

Physics potential of timing layers for future detectors

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Abstract

The physics potential of timing layers with a few tens of pico-second resolution for calorimeters of future detectors in collider experiments is explored. The presented studies show how such layers can be used for identification of separate particles, as well as illustrate the benefit of detecting new event signatures beyond the standard model.

Keywords:

1. Introduction

Future experiments, such as CLIC [1], International Linear Collider (ILC) [2], high-energy LHC (HE-LHC), future circular pp colliders of the European initiative, FCC-hh [3] and the Chinese initiative, SppC [4] will require high precision measurements of particles and jets at large transverse momenta. The usage of timing information for such experiments can provide additional information that can be used to improve particle and jet reconstruction, as well as to reduce background events. For example, high-precision timing will be beneficial for b-tagging for all post-LHC experiments. For CLIC and FCC, high-precision time stamping of calorimeter energy deposits will be essential for background rejection (i.e. fake energy deposits) and pile-up mitigation. Precise timing information is important for improving reconstruction of particle flow objects by reducing overlap of energy showers in highly-granular calorimeters.

From the physics point of view, timing layers can be used for detection of long-lived particles and identification of standard model (SM) particles. At this moment, conceptional design reports for future experiments have not yet fully explored the benefits of the time of flight (TOF) measurements with tens-of-picosecond resolutions for calorimeters.

In this paper we will investigate the benefits of the timing layers with the resolution in the range 10 ps – 1 ns for identification of SM particles. The resolution of 1 ns is standard for the existing and planned calorimeters [1, 2, 3, 4], and is only used as a benchmark for comparisons with more challenging 10 – 20 ps resolution devices. In addition, we investigate the capabilities of timing layers for identification of heavy stable

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31 particles which may be produced beyond the standard model (BSM). We hope such
32 studies can help shape the requirements for future calorimeters, which were already
33 outlined in the CPAD report [5] that emphasized the need to develop fast timing
34 readout for calorimeter measurements.

35 2. Proposal

36 A generic design of hadronic (electromagnetic) calorimeters for future particle colli-
37 sion experiments (HE-LHC, FCC, CLIC, ILC etc.) is based on two main characteristics:
38 (1) high-granularity electromagnetic (ECAL) and hadronic (HCAL) calorimeters with
39 cells ranged from $3 \times 3 \text{ mm}^2$ to $5 \times 5 \text{ cm}^2$. (2) timing with a nanosecond precision
40 that improves background rejection, vertex association, and detection of new particles.
41 According to the CPAD report [5], a development of “picosecond time resolution” for
42 future calorimeters is one of the critical needs. Presently, high-granularity calorime-
43 ters with > 1 millions channels and with tens of pico-second resolution represent a
44 significant challenge due to the large cost.

45 As a part of the HL-LHC upgrade program, CMS and ATLAS experiments are
46 designing high-precision timing detectors with the time resolution of about 30 ps [6, 7].
47 They are based on silicon sensors that add an extra “dimension to event reconstruction.

48 As discussed above, such timing capabilities have not been fully explored for future
49 detectors beyond the HL-LHC upgrade. In particular, the baseline designs of the ECAL
50 and HCAL of the CLIC/FCC detectors have not been optimized for precision timing in
51 the range of a few tens of picoseconds. The latter is considered as an expensive option
52 for many millions of the channels of these highly granular detectors. This opens an
53 opportunity to investigate a cost-effective “timing layer” (with the time resolution of
54 smaller than 30 ps) for the post-LHC detectors. This layer will be installed in front of
55 high-granularity calorimeters, covering both the forward and barrel regions.

56 In this paper we will investigate the physics advantages of installing timing layers
57 in the front of calorimeters of the post-LHC experiments. Typically, thin detectors in
58 front of calorimeters are called “preshower”, and they have been previously installed
59 for the ZEUS, CDF, ATLAS and CMS experiments. The design goal of such detectors
60 is to count the number of charged particles in order to correct for energy losses. The
61 timing information of “MIP” (minimum ionizing particles) is not used for particle iden-
62 tifications, nor precise timing. Unlike the standard preshower detectors, we propose to
63 not only count MIP signals, but also reconstruct high-precision timing and the posi-
64 tion of the MIPs. This timing detector will have a similar granularity as the proposed
65 high-granularity electromagnetic calorimeters, but will have the sensor technology and
66 the readout that are best suited for time stamping of MIP signals. Our proposal is to
67 enclose the EM detectors with two timing layers, one - before the first EM layer, and
68 the other is after the last ECAL layer (but before the HCAL). The two layers of the
69 timing detector allow a robust identification of time stamps by correlating the position
70 and time of the particles passing through the ECAL.

