

/camera_floor/background

NOTHING PRINTED ON RVIZ

/camera_floor/driver/color/camera_info

/camera_floor/driver/color/image_raw

/camera_floor/driver/color/image_raw/compressed

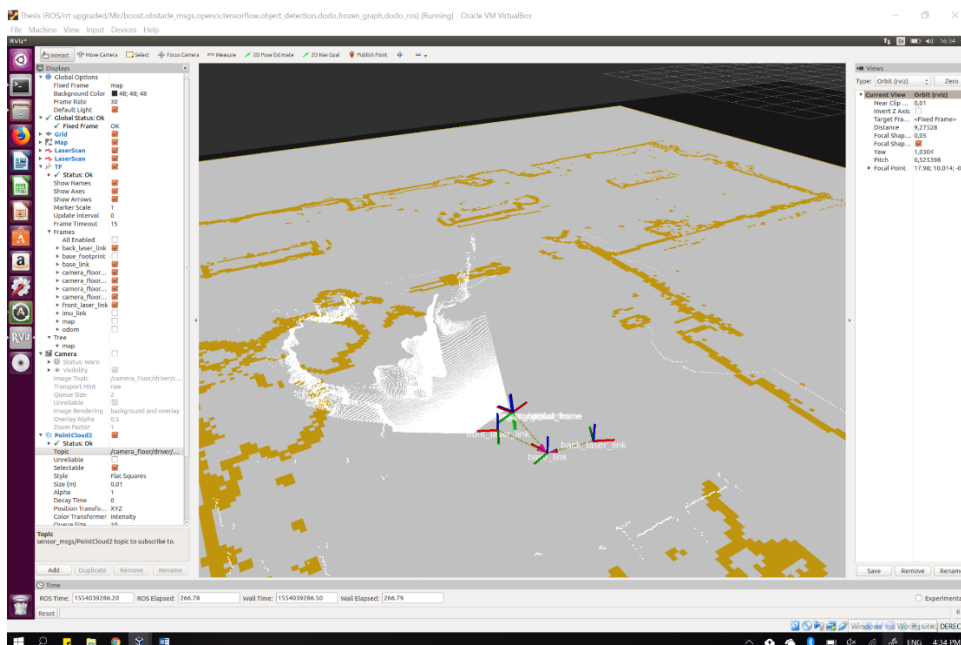
/camera_floor/driver/color/image_raw/compressed/parameter_descriptions

/camera_floor/driver/color/image_raw/compressed/parameter_updates

/camera_floor/driver/depth/camera_info

```
chbloca@chbloca-VirtualBox:~$ rostopic echo -n1 /camera_floor/driver/depth/camera_info
header:
  seq: 64
  stamp:
    secs: 1554040068
    nsecs: 239128282
  frame_id: "camera_floor_depth_optical_frame"
height: 480
width: 640
distortion_model: "plumb_bob"
D: [0.0, 0.0, 0.0, 0.0, 0.0]
K: [382.3329162597656, 0.0, 317.26373291015625, 0.0, 382.3329162597656, 240.86376953125, 0.0, 0.0, 1.0]
R: [1.0, 0.0, 0.0, 0.0, 1.0, 0.0, 0.0, 0.0, 1.0]
P: [382.3329162597656, 0.0, 317.26373291015625, 0.0, 0.0, 382.3329162597656, 240.86376953125, 0.0, 0.0, 1.0, 0.0]
binning_x: 0
binning_y: 0
rot:
  x_offset: 0
  y_offset: 0
  height: 0
  width: 0
  do_rectify: False
---
```

