

Formelsammlung für die schriftliche Prüfung Angewandte Mathematik in der Informatik

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1 Einführung

1.1 Funktionen $f: \mathbb{R} \to \mathbb{R}$

$$f(x) = d \qquad \qquad \text{(konstante Funktion)}$$

$$f(x) = kx + d \qquad \qquad \text{(explizite lineare F.)}$$

$$F(x,y) = \mathbf{n}\mathbf{x} + d = 0 \qquad \qquad \text{(implizite lineare F.)}$$

$$f(x) = ax^k \qquad \qquad \text{(Potenzfunktion)}$$

$$f(x) = \sqrt[k]{x} = x^{1/k} \qquad \qquad \text{(Wurzelfunktion)}$$

$$f(f^{-1}(x)) = x = f^{-1}(f(x)) \qquad \text{(Umkehrfunktion)}$$

1.2 Eigenschaften

$$f(x) = f(-x)$$
 (gerade Funktion)
 $f(x) = -f(-x)$ (ungerade Funktion)

1.3 Polynome

$$p(x) = \sum_{i=0}^{n} a_i x^i$$
 (Polynomfunktion)
$$r(x) = \frac{p_1(x)}{p_2(x)}$$
 (Rationale Funktion)

Faktorisierung

$$p(x) = (x - x_k)^{m_k} \dots (x - x_1)^{m_1} (x - x_0)^{m_0} \cdot q(x)$$

Nullstellen quadratisches Polynom

$$a x^{2} + b x + c = 0$$

$$x_{1,2} = \frac{-b \pm \sqrt{b^{2} - 4ac}}{2a}$$

1.4 Trigonometrische Funktionen

Additions theoreme

$$\sin(x \pm y) = \sin x \cdot \cos y \pm \cos x \cdot \sin y$$

$$\cos(x \pm y) = \cos x \cdot \cos y \mp \sin x \cdot \sin y$$

$$\tan(x \pm y) = \frac{\sin(x \pm y)}{\cos(x \pm y)} = \frac{\tan(x) \pm \tan(y)}{1 \mp \tan(x) \tan(y)}$$

$$\cot(x \pm y) = \frac{\cos(x \pm y)}{\sin(x \pm y)} =$$

Hyperbolische Funktionen

$$\sinh(x) = \frac{e^x - e^{-x}}{2}$$
$$\cosh(x) = \frac{e^x + e^{-x}}{2}$$
$$\tanh(x) = \frac{\sinh(x)}{\cosh(x)}$$

1.5 Vektoroperationen

$$\mathbf{v} \cdot \mathbf{w} = v_1 w_1 + \dots + v_n w_n \qquad \text{(Inneres Produkt)}$$

$$||\mathbf{v}||_2 = \sqrt{\mathbf{v} \cdot \mathbf{v}} \qquad \text{(Betrag, Länge)}$$

$$\hat{\mathbf{v}} = \text{nrm}(\mathbf{v}) = \frac{\mathbf{v}}{||\mathbf{v}||_2} \qquad \text{(Einheitsvektor)}$$

$$\varphi = \angle(\mathbf{v}, \mathbf{w}) \text{ mit } 0 \le \varphi \le \pi$$

$$\cos \varphi = \text{nrm}(\mathbf{v}) \cdot \text{nrm}(\mathbf{w}) \qquad \text{(Winkel 1)}$$

$$\mathbf{v} \cdot \mathbf{w} = ||\mathbf{v}||_2 ||\mathbf{w}||_2 \cos \varphi \qquad \text{(Winkel 2)}$$

1.6 Matrixoperationen

$$\mathbf{A} = a_{ij}$$
 $\mathbf{A}^{\mathsf{T}} = a_{ji}$ (Transponierte)
 $\mathbf{I} = \delta_{ij} = \mathrm{diag}(1, 1, \dots, 1)$ (Einheitsmatrix)
 $\mathbf{A}\mathbf{I} = \mathbf{I}\mathbf{A} = \mathbf{A}$
 $\mathbf{A}\mathbf{A}^{-1} = \mathbf{A}^{-1}\mathbf{A} = \mathbf{I}$ (Inverse)

2 Differential rechnung

2.1 Erste Ableitung

$$x(t)' = \frac{dx}{dt} = \frac{d}{dt}x = \dot{x} = \lim_{h \to 0} \frac{x(t+h) - x(t)}{h}$$