71 In this paper we will explore this idea using a semi-analytical approach and Monte
72 Carlo simulations. A schematic representation of the positions of the timing layers for
73 a generic detector geometry is shown in Fig. 1. In the following, the first timing layer

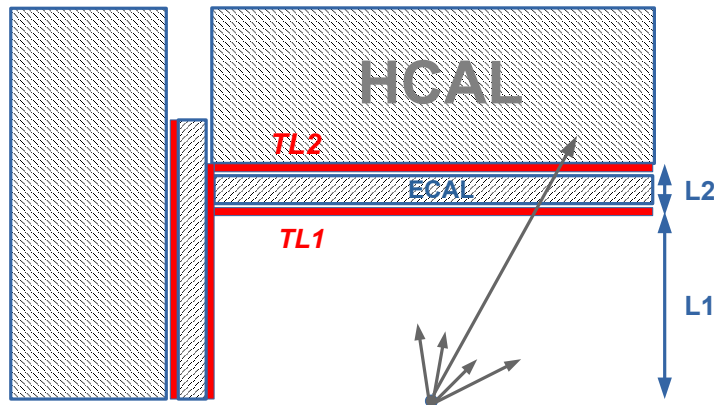


Figure 1: An example of positions of the thin timing layers for a generic detector. The thin timing layers will enclose the electromagnetic calorimeter, allowing a reliable reconstruction of the MIP signals with a timing resolution of the order of 10 ps.

(closest to the interaction point) will be called TL1, while the second timing layer after the electromagnetic calorimeter will be called TL2.

There are several reasons why the second timing layer (TL2) can be useful:

- It can be used to measure the TOF between TL2 and TL1 for identification of stable massive particles without known production vertex. This is especially important for the BSM models predicting stable heavy particles decaying close to the surface of the electromagnetic calorimeter.

For a typical ECAL based on the silicon technology, the distance between TL2 and TL1 is 0.2 – 0.4 m (depending on the calorimeter design). It is not immediately obvious that such a small distance can be used for physics measurements. A particle traveling with the speed of light can cross the distance between TL1 and TL1 within ~ 1 ns. As we will discuss later, this distance is sufficient to provide a large acceptance for heavy particle identification assuming a 10 – 20 ps detectors.

- The second layer is useful in the cases when a long-lived particle (neutral or charged) is produced without precise knowledge of the primary vertex (0,0,0) due to the beam (or pileup) smearing.

- It allows to correlate the hits with the first layer, and thus provides directionality of the hits. This feature can be useful to match the hits with the calorimeter cells and to deal with back-scatter hits which are typically arriving from the hadronic calorimeter at later time.

- It provides the redundancy for the calculation of TOF using the distance from the interaction point which can be determined using tracks.

The second layer of the timing detector can be justified if the recorded time difference between the first and the last ECAL layers of the electromagnetic showers is not significantly different from that expected from a particle traveling with the speed of light. If the travel time is significantly affected by large fluctuations caused by electromagnetic showers, second timing layer cannot effectively be used.

In order to verify this point, we used a full Geant4 (version 10.3) [8] simulation of the SiFCC detector [9] that allows to use the information of the ECAL hits. This detector design has an ECAL built from a highly segmented silicon-tungsten cells with the transverse size of 2×2 cm. The ECAL has 30 layers of tungsten pads with silicon readout, corresponding to $35 X_0$. The first 20 layers use tungsten of 3 mm thickness. The last ten layers use tungsten layers of twice the thickness, and thus have half the sampling fraction. The distance between the centers of the last and first ECAL layer is about 240 mm.

To verify that the time differences between the last and the first ECAL layer is close to the time required for a particle that travels with the speed of light, and can be neglected for the timing layers that have a timing resolution of the order of 1 ns, a sample of single pions (π^\pm) was created with 1 and 10 GeV momentum, respectively. The pseudorapidity for all pions was $\eta = 0$ (central region). The particles were reconstructed in the ECAL calorimeter, and the time difference $\Delta T = T_{\text{last}} - T_{\text{first}}$ of the hits between the last and first ECAL layers was calculated. Only the hits arriving first in time were considered since the electronics typically register¹ the fastest hits (while slower hits can be saved in pipeline buffers).

Figure 2 shows the time distribution of first arriving hits for 1 and 10 GeV pions. It can be seen that the peak positions of the distributions are smaller than 1 ns, as expected for the distance of about 20 cm between the centers of the last and first ECAL layers. Therefore, the hits registered by TL1 and TL2 will be simultaneous for the standard 1 ns resolution readout. They will be fully correlated in time, and are identified as a single crossing particle.

