

Capacity and Scheduling in Small-Cell HetNets

Stephen Hanly

Macquarie University
North Ryde, NSW 2109

Joint Work with Sem Borst, Chunshan Liu and Phil Whiting

Tuesday, January 13, 2015

1 Small Cells and Research Challenges

Talk Summary

- 1 Small Cells and Research Challenges
- 2 Model

Talk Summary

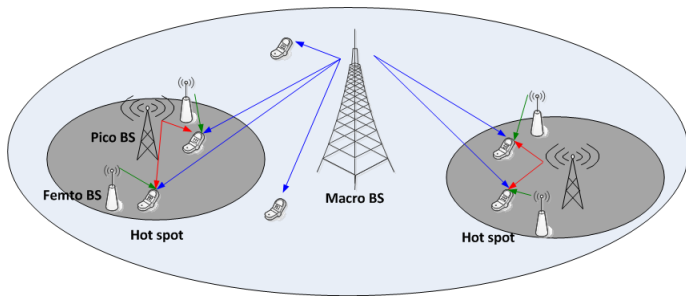
- 1 Small Cells and Research Challenges
- 2 Model
- 3 Main Stability Results

- 1 Small Cells and Research Challenges
- 2 Model
- 3 Main Stability Results
- 4 Discrete Linear Program

- 1 Small Cells and Research Challenges
- 2 Model
- 3 Main Stability Results
- 4 Discrete Linear Program
- 5 Cell Association and Scheduling Algorithms

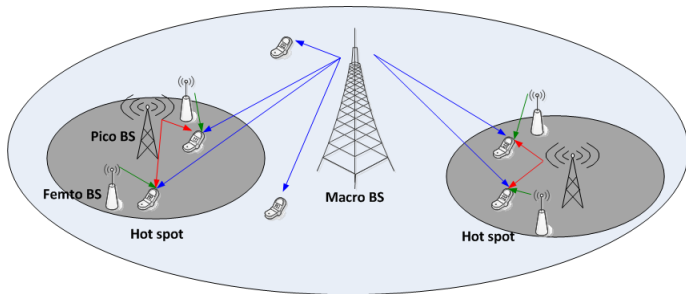
- 1 Small Cells and Research Challenges
- 2 Model
- 3 Main Stability Results
- 4 Discrete Linear Program
- 5 Cell Association and Scheduling Algorithms
- 6 Understanding the Converse

Small Cells and Data Offloading



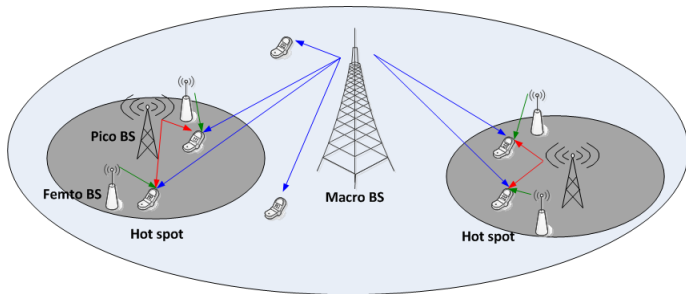
- Re-use spectrum: make cells smaller
- Offload traffic from macro-cells onto pico and femto-cells

Small Cells: Theoretical Challenges



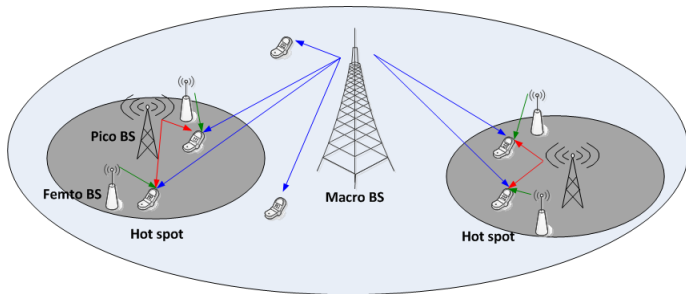
- What is the benefit? Base station densification gain?

Small Cells: Theoretical Challenges

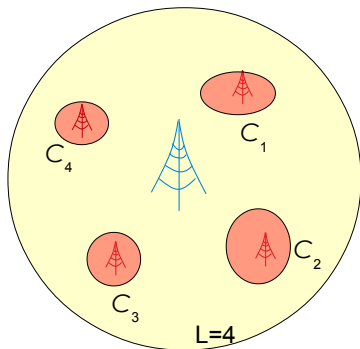


- What is the benefit? Base station densification gain?
- Characterizing capacity

Small Cells: Theoretical Challenges

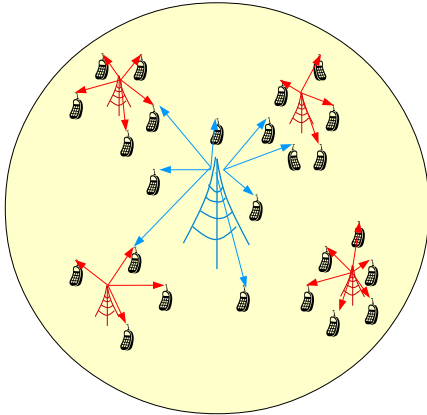


- What is the benefit? Base station densification gain?
- Characterizing capacity
- Optimizing resource allocation and cell association



- One macro Base Station (BS)
- L pico BSs
- All users in coverage of macro BS
- C_ℓ coverage area of pico BS ℓ
- Power levels are fixed
- Macro BS uses higher power than pico BSs

