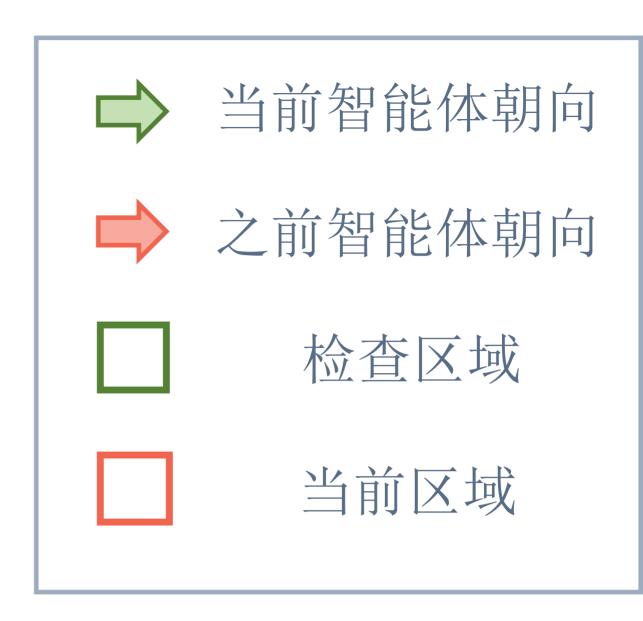
状态矩阵

0	2	2	2	-1	-1	-1	0
0	2	2	2	-1	-1	-1	0
2	1	71	1	1	1,	1	0
2	1	1	1	1	1	1	2
2	1	1	1_	1	1	1	2
2	1	1	1	1	1	1	2
2	1	1	1_	1	1	1	2
2	1	1	1	1	1	1	-2



道路过宽判别矩阵

0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0