If a resolution of the timing layer is of the order of 10 – 20 ps, a physics measurement of TOF would be possible. To check this, Figure 2 shows the hit distribution for (anti)deuterons, denoted as d^\pm . The distributions are significantly different from the π^\pm case. According to the simulation, the 1 GeV (anti)deuterons should be measured on average with the time delay of 0.7 – 1.4 ns between the last and first layers. The value of 0.7 ns was estimated from the mean position of the Landau distribution used to fit the d^\pm curve presented in Figure 2(a), while 1.4 ns was obtained from the mean of this distribution. Even for the most conservative 0.7 ns value, there is an indication that 1 GeV deuterons can be separated from pions that have 0.5 ns time difference. Such a separation can be observed when using a tens-of-picosecond detector. For the 10 GeV particles presented in Figure 2(b), no separation between d^\pm and π^\pm can be observed.

In summary, we have illustrated that a typical difference between TL2 and TL1 (which is approximated by the difference between the last and first ECAL layer) is

¹The Monte Carlo studies used in this paper does not include simulations of calorimeter electronics.

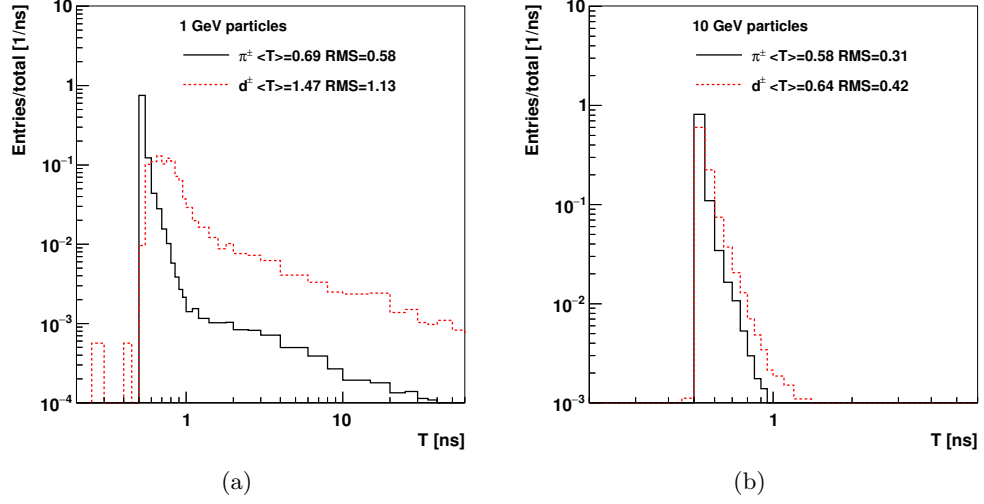


Figure 2: The difference between time of hits between the last and first layer of ECAL for single pions and deuterons with a transverse momentum of (a) 1 GeV and (b) 10 GeV. Only first (fastest) hits were considered to calculate the difference in TOF.

138 sufficient for particle identification using the TOF. As an example, a d^\pm can be identified
 139 and separated from pions for the momentum less than 1 GeV. This means that particles
 140 heavier than deuterons should be identified for a momentum larger than 1 GeV. In the
 141 following, we will abstract from the Geant4 simulations and calculate the kinematic
 142 regions where the identification of heavy stable particles using timing layers is possible.

3. Timing layers for single particles

Now let us discuss the kinematic regions for the TOF measurements in relation to either SM particles or BSM particles. Instead of the full Geant4 simulations, we will use a semi-analytic approach.

For an estimation of the separation power between different mass hypotheses, we will calculate the mass and momentum for which one can achieve a separation significance higher than 3σ (or $p\text{-val} < 0.03$). If there are two particles with a mass m and a reference (fixed) mass m_F , the 3σ separation can be achieved for this condition [10]:

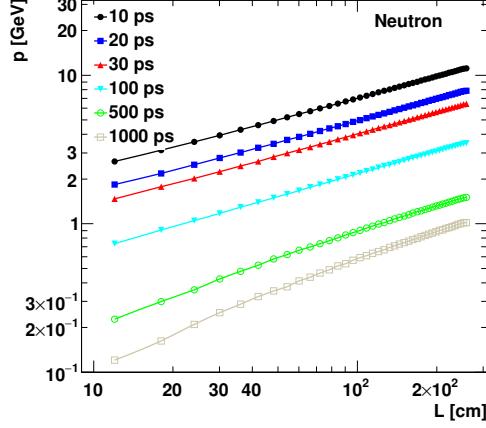
$$\frac{L}{c\sigma_{\text{TOF}}} \left| \sqrt{1 + \frac{m^2}{p^2}} - \sqrt{1 + \frac{m_F^2}{p^2}} \right| > 3 \quad (1)$$

where p is the momentum of a particle with a mass m , L is the length of the particle's trajectory, and σ_{TOF} is the resolution of the timing layer that measures the TOF.

