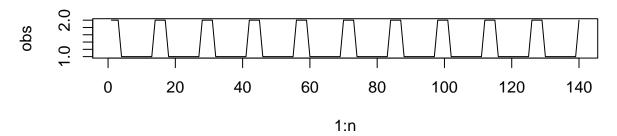
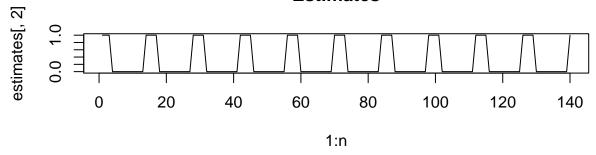
## Hidden Markov Model

```
Modified from: https://www.r-bloggers.com/hmm-example-with-depmixs4/
library(depmixS4)
## Warning: package 'depmixS4' was built under R version 4.0.2
## Loading required package: nnet
## Loading required package: MASS
## Loading required package: Rsolnp
## Warning: package 'Rsolnp' was built under R version 4.0.2
## Loading required package: nlme
# generate our data
n <- 140 # number of transitions (7 days, 10 weeks)
obs \leftarrow \text{rep}(c(c(2, 2), c(2, 1), c(1, 1), c(1, 1), c(1, 1), c(1, 1), c(1, 2)), 10)
set.seed(1234)
# 1. create the model
mod <- depmix(response = obs ~ 1, data=data.frame(obs), nstates=2)</pre>
# 2. fit the model
f <- fit(mod)
## converged at iteration 8 with logLik: 4462.099
summary(f)
## Initial state probabilities model
## pr1 pr2
##
   1 0
##
## Transition matrix
           toS1 toS2
## fromS1 0.744 0.256
## fromS2 0.100 0.900
##
## Response parameters
## Resp 1 : gaussian
       Re1.(Intercept) Re1.sd
## St1
                      2
## St2
# get the estimated state for each timestep
estimates <- posterior(f)</pre>
par(mfrow=c(2,1))
plot(1:n, obs, type='l', main='Observations, X')
plot(1:n, estimates[,2], type='l', main='Estimates')
```

## Observations, X



## **Estimates**



What did it learn?

## head(estimates)

##		state	S1	S2
##	1	1	1	0
##	2	1	1	0
##	3	1	1	0
##	4	2	0	1
##	5	2	0	1
##	6	2	0	1