# ABC-based Forecasting in State Space Models

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**IMS-APRM 2024** 

**Supervisors:** 

Professor Gael M. Martin, Dr. Ruben Loaiza Maya and Associate Professor David Frazier



• Powerful tool for modelling and forecasting the complex dynamics associated with the observed time series data



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- Observed data:  $y_{1:T} = \{y_1, y_2..., y_T\}$
- Unobserved states:  $x_{1:T} = \{x_1, x_2, ..., x_T\}$



Background and Motivation

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$$p(y_t|x_t, \theta)$$



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(Markov) transition density:  $p(x_t|x_{t-1}, \theta)$ 



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 $p(y_t|x_t,\theta)$ Measurement density:

(Markov) transition density:  $p(x_t|x_{t-1},\theta)$ 

Plus

Initial state density:  $p(x_1|\theta)$ 

• May depend on a set of unknown, static parameters  $\theta$ 

Chava Weerasinghe IMS-APRM 2024 2/29 • Distribution of interest is

$$p(y_{T+1}|y_{1:T})$$

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#### Exact Bayesian Forecasting in SSMs

Distribution of interest is

Background and Motivation

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$$p(y_{T+1}|y_{1:T}) = \int_{X} \int_{X} \int_{\Theta} p(y_{T+1}|x_{T+1},\theta) p(x_{T+1}|x_{T},\theta) \times (\underbrace{p(x_{1:T}|y_{1:T},\theta)}) \underbrace{p(\theta|y_{1:T})}_{\theta} d\theta dx_{1:T} dx_{T+1}$$



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- Often readily accessible via
  - Bayesian Markov chain Monte Carlo (MCMC) methods or
  - Particle MCMC variants
- But... challenges remain when the model is **intractable** in some sense

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Background and Motivation

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• Occurs in **two** ways:



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  - **1** when the **dimension** of either **y** or **x** (and the associated  $\theta$ ), or both, is very large

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  - when the data generating process (DGP) unavailable in closed form



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  - **1** when the **dimension** of either **y** or **x** (and the associated  $\theta$ ), or both, is very large
  - when the data generating process (DGP) **unavailable** in closed form
- $\bullet \Rightarrow$  exact Bayesian prediction may not be feasible



Background and Motivation

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• Can be analyzed using approximate computational methods



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- Can be analyzed using approximate computational methods
- High-dimensional SSMs are tackled via variational Bayes (VB) methods:
  - [Tran et al., 2017], [Quiroz et al., 2022], [Loaiza-Maya et al., 2021b], [Frazier et al., 2023]



- Can be analyzed using approximate computational methods
- High-dimensional SSMs are tackled via variational Bayes (VB) methods:
  - [Tran et al., 2017], [Quiroz et al., 2022], [Loaiza-Maya et al., 2021b], [Frazier et al., 2023]
- SSMs with unavailable components are managed via approximate Bayesian computation (ABC):
  - [Dean et al., 2014], [Creel and Kristensen, 2015], [Frazier et al., 2019], [Martin et al., 2019]
  - ⇒ Our focus



Background and Motivation

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#### • The aim of ABC

- is to produce draws from an **approximation** to  $p(\theta|y_{1:T})$
- in the case where DGP cannot be evaluated
- But *can* be **simulated** from



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• Simulate i = 1, 2, ..., N, *i.i.d.* draws of  $\theta^{(i)}$  from  $p(\theta)$ 



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- Simulate i = 1, 2, ..., N, i.i.d. draws of  $\theta^{(i)}$  from  $v(\theta)$
- Simulate

Background and Motivation

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- **pseudo-states**  $x_{1:T}^s(\theta^i)$ , i = 1, 2, ..., N from  $p(x_1^s|\theta^i)$  and  $p(x_t^s | x_{t-1}^s, \theta^i)$ , for t = 2, ..., T.
- **pseudo-data**  $y_{1:T}^s(\theta^i)$ , i = 1, 2, ..., N from  $p(y_t^s|x_t^s, \theta^i)$ , for t = 1, 2, ..., T.

