```
lèa R›wé–5ÿ Attention Matrixÿ f/Transformerj!W⟨N-•êlèa R›g:R6ÿ Self-Attentionÿ v"h8_Ä~Äb •èR ÿ u(N
### **1. •"Qe^hy:**
PG<sup>3</sup>/<sub>4</sub>•"Qe<sup>^</sup>•R u1 \( N \) N*T 'Ï~Äb ÿ ~ô^\N: \( d \)ÿ Ss \( X \in \mathbb{R}^\N \times d} \)ÿ 0 • •Ç~¿`'SØ
- **gå<âwé-5ÿ Queryÿ **ÿ \( Q = X W_Q \)ÿ \( W_Q \in \mathbb{R}^{d \times d_k} \)</p>
- **•.wé-5ÿ Keyÿ **ÿ \( K = X W_K \)ÿ \( W_K \in \mathbb{R}^{d \times d_k} \)
- **P<wé-5ÿ Valueÿ **ÿ \( V = X W_V \)ÿ \( W_V \in \mathbb{R}^{d \times d_v} \)
QvN-\( d_k \setminus TCE \setminus (d_v \setminus f/b - q - \hat{o}^i + \hat{v} - \hat{v} \setminus (d_k = d_v \setminus \hat{v}) = 0
### **2. \;{---lèa R\R ep**
•Çgå‹âTŒ•.v"p¹yï‹¡{—g*_RN S v"lèa R›R epwé–5 \( A \in \mathbb{R}^{\N \times N} \)ÿ
A = Q K^T
k\bar{l}N^*QC \( A_{ij}\) ^hy:{, \( i \) N*OM•n[ù{, \( j \) N*OM•nv,,Qslèz ^\0
### **3. •)e>ÿ Scalingÿ **
N:N^+-2kbp^1yiP<\Phi_CY'[\ddot{u}\Phi_0^+m^Y1\ddot{y}]iR=pw\acute{e}-5\Phi_0^+L\Phi_0^+yiP<\Phi_0^+J\Phi_0^+M^Y1\ddot{y}
A_{\text{scaled}} = \frac{A}{\sqrt{d_k}}
### **4. c©x ÿ Sï• ÿ **
W(‰ãx VhN-ÿ N:••QMg*geOá`ol—2ÿ O O•u(N N ‰Òc©x ÿ c©x P<N: \( -\infty \)ÿ ÿ
A_{\text{masked}} = A_{\text{scaled}} + M \quad \text{masked} = 0 \quad \text{ij} = 0 \quad \text{infty } 
### **5. Softmax RN S **
[ùklN ^L^"u(SoftmaxQýepÿ \ R ep•lcbN:i,s‡R ^ ÿ
\text{Attention Matrix} = \text{Softmax}(A_{\text{scaled}})
\]
QI_ ÿ
```

```
\text{\text{Attention}}_{ij} = \frac{(-x_{\text{scaled}, ij})}{\sum_{k=1}^N}
\exp(A_{\text{scaled}, ik})}
\]
### **6. R gCIBTŒ**
g ~È•"Qúf/lèa R>wé-5N P<wé-5 \( V \) v,,NXyïÿ
\text{Output} = \text{Attention Matrix} \cdot V
\]
### **O*Nãx y:O<ÿ PyTorch~Îh<ÿ **
```python
import torch.nn.functional as F
def compute_attention(Q, K, V, mask=None):
  d_k = Q.size(-1)
  scores = torch.matmul(Q, K.transpose(-2, -1)) / (d_k ** 0.5)
  if mask is not None:
     scores = scores.masked_fill(mask == 0, -1e9)
  attention = F.softmax(scores, dim=-1)
  output = torch.matmul(attention, V)
  return output, attention
### **Qs•.p1**
1. **^v^L(;{---**ÿ wé-5NXIÕšØeHe/c GPUR • 0
2. **z u•`'Y t **ÿ Y,DynamicViT• •Çc©x R"` Rjg•ÿ Y,Ql_ (10)-(11)ÿ 0
3. **Y gB^\:**ÿ (¡{—lèa R>wé–5v,,Y gB^\:N: \( O(N^2 d) \)ÿ ••^•R — O S ÿ Y,z u•lèa R>ÿ 0
```