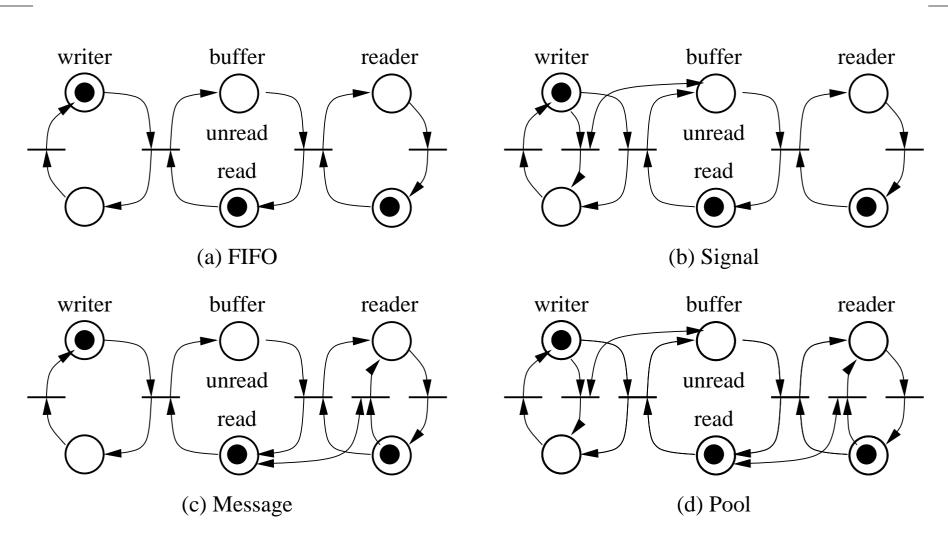
EEE8068 **Real Time Computer Systems ACM models and code examples**

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Taxonomy with Petri nets



Single atomic slot in the middle.

If not atomic, then multiple slots are needed. Why?

ACM FIFO type, 1 slot

```
Process Write:
do forever
{
   wait_until(f=0)
   write_slot();
   f:=1;
}
```

```
Process Read:
do forever
  {
    wait_until(f=1);
    read_slot();
    f=0;
}
```

- Waiting possible on both sides
- No overwriting, no re-reading
- What to protect with critical sections?

ACM Signal type, 3 slots

```
Process Write:
w:=1;
1:=2;
do forever
{
    write_slot(w);
    1:=w;
    w:=¬(r,1);
}
```

```
Process Read:
r:=2;
do forever
{
   wait_until (l<>r)
   r:=1;
   read_slot(r);
}
```

- Waiting possible on the reader side only
- Overwriting possible, no re-reading
- What to protect with critical sections?
- What about the 2-slot signal? Unnecessary delay possible!

ACM Signal type, 2 slots

```
Process Write:
w := 0;
do forever
{
    write_slot(w);
    w := not r;
}
```

```
Process Read:
r := 1;
do forever
{
    r := not r;
    wait_until (w<>r)
    read_slot(r);
}
```

- Waiting possible on the reader side only
- Overwriting possible, no re-reading
- What to protect with critical sections?
- What causes unnecessary delay?

ACM Pool type, 3 slots

```
Process Write:
do forever
{
  write_slot(n);
  l:=n;
  n:=¬(l,r);
  {
```

```
Process Read:
do forever
{
  r:=1;
  read_slot(r);
}
```

- n, I and r are ternary variables (1, 2, 3)
- initialise n:=1, l:=2
- Waiting not allowed
- Overwriting and re-reading
- What to protect with critical sections?

What to do next?

- Motivation: try the demo, review Delay Differential Equations, construct an example of a control system that becomes unstable under increased latency
- Review the concept of ACM
- Review ACM taxonomy and Petri net models for a single atomic slot
- Read the original papers on ACM; they are on Blackboard
- Review the pseudo code discussed in this lecture