$z = B^T w + D^T u$$

$$L_2 = [C^T \quad -A^T C^T \quad \dots \quad (-A^T)^{n-1} C^T]$$

$$\theta_2 = \begin{bmatrix} B^T \\ -B^T A^T \\ \vdots \\ B^T (-A^T)^{n-1} \end{bmatrix}$$

If system is fully controllable

$\Rightarrow L_1 = \text{full rank.}$

$$L_1 \times \begin{bmatrix} 1 & 0 & 0 & \dots \\ 0 & -1 & 0 & \dots \\ \vdots & \vdots & \vdots & \ddots \\ 0 & 0 & 1 & \dots \end{bmatrix} = \text{full rank} \quad (\because \det P \neq 0).$$

\uparrow
P

$$\text{But } (L_1 P)^T = \begin{bmatrix} 1 & 0 & 0 & \dots \\ 0 & -1 & 0 & \dots \\ \vdots & \vdots & \vdots & \ddots \end{bmatrix} \begin{bmatrix} B^T \\ B^T A^T \\ \vdots \\ B^T (-A^T)^{n-1} \end{bmatrix} = \text{full rank.}$$

\downarrow
 $P^T L_1^T$

$$= \begin{bmatrix} B^T \\ -B^T A^T \\ \vdots \\ B^T (-A^T)^{n-1} \end{bmatrix} = \theta_2$$

$\therefore \neg L_1 = \text{full rank} \Rightarrow \theta_2 = \text{full rank}$

system ① is observable.

Now Assume ~~that~~ that ① is observable

$$\Rightarrow O_1 = \begin{bmatrix} c \\ \vdots \\ cA^{n-1} \end{bmatrix} = \text{full rank}$$

$$\Rightarrow O_1^T = \text{full rank.} \quad (\because \text{square})$$

$$O_1^T \times P = \begin{bmatrix} c^T & A^T c^T & \dots & (A^{n-1})^T c^T \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & \dots \\ 0 & -1 & 0 & \dots \\ \vdots & \vdots & \vdots & \ddots \\ 0 & \vdots & \vdots & \vdots \end{bmatrix}$$

$$= \begin{bmatrix} c^T & -A^T c^T & (A^T)^2 c^T & \dots & (-A^T)^{n-1} c^T \end{bmatrix}$$

$$= \mathcal{L}_2 = \text{full rank} \quad (\det P \neq 0)$$

\therefore If system ① is observable \Rightarrow system ② is controllable.

converse can also be proved similarly

5)

$$\dot{x} = \begin{bmatrix} 1 & 2 & -1 \\ 0 & 1 & 0 \\ 1 & -4 & 3 \end{bmatrix} x + \begin{bmatrix} 0 & 0 & 1 \end{bmatrix} u \quad ; \quad y = \begin{bmatrix} 1 & -1 & 1 \end{bmatrix} x$$

$$C = [B \quad AB \quad A^2B]$$

$$= \begin{bmatrix} 0 & -1 & -4 \\ 0 & 0 & 0 \\ 1 & 3 & 8 \end{bmatrix}$$

$$\text{rank} = 2 < 3$$

\therefore not controllable

$$T = \begin{bmatrix} 0 & -1 & 0 \\ 0 & 0 & 1 \\ 1 & 3 & 0 \end{bmatrix}$$

$$x = Tz$$

$$\Rightarrow \dot{z} = \begin{bmatrix} 0 & -4 & 1 \\ 1 & -4 & -2 \\ 0 & 0 & 1 \end{bmatrix} z + \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} u$$

$$z = T^{-1}x = \begin{bmatrix} 3 & 0 & 1 \\ -1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$z_1 = 3x_1 + x_3$$

$$z_2 = -x_1$$

$$z_3 = x_2$$

$\therefore x_2$ is not controllable.

$$\theta = \begin{bmatrix} C \\ CA \\ CA^2 \end{bmatrix} = \begin{bmatrix} 1 & -1 & 1 \\ 2 & -3 & 2 \\ 4 & -7 & 4 \end{bmatrix}$$

$$\text{rank } \theta = 2 < 3$$

\therefore not completely observable

$$T^{-1} = \begin{bmatrix} 1 & -1 & 1 \\ 2 & -3 & 2 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\dot{z} = T^{-1}ATz + T^{-1}Bu$$

$$\dot{z} = \begin{bmatrix} 0 & -1 & 1 \\ -2 & -3 & 2 \\ -5 & 3 & 2 \end{bmatrix} z + \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} u$$

$$y = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix} z$$

z_2 and z_3 are not observable.

$$z_3 = x_3$$

$\therefore x_3$ is not observable.

