

# Lab Assignment 2

## Problem Statement

Write a Python program to simulate different **Linear** and **Non-Linear filters** on a given image. The program should read an input image and apply various types of filters to enhance, smooth, or process the image. Finally, visualize the results for comparison.

## Hints and Guidelines

### Tools to Use:

1. **OpenCV:** For reading images, applying filters, and image processing.
2. **NumPy:** For creating kernels and handling numerical computations.
3. **Matplotlib:** For visualizing the original and filtered images.

### Steps to Approach the Problem:

#### 1. Load the Image:

- Use `cv2.imread` to read the image in BGR format.
- Convert the image to RGB format for better visualization with Matplotlib using `cv2.cvtColor`.

#### 2. Implement Filters:

- Define functions to apply **linear** and **non-linear filters**.
- **Linear Filters:**
  - Create a kernel (e.g., a 5x5 averaging filter) using NumPy.
  - Use `cv2.filter2D` to apply the kernel.
- **Non-Linear Filters:**
  - Use built-in OpenCV functions like:
    - `cv2.GaussianBlur` for Gaussian filtering.
    - `cv2.medianBlur` for Median filtering.
    - `cv2.bilateralFilter` for Bilateral filtering.
    - `cv2.erode` and `cv2.dilate` for Min and Max filtering.

#### 3. Visualize Results:

- Use Matplotlib's `plt.subplots` to create a grid for displaying images side by side.
- Use `axs[i].imshow` to display each filtered image with a title indicating the filter applied.

#### 4. Compare and Analyze:

- Observe how different filters affect the input image (e.g., smoothness, sharpness, noise removal).

