## **SGN-41007 Pattern Recognition and Machine Learning**

Exercise Set 6: February 11–February 15, 2019

Exercises consist of both pen&paper and computer assignments. Pen&paper questions are solved at home before exercises, while computer assignments are solved during exercise hours. The computer assignments are marked by **python** and Pen&paper questions by **pen&paper** 

1. **pen&paper** Count the number of parameters in a neural network

Consider the traditional shallow neural network architecture of Figure 1. Suppose our inputs are  $64 \times 64$  RGB bitmaps of two categories of traffic signs.

Let the network structure be the following:

- The input is  $64 \times 64 \times 3 = 12288$ -dimensional
- On the 1st layer there are 100 nodes (marked in blue)
- On the 2nd layer there are 100 nodes (marked in blue)
- On the 3rd (output) layer there are 10 nodes (marked in blue; one for each class)

Compute the number of parameters (coefficients) in the net.

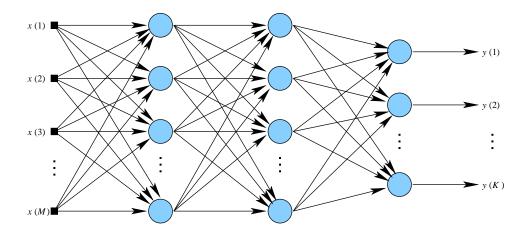


Figure 1: Vanilla neural network.

2. **pen&paper** Consider the following Keras code defining a convolutional neural network.

- a) Draw a diagram of the network similar to the one at the bottom of slide 14 in http://www.cs.tut.fi/courses/SGN-41007/slides/ Lecture6.pdf
- b) Compute the number of parameters of the network at each layer (and explain why).
- 3. | **python** | Load Traffic sign data for deep neural network processing.

Download an extended version of the two class German Traffic Sign Recognition Benchmark (GTSRB) dataset from

```
http://www.cs.tut.fi/courses/SGN-41007/GTSRB_subset_2.zip
```

This time, images are in color and there are about 400 from both classes.

After collecting the data, normalize all samples into range [0,1]; *i.e.*, subtract numpy.min(X) and divide the result by numpy.max(X).

Finally, split the data to training and testing (80% / 20%) using sklearn.cross\_validation.train\_test\_split.

## 4. **python** Define the network in Keras.

Edit the network of Question 2 in your code such that model.summary() gives the following output:

| model.summary()   |        |             |         |
|---|--------|-------------|---------|
| Layer (type)  |        | Shape       | Param # |
| conv2d_49 (Conv2D)  |        | 64, 64, 32) | 2432    |
| max_pooling2d_47 (MaxPooling  | (None, | 16, 16, 32) | 0       |
| conv2d_50 (Conv2D)  | (None, | 16, 16, 32) | 25632   |
| max_pooling2d_48 (MaxPooling  | (None, | 4, 4, 32)   | 0       |
| flatten_15 (Flatten)  | (None, | 512)        | 0       |
| dense_29 (Dense)  | (None, | 100)        | 51300   |
| dense_30 (Dense)  | (None, | 2)          | 202     |
| Total params: 79,566 Trainable params: 79,566 Non-trainable params: 0 |        |             |         |
|   |        |             |         |

5. **python** Compile and train the net.

Compile and train the network following the examples of the lecture slides and documentation at http://keras.io/.

Use the following parameters:

- Loss: categorical crossentropy (same thing as log loss; see previous exercises)
- Optimizer: stochastic gradient descent
- Minibatch size: 32
- Number of epochs: 20

Also add the parameter metrics=['accuracy'] as an argument of model.compile and give the test data to training algorithm model.fit(..., validation\_data = [X\_test, y\_test]) Then, the optimizer will report the test error every epoch.