2.2 Ableitungsregeln

$$(a)' = 0$$
 (Konstante)
 $(x^k)' = kx^{k-1}$ (Potenz)
 $(af \pm bg)' = af' \pm bg'$ (Summenregel)
 $(f \cdot g)' = f' \cdot g + f \cdot g'$ (Produktregel)
 $\left(\frac{f}{g}\right)' = \frac{f' \cdot g - f \cdot g'}{g^2}$ (Quotientenregel)

$$(f \circ g)' = f'(g) \cdot g' \qquad \text{(Kettenregel)}$$

$$(\sin x)' = \cos x \qquad \text{(Kreisfunktionen 1)}$$

$$(\cos x)' = -\sin x \qquad \text{(Kreisfunktionen 2)}$$

$$(\sinh x)' = \cosh(x) \qquad \text{(Hyperbelfunktionen 1)}$$

$$(\cosh x)' = \sinh(x) \qquad \text{(Hyperbelfunktionen 2)}$$

$$(a^x)' = \ln a \cdot a^x \qquad \text{(Exponential 1)}$$

$$(e^x)' = e^x \qquad \text{(Exponential 2)}$$

$$(e^{f(x)})' = e^{f(x)}f'(x) \qquad \text{(Exponential 3)}$$

$$(\ln(f(x)))' = \frac{f'(x)}{f(x)} \qquad \text{(Logarithmus 1)}$$

$$(\ln(x))' = \frac{1}{x} \qquad \text{(Logarithmus 2)}$$

2.3 Newton Verfahren (siehe 7.2)

2.4 Zweite Ableitung

$$x(t)'' = (x')' = \frac{d}{dt}\frac{d}{dt}(x) = \frac{d^2}{dt^2}x = \ddot{x} = x^{(2)}$$

2.5 Partielle Ableitung

$$\frac{\partial f}{\partial x} = \frac{\partial}{\partial x} f(x, y) = f_x =$$

$$= \lim_{h \to 0} \frac{f(x + h, y) - f(x, y)}{h}$$

$$\frac{\partial f}{\partial y} = \frac{\partial}{\partial y} f(x, y) = f_y =$$

$$= \lim_{h \to 0} \frac{f(x, y + h) - f(x, y)}{h}$$

$$\frac{\partial^2 f}{\partial x^2} = \frac{\partial^2}{\partial x^2} f = \frac{\partial}{\partial x} \frac{\partial}{\partial x} f = f_{xx}$$

$$\frac{\partial^2 f}{\partial y^2} = \frac{\partial^2}{\partial y^2} f = \frac{\partial}{\partial y} \frac{\partial}{\partial y} f = f_{yy}$$

$$\frac{\partial^2 f}{\partial x \partial y} = \frac{\partial^2}{\partial x \partial y} f = \frac{\partial}{\partial x} \frac{\partial}{\partial y} f = f_{xy}$$

2.6 Gradient

$$\nabla f = \operatorname{grad} f = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}\right)^{\mathsf{T}} f = \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}\right)^{\mathsf{T}}$$

2.7 Sätze zu Funktionen

Stetigkeit

$$f: D \to \mathbb{R}, \ D \subset \mathbb{R}, f \text{ ist stetig in } x_0$$
 $\iff \lim_{x \to x_0} f(x) = f(x_0)$

Zwischenwertsatz

$$f: [a, b] \to \mathbb{R}$$
 stetig
 $\land (f(a) < C < f(b) \lor f(a) > C > f(b))$
 $\Rightarrow \exists c \in [a, b[: f(c) = C]$

Satz von Rolle

$$f: [a,b] \to \mathbb{R}$$
 stetig
 \land in $]a,b[$ differenzierbar $\land f(a) = f(b)$
 $\Rightarrow \exists x_0 \in]a,b[:f'(x_0) = 0$

Mittelwertsatz der Differentialrechnung

$$f: [a, b] \to \mathbb{R}$$
 stetig
 \land in $]a, b[$ differentiates $\Rightarrow \exists x_0 \in]a, b[: f'(x_0) = \frac{f(b) - f(a)}{b - a}$

Monotonie

$$f: [a,b] \to \mathbb{R} \text{ stetig}$$

$$\land \text{ in }]a,b[\text{ differenzierbar} \to$$

$$\begin{cases} \forall x \in]a,b[:f'(x) \geq 0, & \text{monoton steigend} \\ \forall x \in]a,b[:f'(x) \leq 0, & \text{monoton fallend} \\ \forall x \in [a,b[:f'(x) = 0, & \text{konstant} \end{cases}$$

3 Integralrechnung

3.1 Definition

$$\lim_{n \to \infty, \Delta x_k \to 0} \sum_{k=0}^{n-1} f(\xi_k) \Delta_k = \int_a^b f(x) \ dx$$

