

# Deep neural network for high-contrast imaging

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**INFO8010**

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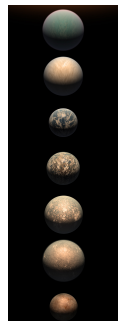
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# Introduction

## Motivation for HCI

### Exoplanets detection via High Contrast Imaging (HCI)

- Most of current identified exoplanets detected via **indirect techniques**
- Indirect techniques very effective within the first AU
- HCI allowing detections for **larger separation** for both "face-on" and "edge-on" systems
- Spectroscopy and HCI giving deeper insights into **exoplanets characteristics**



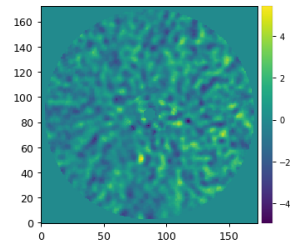
Credits: Nasa

# Introduction

## HCI Main pillars

### HCI five pillars

- Large telescopes  $\Rightarrow$  **Resolution**
- Advanced adaptive optics systems  $\Rightarrow$  **Resolution**
- Coronagraphs  $\Rightarrow$  **Contrast**
- Observing strategies  $\Rightarrow$  **Speckles**
- Post processing techniques  $\Rightarrow$  **Speckles + Contrast**



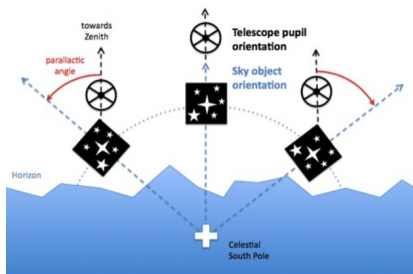
ER51 APCA SNR map

# State of the art

## Observing Strategy

Angular Differential Imaging (Marois, 2006) representing the main observing strategy for HCI

- Set of images taken in **pupil tracking mode**
- Instrument **centred** on given star
- Potential exoplanets **rotating** while stellar diffraction pattern remains **fixed**
- Most of **quasi-static speckles** removed by subtracting the **median** from each frame



Somboonpanyakul and Tamura, 2014

# State of the art

## HCI post-processing techniques

Most recent HCI post-processing techniques relying on **low rank approximation** (PCA/KLIP, Annular PCA, NMF, LLSG)

⇒ **Creation** and **subtraction** of **noise map** to retrieve the planetary signal



Gomez Gonzalez et al., 2016

# State of the art

## HCI post-processing techniques

Procedure steps:

- Estimation of a **reference point spread function** regrouping the instrument noise and star light via low rank approximation
- **Subtraction** of the reference point spread function from the set of images
- **Alignment** of the resulting set of residual images
- Estimation of final frame by **mean-combining** the set of aligned images
- Planetary candidates selection via **signal to noise ratio** thresholding

# State of the art

## Machine learning based post-processing technique

Reformulating the exoplanet detection task as a supervised binary classification problem (Gomez Gonzalez et al. (2018))

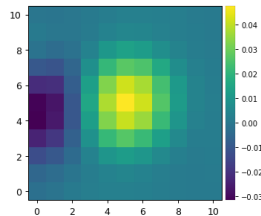
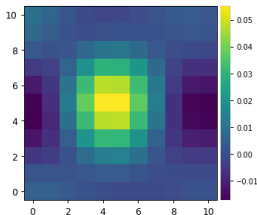
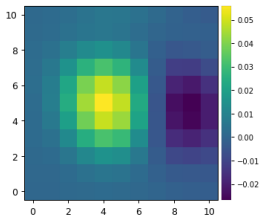
- Estimation of Multi-level Low-rank Approximation Residual (MLAR)
  - Estimation of a **reference point spread function** for several low rank values
  - **Subtraction** of the reference point spread function from the set of images
  - **Alignment** of the resulting set of residual images
  - **Mean-combining** along the temporal axis
  - Patches creation via **cropping** (3D cubes centered on every pixels of the frame)
- Deep neural network to **classify** the resulting patches

# Model

## Time dependent model

Project main objectives:

- **Adapt** the approach of Gomez Gonzales et al. to take into account the **time structure** of the ADI sequence
- Test **other architectures** of deep neural network
- Use **ROC curves** to compare the performance of the algorithms





# Model

## Time dependent model

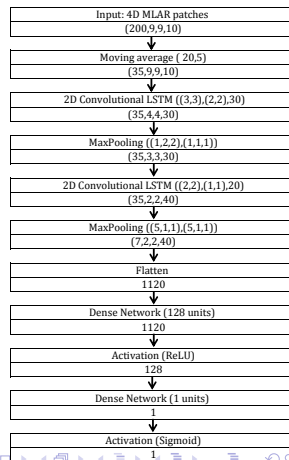
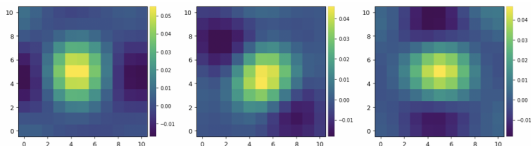
Take into account the time structure of the ADI sequence

