

# BUDAPESTI UNIVERSITY OF TECHNOLOGY AND ECONOMICS

INSTITUTE OF MATHEMATICS

FACULTY OF MATHEMATICS

---

## Linear Regression through Origin

---

*Author:*

Dyussenov Nuraly

*Supervisor:*

Dr. Jozsef Mala

Associate Professor, BME Fac. of Nat. Sci.

Budapest, October 23, 2023



M Ű E G Y E T E M 1 7 8 2

# Contents

<b>1</b>	<b>Introduction</b>	<b>1</b>
<b>2</b>	<b>Theoretical background</b>	<b>2</b>
2.1	Statistics Basics . . . . .	2
2.2	Simple Linear Regression . . . . .	4
2.3	Simple Linear Regression with no intercept term . . . . .	5
2.4	Comparative Analysis . . . . .	6
<b>3</b>	<b>Applications to Linear Regression through Origin</b>	<b>7</b>
3.1	Something to add 1 . . . . .	8
3.2	Something to add 1 . . . . .	8
<b>4</b>	<b>Theoretical results</b>	<b>9</b>
4.1	A theoretical resilt . . . . .	9
4.2	Towards some advanced topic . . . . .	9
<b>5</b>	<b>Programming simulations</b>	<b>10</b>
<b>6</b>	<b>Summary and closing words</b>	<b>11</b>
<b>A</b>	<b>Program Codes</b>	<b>13</b>

# List of Tables

# List of Figures

# 1. Introduction

*"Bla-bla-bla"*

– XY

## 2. Theoretical background

### 2.1 Statistics Basics

**Definition (Data)** Let  $(x_1, \dots, x_n)$ , where  $x_i \in S$  for  $i = 1, \dots, n$ . The set  $S$  is typically  $\mathbb{R}$ ,  $\mathbb{R}^d$ , or it can be any abstract set. However, for our purposes,  $S$  (the sample space) will usually be  $\mathbb{R}$ .

**Definition (Sample)** In statistics, our data are often modeled by a vector  $\mathbf{X} = (X_1, X_2, \dots, X_n)$  of i.i.d. (independent, identically distributed) random variables, called the sample (of which size is  $n$ ), where the random variables  $X_i$  take values in  $\mathbb{Z}$  or  $\mathbb{R}$ . The common distribution of the  $X_i$  is called the parent distribution, and we say that the sample is from that parent distribution.

**Definition (Model)** A statistical model is a family  $\{P_\theta \mid \theta \in \Theta\}$  of distributions on the sample space. When  $\Theta \subset \mathbb{R}^d$ , we say that we have a parametric model, and we call  $\Theta$  the parameter set (space).

**Definition (p-th Quantile of Data)** If  $p \in (0, 1)$ , then a  $p$ -th quantile (or a  $p$ -th percentile) of the data  $(x_1, \dots, x_n)$  is a  $p$ -th quantile of the corresponding empirical distribution function  $\hat{F}_n$ .

**Definition (Sample mean)** Let  $(X_1, \dots, X_n)$  be a sample. Then the random variable

$$\bar{X} = X = \frac{1}{n} \sum_{i=1}^n X_i$$

is called the sample mean.

**Definition (Estimator)** An estimator is a statistic (a function of the sample data) used to estimate an unknown parameter in a statistical model. An estimator for the parameter  $\theta$ , denoted as  $\hat{\theta}$ , is any measurable function of the random variables  $X_1, X_2, \dots, X_n$ .

**Definition (Biased)** If  $\hat{\theta}$  is an estimator of  $\theta$ , then we can define the quantity  $Bias(\hat{\theta}) = \mathbb{E}_\theta[\hat{\theta}] - \theta$ . The estimator  $\hat{\theta}$  is called unbiased if its bias is 0.

**Definition (MSE of an Estimator)** Let us have the model  $\{P_\theta \mid \theta \in \Theta\}$  and let us have the sample  $(X_1, \dots, X_n)$  from it. The mean square error (or the quadratic risk) of an estimator  $\hat{\theta} = \hat{\theta}(X_1, \dots, X_n)$  for the parameter  $\theta$  is defined by

$$\text{MSE}_\theta(\hat{\theta}) = \mathbb{E}_\theta((\hat{\theta} - \theta)^2)$$

when  $\theta$  is the true parameter.

**Steiner's identity:**  $\mathbb{E}((X - a)^2) = \text{Var}(X) + (a - \mathbb{E}(X))^2$

**Interpretation in the context of mean square error (MSE):**

$$\text{MSE}_\theta(\hat{\theta}) = \text{Var}_\theta(\hat{\theta}) + (\text{Bias}_\theta(\hat{\theta}))^2$$

**Definition (Sufficiency)** Let the model be  $\{P_\theta \mid \theta \in \Theta\}$  and  $\mathbf{X} = (X_1, \dots, X_n)$  be a sample from it. The statistic  $T$  is called *sufficient* for the parameter  $\theta$  (or, for the model  $\{P_\theta \mid \theta \in \Theta\}$ ) if the conditional distribution  $P_\theta(\mathbf{X} \in \cdot \mid T = t)$  does not depend on  $\theta$ .

**Theorem (Neyman-Fisher Factorization Theorem)** If the model is  $\{p(x|\theta) \mid \theta \in \Theta\}$  where  $p(x|\theta)$  is a probability mass/density function and  $\mathbf{X} = (X_1, \dots, X_n)$  is a sample from it, then the statistic  $T$  is *sufficient* for the parameter  $\theta$  if and only if we can find nonnegative functions  $g$  and  $h$  such that

$$p_{\mathbf{X}}(x|\theta) = g(T(x), \theta)h(x).$$

**Definition (Likelihood)** Let  $\{p(x, \theta), \theta \in \Theta\}$  be a model. If the observed value of  $X$  is  $x$ , we say that  $p(x|\theta)$  is the *likelihood* of  $\theta$ :  $L(\theta) = p(x|\theta)$ . Thus, we are considering the mass/density as a function of  $\theta$ , for a fixed  $x$ . If  $x = (x_1, \dots, x_n)$  is a realization of the sample  $\mathbf{X} = (X_1, \dots, X_n)$ , then  $p(x|\theta)$  is the product of the marginals,

$$L(\theta) = p(x|\theta) = \prod_{i=1}^n p(x_i|\theta).$$

## **2.2 Simple Linear Regression**



## **2.3 Simple Linear Regression with no intercept term**

## **2.4 Comparative Analysis**

## **3. Applications to Linear Regression through Origin**

### **3.1 Something to add 1**

### **3.2 Something to add 1**

## **4. Theoretical results**

### **4.1 A theoretical resilt**

### **4.2 Towards some advanced topic**

## **5. Programming simulations**

## 6. Summary and closing words

?<ch:closing>?

# **Bibliography**



## A. Program Codes

? $\langle$ ap:codes $\rangle$ ?