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- Select  $\theta^{(i)}$  such that:

$$d\{\eta(y_{1:T}), \eta(y_{1:T}^s(\theta^i))\} \leq \varepsilon,$$



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- Simulate i = 1, 2, ..., N, i.i.d. draws of  $\theta^{(i)}$  from  $v(\theta)$
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- Select  $\theta^{(i)}$  such that:

$$d\{\eta(y_{1:T}), \eta(y_{1:T}^s(\theta^i))\} \leq \varepsilon,$$

- $\eta(.)$  is a (vector) summary statistic
- *d*{.} is a **distance criterion**
- the **tolerance**  $\varepsilon$  is arbitrarily small



- Simulate i = 1, 2, ..., N, i.i.d. draws of  $\theta^{(i)}$  from  $v(\theta)$
- Simulate

Background and Motivation

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- Select  $\theta^{(i)}$  such that:

$$d\{\eta(y_{1:T}), \eta(y_{1:T}^s(\theta^i))\} \leq \varepsilon,$$

- $\eta(.)$  is a (vector) summary statistic
- *d*{.} is a **distance criterion**
- the **tolerance**  $\varepsilon$  is arbitrarily small
- Selected draws  $\Rightarrow$  draws from  $p_{\varepsilon}(\theta|\eta(y_{1:T}))$

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## Existing ABC Literature

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#### **Existing ABC Literature**

- Under correct model specification,
  - ABC posterior Bayesian consistent for the true parameter, asymptotically normal [Frazier et al., 2018] - 'Asymptotic properties of approximate Bayesian computation'
  - also in an explicitly SSM setting [Martin et al., 2019] - 'Auxiliary likelihood-based approximate Bayesian computation in state space models'
  - ABC-based forecasting [Frazier et al., 2019] - 'Approximate Bayesian forecasting'



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  - ABC-based forecasting [Frazier et al., 2019] - 'Approximate Bayesian forecasting'
- Under model misspecification
  - [Frazier et al., 2020] 'Model misspecification in approximate Bayesian computation: consequences and diagnostics'

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## What is left unexplored?

Background and Motivation

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• ABC-based forecasting – with *misspecified* SSMs



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## What is left unexplored?

- **ABC-based forecasting** with *misspecified* SSMs
- If we do not assume the correct model specification  $\Rightarrow$
- the whole focus of the Bayesian forecasting exercise **needs** to change.
  - argument put forward in recent forecasting works by
    - [Loaiza-Maya et al., 2021a] 'Focused Bayesian prediction'
    - [Frazier et al., 2021] 'Loss-based variational Bayes prediction'



## What is left unexplored?

Background and Motivation

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- the whole focus of the Bayesian forecasting exercise needs to change.
  - argument put forward in recent forecasting works by
    - [Loaiza-Maya et al., 2021a] 'Focused Bayesian prediction'
    - [Frazier et al., 2021] 'Loss-based variational Bayes prediction'
- For the first time: ABC-based forecasting + Loss-based Bayesian prediction



#### Loss-based Bayesian Prediction

Essence of the idea:



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#### Loss-based Bayesian Prediction

- Essence of the idea:
- In the spirit of the various generalized Bayesian *inferential* methods,
  - [Bissiri et al., 2016]; [Giummolè et al., 2019]; [Knoblauch et al., 2019]; [Pacchiardi and Dutta, 2021]
- replace the likelihood function (log-score loss) in the conventional Bayesian update
- by the *particular* **predictive loss** that matters for the particular forecasting problem being tackled



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## Loss-based Bayesian Prediction in SSMs

• Assume a class of plausible **predictive SSMs** for  $Y_{T+1}$ , conditioned on information  $\mathcal{F}_T$ :

$$\mathcal{P}^{(T)} := \{P_{\theta}^{(T)}, \theta \in \Theta\}$$

- **Key thing:** Do not assume  $P_0 \in \mathcal{P}^{(T)}$
- Construct the loss-based posterior/Gibbs posterior  $p_L(\theta|y_{1:T})$ 
  - via some (positively-oriented) scoring rule

$$S_T(\theta) := \sum_{t=1}^{T} s(P_{\theta}^{(t)}, y_{t+1})$$



#### Loss-based Bayesian Prediction in SSMs

• ⇒ Loss-based predictive

$$p_{L}(y_{T+1}|y_{1:T})$$

$$= \int_{X} \int_{X} \int_{\Theta} p(y_{T+1}|x_{T+1}, \theta) p(x_{T+1}|x_{T}, \theta)$$

$$\times p(x_{T}|y_{1:T}, \theta) p_{L}(\theta|y_{1:T}) d\theta dx_{1:T} dx_{T+1}$$

