

COMPUTER SCIENCE AND ENGINEERING

Indian Institute of Technology, Palakkad

CS5016: Computational Methods and Applications

 $\frac{Coding~Assignment~6}{Ordinary~Differential~Equations}$

07 Apr, 2021

Max points: 100

A few instructions

- Codes should be compatible with *Python3* and should run on Ubuntu.
- Code for each question should be placed in a separate stand-alone files.
- Codes should be well-commented.
- Appropriate exceptions should be raised and handled.
- 1. Write a function that uses the forward Euler method to solve the ODE x'(t) = -2x(t), with initial condition x(0) = 5, in the interval [0, 10], computes a polynomial that passes through the discrete solution points of the ODE. Visualize the solution for discretization step sizes $\{0.1, 0.5, 1, 2, 3\}$ along with the exact solution, all on the same figure.

[10]

2. Write a function that uses the backward Euler method to solve the ODE x'(t) = -2x(t), with initial condition x(0) = 5, in the interval [0, 10], computes a polynomial that passes through the discrete solution points of the ODE. Visualize the solution for discretization step sizes $\{0.1, 0.5, 1, 2, 3\}$ along with the exact solution, all on the same figure.

[10]

3. A simple gravity pendulum is an idealized mathematical model of a real pendulum. It has a weight (or bob) on the end of a massless cord suspended from a pivot, without friction¹. The ODE which represents the motion of a simple pendulum is

$$\frac{d^2(\theta(t))}{dt^2} + \frac{g}{L}\sin\theta(t) = 0$$

where g is acceleration due to gravity, L is the length of the pendulum, and θ is the angular displacement. Use the forward Euler method to estimate the pendulum's position. You are also expected to animate motion of the pendulum using Python's matplotlib library.

[30]

4. Since its introduction in the 1920's, the *Van der Pol equation*² has been a prototype for systems with self-excited limit cycle oscillations. This equation is now considered as a basic model for oscillatory processes in physics, electronics, biology, neurology, sociology and economic. The equation is described by the following second order ODE:

$$\frac{d^2x(t)}{dt^2} - \mu(1 - x(t)^2)\frac{dx(t)}{dt} + x(t) = 0$$

¹https://en.wikipedia.org/wiki/Pendulum_(mathematics)

²https://en.wikipedia.org/wiki/Van_der_Pol_oscillator

It is known that solution of the above equation is periodic when $\mu > 0$. Write a function that takes the parameter μ (a positive real number) and initial condition as arguments, and computes the period T of the solution. Your code is also expected to plot the solution.

[30]

HINT: Use the function scipy.integrate.solve_ivp.

5. In physics and classical mechanics, the three-body problem involves taking the initial positions and velocities (or momenta) of three point masses and solving for their subsequent motion according to Newton's laws of motion and Newton's law of universal gravitation. Unlike two-body problems, no general closed-form solution exists for this problem, and numerical methods are generally required³.

Consider 3 bodies of mass 1/G (where G is the gravitational constant) that are placed in the x-y plane with initial vector position $\mathbf{r}_i(0) = (x_{0,i}, y_{0,i})$ for $i \in \{1, 2, 3\}$ and zero initial velocity. Let $\mathbf{r}_i(t)$ denote the position vector of the i^{th} body at time t. Then, the bodies are governed by the following system of ODEs

$$\ddot{r}_{1}(t) = \frac{r_{2}(t) - r_{1}(t)}{\|r_{2}(t) - r_{1}(t)\|^{3}} + \frac{r_{3}(t) - r_{1}(t)}{\|r_{3}(t) - r_{1}(t)\|^{3}}$$

$$\ddot{r}_{2}(t) = \frac{r_{1}(t) - r_{2}(t)}{\|r_{1}(t) - r_{2}(t)\|^{3}} + \frac{r_{3}(t) - r_{2}(t)}{\|r_{3}(t) - r_{2}(t)\|^{3}}$$

$$\ddot{r}_{3}(t) = \frac{r_{1}(t) - r_{3}(t)}{\|r_{1}(t) - r_{3}(t)\|^{3}} + \frac{r_{2}(t) - r_{3}(t)}{\|r_{2}(t) - r_{3}(t)\|^{3}}$$

Write a function that takes the initial position of the 3 bodies as its argument, and visualizes their trajectories with help of Python's scipy.integrate and matplotlib libraries.

[20]

 $^{^3}$ https://en.wikipedia.org/wiki/Three-body_problem