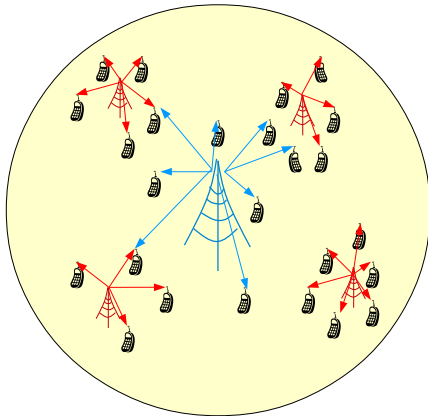
Time Sharing and Cell Association



- Time Share Spectrum

- Macro Cell versus Pico Cells
- Almost Blanking SubFrames

Time Sharing and Cell Association



- Time Share Spectrum
 - Macro Cell versus Pico Cells
 - Almost Blanking SubFrames
- Cell Range Expansion for Picos
 - Expand pico-cells to cover more mobiles
 - Contract pico-cells and send at Higher Rate

Research Problems

- 1 How to split the time between macro and picos?
- 2 How to decide the cell association?

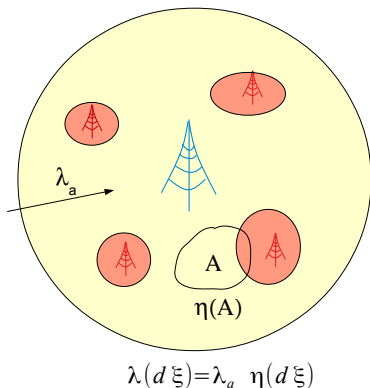
- ① How to split the time between macro and picos?
- ② How to decide the cell association?
- For cell association, one way is via **biasing**: add a bias to the measured power level to encourage offloading.

- ① How to split the time between macro and picos?
- ② How to decide the cell association?
 - For cell association, one way is via **biasing**: add a bias to the measured power level to encourage offloading.
 - We will address both 1. and 2. in a **joint approach**

- ① How to split the time between macro and picos?
- ② How to decide the cell association?
 - For cell association, one way is via **biasing**: add a bias to the measured power level to encourage offloading.
 - We will address both 1. and 2. in a **joint approach**
 - We will discover biasing based on **rate ratios**, not power levels

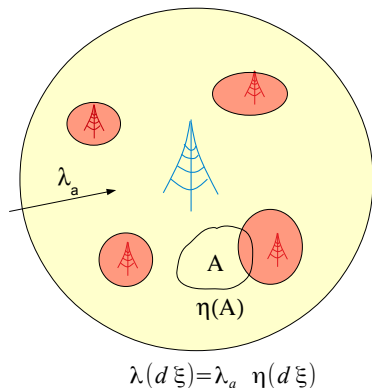
- 1 Small Cells and Research Challenges
- 2 Model**
- 3 Main Stability Results
- 4 Discrete Linear Program
- 5 Cell Association and Scheduling Algorithms
- 6 Understanding the Converse

Arrivals in Space and Time



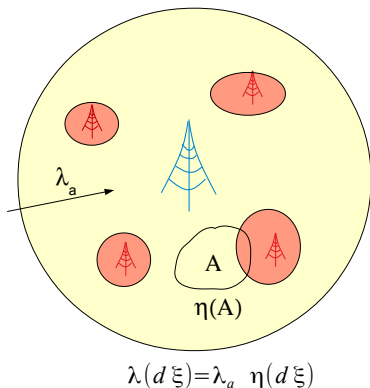
- Files arrive at rate λ_a files/slot (Poisson)
- $\eta(\cdot)$ gives a probability measure on the macrocell area
- Spatial arrival intensity is $\lambda(d\xi) = \lambda_a \eta(d\xi)$

Arrivals in Space and Time



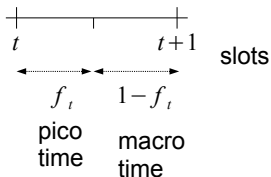
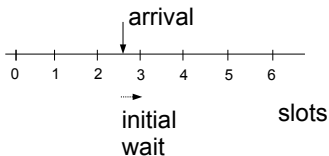
- Files arrive at rate λ_a files/slot (Poisson)
- $\eta(\cdot)$ gives a probability measure on the macrocell area
- Spatial arrival intensity is $\lambda(d\xi) = \lambda_a \eta(d\xi)$
- n th arrival has length D_n bits; $\mathbb{E}[D_n] = D$

Arrivals in Space and Time



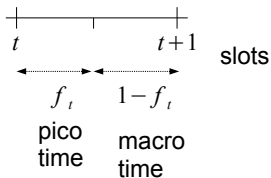
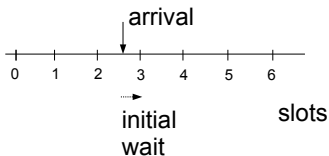
- Files arrive at rate λ_a files/slot (Poisson)
- $\eta(\cdot)$ gives a probability measure on the macrocell area
- Spatial arrival intensity is $\lambda(d\xi) = \lambda_a \eta(d\xi)$
- n th arrival has length D_n bits; $\mathbb{E}[D_n] = D$
- How large can λ_a be?