• Consider the **loss-based predictive**  $p_L(y_{T+1}|y_{1:T})$  which is constructed based on  $p_L(\theta|y_{1:T})$  via

$$S_T(\theta) := \sum_{t=1}^T s(\underbrace{p(y_{t+1}|y_{1:T}, \theta)}_{\text{with marginal of } x_{1:T}}, y_{t+1})$$

• Intractable SSM model  $\Rightarrow p_L(\theta|y_{1:T})$  out of reach



#### Our solution..

• Approximate  $p_L(\theta|y_{1:T})$  using **ABC** 

Loss-based ABF 00000000



#### Our solution..

- Approximate  $p_L(\theta|y_{1:T})$  using **ABC** 
  - In the spirit of 'auxiliary model'- based ABC:
    - [Drovandi et al., 2011], [Drovandi et al., 2015] and [Martin et al., 2019]
  - We choose an auxiliary model
    - that is a 'reasonable' approximation to the assumed **SSM** &
    - admit a **closed-form predictive** (with parameter vector  $\beta$ )



#### Our solution..

- Approximate  $p_L(\theta|y_{1:T})$  using **ABC** 
  - In the spirit of 'auxiliary model'- based ABC:
    - [Drovandi et al., 2011], [Drovandi et al., 2015] and [Martin et al., 2019]
  - We choose an auxiliary model
    - that is a 'reasonable' approximation to the assumed **SSM** &
    - admit a **closed-form predictive** (with parameter vector  $\beta$ )
  - Define the score-based criterion as:

$$S_T(\beta) := \sum_{t=0}^{T-1} s(P_{\beta}^{(t)}, y_{t+1})$$

• **NOTE:** this is useful *even when the DGP itself is tractable* 

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## How Do We Choose the Summary Statistics?

- *Summary statistics* : average of the first-derivative of  $S_T(\beta)$  using a scoring rule  $s_j$ 
  - evaluated at  $\hat{\beta}_j(y_{1:T})$ : optimizer of  $S_T(\beta)$  using  $s_j$



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# How Do We Choose the Summary Statistics?

- Summary statistics: average of the first-derivative of  $S_T(\beta)$ using a scoring rule  $s_i$ 
  - evaluated at  $\hat{\beta}_i(y_{1:T})$ : optimizer of  $S_T(\beta)$  using  $s_i$
- That is,

$$\eta_j(\boldsymbol{y}_{1:T}^s) = \left. T^{-1} \frac{\partial \sum_{t=1}^T s_j(P_{\beta}^{(t)}, \boldsymbol{y}_{t+1}^s(\boldsymbol{\theta^i}))}{\partial \beta} \right|_{\beta = \hat{\beta}_j(y_{1:T})}$$

and:

$$\eta_{j}(\mathbf{y}_{1:T}) = T^{-1} \frac{\partial \sum_{t=1}^{T} s_{j}(P_{\beta}^{(t)}, \mathbf{y}_{t+1})}{\partial \beta} \bigg|_{\beta = \hat{\beta}_{j}(y_{1:T})} = 0$$

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#### Distance Criterion

• ABC distance : Mahalanobis distance

$$\begin{split} &d\{\eta\left(y_{1:T}^{s}\right),\eta\left(y_{1:T}\right)\}\\ &=&\sqrt{\left[\bar{S}_{j}\left\{y_{1:T}^{s}(\theta^{i});\hat{\beta}_{j}(y_{1:T})\right\}\right]'\hat{\Sigma}\left[\bar{S}_{j}\left\{y_{1:T}^{s}(\theta^{i});\hat{\beta}_{j}(y_{1:T})\right\}\right]}, \end{split}$$

- where  $\hat{\Sigma}$  is the inverse of the (estimated) covariance matrix of  $\eta_j(y^s_{1:T})$  across draws and
- $\bar{S}_{j}\left\{y_{1:T}^{s}(\theta^{i}); \hat{\beta}_{j}(y_{1:T})\right\} = T^{-1} \frac{\partial \sum_{t=1}^{T} s_{j}(P_{\beta}^{(t)}, y_{t+1}^{s}(\theta^{i}))}{\partial \beta} \bigg|_{\beta = \hat{\beta}_{j}(y_{1:T})}$



- The accepted draws of  $\theta$  produced by the ABC algorithm  $\Rightarrow$
- are the draws from loss-based ABC posterior,  $p_{L,\varepsilon}(\theta|\eta(y_{1:T}))$



