

•Ü{Ç‘ºe±0 DynamicViT: Efficient Vision Transformers with Dynamic Token Sparsification0 N-O•u(N†Nâ

1. **\@•èry_•b•_q**ÿ Ql_ 1ÿ ÿ

$$\begin{aligned} & \backslash \\ & z_{\{\text{local}\}} = \text{MLP}(x) \in \mathbb{R}^{N \times C'} \\ & \backslash \\ & QvN- \backslash (C' = C/2) \text{ÿ } u(N\check{Z}-M\sim\hat{o}0 \end{aligned}$$

2. **Qh\@ry_•€ZT **ÿ Ql_ 2-3ÿ ÿ

$$\begin{aligned} & \backslash \\ & z_{\{\text{global}\}} = \text{Agg}(\text{MLP}(x), \hat{D}) \in \mathbb{R}^{C'} \\ & \backslash \\ & \in ZT \text{ Q\'ep } \backslash (\text{Agg}) \backslash [\check{s}^\circ N:^\wedge \& c \otimes x \text{ } v,^\wedge s W G I`S \text{ } \text{ÿ} \\ & \backslash \\ & \text{Agg}(u, \hat{D}) = \frac{\sum_{i=1}^N \hat{D}_i u_i}{\sum_{i=1}^N \hat{D}_i} \\ & \backslash \end{aligned}$$

3. **\@•è-Qh\@ry_•‡•T N i,s‡~,mK**ÿ Ql_ 4-5ÿ ÿ

$$\begin{aligned} & \backslash \\ & z_i = [z_{\{\text{local}\}_i}, z_{\{\text{global}\}}] \\ & \backslash \\ & \backslash \\ & \pi = \text{Softmax}(\text{MLP}(z)) \in \mathbb{R}^{N \times 2} \\ & \backslash \\ & \bullet \text{“Q\'uk\I N}^* \text{token}^\wedge \ll O^\acute{Y} u Y \text{ÿ } \backslash (\pi_{\{i,1\}}) \text{ÿ } b \text{ } N" \text{ } \text{ÿ } \backslash (\pi_{\{i,0\}}) \text{ÿ } v, i, s \neq 0 \end{aligned}$$

4. **Gumbel-Softmax‘Çh7**ÿ Ql_ 7ÿ ÿ

$$\begin{aligned} & \backslash \\ & D = \text{Gumbel-Softmax}(\pi)_{\{*,1\}} \in \{0,1\}^N \\ & \backslash \\ & u(N\check{Z}S\check{i}_\otimes R \text{ } v,,N\oslash P < Q^3 \{V^\circ \text{Çh}70 \end{aligned}$$

5. **lèa R›c⊗x ‹i{—**ÿ Ql_ 9-11ÿ ÿ

$$\begin{aligned} & \backslash \\ & P = QK^T / \sqrt{C} \\ & \backslash \\ & \backslash \\ & G_{\{ij\}} = \begin{cases} 1 & \& \text{if } i=j \\ \hat{D}_j & \& \text{if } i \neq j \end{cases} \\ & \backslash \\ & \backslash \\ & \tilde{A}_{\{ij\}} = \frac{\exp(P_{\{ij\}})G_{\{ij\}}}{\sum_{k=1}^N \exp(P_{\{ik\}})G_{\{ik\}}} \\ & \backslash \\ & \bullet \bullet \text{Çc} \otimes x \text{ } w \acute{e} - 5 \backslash (G \backslash) \text{ } -; e - ^ \ll N" \text{ } _ \text{ token } v,, N \nabla N'0 \end{aligned}$$

6. **(-~Ãvîh **ÿ Ql_ 12-16ÿ ÿ

- R |{c_Y1ÿ \ (L_{\text{cls}}) = \text{CrossEntropy}(y, \bar{y})\)
- •ê„,™•c_Y1ÿ \ (L_{\text{distill}}) = \frac{1}{\sum \hat{D}_i} \sum \hat{D}_i (t_i - t'_i)^2\)
- KLec^!c_Y1ÿ \ (L_{\text{KL}}) = \text{KL}(y || y')\)
- kÔO(-!g_c_Y1ÿ \ (L_{\text{ratio}}) = \frac{1}{BS} \sum_{b,s} (\rho^{(s)} - \frac{1}{N} \sum_i \hat{D}_{i^{(b,s)}})^2\)
- `;c_Y1N:R gCTœÿ \ (L = L_{\text{cls}} + \lambda_{\text{KL}} L_{\text{KL}} + \lambda_{\text{distill}} L_{\text{distill}} + \lambda_{\text{ratio}} L_{\text{ratio}})\)

•ÜN›Ql_ QqT [žs°N†R““ tokenz u•S v„h8_Ãg:R6ÿ S bi‘‰•`“„mK0 Si_®R Rjg•TœxINöSËY}v„lèa R›c©