- Estimation of Multi-level Low-rank Approximation Residual (MLAR)
  - Estimation of a **reference point spread function** for several low rank values
  - **Subtraction** of the reference point spread function from the set of images
  - **Alignment** of the resulting set of residual images
  - ~~mean-combining along the temporal axis~~
  - Patches creation via **cropping** (4D cubes centered on every pixels of the frame)
  - Estimation of moving averages to reduce the **noise level** and **size of the 4D patches**
- Deep neural network to **classify** the resulting patches

# Model Architecture

Deep neural network architecture based on:

- 2D convolutional LSTMs
- Maxpooling layers
- Dense layers



# Model

## Training and learning samples

Estimation of positive and negative classes done **annulus-wise**:

- Positive class  $C^+$ :
  - Positive MLAR patches obtained by **injecting fake companions**
  - Flux values for the **learning sample** → companions with a SNR between 3 and 5
  - Flux values for the **test sample** → companions with a SNR between 1 and 3
- Negative class  $C^-$ :
  - Exploit the rotation associated with ADI techniques → **flip the sign** of the parallactic angles
  - Sample **mixing**, **rotations** and **shifts** to create more samples

# Results

## Datasets

Selected pre-processed datasets:

- VLT NACO: Beta pictoris (ADI sequence containing 204 frames, integration time of 8 s, field rotation of 83 degrees)
- VLT SPHERE: ERI 51 (ADI sequence containing 197 frames, integration time of 4 s, field rotation of 49.3 degrees)

⇒ Optimal architecture selection based on **loss function value**

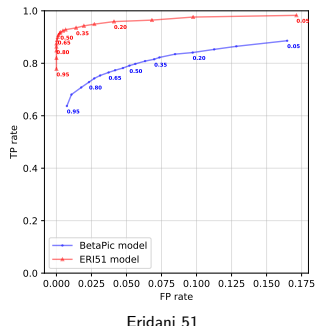
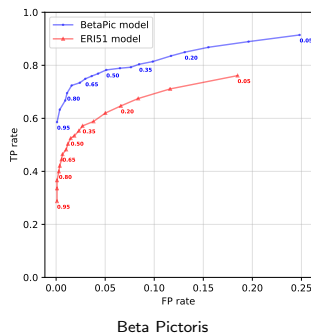
⇒ Datasets considered **separately** and **jointly**

⇒ **Performance comparison** with the SODINN based on ROC curves

# Results

## ROC curves

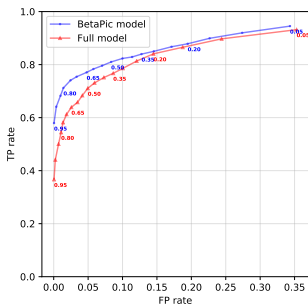
ROC curve for separate models:



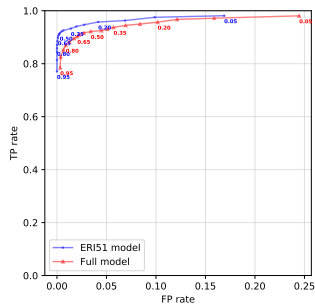
# Results

## ROC curves

ROC curve for joint model:



Beta Pictoris

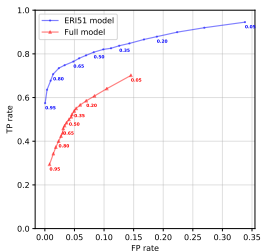


Eridani 51

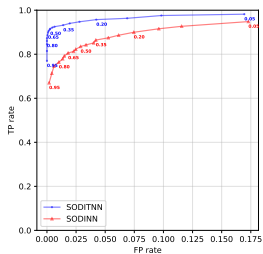
# Results

## ROC curves

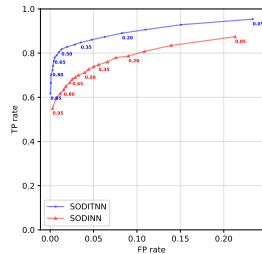
### Comparison with SODINN:



Beta Pictoris



Eridani 51



Beta Pictoris + Eridani 51

# Conclusion

## Exoplanets detection via deep learning methods

- New deep neural network architecture using the **temporal structure** of ADI sequences
- **Several architectures** tested on ADI datasets
- Model parametrization using the **ERI 51** and **Beta Pictoris** datasets separately or jointly
- **Background noise structures** leading to differentiate models
- **Full model** providing results close to the **dedicated ones**
- All three considered models **performing better** than SODINN