#### Loss-based ABF

- The accepted draws of  $\theta$  produced by the ABC algorithm  $\Rightarrow$
- are the draws from loss-based ABC posterior,  $p_{I,\varepsilon}(\theta|\eta(y_{1:T}))$
- Loss-based ABC predictive :

$$g_{L}(y_{T+1}|y_{1:T})$$

$$= \int_{X} \int_{X} \int_{\theta} p(y_{T+1}|x_{T+1},\theta) p(x_{T+1}|x_{T},\theta) p(x_{T}|\theta,y_{1:T})$$

$$\times p_{L,\varepsilon}(\theta|\eta(y_{1:T})) d\theta dx_{T} dx_{T+1}$$

• ⇒ loss-based ABC forecasting (loss-based ABF)

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- Using the **auxiliary model predictive** *directly* in a generalized Bayesian update
  - Avoids the use of a SSM representation
  - But, use of a *simpler model* in a focused up-date well be adequate
  - ⇒ [Loaiza-Maya et al., 2021a] 'Focused Bayesian prediction' (FBP)



- Predictive class,  $P_{a}^{(t)}$  is a SSM:
  - SV model for a continuous financial return, y<sub>t</sub>

$$y_t = \mu + e^{\alpha_t/2} e_t \quad ; \quad e_t \sim N(0, 1)$$

$$\alpha_t = \bar{h}_\alpha + \phi(\alpha_{t-1} - \bar{h}_\alpha) + w_t \quad ; \quad w_t \sim N(0, \sigma_\alpha^2)$$

$$\alpha_0 \sim N\left(\bar{h}_\alpha, \frac{\sigma_\alpha^2}{1 - \phi^2}\right),$$

$$\bullet \ \theta = (\phi, \sigma_{\alpha}^2, \mu, \bar{h}_{\alpha})'$$

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• True DGP



- True DGP
  - A model that matches the assumed SV model
    - ⇒ Correct model specification



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- True DGP
  - A model that matches the assumed SV model
    - ⇒ Correct model specification
  - SV model that better replicates the stylized features of financial returns data, as used by [Loaiza-Maya et al., 2021a]

$$z_t = e^{h_t/2} \epsilon_t$$

$$h_t = \bar{h} + a(h_{t-1} - \bar{h}) + \sigma_h \eta_t$$

$$y_t = G^{-1}(F_z(z_t))$$

- ⇒ Implied copula of a stochastic volatility model combined with a **skewed normal marginal**,  $g(y_t)$  (imposed via  $G^{-1}$ )
- ⇒ Model misspecification
- Predicting extreme returns accurately is important
- Will **focus** on that goal  $\Rightarrow$  use an appropriate  $s_i$  in the update

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- Two auxiliary models are used:
  - 1 a Gaussian ARCH(1) model
  - 2 a Gaussian GARCH(1,1) model



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- Two auxiliary models are used:
  - a Gaussian ARCH(1) model
  - 2 a Gaussian GARCH(1,1) model
- Results for three types of **scores** reproduced here:
  - Log score (LS)
  - Censored log score (CLS) (rewards predictive accuracy in a tail)
  - Continuously ranked probability score (CRPS) (rewards the assignment of high predictive mass near to the realized value)
    - [Gneiting and Raftery, 2007]



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    - [Gneiting and Raftery, 2007]
- Will discuss the results based on **Gaussian GARCH(1,1)** model under **model misspecification**

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#### Loss-based ABF Average out-of-sample score

	LS	CLS<10%	CLS <sub>&gt;80%</sub>	CLS>90%	CRPS
ABC Score					
LS	-1.3427	-0.3586	-0.4900	-0.2975	-0.5331
$\text{CLS}_{<10\%}$	-1.4117	-0.3572	-0.5122	-0.3037	-0.5616
CLS <sub>&gt;80%</sub>	-2.0917	-0.8118	-0.4675	-0.2822	-0.6082
$\text{CLS}_{>90\%}$	-2.4259	-0.8961	-0.4715	-0.2777	-0.6509
CRPS	-1.3371	-0.3629	-0.4881	-0.2998	-0.5309
<b>Exact Bayes</b>	-1.3343	0.3618	-0.4882	-0.3003	-0.5304

- Rows ⇒ Scoring rules used in underlying loss-based ABF results
- Last Row ⇒ Exact (but misspecified) Bayesian predictive
- **Columns** ⇒ Measure of out-of-sample accuracy