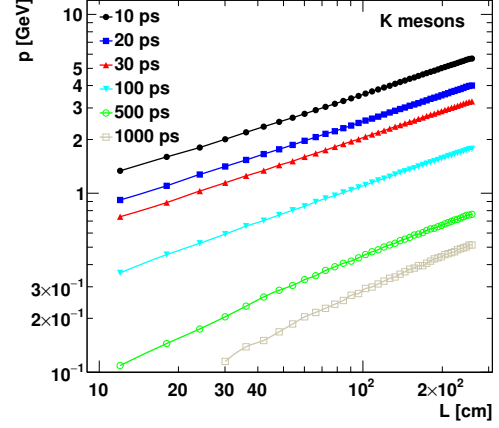
Figure 3 shows the 3σ separation from the pion mass hypothesis ($m_F = m_\pi$) using the same procedure as discussed in [10]. The calculations are performed for several options for the resolution of the timing layer, from 10 ps to 1 ns, as a function of the travel length L and the momenta. For a 20-ps detector and for a typical travel distance of $L \sim 1.5 - 2$ m from the interaction point to the electromagnetic calorimeter, neutrons (and protons) can be separated from the pion hypothesis up to 7 GeV. The separation of K -mesons can be performed up to 3 GeV. This momentum range should be sufficient for a reliable particle identification in a wide momentum range for physics studies focused on single-particle reconstruction. This can also be used for jets that are dominated by this momentum range of separate particles. For a detector with a 1 ns, the separation can only be possible up to 300 – 500 MeV. This is smaller than a typical minimum momentum of 0.5 GeV for particles considered for high-energy proton colliders. Therefore, a timing layer with 1-ns resolution cannot effectively be used for particle identification in such experiments.

Having discussed a rather classical case of identification of neutrons (or protons) and the K -mesons from the pion hypothesis, let us turn to the BSM searches for heavy particles. The most abundant SM background for light BSM particles from primary interactions are protons and neutrons. Other stable particles, that can be produced mainly in detector material (or in the interactions in the beam pipe) and detected by calorimeter are deuterons and α particles (composed of two protons and two neutrons). Although the rate of the α particles is low since they can easily be stopped by detector material, it is not impossible that the residual rate of such particle may still represent background for BSM searches that have a small production rate. Therefore, we will choose $m_F = m_\alpha \simeq 3.73$ GeV as a reference² in Eq. 1, and evaluate the 3σ separation for a wide range of masses and momentum starting from 4 GeV. For many planned experiments the distance between the interaction point and the first layer of the electromagnetic calorimeter is 1.5 – 2.5 m. Therefore, for a representative purpose, we will use $L = 2$ m and consider 0.2 m for the separation distance between the TL2 and TL1 timing layers.

²We should emphasize that this choice of α particles for the reference mass scale is arbitrary and is only motivated by our attempt to check the 3σ separation in the momentum region < 10 GeV.

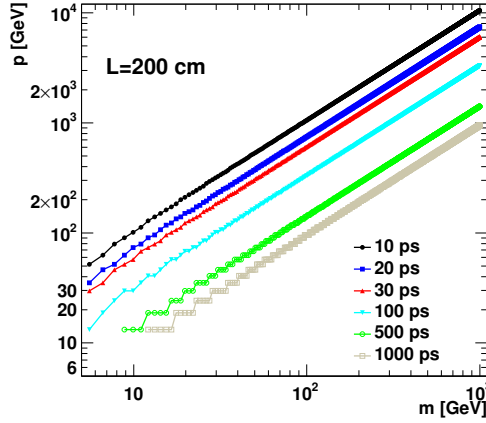


(a) Neutrons

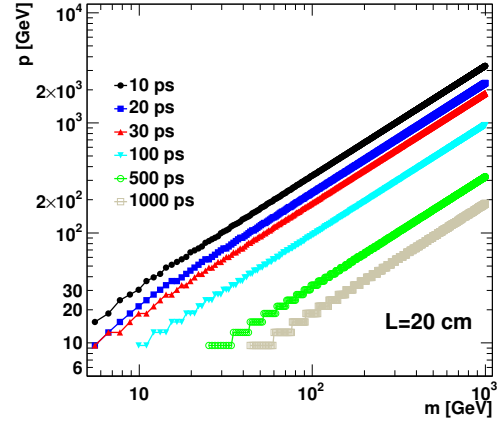


(b) K -mesons

Figure 3: The 3σ separation from the pion mass hypothesis for neutrons and K -mesons as a function of the length of the particle's trajectory L and the momentum p . For neutral particles the value of L approximately corresponds the distance between the interaction point and the surface of the ECAL for $\eta = 0$.



