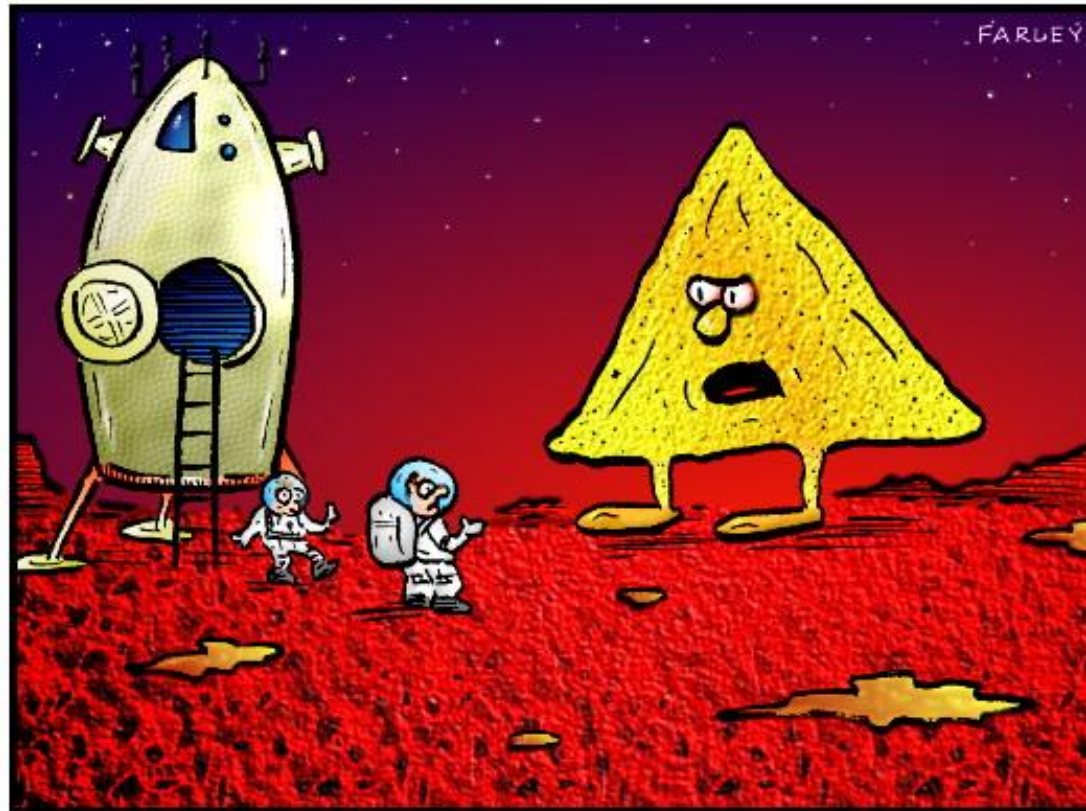


CS 162 Nachos Tutorial

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"This is the planet where nachos rule."

Outline

- What is Nachos?
 - Capabilities, purpose, history
- How does it work?
- How do I get started?

What is Nachos?

- An instructional operating system
- Includes many facets of a real OS:
 - Threads
 - Interrupts
 - Virtual Memory
 - I/O driven by interrupts
- You can (and will) modify and extend it

What else is Nachos?

- Nachos also contains some hardware simulation.
 - MIPS processor
 - Can handle MIPS code in standard COFF, except for floating point instructions
 - You can (and will) write code in C, compile it to MIPS and run it on Nachos.
 - Console
 - Network interface
 - Timer

Why Nachos?

- What better way to learn how an OS works than by building one?
- Much easier and more reasonable to build a simulated one in Java
- Skeleton code allows us to work on, replace, or upgrade one piece at a time.

History of Nachos

- Originally created here at Berkeley in 1992 in C++
- By Wayne A. Christopher, Steven J. Procter, and Thomas E. Anderson
- Used at many universities
- Rewritten in Java by Daniel Hettena
 - Now simpler, easier to grade, type-safe, portable, and more students now know Java.

How are we using it?

- Four Nachos assignments - “Phases”
- Phase 1 - Threading
- Phase 2 - Multiprogramming
- Phase 3 - Caching and Virtual Memory
- Phase 4 - Networks and Distributed Systems

How does Nachos work?

