

# Inference (learning)

Given a sample  $X_1, X_2, \dots, X_n \sim F$ ,

how do we infer  $F$ ?

Def Statistical model = set of distributions  
(or densities, regression fns, etc)

Def parametric model = set of distributions  
parametrized by a finite # of parameters

Ex.

$$\mathcal{F} = \left\{ f_{\mu, \sigma^2}(x) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right) : \mu \in \mathbb{R}, \sigma^2 > 0 \right\}$$

In general, we write

$$\mathcal{F} = \{f_\theta(x) : \theta \in \Theta\}$$

↖ parameter space

$$P_\theta[A] := \int_A f_\theta(x) dx \quad \mathbb{E}_\theta[r(X)] = \int r(x) f_\theta(x) dx$$

Def non-parametric model = model that's not parametric

Ex.  $X_1, X_2, \dots, X_n$  correspond to flips of a coin (i.e. Bernoulli RV). The goal is to estimate parameter  $p = \text{prob. of heads}$ .

Ex.  $X_1, X_2, \dots, X_n \sim F$ , Goal is to approximate  $F$ .

Ex.  $\begin{pmatrix} X_1 \\ y_1 \end{pmatrix}, \begin{pmatrix} X_2 \\ y_2 \end{pmatrix}, \dots, \begin{pmatrix} X_n \\ y_n \end{pmatrix}$  pairs of data

Goal is to approximate  $v(x) = \mathbb{E}[Y | X=x]$

$X_i = \text{"features"}$  (image of pixels)

$y_i = \text{"output"}$  (age)

May assume  $v(x)$  has the form of a neural network  $n_\theta$

$$\left( n_\theta = \sigma(Ax + b), \quad \theta = [A, b] \right)$$

## Point estimation

point estimate = "best guess" of some quantity of interest

- $\theta$ : unknown fixed parameter
- $\hat{\theta}_n$ : point estimate of  $\theta$  from data  $X_1, \dots, X_n$ 
  - This is a random variable

### Assumption

Samples  $X_1, X_2, \dots, X_n$  drawn iid from some  $f_\theta(x)$  where  $\theta \in \Theta$

Def  
We say  $\hat{\theta}_n$  is unbiased if  $\mathbb{E}[\hat{\theta}_n] = \theta$

Def  
We say  $\hat{\theta}_n$  is consistent if  $\hat{\theta}_n \xrightarrow{P} \theta$

Ex.  $S_n^2 = \frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{X}_n)^2$

- $\mathbb{E}[S_n^2] = \sigma^2 \Rightarrow S_n^2$  is unbiased
- $V[S_n^2] \rightarrow 0 \Rightarrow S_n^2$  is consistent

Def The standard error of a point estimator  $\hat{\theta}_n$  for  $\theta$  is

$$se(\hat{\theta}_n) = \sqrt{V[\hat{\theta}_n]}.$$

Def The mean squared error of a point estimate  $\hat{\theta}_n$  for  $\theta$  is

$$MSE = \mathbb{E}_{\theta}[(\hat{\theta}_n - \theta)^2]$$

↑

expectation w.r.t. distribution  $f_{\theta}(x_1, \dots, x_n) = \prod_{i=1}^n f_{\theta}(x_i)$

Ex.  $X_1, \dots, X_n \sim \text{Ber}(p) = \begin{cases} 1 & \text{w.p. } p \\ 0 & \text{o.w.} \end{cases}$

$$\hat{p}_n = \frac{1}{n} \sum_{i=1}^n X_i$$

- is  $\hat{p}_n$  unbiased?  
 $\mathbb{E}[\hat{p}_n] = \frac{1}{n} \sum_{i=1}^n \mathbb{E}[X_i] = \frac{1}{n} \sum_{i=1}^n p = p$  ✓
- what is  $se(\hat{p}_n)$ ?  
 $\sqrt{V[\hat{p}_n]} = \sqrt{\frac{1}{n} \sum_{i=1}^n V[X_i]} = \sqrt{\frac{1}{n} (1-p)p}$



## Theorem

$$\mathbb{E}_\theta[(\hat{\theta}_n - \theta)^2] = \underbrace{\mathbb{E}[\hat{\theta}_n - \theta]^2}_{(\text{bias})^2} + \mathbb{E}[(\hat{\theta}_n - \mathbb{E}\hat{\theta}_n)^2] \quad (\text{variance})$$

## Theorem

bias  $\rightarrow 0$ , se  $\rightarrow 0 \Rightarrow$  consistent

## Def

An estimator is asymptotically normal if

$$\frac{\hat{\theta}_n - \theta}{\text{se}(\hat{\theta}_n)} \xrightarrow{d} N(0, 1)$$

Ex  $\hat{p}_n$  from previous example (CLT)

## Confidence Sets

Def. A  $1-\alpha$  confidence interval for a parameter

$\theta$  is an interval  $C_n = (a_n, b_n)$ , where  $a_n, b_n$  are functions of  $X_1, \dots, X_n$  st.

$$P_\theta[\theta \in C_n] \geq 1 - \alpha \quad \forall \theta \in \Theta$$

$C_n$  = random

$\theta$  = fixed