(a) for $L = 2$ m



(b) for $L = 0.2$ m

Figure 4: The 3σ separation from α particles for heavy particles assuming timing layers with different resolutions for TOF, and using (a) $L = 2$ m and (b) $L = 0.2$ m. The first value of L approximately equals to a typical distance from the interaction vertex to the first layer TL1, while the second value is the typical distance between two timing layers enclosing an electromagnetic calorimeter, assuming a typical calorimeter based on the silicon technology.

Figure 4 shows the particle identification power for different choices of the timing layer resolution and the travel distance L (see Fig. 1). For $L = 2$ m, which approximately corresponds to the distance from the interaction point and the TL1 when a particle travels at $\eta = 0$, one can see that a stable heavy particle with a mass of 100 GeV can be reconstructed up to 400 GeV assuming a 20-ps timing layer, but only up to 50 GeV using the standard 1-ns readout for time measurement.

In the case when TOF is measured between the two layers, TL1 and TL2, assuming a successful spacial match of the hits, the knowledge of the interaction vertex is not required. This type of measurements can be beneficial for neutral particles in collisions with large pile-up (multiple number of vertexes). The identification power in the case when the travel distance $L = 0.2$ m, i.e. when it is close to the distance between TL2 and TL1, is shown in Figure 4(b). For a stable particle with a mass of 100 GeV, the identification is possible up to 100 GeV in momentum. The standard calorimeter with 1 ns resolution can only perform the identification up to 20 GeV.

4. Showcase for the Dark QCD model

The arguments discussed before can be illustrated using a concrete physics scenario for BSM models. In particular, we will consider the dark QCD model [11, 12]. It predicts the existence of the so-called “emerging” jets that are created in the decays of new long-lived neutral particles (dark hadrons), produced in a parton-shower process by dark QCD. The process includes two mediators with masses Mx , each of which decays promptly to a SM quark and a dark quark. The final-state signature consists of four jets with high transverse momenta, with two “emerging” jets originating from “dark” quarks. Such jets contain many displaced vertices arising from the decays of the dark pions produced in the dark parton shower.

Recently searches for the emerging jets in pp collisions have been performed [13] by the CMS Collaboration. The emerging jet contains multiple displaced vertices and multiple tracks with large impact parameters. Assuming that the mass of the dark pion is 5 GeV, the signal acceptance using this approach does not exceed 40% at large masses of the mediators (see Figure 4 of [13]). The decay length of a dark pion defines the distance from the interaction vertex of pp collisions to the point where the jet emerges. The emerging jet contains multiple displaced vertices that are reconstructed using a tracker [13].

Alternatively, emerging jets can be reconstructed using calorimeters with high-resolution time measurements. This method is expected to have advantages for the measurements of dark pions with a large decay length, i.e. in the situations where the tracker has a low reconstruction acceptance and resolution since only a few outer layers can be used for track reconstruction. It was also pointed out [12] that the emerging jets may have significant fraction of neutral particles and the reconstruction using charged tracks can have a low acceptance.

To estimate the performance of the timing layers in reconstructing emerging jets, we will use the same Monte Carlo settings as for Ref. [13]: The pp collision event samples were generated with the “hidden valley” model framework in PYTHIA 8.2 assuming a centre-of-mass energy of 13 TeV and a fixed mass of 5 GeV for the dark pions. The

samples were created after changing the decay distance $c\tau$ of the dark pions. The mass Mx of the mediator was also varied.

To calculate the detector acceptance, the semi-analytical formalism based on Eq. 1 is used. In this relation $L = c\tau$ is the distance traveled by the dark pion with a mass m before it decays to the emerging jet. After the dark pion creates a SM jet, we assume that such emerging jets travel to the surface of the timing layer with the speed of light for all values of m . This is naturally to expect since the emerging SM jets consist of light stable particles (mostly photons and pions).