3.2 Eigenschaften

$$a,b \in \mathbb{R} \land a < b \quad f,g : [a,b] \to \mathbb{R} \text{ integrierbar}$$

$$\text{für } f(x) \ge 0 : \int_a^b f(x) dx \ge 0$$

$$\text{für } f(x) \le 0 : \int_a^b f(x) dx \le 0$$

$$\text{für } f(x) \le g(x) : \int_a^b f(x) dx \le \int_a^b g(x) dx$$

$$\int_a^b f(x) dx + \int_b^c f(x) dx = \int_a^c f(x) dx$$

$$\int_a^a f(x) dx = 0$$

$$\int_a^b f(x) dx = -\int_b^a f(x) dx$$

3.3 Mittelwertsatz der Integralrechnung

$$f: [a, b] \to \mathbb{R} \text{ stetig} \Rightarrow \exists \ \xi \in [a, b] \text{ sodass}$$

$$\int_a^b f(x) dx = f(\xi)(b - a)$$

Mittelwert einer Funktion

$$\bar{f} = \frac{1}{b-a} \int_{a}^{b} f(x) dx$$

Quadratisches Mittel

$$\bar{f} = \sqrt{\frac{1}{b-a} \int_a^b (f(x))^2 dx}$$

3.4 Hauptsatz Different.-/Integralrechnung

$$f: [a, b] \to \mathbb{R} \text{ stetig } \land \lambda \in [a, b] \Rightarrow$$

$$F_{\lambda}(x) = \int_{\lambda}^{x} f(t)dt \qquad \text{(Stammfunktion von } f)$$

$$F'_{\lambda}(x) = f(x)$$

Bestimmtes Integral

$$\int_{a}^{b} f(x)dx = [F(x)]_{a}^{b} = F(x)|_{a}^{b} = F(b) - F(a)$$

Unbestimmtes Integral

$$\int f(x)dx = F(x) + C$$

3.5 Elementare Integrationsregeln

$$a,b,\lambda_1,k,C\in\mathbb{R} \qquad f,g: \ [a,b]\to\mathbb{R} \ \text{integrierbar}$$

$$\int_a^b (f(x)+g(x))dx=\int_a^b f(x)dx+\int_a^b g(x)dx$$

$$\int_a^b \lambda_1 f(x)dx=\lambda_1\int_a^b f(x)dx \qquad \text{(Linearität)}$$

$$\int kdx=kx+C \qquad \text{(Konstante)}$$

$$\int_a^b dx=\int_a^b 1\cdot dx=x\Big|_a^b=b-a \qquad \text{(Bereich)}$$

$$\int x^k dx=\frac{x^{k+1}}{k+1}+C \qquad \text{(Potenz)}$$

$$\int \sqrt{x} dx = \int x^{\frac{1}{2}} dx = \frac{x^{3/2}}{3/2} + C$$
 (Wurzel)

$$\int e^{kx} dx = \frac{1}{k} e^{kx} + C \tag{e}$$

$$\int \frac{1}{x} dx = \ln|x| + C \tag{Kehrwert}$$

$$\int \sin x dx = -\cos x + C \tag{Sinus}$$

$$\int \cos x dx = \sin x + C \tag{Cosinus}$$

$$\int \sinh x dx = \cosh x + C \qquad (Sinus Hyp.)$$

$$\int \cosh x dx = \sinh x + C \qquad (Cosinus Hyp.)$$

$$\int \ln x dx = x \ln x - x + C \tag{ln}$$

3.6 Partielle Integration

$$\int f'(x)g(x)dx = f(x)g(x) - \int f(x)g'(x)dx + C$$

3.7 Integration mit Substitution

$$\int_{a}^{b} f(g(t))g'(t)dt = \int_{g(a)}^{g(b)} f(x)dx = F(x)\Big|_{g(a)}^{g(b)}$$

3.8 Integration 2D

$$V = \iint_{D} f(x, y) dD = \int_{a_{2}}^{b_{2}} \int_{a_{1}}^{b_{1}} f(x, y) \ dxdy$$

Normalbereich

mit
$$D = \{(x,y) : a \le x \le b, g(x) \le y \le h(x)\}$$

$$\iint\limits_D f(x,y) dx dy = \int\limits_{x=a}^b \left(\int\limits_{y=g(x)}^{h(x)} f(x,y) dx\right) dy$$

3.9 Integration 3D

$$\iiint\limits_{\Omega} f(x,y,z)dxdydz = \int\limits_{a_3}^{b_3} \int\limits_{a_2}^{b_2} \int\limits_{a_1}^{b_1} f(x,y,z) \ dxdydz$$

Normalbereich

mit
$$\Omega = \{(x, y, z) : a_1 \le x_1 \le b_1,$$

 $a_2(x_1) \le x_2 \le b_2(x),$
 $a_3(x_1, x_2) \le x_3 \le b_3(x_1, x_2)\}$

$$\iiint\limits_{\Omega} f(x_1, x_2, x_3) dx_3 dx_2 dx_1 =$$

$$\int_{x_1=a_1}^{b_1} \int_{x_2=a_2(x_1)}^{b_2(x_1)} \int_{x_3=a_3(x_1,x_2)}^{b_3(x_1,x_2)} f(x_1,x_2,x_3) \ dx_3 dx_2 dx_1$$