Pico versus Macro time



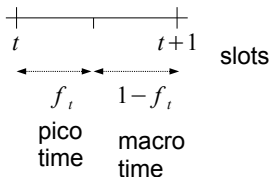
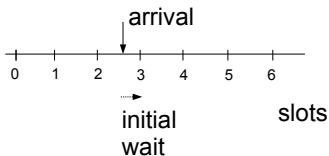
- Macro BS schedules files in macro-time
- All pico BSs can be scheduled simultaneously in pico-time

Pico versus Macro time



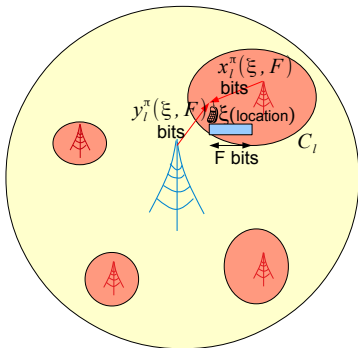
- Macro BS schedules files in macro-time
- All pico BSs can be scheduled simultaneously in pico-time
- A pico BS schedules files in its coverage area
- Not all files need be scheduled

Pico versus Macro time



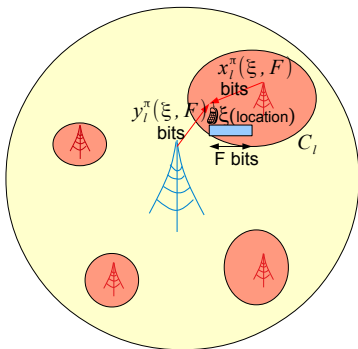
- Macro BS schedules files in macro-time
- All pico BSs can be scheduled simultaneously in pico-time
- A pico BS schedules files in its coverage area
- Not all files need be scheduled
- We will consider only **clearing schedules**
- Clearing schedules include FCFS (one at a time) and PS (parallel processing)

Location based policies



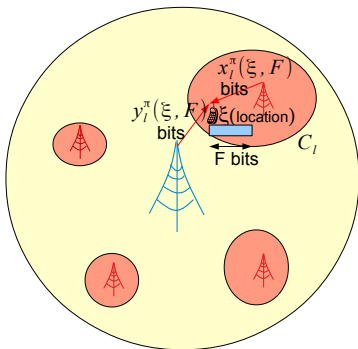
- Schedules determined via only the location ξ and the size F (bits) of the file

Location based policies



- Schedules determined via only the location ξ and the size F (bits) of the file
- If π is such a scheduler, $\xi \in \mathcal{C}_\ell$, and F is the file size then:
 - $x_\ell^\pi(\xi, F)$ bits are from pico BS ℓ
 - $y_\ell^\pi(\xi, F)$ are from macro BS

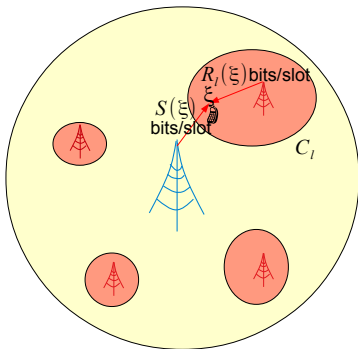
Location based policies



- Schedules determined via only the location ξ and the size F (bits) of the file
- If π is such a scheduler, $\xi \in \mathcal{C}_\ell$, and F is the file size then:
 - $x_\ell^\pi(\xi, F)$ bits are from pico BS ℓ
 - $y_\ell^\pi(\xi, F)$ are from macro BS
- If n th arrival is of size D_n bits and located at ξ_n then

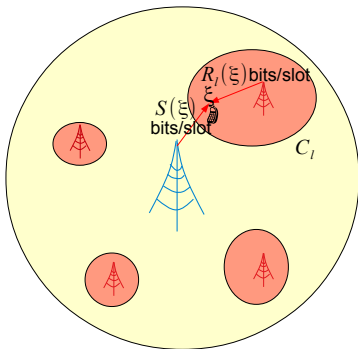
$$x_\ell^\pi(\xi_n, F_n) + y_\ell^\pi(\xi_n, F_n) = D_n$$

Data rates



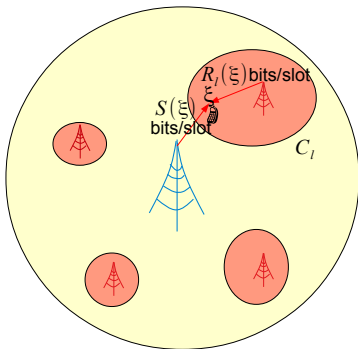
- Assume no interference between picocells (will relax later)
- So there is no interference in the system!

Data rates



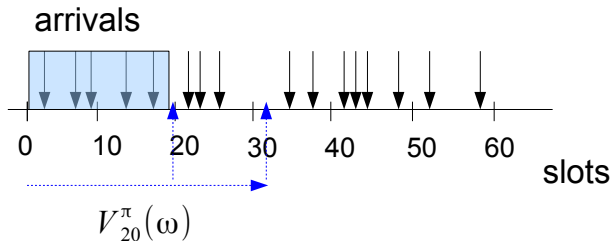
- Assume no interference between picocells (will relax later)
- So there is no interference in the system!
- At any point ξ there is a macro-cell rate of $S(\xi)$ bits/slot
- At any point $\xi \in C_\ell$ there is a pico-cell rate of $R_\ell(\xi)$ bits/slot

Data rates



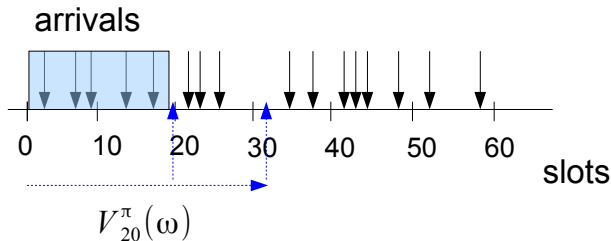
- Assume no interference between picocells (will relax later)
- So there is no interference in the system!
- At any point ξ there is a macro-cell rate of $S(\xi)$ bits/slot
- At any point $\xi \in C_\ell$ there is a pico-cell rate of $R_\ell(\xi)$ bits/slot
- A file can be served by macro and pico BSs in the same slot

Buildup of work



- Fix a location-based policy π and outcome $\omega \in \Omega$.
- Let $V_T^{\pi}(\omega)$ be time needed to clear all files that arrive in $[0, T]$

Buildup of work



- Fix a location-based policy π and outcome $\omega \in \Omega$.
- Let $V_T^{\pi}(\omega)$ be time needed to clear all files that arrive in $[0, T]$
- Clearly π is NOT stable if

$$\liminf_{T \uparrow \infty} \frac{V_T^{\pi}}{T} > 1$$

on an event of nonzero probability.

