

# Cricket Ball Trajectory Prediction – Assessment Report

## 1. Introduction

This assessment focuses on detecting, tracking, and analyzing the trajectory of a cricket ball from match videos. The system generates accurate frame-wise ball coordinates in CSV format and produces trajectory overlay videos for visualization.

## 2. Dataset

The dataset consists of multiple cricket match videos in .mp4 and .mov formats. The ball is fast-moving, small in size, sometimes occluded, and under varying lighting conditions.

## 3. Modelling Decisions

A hybrid approach combining Classical Computer Vision and Deep Learning was adopted:

Classical CV: HSV color filtering, background subtraction (MOG2), contour analysis, and circularity checks

YOLOv8: Used for verification of candidate centroids  
Single-object temporal tracking with distance-based gating  
Trajectory tail visualization for smooth motion representation

## 4. Fallback Logic

The detection system implements a hierarchical fallback mechanism:

Primary: Classical CV detection Secondary: YOLOv8 verification if CV fails or candidate is suspicious

## 5. Assumptions Made

Only one ball per frame  
Maximum ball movement between frames  $\leq 120$  pixels  
Ball roughly circular with area 15–250 px<sup>2</sup>  
Videos frame rates approximately 25–60 FPS

## 6. Issues Identified & Fixes

Issue	Original Behavior	Fix Implemented
Detection fails for blurred balls	Classical CV misses ball	Added YOLO verification
Centroid jumps to wrong object	Noise, occlusion	Temporal consistency + MAX_JUMP filter
Tensor rounding error in CSV	`TypeError: type Tensor` Convert YOLO confidence tensor to float before rounding	
Inconsistent trajectory	Missing frames	Kalman filter fallback prediction

## 7. Example Outputs

**Trajectory Overlay Video:** Smooth red tail showing ball motion. Green circle marks the current centroid.

**CSV Annotation:**

frame,x,y,confidence,visible 0,620,340,0.82,1 1,628,338,0.79,1 2,,,0,0

## 8. Model Performance Improvements

Hybrid detection reduced false positives significantly  
Trajectory tail smoothing reduced centroid jitter  
Temporal filtering eliminated unrealistic jumps  
YOLO fallback ensures detection under motion blur and occlusion

## 9. Conclusion

The hybrid pipeline successfully detects and tracks the cricket ball across multiple videos, generating accurate CSV annotations and trajectory videos. The system is robust, visually smooth, and ready for extension with velocity, bounce detection, or custom YOLO training.

## 10. Future Work

Bounce detection and impact point prediction  
Velocity and angle estimation  
Custom YOLO model fine-tuning on cricket ball dataset