6.

M =

$$M = \begin{bmatrix} C \\ CA \\ \vdots \\ CA^{n-1} \end{bmatrix}$$

$$A \quad n \times n$$

$$C \quad 1 \times n$$

$$x \in \ker(M)$$

$$\Rightarrow Mx = 0$$

$$\Rightarrow \begin{bmatrix} Cx \\ CAx \\ CA^2x \\ \vdots \\ CA^{n-1}x \end{bmatrix} = 0 \quad \text{--- (1)}$$

To prove $Ax \in \ker(M)$

$$M \cdot Ax = \begin{bmatrix} CAx \\ CA^2x \\ \vdots \\ CA^nx \end{bmatrix}$$

$$= \begin{bmatrix} 0 \\ \vdots \\ 0 \\ CA^nx \end{bmatrix}$$

from (1)

from Cayley hamilton theorem

$$A^n = \alpha_0 I + \alpha_1 A + \alpha_2 A^2 + \dots + \alpha_{n-1} A^{n-1}$$

$\therefore A^n$ can be expressed as ^{Linear combⁿ} sum of $\{I, A, A^2, \dots, A^{n-1}\}$

$$\therefore Cx, CAx, \dots, CA^{n-1}x = 0$$

$$\Rightarrow CA^n x = 0$$

$$\therefore M - Ax = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ 0 \end{bmatrix}$$

$$\therefore Ax \in \ker(W)$$

$$\Rightarrow \dot{x} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{bmatrix} x \quad ; \quad y = [c_1 \ c_2 \ c_3] x$$

$$O = \begin{bmatrix} C \\ CA \\ CA^2 \end{bmatrix}$$

$$= \begin{bmatrix} c_1 & c_2 & c_3 \\ c_1 & 0 & -c_3 \\ c_1 & 0 & c_3 \end{bmatrix}$$

$$\{c_1 \ c_2 \ c_3\} = \{1 \ 1 \ 0\} \rightarrow \underline{\text{NOT}} \text{Observable}$$

$$\{1 \ 1 \ 1\} \rightarrow \text{OBSERVABLE}$$

General condition rank O . . .

$$\det \neq 0$$

$$\Rightarrow c_1, c_2, c_3 \neq 0.$$

(iv) general case

$$A = \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix}$$

$$\Rightarrow A^2 = \begin{bmatrix} \lambda_1^2 & 0 & 0 \\ 0 & \lambda_2^2 & 0 \\ 0 & 0 & \lambda_3^2 \end{bmatrix}$$

$$O = \begin{bmatrix} c_1 & c_2 & c_3 \\ c_1 \lambda_1 & c_2 \lambda_2 & c_3 \lambda_3 \\ c_1 \lambda_1^2 & c_2 \lambda_2^2 & c_3 \lambda_3^2 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 1 & 1 \\ \lambda_1 & \lambda_2 & \lambda_3 \\ \lambda_1^2 & \lambda_2^2 & \lambda_3^2 \end{bmatrix} \begin{bmatrix} c_1 & 0 & 0 \\ 0 & c_2 & 0 \\ 0 & 0 & c_3 \end{bmatrix}$$

fully observable $\Rightarrow \text{rank} = 3 \Rightarrow \det \neq 0$

$$\Rightarrow c_1, c_2, c_3 \neq 0 \quad \text{and} \quad (\lambda_1 - \lambda_2)(\lambda_2 - \lambda_3)(\lambda_3 - \lambda_1) \neq 0$$