- 1 Small Cells and Research Challenges
- 2 Model
- 3 Main Stability Results**
- 4 Discrete Linear Program
- 5 Cell Association and Scheduling Algorithms
- 6 Understanding the Converse

Recall main parameters

$\lambda_a \eta(d\xi) = \lambda(d\xi)$, $\eta(d\xi)$ spatial intensity of arrivals

$R_\ell(\xi), S_\ell(\xi)$ Rates for pico and macro at location ξ

$x_\ell(\xi), y_\ell(\xi)$ bit assignments at location ξ

D mean download file size

Continuous Linear Program

Consider the following continuous LP:

$$\begin{array}{ll} \min & \tau = f + \sum_{\ell=1}^L \int \frac{y_{\ell}(\xi)}{S_{\ell}(\xi)} \lambda(d\xi) \\ \text{sub} & \int \frac{x_{\ell}(\xi)}{R_{\ell}(\xi)} \lambda(d\xi) \leq f \quad \forall \ell \\ & x_{\ell}(\xi) + y_{\ell}(\xi) \geq D, \end{array}$$

where f represents pico-time.

Let τ^* be the optimal value of the program.

Theorem (Hanly, Whiting)

Let τ^ be optimal solution to the LP. If $\tau^* < 1$, \exists a clearing schedule π with ergodic properties.*

Also define $S_n^\pi(\omega) :=$ sojourn time n th job, then π satisfies,

$$\mathbb{E}[S_n^\pi(\omega)] < \bar{S} < \infty \quad (1)$$

Theorem (Hanly, Whiting)

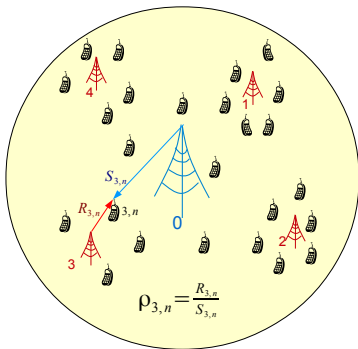
Let τ^ be the solution to the continuous LP. Suppose that $\tau^* > 1$ then there is a fixed constant $\eta > 0$, such that for any clearing schedule π*

$$\liminf_{T \uparrow \infty} \frac{V_T^\pi(\omega)}{T} = 1 + \eta \quad \text{almost surely.}$$

Talk Summary

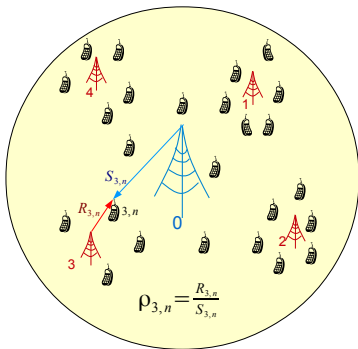
- 1 Small Cells and Research Challenges
- 2 Model
- 3 Main Stability Results
- 4 Discrete Linear Program**
- 5 Cell Association and Scheduling Algorithms
- 6 Understanding the Converse

Discrete Model



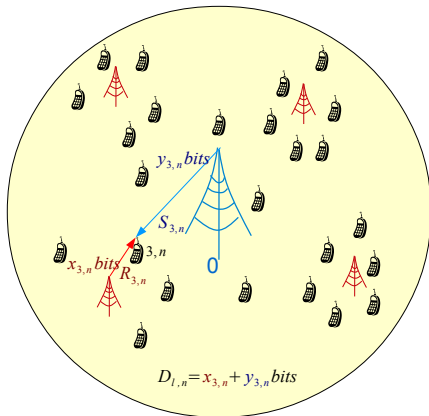
- Let instantaneous rate of n th user provided by pico BS be denoted by R_n
- Instantaneous rate of user provided by macro BS be denoted by S_n

Discrete Model



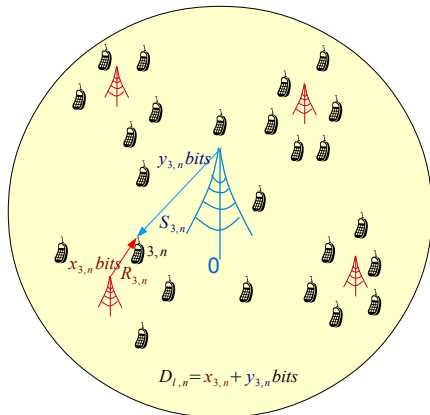
- Let instantaneous rate of n th user provided by pico BS be denoted by R_n
- Instantaneous rate of user provided by macro BS be denoted by S_n
- The rate ratio is defined by $\rho_n = \frac{R_n}{S_n}$

Problem Formulation



- Let D_n denote the amount of bits of data required by a user.
- D_n can be split into x_n bits of data from pico BS and y_n bits of data from the macro BS.