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Background and Motivation

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- Positively-oriented scores ⇒ large ( in bold ) is good
- Looking for bold values on the diagonal
  - The predictive constructed via the use of a particular scoring rule predicts best according to that rule

'Coherent predictions' are in evidence

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• Loss-based ABF > misspecified exact Bayes



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#### Comparison of loss-based ABF and FBP

#### Panel A: Loss-based ABF Average out-of-sample score

Scoring rule	LS	CLS<10%	CLS <sub>&gt;80%</sub>	CLS>90%	CRPS
ABC-LS	-1.3427	-0.3586	-0.4900	-0.2975	-0.5331
ABC-CLS<10%	-1.4117	-0.3572	-0.5122	-0.3037	-0.5616
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ABC-CRPS	-1.3371	-0.3629	-0.4881	-0.2998	-0.5309
Exact	-1.3343	-0.3618	-0.4882	-0.3003	-0.5304

#### Panel B: FBP Average out-of-sample score

Scoring rule	LS	$\mathrm{CLS}_{<10\%}$	$\mathrm{CLS}_{>80\%}$	CLS>90%	CRPS
FBP-LS	-1.3471	-0.3694	-0.4840	-0.2954	-0.5340
FBP-CLS<10%	-1.3669	-0.3593	-0.5094	-0.3212	-0.5380
FBP-CLS>80%	-2.0718	-0.9227	-0.4491	-0.2657	-0.5888
FBP-CLS <sub>&gt;90%</sub>	-2.5938	-1.1223	-0.4579	-0.2644	-0.6357
FBP-CRPS	-1.3485	-0.3786	-0.4839	-0.2973	-0.5319
Exact	-1.3343	-0.3618	-0.4882	-0.3003	-0.5304

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Comparison of loss-based ABF and FBP

- Both methods produce *coherent* predictions
- Dominance of loss-based ABF over FBP is not uniform
  - Likely to depend on the extent to which assumed SSM is misspecified



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- Applying **loss-based ABF** to daily returns data on the S & P500 index
- Assumed predictive class:
  - SV model with  $\alpha$ -Stable errors for a continuous financial return,  $y_t$ ,

$$y_t = e^{h_t/2} \varepsilon_t$$
 ;  $\varepsilon_t \stackrel{iid}{\sim} N(0,1)$ 

$$h_t = \omega + \rho h_{t-1} + \sigma_h \eta_t$$
 ;  $\eta_t \stackrel{iid}{\sim} S(\alpha, -1, 0, dt = 1)$ 

- Transition density is unavailable
- ⇒ Truly intractable SSM

• 
$$\theta = (\omega, \rho, \sigma_h^2, \alpha)'$$



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# **Empirical Illustration: Results**

#### Panel A: Loss-based ABF Average out-of-sample score

	LS	CLS<10%	CLS<20%	CLS>80%	CLS>90%
Scoring rule	-				
ABC-LS	3.3967	0.0268	0.2923	0.5170	0.1523
ABC-CLS <sub>&lt;10%</sub>	3.4058	0.0391	0.3048	0.5122	0.1500
ABC-CLS<20%	3.4053	0.0383	0.3041	0.5126	0.1502
ABC-CLS <sub>&gt;80%</sub>	3.3772	0.0052	0.2713	0.5192	0.1547
ABC-CLS>90%	3.3849	0.0134	0.2790	0.5191	0.1540

#### Panel B: FBP Average out-of-sample score

	LS	CLS<10%	CLS<20%	CLS>80%	CLS>90%
Scoring rule					
FBP-LS	3.3467	-0.0262	0.2406	0.4801	0.1473
FBP-CLS<10%	3.1051	0.0463	0.3096	0.1903	-0.1119
FBP-CLS<20%	3.1788	0.0417	0.3085	0.2645	-0.0430
FBP-CLS>80%	3.3293	-0.0515	0.2155	0.4860	0.1531
FBP-CLS <sub>&gt;90%</sub>	3.1941	-0.1204	0.1042	0.4820	0.1543

- Conclusions are a bit mixed
- But overall, loss-based ABF > FBP



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  - Loss-based ABF



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  - Coherent predictions are in evidence
  - More accurate forecasts than the exact (misspecified) predictive
  - Often more accurate than the FBP results
- Little to lose from adopting the ABC-based approach, and much to gain!

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# Thank you!

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