## Pseudo Code:

- plaintext
1. Import required libraries (cv2, numpy, matplotlib).
  2. Define a function to apply linear filters:
    - Use `cv2.filter2D` with a custom kernel.
  3. Define a function to apply non-linear filters:
    - Use OpenCV functions for median, Gaussian, bilateral, min, and max filters.
  4. Read an image using `cv2.imread`.
  5. Display the original image.
  6. Apply the linear and non-linear filters using the defined functions.
  7. Visualize the original and filtered images using Matplotlib.

```
In [1]: # Download assignment files
!wget https://github.com/buntyke/vnr_dlc2024_labs/releases/download/DLCVLab2/virat-kohli.jpg

--2024-12-08 06:56:08-- https://github.com/buntyke/vnr_dlc2024_labs/releases/download/DLCVLab2/virat-kohli.jpg
Resolving github.com (github.com)... 20.27.177.113
Connecting to github.com (github.com)|20.27.177.113|:443... connected.
HTTP request sent, awaiting response... 302 Found
Location: https://objects.githubusercontent.com/github-production-release-asset-2e65be/878811324/f8e3cc53-6cc8-446d-b1ce-2e161a17cd76?X-Amz-Algorithm=AWS4-HMAC-SHA256&X-Amz-Credential=releaseassetproduction%2F20241208%2Fus-east-1%2Fs3%2Faws4_request&X-Amz-Date=20241208T065609Z&X-Amz-Expires=300&X-Amz-Signature=3f99bbee0a7369ca617795f05c3262b83fcc6ee8cd37b8f954957aa218c3299b&X-Amz-SignedHeaders=host&response-content-disposition=attachment%3B%20filename%3Dvirat-kohli.jpg&response-content-type=application%2Foctet-stream [following]
--2024-12-08 06:56:09-- https://objects.githubusercontent.com/github-production-release-asset-2e65be/878811324/f8e3cc53-6cc8-446d-b1ce-2e161a17cd76?X-Amz-Algorithm=AWS4-HMAC-SHA256&X-Amz-Credential=releaseassetproduction%2F20241208%2Fus-east-1%2Fs3%2Faws4_request&X-Amz-Date=20241208T065609Z&X-Amz-Expires=300&X-Amz-Signature=3f99bbee0a7369ca617795f05c3262b83fcc6ee8cd37b8f954957aa218c3299b&X-Amz-SignedHeaders=host&response-content-disposition=attachment%3B%20filename%3Dvirat-kohli.jpg&response-content-type=application%2Foctet-stream
Resolving objects.githubusercontent.com (objects.githubusercontent.com)... 185.199.108.133, 185.199.109.133, 185.199.110.133, ...
Connecting to objects.githubusercontent.com (objects.githubusercontent.com)|185.199.108.133|:443... connected.
HTTP request sent, awaiting response... 200 OK
Length: 243387 (238K) [application/octet-stream]
Saving to: 'virat-kohli.jpg'

virat-kohli.jpg      100%[=====>] 237.68K  1.42MB/s   in 0.2s

2024-12-08 06:56:10 (1.42 MB/s) - 'virat-kohli.jpg' saved [243387/243387]
```

```
In [2]: ### WRITE CODE HERE ###
import cv2
import numpy as np
from matplotlib import pyplot as plt

def apply_linear_filter(image, kernel):
    filtered_image = cv2.filter2D(image, -1, kernel)
    return filtered_image

def apply_nonlinear_filter(image, filter_type):
    if filter_type == "median":
        filtered_image = cv2.medianBlur(image, 5)
```

```

elif filter_type == "gaussian":
    filtered_image = cv2.GaussianBlur(image, (5, 5), 0)
elif filter_type == "bilateral":
    filtered_image = cv2.bilateralFilter(image,15,75,75)
elif filter_type == "min":
    filtered_image = cv2.erode(image,
                               cv2.getStructuringElement(cv2.MORPH_RECT, (5,5)))
elif filter_type == "max":
    filtered_image = cv2.dilate(image,
                                cv2.getStructuringElement(cv2.MORPH_RECT, (5,5)))
else:
    raise ValueError("Invalid non-linear filter type.")
return filtered_image

image_path = "./virat-kohli.jpg"
image = cv2.imread(image_path)

fig, axs = plt.subplots(1,3,figsize=(10,5))

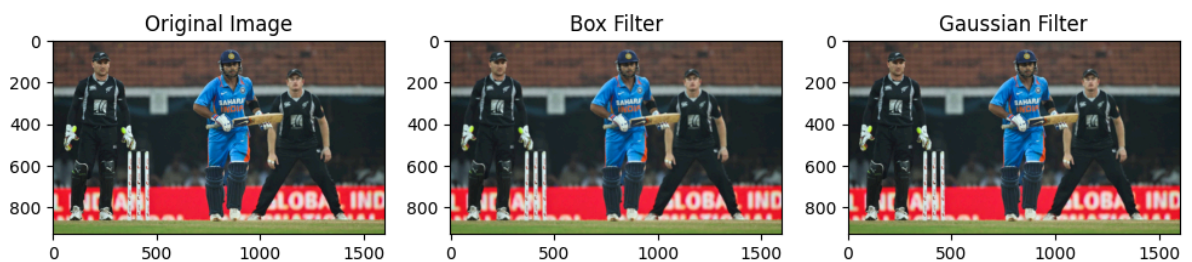
# Display the original image
axs[0].imshow(cv2.cvtColor(image, cv2.COLOR_BGR2RGB))
axs[0].set_title("Original Image")

# Box Filter 5X5
kernel = np.ones((5, 5), np.float32) / 25
linear_filtered_image = apply_linear_filter(image, kernel)
axs[1].imshow(cv2.cvtColor(linear_filtered_image, cv2.COLOR_BGR2RGB))
axs[1].set_title("Box Filter")

# Gaussian Filter
gaussian_filtered_image = apply_nonlinear_filter(image, "gaussian")
axs[2].imshow(cv2.cvtColor(gaussian_filtered_image, cv2.COLOR_BGR2RGB))
axs[2].set_title("Gaussian Filter")

plt.tight_layout()
plt.show()

```



```

In [3]: fig, axs = plt.subplots(2,3,figsize=(10,10))

# Display the original image
axs[0,0].imshow(cv2.cvtColor(image, cv2.COLOR_BGR2RGB))
axs[0,0].set_title("Original Image")

# Min Filter 5 x 5
min_filtered_image = apply_nonlinear_filter(image, "min")
axs[0,1].imshow(cv2.cvtColor(min_filtered_image, cv2.COLOR_BGR2RGB))
axs[0,1].set_title("Min Filter")

# Max Filter 5 x 5
max_filtered_image = apply_nonlinear_filter(image, "max")
axs[0,2].imshow(cv2.cvtColor(max_filtered_image, cv2.COLOR_BGR2RGB))
axs[0,2].set_title("Max Filter")

# Median Filter 5 x 5
median_filtered_image = apply_nonlinear_filter(image, "median")