Problem Formulation



- Let D_n denote the amount of bits of data required by a user.
- D_n can be split into x_n bits of data from pico BS and y_n bits of data from the macro BS.
- It therefore requires $\frac{x_n}{R_n}$ secs from pico BS and $\frac{y_n}{S_n}$ secs from macro BS
- The problem is to **minimize the total time** to satisfy all the data demands in the network.

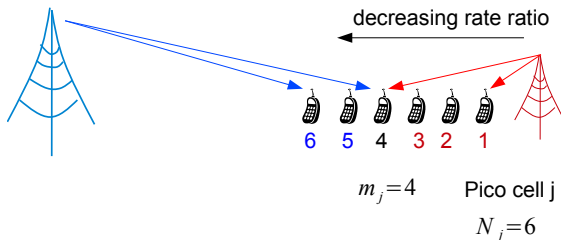
Problem Formulation: General

- The problem to be solved is the following linear program:

$$\begin{aligned} \min \quad & f + \sum_{l=0}^L \sum_{n=1}^{N_l} \frac{y_{l,n}}{S_{l,n}} \\ \text{sub} \quad & \sum_{n=1}^{N_l} \frac{x_{l,n}}{R_{l,n}} \leq f \quad \forall l \\ & x_{l,n} + y_{l,n} \geq D_{l,n} \quad \forall l, \forall n = 1, 2, \dots, N_l \\ & f \geq 0, x_{l,n} \geq 0, y_{l,n} \geq 0 \quad \forall l, \forall n = 1, 2, \dots, N_l \end{aligned}$$

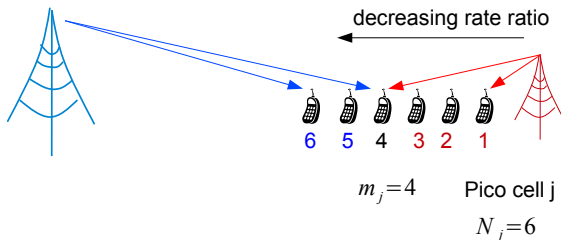
where f is the time allocated to the picocells.

A One Dimensional Formulation



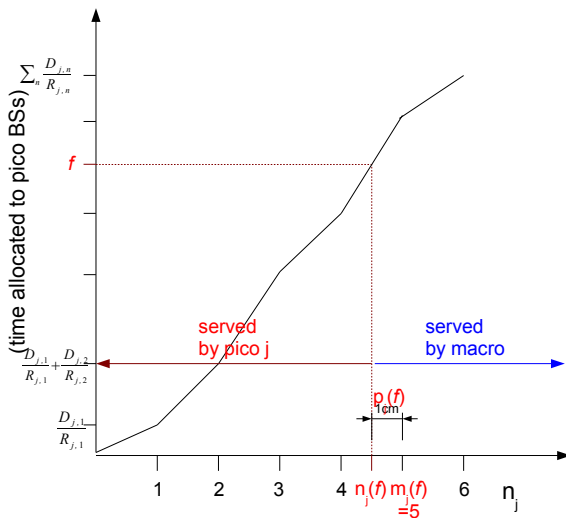
- Linear Programming theory tells us that the **rate ratios** $\rho := \frac{R}{S}$ are the **key to the optimal cell association**
- Order the users in pico cell in decreasing order of the rate ratio

A One Dimensional Formulation

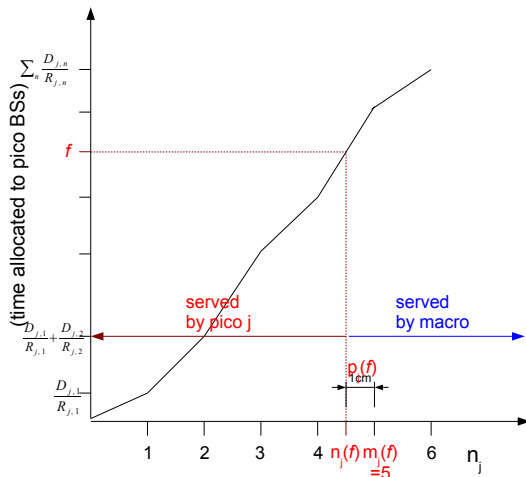


- Linear Programming theory tells us that the **rate ratios** $\rho := \frac{R}{S}$ are the **key to the optimal cell association**
- Order the users in pico cell in decreasing order of the rate ratio
- Then there will be a user m_j in pico cell j such that
 - users $1, 2, \dots, m_j - 1$ will be 100 % served by the pico cell BS ($y_{j,n} = 0$ for these users)
 - users $m_j + 1, 2, \dots, N_j$ will be 100 % served by the macro cell BS ($x_{j,n} = 0$ for these users)
 - user m_j may get its service from both base stations (pico and macro)

A One Dimensional Formulation



A one dimensional formulation



The macro-cell time required to service users near pico cell j is

$$g_j(f) = p_j(f) \frac{D_{j,m_j(f)}}{S_{j,m_j(f)}} + \sum_{n=m_j(f)+1}^{N_j} \frac{D_{j,n}}{S_{j,n}}$$