For the timing layers, the signature of emerging jets is time delays compared to the other SM jets. The production vertex cannot be observed by the timing layers if such jets emerge before TL1. After events are generated, the weighted averages of the decay distances of all particles that originate from the dark pions, using the particle momentum as the weight, were calculated. This decay distance is used to approximate the decay length, without using applying a jet reconstruction. The calculation for the 3σ separation assumes $m_F = m_\alpha \simeq 3.73$ GeV although such a choice can be rather arbitrary. This value of m_F is used to give a conservative³ estimate of the arrival time of the emerging SM jets.

The acceptance of reconstruction of the emerging jet events was calculated by counting the number of events that pass the Eq. 1 condition with the parameters as discussed before, divided by the total number of entries without this requirement. Figure 5 shows the acceptance as a function of the mediator mass Mx and the decay distance of the dark pions. This figure can directly be compared to the similar acceptance figure for the method based on tracks [13]. The acceptance based on the TOF is significantly larger for low Mx and large $L = c\tau$ of the dark pions, compared to a similar acceptance distribution based on tracking information. The acceptance is larger for the timing layers with a resolution smaller than 100 ps, than for the standard 1-ns calorimeter resolution.

Now we will be interested in the acceptance of the reconstruction of dark pions as a function of their mass and their lifetime assuming a fixed mass Mx of the mediator. This time we will consider the HE-LHC environment with pp collisions at a centre-of-mass energy of 27 TeV. The Monte Carlo settings for the signal model were similar to those discussed in [13, 14]. The mass of the mediator was set to 10 TeV, while the mass of the dark pion was varied in the range between 5 GeV and 1 TeV. The dark pion decay length, $c\tau$, was varied between 1 mm and 1000 mm (independent of its mass). Other parameters were also appropriately modified to allow a sufficient phase space for the dark meson production. The mass of the dark pion is assumed to be one half the mass of the dark quark. The mass of the dark ρ is four times of the dark pion mass. The width of the mediator particle is assumed to be small as compared to the detector mass resolution.

As before, the acceptance of reconstruction of the emerging jets by measuring the timing information was calculated by counting the number of events that pass the Eq. 1 condition with the parameters as discussed before, divided by the total number of entries without this requirement. Figure 6 shows the efficiency as a function of $c\tau$

³One can argue that the SM jets mainly consist of light-flavour hadrons and photons, therefore, m_F is significantly lower.

and the mass of the dark pion. It can be seen that a detector with the standard 1-ns resolution does not have acceptance for the dark meson measurements. The acceptance is significantly larger for the timing layers that have a resolution smaller than 100 ns. The acceptance is small for small $c\tau$ or small masses, which is the expected feature of the timing measurement. The timing layers with 20-ps resolution have 100% acceptance for large values of $c\tau$ and dark-meson masses. The efficiency as a function of the particle velocity for the timing layers with the 20-ps and 1-ns resolutions is shown in the [Appendix A](#).

Note that the obtained results are relatively general since they are formulated in the terms of masses and decay lengths, i.e. independent of the position of the timing layers and other details relevant to the detector geometry.

5. Summary

This paper discusses the benefits of the timing layers positioned in front of the hadronic calorimeters. Using the full Geant4 simulations and a semi-analytic approach, the figures of merits for identification of single particles using timing layers with resolutions of 10 ps – 1 ns were calculated. It was illustrated how such layers can be used for single particle identification and identification of heavy long-lived particles in the context of the dark QCD model. It was shown that the timing layers lead to a significant benefit for reconstruction of heavy long-lived particles in the region of $c\tau$ and momentum where track measurements have low reconstruction acceptance.