3.10 Satz von Fubini

$$\int_{\Omega} f(\mathbf{x}) d\mathbf{x} = \int_{\Omega} f(x_1, \dots, x_n) dx_1 \dots dx_n =
\int_{I_n} (\dots (\int_{I_2} \dots (\int_{I_1} f(x_1, \dots, x_n) dx_1) dx_2) \dots dx_n =
\int_{I_1} (\dots (\int_{I_2} \dots (\int_{I_n} f(x_1, \dots, x_n) dx_n) dx_{n-1}) \dots dx_1$$

3.11 Uneigentliche Integrale

$$\lim_{b \to \infty} \int_a^b f(x) dx = \int_a^\infty f(x) dx \qquad \text{(unbegrenzt oben)}$$

$$\lim_{a \to -\infty} \int_a^b f(x) dx = \int_{-\infty}^b f(x) dx \qquad \text{(unbegrenzt unten)}$$

$$\lim_{c \to b} \int_a^c f(x) dx \qquad \text{(Grenzwert c } \to b)$$

4 Differentialgleichungen

4.1 GDGL

$$\begin{split} y^{(n)} &= f(x,y,y',y'',\dots,y^{(n-1)}) & \text{(explizit)} \\ F(x,y,y',y'',\dots,y^{(n)}) &= 0 & \text{(implizit)} \\ F(y,y',y'',\dots,y^{(n)}) &= g(x) = 0 & \text{(homogen)} \\ F(y,y',y'',\dots,y^{(n)}) &= g(x) \neq 0 & \text{(inhomogen)} \end{split}$$

 $Linearit \ddot{a}t$

$$a_n(.)y_{(n)} + a_{n-1}(.)y_{(n-1)} + \cdots + a_0(.)y + b(.) = 0$$

mit differenzierbaren Funktionen $a_i(.), b(.)$

Ordnung

$$y^{(n)} = f(x, y, y', y'', \dots, y^{(n-1)}) \rightarrow (n\text{-te Ordnung})$$

4.2 Elementar lösbare GDGL

$$y'(x) = a(x)y(x) + b(x)$$
 (expl. lin. 1. Ordn.)
 $y'(x) = a(x)y(x) + b(x)(y(x))^k$ (Bernoulli)
 $y'(x) = f(y(x)) \cdot g(x)$ (trennbare Variablen)
 $y'(x) = f(ax + by(x) + c)$ (Substitution)

4.3 Differentialoperatoren

Gradient (siehe 2.6)

Divergenz

$$\nabla \cdot \mathbf{v} = \operatorname{div} \mathbf{v} \stackrel{\text{(in 2D)}}{=} \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y} \right) \cdot \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \frac{\partial v_1}{\partial x} + \frac{\partial v_2}{\partial y}$$

Laplace

$$\Delta = \nabla \cdot \nabla = \nabla^2 \stackrel{\text{(in 2D)}}{=} \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}$$

4.4 PDGL 2. Ordnung

$$a \cdot u_{xx} + b \cdot u_{xy} + d \cdot u_x + e \cdot u_y + k \cdot u = g(x, y)$$

 $b^2 - 4ac > 0$ (hyperbolisch)
 $b^2 - 4ac = 0$ (parabolisch)
 $b^2 - 4ac < 0$ (elliptisch)

4.5 Numerische Integration

Explizites Eulerverfahren (siehe 7.6)

5 Weitere Analysis Themen

5.1 Kugelkoordinaten

$$x = r\cos\varphi\sin\theta, \quad y = r\sin\varphi\sin\theta, \quad z = r\cos\theta$$

 $r = \sqrt{x^2 + y^2 + z^2}, \quad \theta = \arccos\frac{z}{r}, \quad \varphi = \arctan\frac{y}{r}$

5.2 Rotationsmatrix

$$\mathbf{p}' = \begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \mathbf{R}(\theta)\mathbf{p}$$

5.3 Parametrische Abbildung

$$f(t_1, \dots, t_n) = (x_1(t_1, \dots, t_n), \dots, x_m(t_1, \dots, t_n))^{\mathsf{T}}$$

$$f(t) = (x(t), y(t))^{\mathsf{T}} \qquad (2D \text{ Kurve})$$

$$f(t) = (x(t), y(t), z(t))^{\mathsf{T}} \qquad (3D \text{ Kurve})$$

$$f(s, t) = (x(s, t), y(s, t), z(s, t))^{\mathsf{T}} \qquad (3D \text{ Fläche})$$

5.4 Tangentialvektor

$$\dot{\gamma}(\tau) = \left(\gamma_1'(\tau), \dots, \gamma_n'(\tau)\right)^{\mathsf{T}} \neq \emptyset$$

$$\mathbf{t}(\tau) = \frac{\dot{\gamma}(\tau)}{||\dot{\gamma}(\tau)||_2}$$

5.5 Bogenlänge einer Kurve

$$L = \int_{a}^{b} ||\dot{\gamma}(t)||_{2} dt = \int_{a}^{b} \left(\sum_{i=1}^{n} (\gamma_{1}'(t))^{2} \right)^{\frac{1}{2}}$$