/camera_floor/driver/depth/color/points



```

chbloca@chbloca-VirtualBox:~$ rostopic type /camera_floor/driver/depth/image_rect_raw
sensor_msgs/Image
chbloca@chbloca-VirtualBox:~$ rostopic info /camera_floor/driver/depth/image_rect_raw
Type: sensor_msgs/Image

Publishers:
 * /camera_floor/driver (http://192.168.12.20:43481/)

Subscribers: None

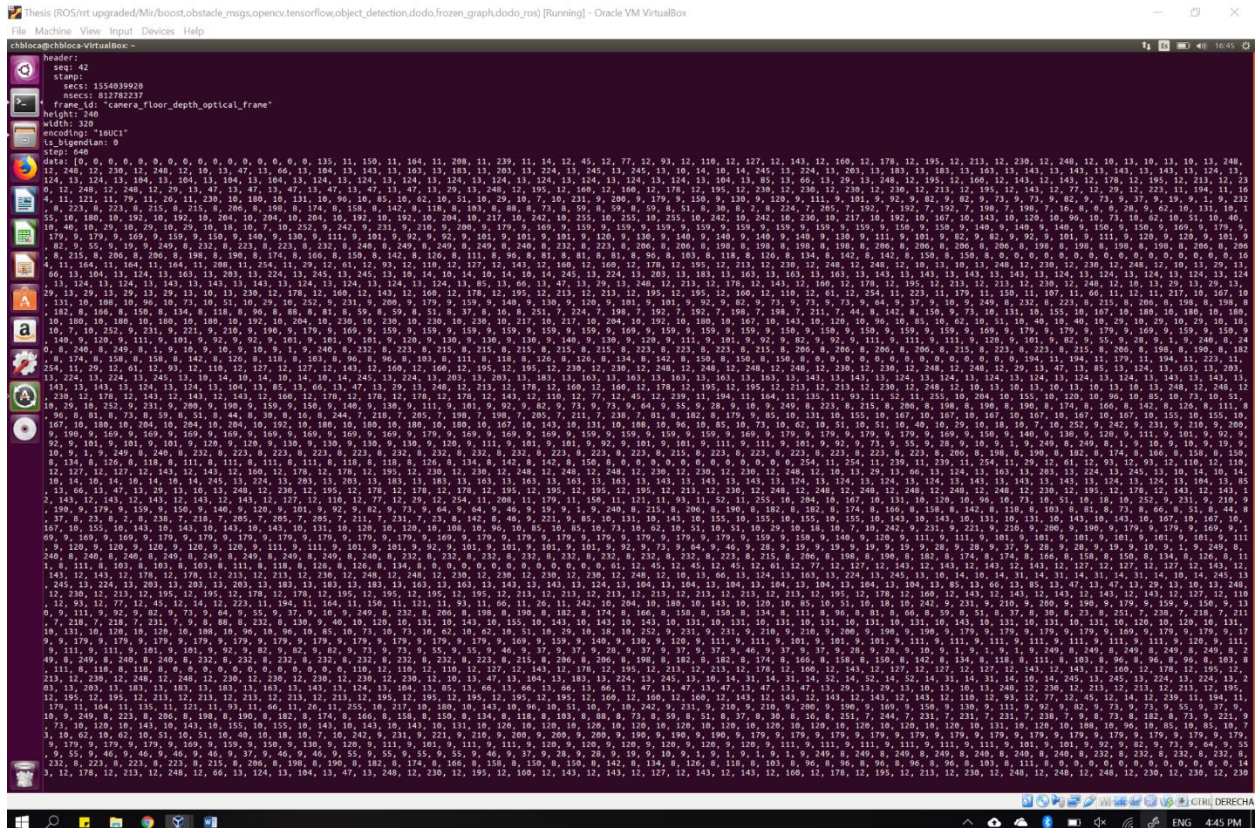
chbloca@chbloca-VirtualBox:~$ rosmmsg
rosmmsg is a command-line tool for displaying information about ROS Message types.

Commands:
    rosmmsg show      Show message description
    rosmmsg info      Alias for rosmmsg show
    rosmmsg list       List all messages
    rosmmsg md5        Display message md5sum
    rosmmsg package    List messages in a package
    rosmmsg packages   List packages that contain messages

Type rosmmsg <command> -h for more detailed usage

chbloca@chbloca-VirtualBox:~$ rosmmsg info sensor_msgs/Image
sensor_msgs/Image sensor_msgs/Imu
chbloca@chbloca-VirtualBox:~$ rosmmsg info sensor_msgs/Image
std_msgs/Header header
  uint32 seq
  time stamp
  string frame_id
uint32 height
uint32 width
string encoding
uint8 is_bigendian
uint32 step
uint8[] data

