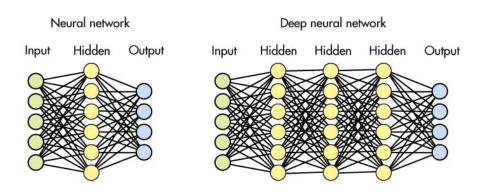
MIDS W207 Applied Machine Learning

Week 6 Live Session Slides

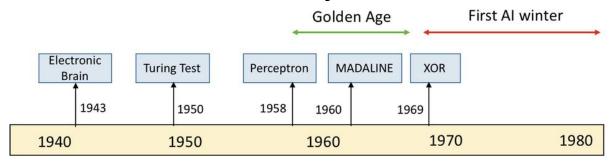
Deep learning algorithm structured similar to the organization of neurons in the brain

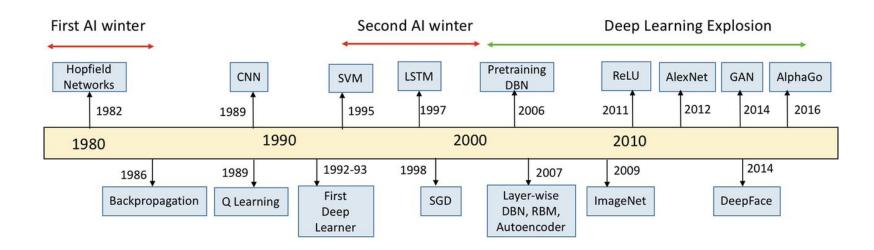
A neural network is a series of algorithms that endeavors to recognize underlying relationships in a set of data through a process that mimics the way the human brain operates.

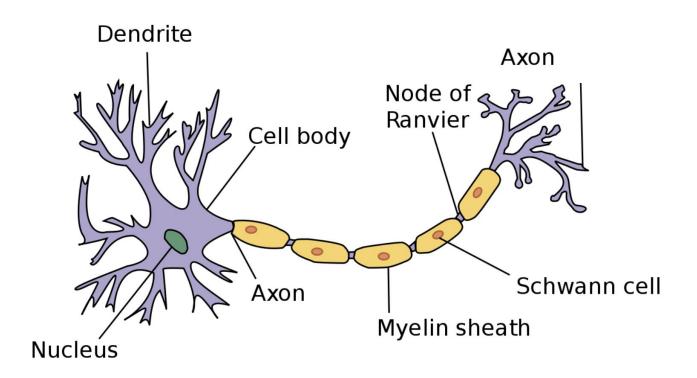
Neural networks can adapt to changing input; so the network generates the best possible result without needing to redesign the output criteria.

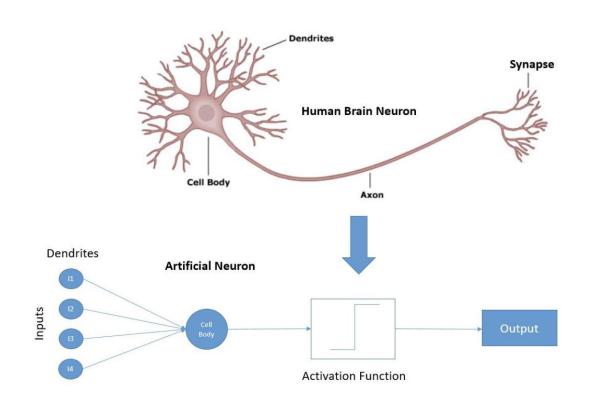


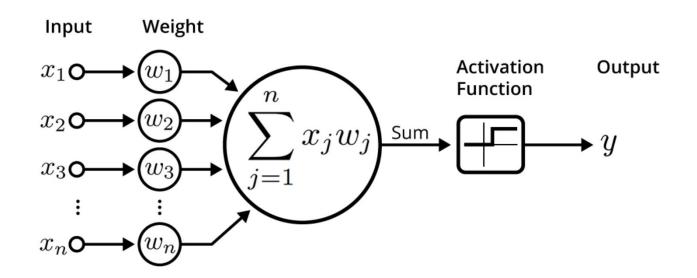
Neural Networks: History and Timeline



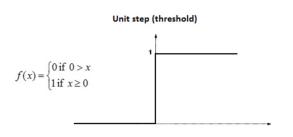


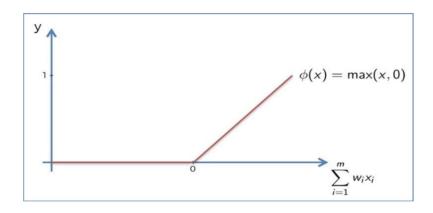


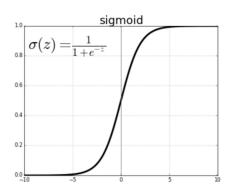


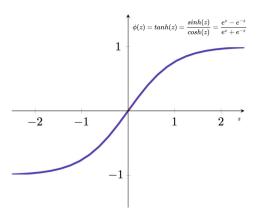


Neural Networks: Activation Functions

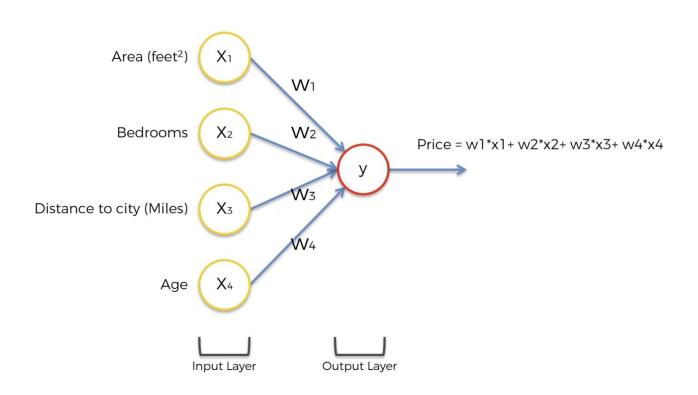




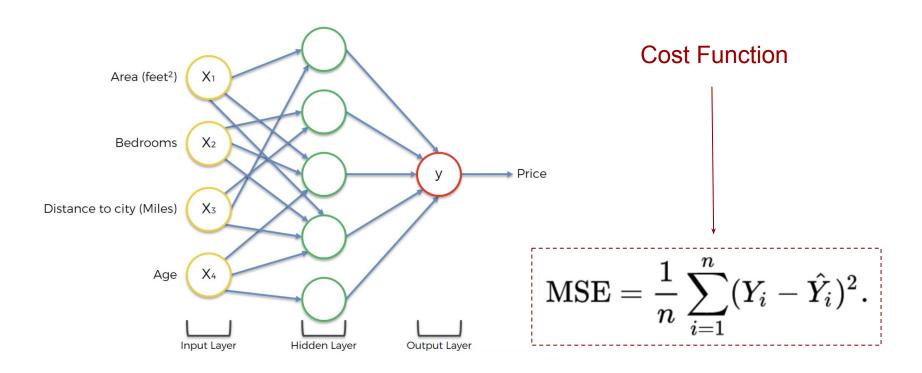




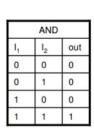
Neural Networks: Example (Property Valuation)

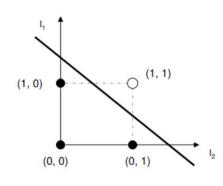


Neural Networks: Example (Property Valuation)

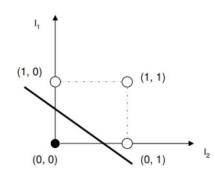


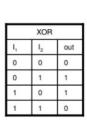
Neural Networks: Perceptron

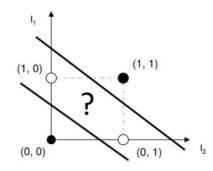




OR		
I ₁	l ₂	out
0	0	0
0	1	1
1	0	1
1	1	1







Neural Networks: Perceptron (XOR)

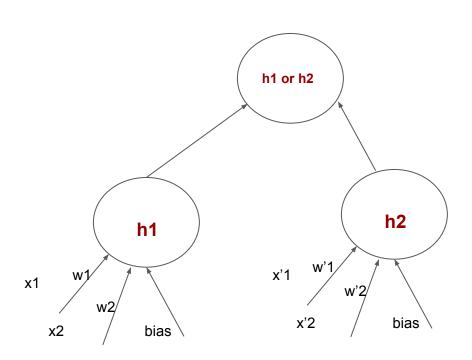
h1

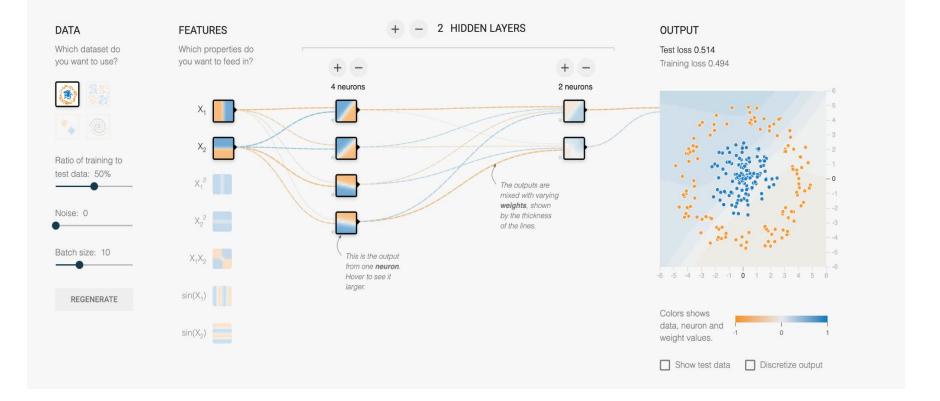
h2

X1	X2	Y	X1 AND ¬X2	rX1 AND X2	h1 OR h2
0	0	0	0	0	0
0	1	1	0	1	1
1	0	1	1	0	1
1	1	0	0	0	0

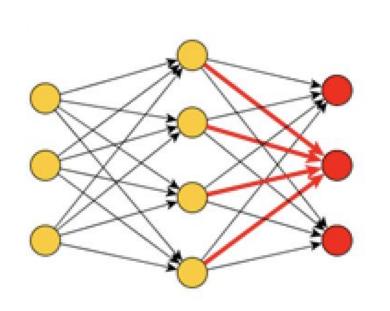
$$y = \begin{cases} 0, & \text{if } w \cdot x + b \le 0 \\ 1, & \text{if } w \cdot x + b > 0 \end{cases}$$

Neural Networks: Perceptron (XOR)

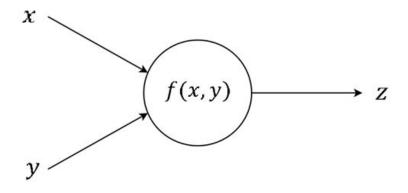




Neural Networks: Forward Propagation



Forwardpass



Chain Rule

Suppose you have a composite function:

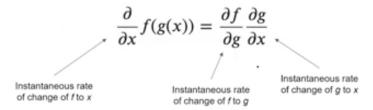
$$h(x) = f(g(x))$$

and both f and g are differentiable functions.

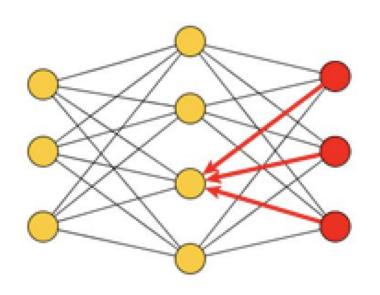
Then the chain rule says that the derivative of h is the following product:

$$h'(x) = f'(g(x))g'(x)$$

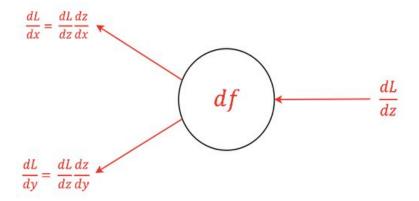
The chain rule expressed with partial derivatives:

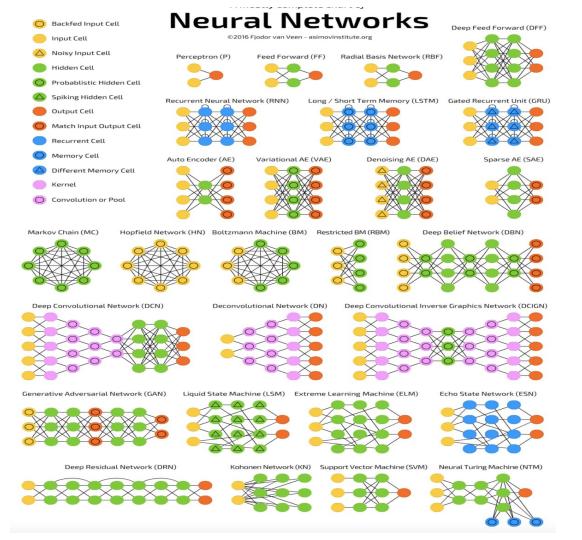


Neural Networks: Backpropagation

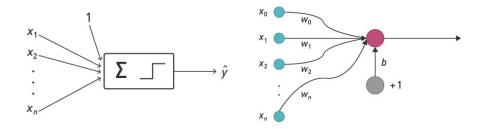


Backwardpass





Neural Networks: Perceptron



- Discriminative classifier: learns decision boundary
- Perceptron fires if predicted value is positive

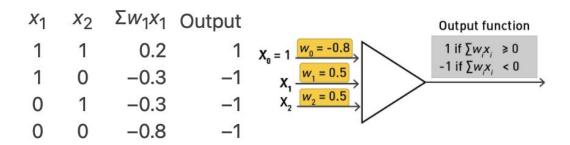
$$h(x_i) = b + \sum_{d=1}^{D} w_d x_{id}$$

b allows for nonzero threshold

$$output = \begin{cases} 0 & if \sum_{j} w_{j}x_{j} < threshold \\ 1 & if \sum_{j} w_{j}x_{j} > threshold \end{cases}$$

Neural Networks: Perceptron (AND)

A perceptron for AND:



Two weights and intercept

$$h(x_i) = b + w_1 x_{i1} + w_2 x_{i2}$$

Neural Networks: Perceptron (XOR)

X2	Y	
0	0	b ≤ 0
1	1	\rightarrow b + w2 > 0
0	1	\rightarrow b + w1 > 0
1	0	b + w1 + w2 ≤ 0
	0 1 0 1	X2 Y 0 0 1 1 0 1 1 0

$$y = \begin{cases} 0, & \text{if } w \cdot x + b \le 0 \\ 1, & \text{if } w \cdot x + b > 0 \end{cases}$$

Perceptron: Rosenblatt's Algorithm

```
initialize weights randomly
while termination condition is not met:
       initialize \Delta w_i = 0
       for each training example (X_i, Y_i):
               compute predicted output Y,
               for each weight w_i:
                      \Delta w_j = \Delta w_j + \eta \left( Y_i - \hat{Y}_i \right) X_i
       for each weight w_i:
               w_i = w_i + \Delta w_i
```

Neural Networks: Gradient Descent

• Training rule (Rosenblatt)

$$\Delta w_j = \Delta w_j + \eta (Y_i - \hat{\mathbf{Y}}) X_i$$

· Gradient descent (stochastic)

$$\beta < -\beta + R(Y_i - \hat{Y}_i)X_i$$

- Key is the \boldsymbol{Y}_i .
 - \circ Perceptron: Y_i is step function; either 0 or 1.
 - \circ Gradient descent: Y_i is smooth function; continuous.
 - Gradient provides continuous surface