Spezialfall \mathbb{R}^2

$$L = \int_{a}^{b} \sqrt{1 + (f'(t))^{2}} \quad \text{mit} \quad \gamma(t) = (t, f(t))^{\mathsf{T}}$$

5.6 Weitere Funktionen

$$\gamma(\theta) = \begin{pmatrix} a \cdot \theta \cdot \cos \theta \\ a \cdot \theta \cdot \sin \theta \end{pmatrix}$$
 (Archim. Spirale)
$$\gamma(\theta) = \begin{pmatrix} a \cdot \cos \theta \\ a \cdot \sin \theta \\ b \cdot \theta \end{pmatrix}$$
 (Helix)

5.7 Multivariate Extrema

Tangential hyperebene

$$g(\mathbf{x}_0 + \Delta \mathbf{x}) = f(\mathbf{x}_0) + \frac{\partial f}{\partial x_1}(\mathbf{x}_0) \Delta x_1 + \dots$$

$$\dots + \frac{\partial f}{\partial x_n}(\mathbf{x}_0) \Delta x_n$$
mit $\Delta x_i = x_i - x_{0,i}$ und $\Delta \mathbf{x} = (\Delta x_1, \dots, \Delta x_n)$

$$df = \sum_{i=1}^{n} \frac{\partial f}{\partial x_i} \Delta x_i \quad \text{(Totales Differential)}$$

 $Hessematrix \mathbf{H}_f$

$$\left(\frac{\partial^2 f}{\partial x_i \partial x_j}\right)_{i,j} = \begin{bmatrix}
\frac{\partial^2 f}{\partial x_1^2} & \frac{\partial^2 f}{\partial x_1 \partial x_2} & \cdots & \frac{\partial^2 f}{\partial x_1 \partial x_n} \\
\frac{\partial^2 f}{\partial x_2 \partial x_1} & \frac{\partial^2 f}{\partial x_2^2} & \cdots & \vdots \\
\vdots & \vdots & \ddots & \vdots \\
\frac{\partial^2 f}{\partial x_n \partial x_1} & \cdots & \frac{\partial^2 f}{\partial x_n^2}
\end{bmatrix}$$

5.8 Jakobi Matrix J_f

$$\left(\frac{\partial f_i}{\partial x_j}\right)_{i=1,\dots,m,j=1,\dots,n} = \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} & \cdots & \frac{\partial f_1}{\partial x_n} \\ \frac{\partial f_2}{\partial x_1} & \frac{\partial f_2}{\partial x_2} & \cdots & \vdots \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial f_m}{\partial x_1} & \cdots & \frac{\partial f_m}{\partial x_n} \end{bmatrix}$$

5.9 Jakobi Verfahren (multivariat)

$$\mathbf{x}_{n+1} = \mathbf{x}_n - \left(\mathbf{J}_f(\mathbf{x}_n)\right)^{-1} f(\mathbf{x}_n)$$

(Erinnerung)

5.10 Kettenregel

 $f,g:\mathbb{R}\to\mathbb{R}$

$$(f \circ g)' = f'(g(x)) \cdot g'(x)$$

$$\gamma : [a, b] \to \mathbb{R}^n, \ t \to (x_1(t), \dots, x_n(t))^\mathsf{T}, \ f : \mathbb{R}^n \to \mathbb{R},$$

$$\mathbf{x} = (x_1, \dots, x_n) \to f(x_1, \dots, x_n) = f(\mathbf{x})$$

$$\frac{d(f \circ g)}{dt}(\mathbf{x}(t)) = \frac{\partial f}{\partial x_1}(\mathbf{x}(t)) \frac{dx_1}{dt}(t) + \dots$$

$$+ \frac{\partial f}{\partial x_n}(\mathbf{x}(t)) \frac{dx_n}{dt}(t) = \nabla f \cdot \frac{d\mathbf{x}}{dt}$$

$$f\ddot{u}r \ n=1,2$$

$$\frac{df}{dt} = \frac{df}{dg}\frac{dg}{dt}, \qquad \frac{df}{dt} = \frac{df}{dx}\frac{dx}{dt} + \frac{df}{dy}\frac{dy}{dt}$$

5.11 Kurvenintegral 1. Art

$$\int_{a}^{b} f(\gamma(t)) ||\gamma'(t)||_{2} dt = \int_{C} f ds$$

5.12 Kurvenintegral 2. Art

$$\int_{a}^{b} \mathbf{f}(\mathbf{r}(t)) \cdot \mathbf{r}'(t) dt = \int_{C} \mathbf{f} \ d\mathbf{s}$$

6 Folgen und Reihen

6.1 Konvergenz

$$\lim_{n \to \infty} a_n = a \iff \forall \varepsilon > 0 \; \exists \; n_0 \in \mathbb{N} \; \forall n > n_0 :$$
$$|a_n - a| < \varepsilon$$