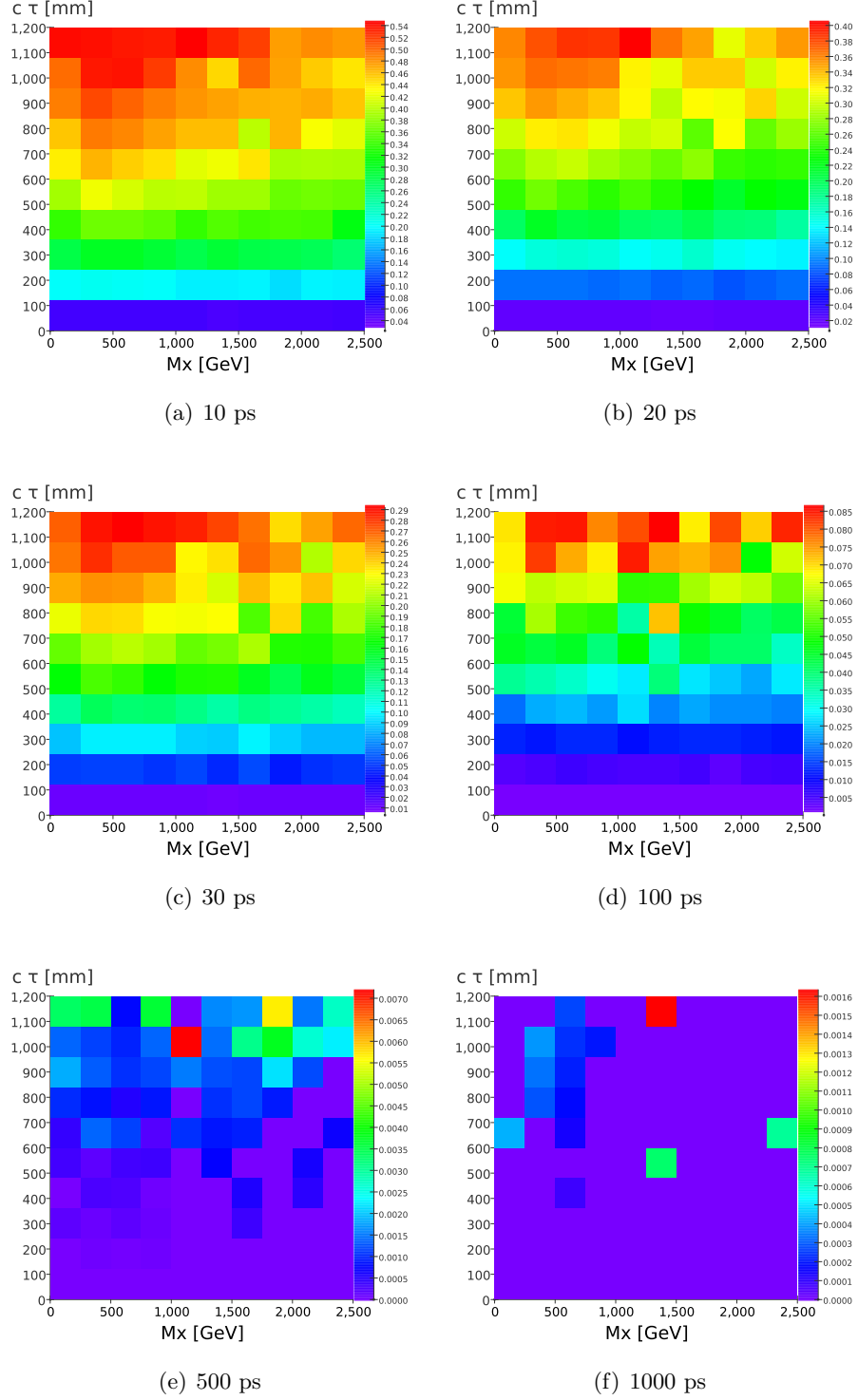


Figure 5: The acceptance for the reconstruction of emerging jets using the timing layers with different timing resolutions as a function of the mediator mass Mx and the $c\tau$ of the dark pions with the mass of 5 GeV. The PYTHIA8 simulations are performed for the pp collisions at $\sqrt{s} = 13$ TeV.