```

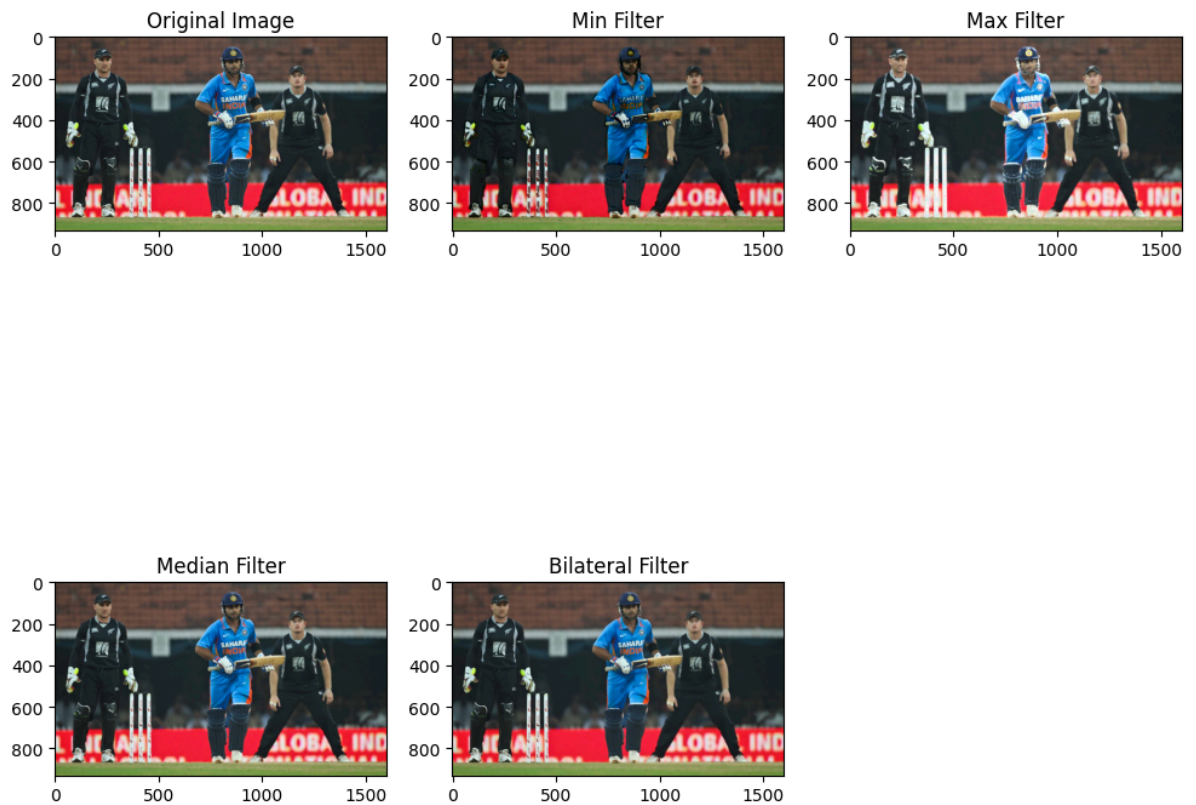
```

axs[1,0].imshow(cv2.cvtColor(median_filtered_image, cv2.COLOR_BGR2RGB))
axs[1,0].set_title("Median Filter")

# Bilateral Filter
bil_filtered_image = apply_nonlinear_filter(image, "bilateral")
axs[1,1].imshow(cv2.cvtColor(bil_filtered_image, cv2.COLOR_BGR2RGB))
axs[1,1].set_title("Bilateral Filter")

axs[1,2].axis('off')
plt.tight_layout()
plt.show()

```



In [ ]: