Exercise group #2

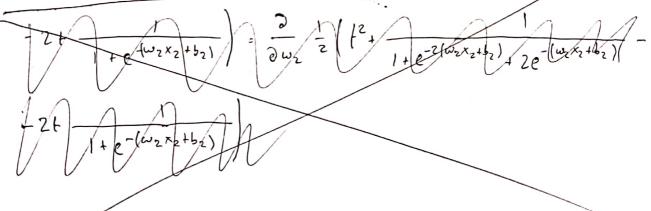
Fundamentals of Robot Vision

a) $\hat{y}_1 = 6(2_1) = 6(\omega_1 x_1 + b_1) = \frac{1}{1+e^{-(\omega_1 x_1 + b_1)}} = \frac{1}{1+e^{-(\omega_2 x_2 + b_2)}} = \frac{1}{1+e^{-(\omega_2 x_2$

$$= \frac{1}{1 + e^{-14 \cdot \frac{1}{2} + 01}} = \frac{1}{1 + e^{-2}} = 0.8808$$

b) $E = \frac{1}{2}(t-5)^2 = \frac{1}{2}(1-0.8808)^2 = 0.0071$

() $\frac{\partial}{\partial \omega_2} E = \frac{\partial}{\partial \omega_2} \frac{1}{2} \left(t - \frac{1}{1 + e^{-(\omega_2 \times_2 + L_2)}} \right)^2 = \frac{1}{2} \left(\frac{1}{1 + e^{-(\omega_2 \times_2 + L_2)}} \right)^2$



$$\frac{\partial}{\partial x} \mathcal{E}(x) = \mathcal{E}(x) \left(1 - \mathcal{E}(x) \right)$$

$$= -\frac{\partial}{\partial \omega_{z}} \left(\frac{1}{1 + e^{-(\omega_{z}x_{z} + b_{z})}} \right) = -\frac{1}{1 + e^{-(\omega_{z}x_{z} + b_{z})}} \left(1 - \frac{1}{1 + e^{-(\omega_{z}x_{z} + b_{z})}} \right)$$

$$= -\frac{1}{1 + e^{-(x_{z}x_{z} + b_{z})}} \left(1 - \frac{1}{1 + e^{-(x_{z}x_{z} + b_{z})}} \right) = -0.105$$

$$\frac{\partial}{\partial \omega_{z}} \mathcal{E} = \frac{\partial}{\partial \omega_{z}} \frac{1}{2} \left(t_{z} - \frac{1}{1 + e^{-(\omega_{z}(\omega_{z}x_{z} + b_{z}) + b_{z})}} \right)^{2} =$$

$$= -\frac{1}{1 + e^{-(\omega_{z}(\omega_{z}x_{z} + b_{z})} + b_{z})} \left(1 - \frac{1}{1 + e^{-(\omega_{z}(\omega_{z}x_{z} + b_{z}) + b_{z})}} \right)^{2} =$$

$$= -\frac{1}{1 + e^{-(\omega_{z}x_{z} + b_{z})}} \left(1 - \frac{1}{1 + e^{-(\omega_{z}x_{z} + b_{z})}} \right)^{2} = -0.25$$

$$= -0.25$$

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