# YUCHEN WU

Toronto, Ontario, Canada

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https://cheneyuwu.github.io/

#### ACADEMIC HISTORY

# MASc in Aerospace Science and Engineering

Sept. 2020 - Present

University of Toronto Institute for Aerospace Studies (UTIAS), Canada

Supervisor: Prof. Timothy D. Barfoot

Thesis: VT&R3: Generalizing the Visual Teach & Repeat Navigation Framework

# BASc in Engineering Science (Robotics)

Sept. 2015 - Apr. 2020

University of Toronto, Canada

CGPA: 3.93 / 4.0, graduated with High Honours

Supervisor: Prof. Florian Shkurti and Prof. Jonathan Kelly

Thesis: Combining Reinforcement Learning and Imitation Learning through Reward Shaping for Continuous Control

### EMPLOYMENT HISTORY

# Intel Corporation, Toronto, Canada

May 2018 - May 2019

Software Engineer Intern

Product: Intel HLS Compiler and Intel FPGA SDK for OpenCL

- Intel HLS Compiler: a high-level synthesis (HLS) tool that takes in untimed C++ code and generates productionquality register transfer level (RTL) code optimized for Intel FPGAs
- Intel FPGA SDK for OpenCL: development environment that enables software developers to accelerate applications by targeting heterogeneous platforms with Intel CPUs and FPGAs.

## **SKILLS**

Communication Mandarin, English

**Programming** C/C++, Python, JavaScript, Java

Software/Libraries MATLAB, Robot Operating System (ROS), MuJoCo, OpenCV, PyTorch, TensorFlow

#### **PUBLICATIONS**

### Are We Ready for Radar to Replace Lidar in All-Weather Mapping and Localization?

Keenan Burnett\*, **Yuchen Wu\***, David J. Yoon, Angela P. Schoellig, Timothy D. Barfoot

Accepted to IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2022

# Boreas: A Multi-Season Autonomous Driving Dataset

Keenan Burnett, David J. Yoon, **Yuchen Wu**, Andrew Zou Li, Haowei Zhang, Shichen Lu, Jingxing Qian, Wei-Kang Tseng, Andrew Lambert, Keith Y.K. Leung, Angela P. Schoellig, Timothy D. Barfoot Submitted to *International Journal of Robotics Research (IJRR)* 

# Shaping Rewards for Reinforcement Learning with Imperfect Demonstrations using Generative Models

Yuchen Wu, Malissa Mozifian Florian Shkurti

IEEE International Conference on Robotics and Automation (ICRA), 2021

#### OPEN-SOURCE PROJECTS

## Visual Teach and Repeat 3 (VT&R3)

# https://github.com/utiasASRL/vtr3

• An end-to-end navigation system for long-range and long-term mobile robot path following using a lidar, radar, or camera as the primary sensor.

#### **AWARDS**

Vector Scholarship in AI, Vector Institute	2020
CRA Outstanding Undergraduate Researchers Honorable Mentions	2020
University of Toronto Dean's Honours List	2015 - 2020
University of Toronto Excellence Awards (UTEA)	2019
${\bf Garnet\ W.\ Mckee\ -\ Lachlan\ Gilchrist\ Scholarship},\ {\bf Uof T}$	2017

### STUDENT ACTIVITIES

## UofT aUToronto Team, Student Advisor,

Sept. 2021 - Jun. 2022

• 1st place overall in the first competition of the four-year SAE AutoDrive Challenge Series II.

# ROB310 Mathematics for Robotics, Teaching Assistant

Fall 2021

## University of Toronto, Research Assistant

May 2019 - Sept. 2019

- Supervisor: Prof. Florian Shkurti at the Department of Computer Science
- Worked on reinforcement and imitation learning for control.

### UofT Machine Intelligence Student Team, Academic Lead

Sept. 2018 - May 2019

- Built a machine learning community for undergrad students.
- Organized MIST101, a workshop on machine learning fundamentals.

# University of Toronto, Research Assistant

May 2017 - Sept. 2017

- Supervisor: Prof. Jianwen Zhu at the Department of Electrical and Computer Engineering
- Worked on accelerating the training and inference of deep CNN on multi-core CPU.

# National University of Singapore, Research Assistant

May 2016 - July 2016

- Supervisor: Prof. Shailendra Joshi at the Department of Mechanical Engineering
- Worked on computational modeling and analysis of nano/micro lattice structure.