A one dimensional formulation

The problem is therefore to minimize the following function of the scalar parameter f :

$$f + \sum_{l=1}^L g_l(f)$$

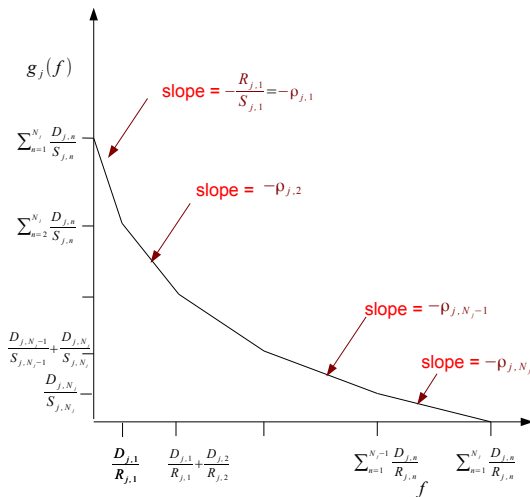
A one dimensional formulation

The problem is therefore to minimize the following function of the scalar parameter f :

$$f + \sum_{l=1}^L g_l(f)$$

The range for the optimization is $0 \leq f \leq \max_{l=1}^L \sum_{n=1}^{N_l} \frac{D_{l,n}}{S_{l,n}}$.

A one dimensional formulation



- Recall that the problem is to minimize the function $f + \sum_{l=1}^L g_l(f)$

Edge rate condition

- Recall that the problem is to minimize the function $f + \sum_{l=1}^L g_l(f)$
- The derivative at any *non-break-point* f is therefore $1 - \sum_{l=1}^L \rho_l(f)$.

Edge rate condition

- Recall that the problem is to minimize the function $f + \sum_{l=1}^L g_l(f)$
- The derivative at any *non-break-point* f is therefore $1 - \sum_{l=1}^L \rho_l(f)$.
- But the *optimum* will occur at one of the break points, where the derivative changes.

Edge rate condition

- Recall that the problem is to minimize the function $f + \sum_{l=1}^L g_l(f)$
- The derivative at any *non-break-point* f is therefore $1 - \sum_{l=1}^L \rho_l(f)$.
- But the *optimum* will occur at one of the break points, where the derivative changes.
- **edge rate condition:** The time allocation f to pico-cells is optimal if and only if

$$\sum_{l=1}^L \rho_{l,f-} \geq 1 \geq \sum_{l=1}^L \rho_{l,f+}$$

Edge rate condition

- Recall that the problem is to minimize the function $f + \sum_{l=1}^L g_l(f)$
- The derivative at any *non-break-point* f is therefore $1 - \sum_{l=1}^L \rho_l(f)$.
- But the *optimum* will occur at one of the break points, where the derivative changes.
- **edge rate condition:** The time allocation f to pico-cells is optimal if and only if

$$\sum_{l=1}^L \rho_{l,f-} \geq 1 \geq \sum_{l=1}^L \rho_{l,f+}$$

- We only need to check the $1 + \sum_{l=1}^L N_l$ break points, where the derivative changes, for the edge-rate condition.

Talk Summary

- 1 Small Cells and Research Challenges
- 2 Model
- 3 Main Stability Results
- 4 Discrete Linear Program
- 5 Cell Association and Scheduling Algorithms**
- 6 Understanding the Converse

Recall theorem for existence of schedule

Theorem (Hanly, Whiting)

Let τ^ be optimal solution to the LP. If $\tau^* < 1$, \exists a clearing schedule π with ergodic properties.*

Recall theorem for existence of schedule

Theorem (Hanly, Whiting)

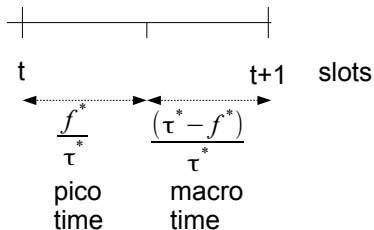
Let τ^ be optimal solution to the LP. If $\tau^* < 1$, \exists a clearing schedule π with ergodic properties.*

The optimal solution of the continuous LP is characterized by **rate ratio thresholds** ρ_ℓ^* , $\ell = 1, 2, \dots, L$:

$$x_\ell^*(\xi) = \begin{cases} D & \rho_\ell(\xi) > \rho_\ell^* \\ 0 & \text{o.w.} \end{cases} \quad (2)$$

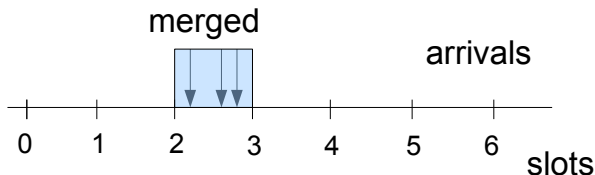
We will now show that these thresholds can be used to construct an optimal schedule.

Construction of a stabilizing schedule



- Suppose $\tau^* < 1$ and let f^* be the optimal value of f from continuous LP.
- Allocate $\frac{f^*}{\tau^*}$ of each slot to picos.
- Allocate $\frac{\tau^* - f^*}{\tau^*}$ of each slot to the macro.
- Assign each file to pico or macro based on rate-ratio threshold ρ_ℓ^* .

Construction of a stabilizing schedule



- All files that arrive during a slot are merged into one job
- Service time of each job can be computed (location-based policy)
- Each BS serves jobs in FCFS order
- D/G/1 queue at each base station.

