## 状态矩阵

0	0	0	2	-1	-1	-1	0
0	0	0	2	-1	-1	-1	0
0	2	2	1	71	1	1	0
0	2	2	1	1	1	1	2
0	0	0	1	1	1	1	2
0	0	0	1	1	1	1	2
0	0	0	0	0	1	1	2

## 道路过宽判别矩阵

0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0