```



/camera_floor/driver/depth/image_rect_raw/compressed

/camera_floor/driver/depth/image_rect_raw/compressed/parameter_descriptions

/camera_floor/driver/depth/image_rect_raw/compressed/parameter_updates

/camera_floor/driver/extrinsics/depth_to_color

/camera_floor/driver/parameter_descriptions

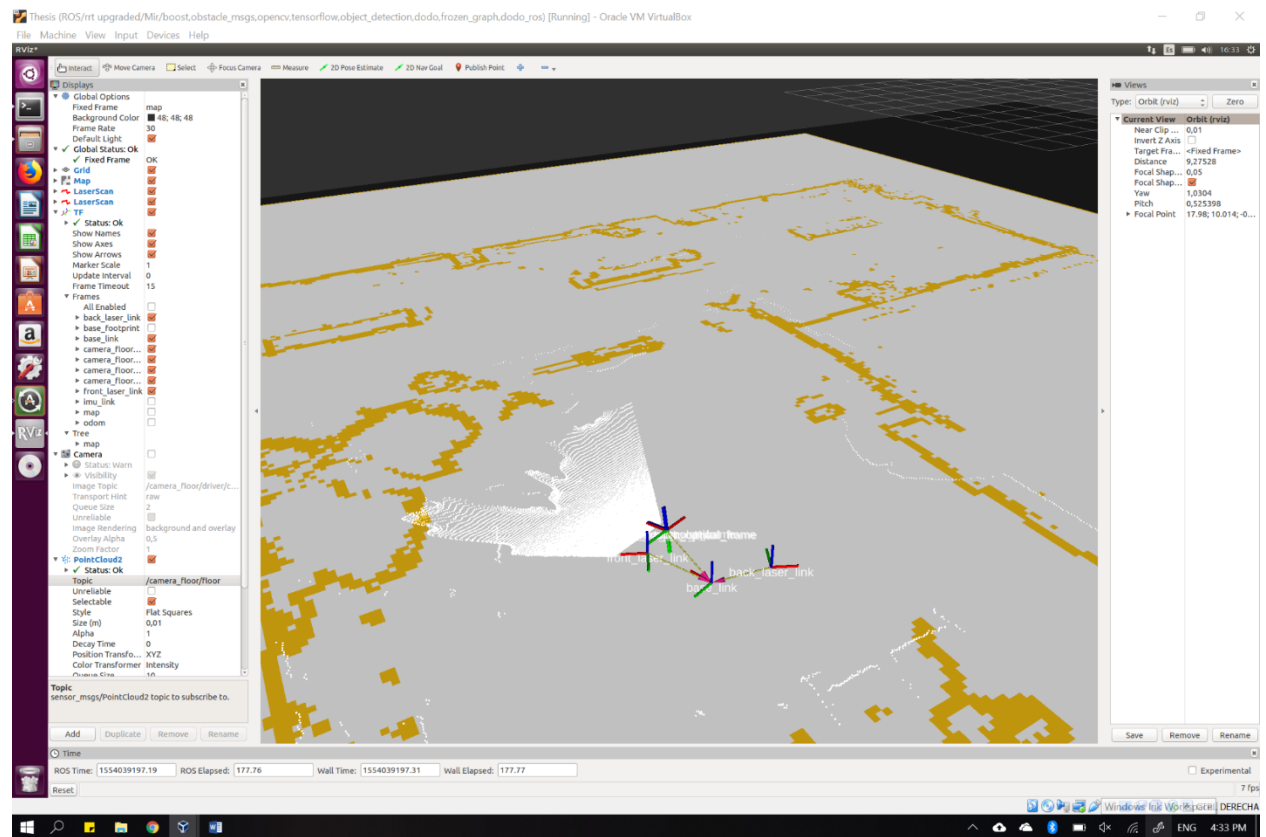