Construction of a stabilizing schedule

- The workload arriving at the macro BS queue can be shown to be $\tau^* - f^*$ slots/slot
- The service rate of the macro BS is $\frac{\tau^* - f^*}{\tau^*}$ slots/slot
- So the utilization of the macro BS is τ^*

Construction of a stabilizing schedule

- The workload arriving at the macro BS queue can be shown to be $\tau^* - f^*$ slots/slot
- The service rate of the macro BS is $\frac{\tau^* - f^*}{\tau^*}$ slots/slot
- So the utilization of the macro BS is τ^*

- The workload arriving at a pico BS can be shown to be at most f^* slots/slot
- The service rate of each pico BS is $\frac{f^*}{\tau^*}$ slots/slot
- So the utilization of each pico BS is at most τ^*

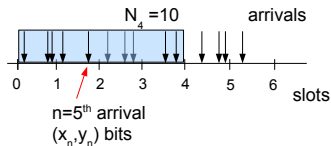
Construction of a stabilizing schedule

- The workload arriving at the macro BS queue can be shown to be $\tau^* - f^*$ slots/slot
- The service rate of the macro BS is $\frac{\tau^* - f^*}{\tau^*}$ slots/slot
- So the utilization of the macro BS is τ^*
- The workload arriving at a pico BS can be shown to be at most f^* slots/slot
- The service rate of each pico BS is $\frac{f^*}{\tau^*}$ slots/slot
- So the utilization of each pico BS is at most τ^*
- If $\tau^* < 1$ then each D/G/1 queue is stable.

Talk Summary

- 1 Small Cells and Research Challenges
- 2 Model
- 3 Main Stability Results
- 4 Discrete Linear Program
- 5 Cell Association and Scheduling Algorithms
- 6 Understanding the Converse**

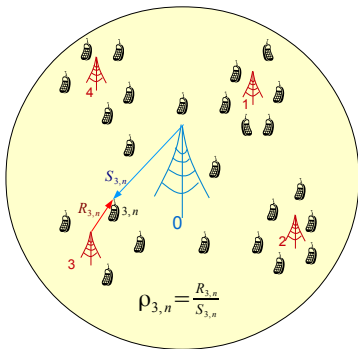
Understanding the converse



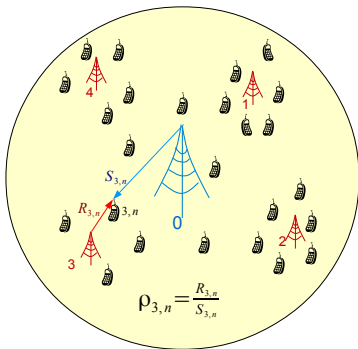
- Suppose $\tau^* > 1$, and let π be a clearing schedule.
- Let N_T be the number of arrivals during $[0, T]$.
- Let x_n be number of pico-cell bits for the n th arrival
- Let y_n be number of macro-cell bits for the n th arrival

Understanding the converse

- Imagine all the N_T arrivals being present at time zero

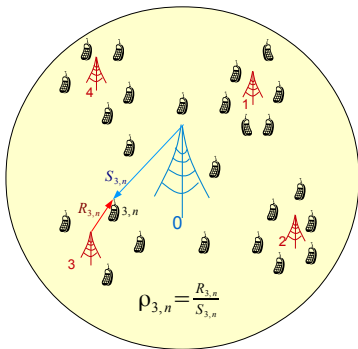


Understanding the converse



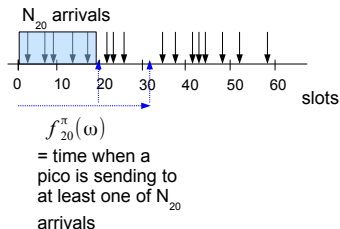
- Imagine all the N_T arrivals being present at time zero
- Let V_T^{LP} be the minimum time in the corresponding discrete LP

Understanding the converse



- Imagine all the N_T arrivals being present at time zero
- Let V_T^{LP} be the minimum time in the corresponding discrete LP
- We can analyze this and show that $\liminf_{T \uparrow \infty} \frac{V_T^{LP}}{T} > 1 + \eta$

Understanding the converse

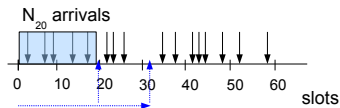


- Now consider the actual system under policy π
- Let f_T^{π} be the total time in which at least one of the N_T files is getting pico-service

Discrete Linear Program

$$\begin{aligned}
 \min \quad & f + \sum_l \sum_n \frac{y_{l,n}}{S_{l,n}} \\
 \text{sub.} \quad & \sum_n \frac{x_{l,n}}{R_{l,n}} \leq f \quad \forall l \\
 & x_{l,n} + y_{l,n} \geq D_{l,n} \quad \forall l, n
 \end{aligned}$$

Understanding the converse



$f_{20}^{\pi}(\omega)$
 = time when a
 pico is sending to
 at least one of N_{20}
 arrivals

Discrete Linear Program

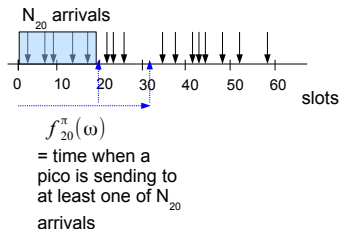
$$\begin{aligned} \min \quad & f + \sum_l \sum_n \frac{y_{l,n}}{S_{l,n}} \\ \text{sub.} \quad & \sum_n \frac{x_{l,n}}{R_{l,n}} \leq f \quad \forall l \\ & x_{l,n} + y_{l,n} \geq D_{l,n} \quad \forall l, n \end{aligned}$$

- Now consider the actual system under policy π
- Let f_T^{π} be the total time in which at least one of the N_T files is getting pico-service
- Then

$$V_T^{\pi} = f_T^{\pi} + \sum_{n=1}^{N_T} \frac{y_n}{S_n},$$

$$\sum_{n \in \mathcal{C}_{\ell}} \frac{x_n}{R_n} \leq f_T^{\pi}$$

Understanding the converse



Discrete Linear Program

$$\begin{aligned}
 \min \quad & f + \sum_l \sum_n \frac{y_{l,n}}{S_{l,n}} \\
 \text{sub.} \quad & \sum_n \frac{x_{l,n}}{R_{l,n}} \leq f \quad \forall l \\
 & x_{l,n} + y_{l,n} \geq D_{l,n} \quad \forall l, n
 \end{aligned}$$