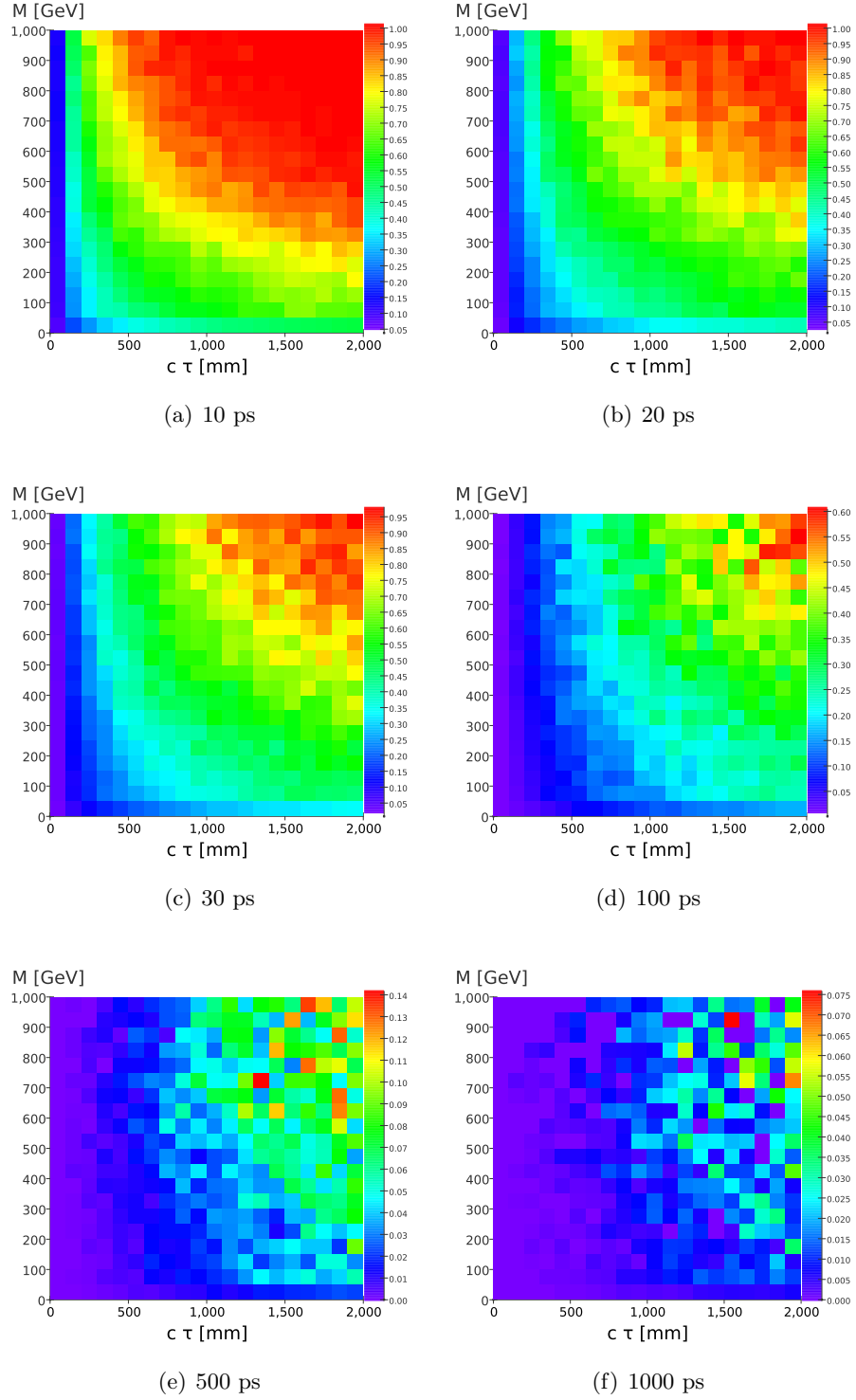


Figure 6: The acceptance for the reconstruction of emerging jets using the timing layers with different timing resolutions as a function of the mass of the dark pions and their $c\tau$. The mediator mass was fixed to 10 TeV. The PYTHIA8 simulations are performed for the pp collisions at $\sqrt{s} = 27$ TeV.

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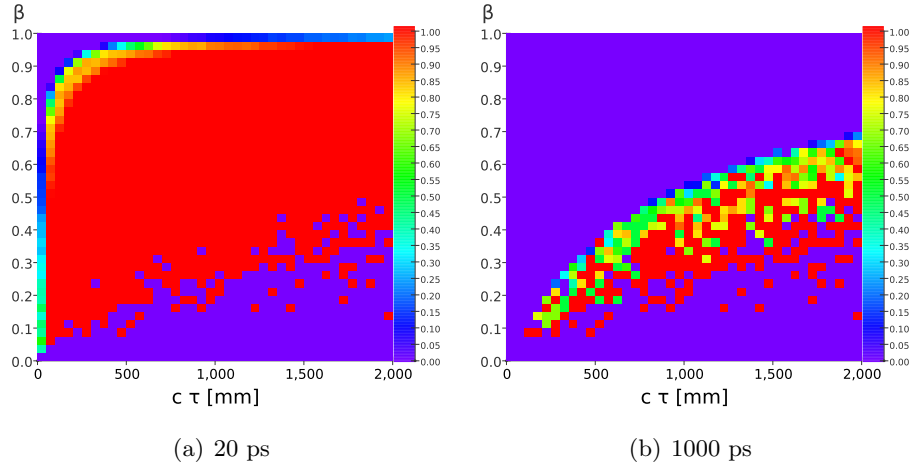


Figure A.7: The efficiency for the reconstruction of emerging jets using the timing layers with different timing resolutions. The plot shows the efficiency as a function of $c\tau$ and the particle velocity β

327 Appendices

328 Appendix A. Appendix

329 Figure A.7 shows the reconstruction efficiency as a function of $c\tau$ and the particle
 330 velocity $\beta = |p|/E$, for the two extreme cases of the timing layers.