/camera_floor/driver/parameter_updates

/camera_floor/filter/parameter_descriptions

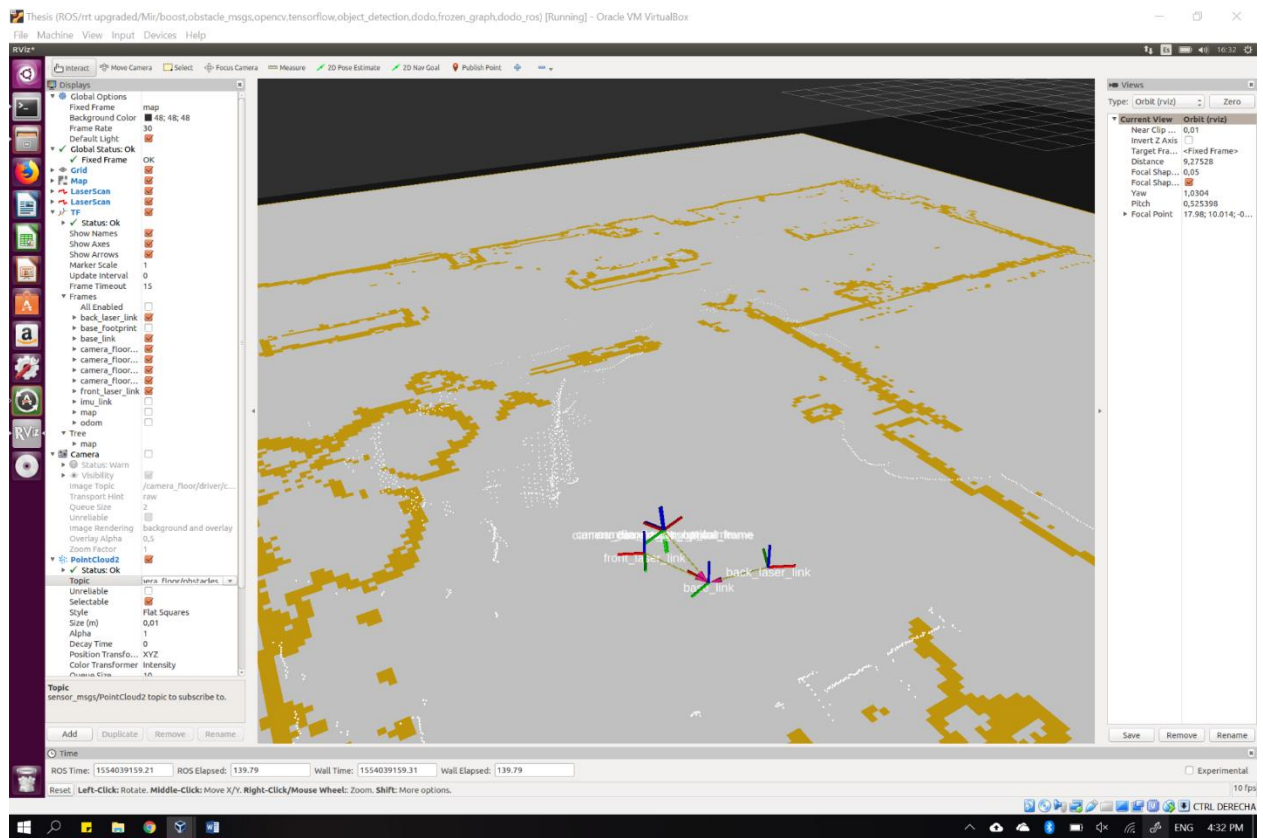
/camera_floor/filter/parameter_updates

/camera_floor/filter/visualization_marker

/camera_floor/floor



/camera_floor/obstacles



/camera_floor/transform/parameter_descriptions

/camera_floor/transform/parameter_updates