Geometrische Reihe

$$\lim_{m \to \infty} \sum_{k=0}^{m-1} q^k = \lim_{m \to \infty} \frac{1 - q^m}{1 - q} = \frac{1}{1 - q}$$

Quotientenkriterium

$$\lim_{n \to \infty} \left| \frac{a_{n+1}}{a_n} \right| \begin{cases} < 1 & \text{konvergent} \\ > 1 & \text{divergent} \end{cases}$$

6.2 Gamma Funktion

$$\Gamma(x) = \int_0^\infty t^{x-1} e^{-t} dt, \quad x > 0$$

6.3 Binomischer Lehrsatz

$$(x+y)^n = \sum_{k=0}^n \binom{n}{k} x^{n-k} y^k$$
$$\binom{n}{k} = \frac{n!}{k!(n-k!)}$$

6.4 Exponentialfunktion

$$\lim_{n \to \infty} \left(1 + \frac{x}{n} \right)^n = e^x$$

6.5 Potenzreihe

$$\sum_{k=0}^{\infty} c_k (x-a)^k = c_0 + c_1 (x-a) + c_2 (x-a)^2 + \dots$$

6.6 Taylorreihe

$$f(x) = \sum_{k=0}^{\infty} \frac{f^{(k)}(x_0)}{k!} (x - x_0)^k$$

$$T_{f,n}(x) = T_{f,n}(x_0 + h) = \sum_{k=0}^{n} \frac{f^{(k)}(x_0)}{k!} (h)^k$$

$$= f(x_0) + hf'(x_0) + \frac{h^2}{2} f''(x_0) + \dots$$

6.7 Fourierreihe

$$f(x) = \frac{a_0}{2} + \sum_{k=1}^{\infty} (a_k \cos(kx) + b_x \sin(kx))$$
$$a_k = \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) \cos(kx) dx, \quad k \ge 0$$
$$b_k = \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) \sin(kx) dx, \quad k \ge 1$$

7 Numerik

7.1 Maschinengenauigkeit

$$\xi = m \cdot 2^e \in \mathbb{R}, \ 0 \le m < 1, \ x_{\rm li} < \xi < x_{\rm re}$$
mit $x_{\rm li}, x_{\rm re} \dots$ nächste normalisierte Maschinenzahlen mit k Bit Mantisse

$$\frac{\Delta \xi}{\xi} \leq \frac{2^{e-k-1}}{m \cdot 2^e} = \frac{1}{2} 2^{-k} = \varepsilon$$

7.2 Newton Verfahren

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$$

7.3 Konvergenzgeschwindigkeit

$$|x_{k+1} - x^*| \le c|x_k - x^*|^p$$

7.4 Finite Differenzen

f' Vorwärts

$$f'(x_0) = \frac{f(x_0 + h) - f(x_0)}{h} + O(h)$$

f' Rückwärts

$$f'(x_0) = \frac{f(x_0) - f(x_0 - h)}{h} + O(h)$$

f' Zentral

$$f'(x_0) = \frac{f(x_0 + h) - f(x_0 - h)}{2h} + O(h^2)$$

f" Zentral

$$f''(x_0) = \frac{f(x_0 + h) - 2f(x_0) + f(x_0 - h)}{h^2} + O(h^2)$$

Multivariat, $f: \mathbb{R}^2 \to \mathbb{R}$

$$f_{x}(x,y) \approx \left(f(x+h_{x},y) - f(x,y) \right) / h_{x}$$

$$f_{y}(x,y) \approx \left(f(x,y+h_{y}) - f(x,y) \right) / h_{y}$$

$$f_{xx}(x,y) \approx \frac{f(x+h_{x},y) - 2f(x,y) + f(x-h_{x},y)}{h_{x}^{2}}$$

$$f_{yy}(x,y) \approx \frac{f(x,y+h_{y}) - 2f(x,y) + f(x,y-h_{y})}{h_{y}^{2}}$$

$$f_{xy}(x,y) \approx \left[f(x+h_{x},y+h_{y}) - f(x+h_{x},y-h_{y}) - f(x-h_{x},y+h_{y}) + f(x-h_{x},y-h_{y}) \right]$$

$$\cdot \frac{1}{4h_{x}h_{y}}$$

7.5 Quadratur

$$I \approx Q_n[f] = \sum_{i=0}^{n} w_i f(x_i)$$

Untersumme

$$Q_n[f] = \frac{b-a}{n} \sum_{k=0}^{n-1} f(x_k)$$

Trapezregel

$$Q_n[f] = \frac{b-a}{n} \sum_{k=0}^{n-1} \frac{f(x_k) + f(x_{k+1})}{2}$$

Simpsonregel

$$\frac{b-a}{n\cdot 6} \left(f(x_0) + f(x_n) + 4\sum_{k=0}^{n-1} \frac{f(x_k) + f(x_{k+1})}{2} + 2\sum_{k=0}^{n-2} f(x_{k+1}) \right)$$

