DO YOU REALLY NEED

HELP FOR SUCH QUESTIONS?

• 1 (b) ___ (2) |

Because it is very convenient from or mothematical point of view. It is nothing but the overage "Euclidean olistance" between the output and input images. As such, it is based on the L2 morm, which is the standard measure of "length" in vector spaces

• 2 (a) ___ (1), (2) I

Similar to One of the Exams in 2011/2012: 2(c). BUT there are three significant olifferences:

* A - the type of data: 2D image vs 1D signal;

* B - their functional form,

owvoy from the breakdown point:

not given us polynomial;

* C- the number of continuous observatives, away from the breakdown point: 7 vs 3.

How do such differences ofter the solution?

I will not "spoom-feed" you with more help, since all such points hove been thoroughly discussed ofwins the course.