- Entirely written in Java
- Broken into Java packages:
 - nachos.ag (autograder classes)
 - nachos.machine (most of the action)
 - nachos.network (Phase 4)
 - nachos.security (tracks privilege)
 - nachos.threads (Phase 1)
 - nachos.userprog (Phase 2)
 - nachos.vm (Phase 3)

Booting Nachos

- When you run Nachos, it starts in `nachos.machine.Machine.main`
- `Machine.main` initializes devices - interrupt controller, timer, MIPS processor, console, file system
- Passes control to the autograder.
- `AutoGrader` will create a kernel and start it (this starts the OS)

The Machine!

- `nachos.machine.Machine`
- Kicks off the system, and provides access to various hardware devices:
 - `Machine.interrupt()`
 - `Machine.timer()`
 - `Machine.console()`
 - `Machine.networkLink()`

Interrupt Controller

- Kicks off hardware interrupts
- `nachos.machine.Interrupt` class maintains an event queue, clock
- Clock ticks under two conditions:
 - One tick for executing a MIPS instruction
 - Ten ticks for re-enabling interrupts
- After any tick, Interrupt checks for pending interrupts, and runs them.
- Calls device event handler, not software interrupt handler

Interrupt Controller (cont.)

- Important methods, accessible to other hardware simulation devices:
 - `schedule()` takes a time, handler
 - `tick()` takes a boolean (1 or 10 ticks)
 - `checkIfDue()` invokes due interrupts
 - `enable()`
 - `disable()`
- All hardware devices depend on interrupts - they don't get threads.

Timer

- `nachos.machine.Timer`
- Hardware device causes interrupts about every 500 ticks (not exact)
- Important methods:
 - `getTime()` tells many ticks so far
 - `setInterruptHandler()` tells the timer what to do when it goes off
- Provides preemption

Serial Console

- Java interface `nachos.machine.SerialConsole`
- Contains methods:
 - `readByte()` returns one byte (or -1) and waits to interrupt when it has more
 - `writeByte()` takes one byte and waits to interrupt when its ready for more
 - `setInterruptHandlers()` tells the console who to call when it receives data or finishes sending data
- Normally implemented by `nachos.machine.StandardConsole`, hooked up to `stdin` and `stdout`

Other Hardware Devices

- Disk
 - Didn't make the jump to Java from C++, we don't use it for our Nachos assignments
- Network Link
 - Similar to console, but packet based.
 - Used for Phase 4.
 - You should be able to figure it out by then.

The Kernel

- Abstract class `nachos.machine.Kernel`
- Important methods
 - `initialize()` initializes the kernel, duh!
 - `selfTest()` performs test (not used by ag)
 - `run()` runs any user code (none for 1st phase)
 - `terminate()` Game over. Never returns.
- Each Phase will have its own Kernel subclass

Threading

- Happens in package `nachos.threads`
- All Nachos threads are instances of `nachos.thread.KThread` (or subclass)
- `KThread` has status
 - New, Ready, Running, Blocked, Finished
- Every `KThread` also has a `nachos.machine.TCB`
- Internally implemented by Java threads

Running threads

- Create a `java.lang.Runnable()`, make a `Kthread`, and call `fork()`.
- **Example:**

```
class Sprinter implements Runnable {  
    public void run() {  
        // run real fast  
    }  
}
```

```
Sprinter s = new Sprinter();  
new KThread(s).fork();
```

Scheduler

- Some subclass of `nachos.machine.Scheduler`
- Creates `ThreadQueue` objects which decide what thread to run next.
- Defaults to `RoundRobinScheduler`
- Specified in Nachos configuration file

Nachos Configuration

- nachos.conf file lets you specify many options
 - which classes to use for Kernel, Scheduler
 - whether to be able to run user progs
 - etc.
- Different one for each project.

How to get started

- Go to class web page
- Download and install nachos package
- Read the README, make sure you can make proj1 OK
- The first phase will be posted soon with detailed instructions for first Nachos assignment

Advice

- One step at a time. Get a little bit working. Then a little more. Then a little more, etc.
- Find a good tool, including a debugger, and use it. One choice - Eclipse.

For More Information

- README file in the installation has lots of good stuff
- See the Class Web Page for intros, background, and the code itself.
- Read the code! You can see exactly what is going on.