7.6 Explizites Eulerverfahren

$$y_{n+1} = y_n + h \cdot f(t_n, y_n)$$
, mit $f(t_n, y_n) = y'_n$

8 Lösen linearer Gleichungssys.

8.1 LU Zerlegung

$$\mathbf{L}_{(0)}[j] = \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & \ddots & & & \\ & & 1 & \vdots \\ \vdots & & l_{j+1,j} & & \\ & & \vdots & \ddots & 0 \\ 0 & & l_{n,j} & 0 & 1 \end{bmatrix}, \quad l_{i,j} = -\frac{a_{ij}}{a_{jj}}$$

$$\begin{aligned} \mathbf{A} &= \mathbf{L}_{(0)}^{-1} \mathbf{L}_{(0)} \mathbf{A} = \mathbf{L}_{(0)}^{-1} \mathbf{A}_{(1)} = \mathbf{L}_{(0)}^{-1} \mathbf{L}_{(1)}^{-1} \mathbf{L}_{(1)} \mathbf{A}_{(1)} \\ &= \mathbf{L}_{(0)}^{-1} \mathbf{L}_{(1)}^{-1} \mathbf{A}_{(2)} = \dots = \mathbf{L}_{(0)}^{-1} \mathbf{L}_{(1)}^{-1} \dots \mathbf{L}_{(n-2)}^{-1} \mathbf{A}_{(n-1)} \\ &= \mathbf{L} \cdot \mathbf{U} \end{aligned}$$

8.2 Cholesky Zerlegung

$$\mathbf{A} = \mathbf{L} \ \mathbf{L}^\mathsf{T}$$

$$l_{jj} = \pm \sqrt{a_{jj} - \sum_{k=1}^{j-1} l_{jk}^2}, \ l_{ij} = \frac{1}{l_{jj}} \left(a_{ij} - \sum_{k=1}^{j-1} l_{ik} \ l_{jk} \right)$$

8.3 Jacobi Verfahren

$$x_i^{(k+1)} = \frac{1}{a_{ii}} \left(b_i - \sum_{j=1, j \neq i}^n a_{ij} \ x_j^{(k)} \right)$$

8.4 Gauß-Seidel-Verfahren

$$x_i^{(k+1)} = \frac{1}{a_{ii}} \left(b_i - \sum_{j=1}^{i-1} a_{ij} \ x_j^{(k+1)} - \sum_{j=i+1}^{n} a_{ij} \ x_j^{(k)} \right)$$

8.5 SOR-Verfahren

$$x_{i \text{ (sor)}}^{(k+1)} = (1 - \omega) x_{i}^{(k)} + \omega x_{i \text{ (gauß)}}^{(k+1)}$$

8.6 Verfahren des steilsten Abstiegs

$$\mathbf{x}^{(k+1)} = \mathbf{x}^{(k)} - \alpha^{(k)} \nabla f(\mathbf{x}^{(k)})$$
$$-\nabla f(\mathbf{x}^{(k)}) = \mathbf{b} - \mathbf{A}\mathbf{x}^{(k)} = \mathbf{r}^{(k)}$$
$$\alpha^{(k)} = \frac{(\mathbf{r}^{(k)})^{\mathsf{T}} \mathbf{r}^{(k)}}{(\mathbf{r}^{(k)})^{\mathsf{T}} \mathbf{A}^{\mathsf{T}} \mathbf{r}^{(k)}}$$

9 Interpolation

9.1 Vandermonde-Matrix

$$\begin{bmatrix} 1 & x_0 & x_0^2 & \dots & x_0^n \\ 1 & x_1 & x_1^2 & \dots & x_1^n \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_n & x_n^2 & \dots & x_n^n \end{bmatrix} \cdot \begin{bmatrix} a_0 \\ a_1 \\ \vdots \\ a_n \end{bmatrix} = \begin{bmatrix} y_0 \\ y_1 \\ \vdots \\ y_n \end{bmatrix}$$

9.2 Lagrange Polynom

$$\ell_i^{[n]} = \prod_{j=0, j \neq i}^{n} \frac{x - x_j}{x_i - x_j}$$
$$p(x) = \sum_{i=0}^{n} y_i \cdot \ell_i^{[n]}(x)$$

9.3 Spline

$$f(x) \approx \sum_{i} f(x_i) \cdot N_i(x)$$
$$N_i(x_i) = 1$$
$$N_i(x_{i \neq i}) = 0$$

9.4 Bilinear

$$f(x,y) = \begin{bmatrix} 1-x \\ x \end{bmatrix}^{\mathsf{T}} \begin{bmatrix} f_{00} & f_{01} \\ f_{10} & f_{11} \end{bmatrix} \begin{bmatrix} 1-y \\ y \end{bmatrix}^{\mathsf{T}}$$