- Now consider the actual system under policy π
- Let f_T^{π} be the total time in which at least one of the N_T files is getting pico-service
- Then

$$V_T^{\pi} = f_T^{\pi} + \sum_{n=1}^{N_T} \frac{y_n}{S_n},$$

$$\sum_{n \in \mathcal{C}_{\ell}} \frac{x_n}{R_n} \leq f_T^{\pi}$$

- So $(f_T^{\pi}, x_n, y_n, \dots)$ is feasible for the earlier discrete LP

Hence

$$\liminf_{T \uparrow \infty} \frac{V_T^\pi}{T} \geq \frac{V_T^{LP}}{T} > 1 + \eta$$

which implies that π is unstable.

Extensions

- Given stabilizing schedule is NOT dynamic and can greatly be improved

Extensions

- Given stabilizing schedule is NOT dynamic and can greatly be improved
- We can analyze Processor Sharing at each BS which gets much better delay performance

Extensions

- Given stabilizing schedule is NOT dynamic and can greatly be improved
- We can analyze Processor Sharing at each BS which gets much better delay performance
- Assumption that statistics are known can be relaxed

Extensions

- Given stabilizing schedule is NOT dynamic and can greatly be improved
- We can analyze Processor Sharing at each BS which gets much better delay performance
- Assumption that statistics are known can be relaxed
- The assumption that there is no pico-cell interference can be relaxed:
 - Assume fixed power levels when pico scheduled to be “on”

- Given stabilizing schedule is NOT dynamic and can greatly be improved
- We can analyze Processor Sharing at each BS which gets much better delay performance
- Assumption that statistics are known can be relaxed
- The assumption that there is no pico-cell interference can be relaxed:
 - Assume fixed power levels when pico scheduled to be “on”
 - Many different modes: subsets of pico BSs that are simultaneously activated

- Given stabilizing schedule is NOT dynamic and can greatly be improved
- We can analyze Processor Sharing at each BS which gets much better delay performance
- Assumption that statistics are known can be relaxed
- The assumption that there is no pico-cell interference can be relaxed:
 - Assume fixed power levels when pico scheduled to be “on”
 - Many different modes: subsets of pico BSs that are simultaneously activated
 - The pico rates at a location are mode-dependent

- Given stabilizing schedule is NOT dynamic and can greatly be improved
- We can analyze Processor Sharing at each BS which gets much better delay performance
- Assumption that statistics are known can be relaxed
- The assumption that there is no pico-cell interference can be relaxed:
 - Assume fixed power levels when pico scheduled to be “on”
 - Many different modes: subsets of pico BSs that are simultaneously activated
 - The pico rates at a location are mode-dependent
 - Problem remains a continuous LP, but with a huge number of variables

- Given stabilizing schedule is NOT dynamic and can greatly be improved
- We can analyze Processor Sharing at each BS which gets much better delay performance
- Assumption that statistics are known can be relaxed
- The assumption that there is no pico-cell interference can be relaxed:
 - Assume fixed power levels when pico scheduled to be “on”
 - Many different modes: subsets of pico BSs that are simultaneously activated
 - The pico rates at a location are mode-dependent
 - Problem remains a continuous LP, but with a huge number of variables
 - Good but suboptimal schemes can be found focusing on the most important modes

- Given stabilizing schedule is NOT dynamic and can greatly be improved
- We can analyze Processor Sharing at each BS which gets much better delay performance
- Assumption that statistics are known can be relaxed
- The assumption that there is no pico-cell interference can be relaxed:
 - Assume fixed power levels when pico scheduled to be “on”
 - Many different modes: subsets of pico BSs that are simultaneously activated
 - The pico rates at a location are mode-dependent
 - Problem remains a continuous LP, but with a huge number of variables
 - Good but suboptimal schemes can be found focusing on the most important modes
- Extensions to multiple macro-cells

- Theory can be used as a basis for the search for adaptive algorithms
- Can be used as a cell planning tool since capacity is a function of base station locations

Concluding Remarks

- Formulated a notion of capacity for a dynamic HetNet consisting of one macrocell, multiple picocells

Concluding Remarks

- Formulated a notion of capacity for a dynamic HetNet consisting of one macrocell, multiple picocells
- Characterized capacity in terms of the solution of a deterministic, continuous Linear Program

Concluding Remarks

- Formulated a notion of capacity for a dynamic HetNet consisting of one macrocell, multiple picocells
- Characterized capacity in terms of the solution of a deterministic, continuous Linear Program
- Showed how ABS slot and cell association can be solved jointly

Concluding Remarks

- Formulated a notion of capacity for a dynamic HetNet consisting of one macrocell, multiple picocells
- Characterized capacity in terms of the solution of a deterministic, continuous Linear Program
- Showed how ABS slot and cell association can be solved jointly
- Showed how rate ratio thresholds provide the right way to bias pico-cells

Concluding Remarks

- Formulated a notion of capacity for a dynamic HetNet consisting of one macrocell, multiple picocells
- Characterized capacity in terms of the solution of a deterministic, continuous Linear Program
- Showed how ABS slot and cell association can be solved jointly
- Showed how rate ratio thresholds provide the right way to bias pico-cells
- Questions?