9.5 Normalisierte baryzentrische Koordinaten

$$\mathbf{q} = \lambda_0 \mathbf{p}_0 + \lambda_1 \mathbf{p}_1 + \dots + \lambda_{n-1} \mathbf{p}_{n-1}$$

$$\sum_{i=0}^{n-1} \lambda_i = 1$$

9.6 Polynomapproximation

$$y_{i} = a_{0} + a_{1}x_{i} + a_{2}x_{i}^{2} + \dots + a_{n}x_{i}^{n} \quad \text{(Polynom)}$$

$$\begin{bmatrix} 1 & x_{0} & x_{0}^{2} & \dots & x_{0}^{n} \\ 1 & x_{1} & x_{1}^{2} & \dots & x_{1}^{n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_{m} & x_{m}^{2} & \dots & x_{m}^{n} \end{bmatrix} \cdot \begin{bmatrix} a_{0} \\ a_{1} \\ \vdots \\ a_{n} \end{bmatrix} = \begin{bmatrix} y_{0} \\ y_{1} \\ \vdots \\ y_{m} \end{bmatrix}$$

$$\mathbf{a} = (\mathbf{A}^{\mathsf{T}} \mathbf{A})^{-1} \mathbf{A}^{\mathsf{T}} \mathbf{y}$$

Annahme Grad n=2

$$a_1 = \frac{\sum_{i=0}^{m} (x_i - \bar{x})(y_i - \bar{y})}{\sum_{i=0}^{m} (x_i - \bar{x})}, \quad a_0 = \bar{y} - c_1 \bar{x}$$

10 Zufallszahlen

10.1 Monte Carlo Integration

$$\int_0^1 f(x)dx \approx \frac{1}{N} \sum_{i=1}^N f(\xi_i) \quad \text{mit} \quad \xi_i \in [0, 1]$$

10.2 Linearer Kongruenzgenerator

$$z_{i+1} = (a \cdot z_i + d) \mod m$$

10.3 van-der-Corput Sequenz

$$g_b(n) = \sum_{k=0}^{L-1} d_k(n) b^{-(1+k)}$$

10.4 Wahrscheinlichkeit innerhalb Intervall

$$P(a \le X \le b) = \int_{a}^{b} p(x)dx$$
$$\int_{-\infty}^{\infty} p(x)dx = 1$$

10.5 Kumulierte Wahrscheinlichkeitsdichtef.

$$P(X) = \int_{-\infty}^{X} p(x)dx$$

$$P(X,Y) = \int_{-\infty}^{Y} \int_{-\infty}^{X} p(x,y)dxdy$$

Randdichten

$$p(x) = \int p(x,y)dy$$
$$p(y) = \int p(x,y)dx$$

Bedingte WDF

$$p(y|x) = \frac{p(x,y)}{p(x)}$$

11 Komplexe Zahlen

$$z = a + ib$$
 (kartesisch)
 $i^2 = -1$
 $i = \sqrt{-1}$ (imaginäre Einheit)

11.1 Operationen kartesisch

Addition / Multiplikation

$$(a+ib) + (c+id) = ((a+c) + i(b+d))$$

 $(a+ib) \cdot (c+id) = ((ac-bd) + i(ad+bc))$

Division

$$|z| = \sqrt{a^2 + b^2}$$
 (Betrag)

$$\bar{z} = a - ib$$
 (konjugiert Komplex)

$$z = \frac{z_1}{z_2} = \frac{z_1}{z_2} \cdot \frac{\bar{z}_1}{\bar{z}_2} = \frac{z_1 \cdot \bar{z}_2}{|z_2|^2}$$

11.2 Euler'sche Formel

$$e^{ix} = \cos x + i \sin x$$

$$z = r \cdot e^{i\varphi}$$

$$e^{z} = e^{a+ib} = e^{a}(\cos b + i \sin b)$$

Multiplikation

$$z = z_1 \cdot z_2 = r_1 \cdot r_2 \cdot e^{i(\varphi_1 + \varphi_2)}$$

Trigonometrischer Zusammenhang

$$\cos x = \operatorname{Re}(e^{ix}) = \frac{e^{ix} + e^{-ix}}{2}$$
$$\sin x = \operatorname{Im}(e^{ix}) = \frac{e^{ix} - e^{-ix}}{2i}$$

11.3 Fourier Transformation

$$F(u) = \int_{-\infty}^{\infty} f(x)e^{-i2\pi u \cdot x} dx$$
$$= \int_{-\infty}^{\infty} f(x)(\cos(2\pi u \cdot x) - i\sin(2\pi u \cdot x)) dx$$
$$f(x) = \int_{-\infty}^{\infty} F(u)e^{i2\pi x \cdot u} du$$

Diskret

$$X_k = \sum_{n=0}^{N-1} x_n \cdot e^{-i\frac{2\pi}{N}kn}$$
$$= \sum_{n=0}^{N-1} x_n \cdot \left(\cos(\frac{2\pi}{N}kn) - i\sin(\frac{2\pi}{N}kn)\right)$$