



Final year Ph.D. in Computer Science

Education

Stanford University - Sep 2023 - Current

Student of New Faculty (SNF) in Electrical Engineering

Robotics and Embodied Artificial Intelligence Lab, Shuran Song

Columbia University - Jan 2021 - Current

Ph.D. candidate in Computer Science

Columbia Artificial Intelligence and Robotics Lab, Shuran Song

GPA: 4.02/4.0

Publications

Universal Manipulation Interface

ArXiv Preprint Webpage

Cheng Chi, Zhenjia Xu, Chuer Pan, Eric Cousineau, Ben Burchfiel, Russ Tedrak Shuran Song

Diffusion Policy: Visuomotor Policy Learning via Action Diffusion

2023 Robotics: Science and Systems (RSS) Webpage

Cheng Chi, Siyuan Feng, Yilun Du, Zhenjia Xu, Eric Cousineau, Ben Burchfiel, Shuran Song

RoboNinja: Learning and Adaptive Cutting Policy for Multi-Material Objects

2023 Robotics: Science and Systems (RSS) Webpage

Cheng Chi, Benjamin Burchfiel, Eric Cousineau, Siyuan Feng, Shuran Song

Cloth Funnels: Canonicalized-Alignment for Multi-Purpose Garment Manipulation

2023 International Conference on Robotics and Automation (ICRA) Webpage

Alper Canberk, Cheng Chi, Huy Ha, Ben Burchfiel, Eric Cousineau, Siyuan Feng, Shuran Song

Iterative Residual Policy

for Goal-Conditioned Dynamic Manipulation of Deformable Objects

2022 Robotics: Science and Systems (RSS) Webpage

Cheng Chi, Benjamin Burchfiel, Eric Cousineau, Siyuan Feng, Shuran Song

★ Best Paper Award ★ ★ Best Student Paper Award Finalist ★

DextAlRity: Deformable Manipulation Can be a Breeze

2022 Robotics: Science and Systems (RSS) Webpage

Zhenjia Xu, Cheng Chi, Benjamin Burchfiel, Eric Cousineau, Siyuan Feng, Shuran Song

★ Best Systems Paper Award Finalist ★

GarmentNets: Category Level Pose Estimation for Garments via Canonical Space Shape Completion

2021 The International Conference on Computer Vision (ICCV) Webpage

Cheng Chi, Shuran Song

Occlusion-robust Deformable Object Tracking without Physics Simulation 2019 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)

Cheng Chi, Dmitry Berenson Webpage

Awards

2022 Robotics: Science and Systems (RSS) Webpage

★ Best Paper Award

★ Best Student Paper Award Finalist

★ Best Systems Paper Award Finalist

Awards

2023 Nvidia Graduate Fellowship Finalist Webpage

Industry Experience

Toyota Research Institute - Jun 2023 - Aug 2023

Research Intern @ Large Behavior Model Team

· Developed Universal Manipulation Interface for large-scale in-the-wild data collection

Toyota Research Institute - Jun 2022 - Aug 2022

Research Intern @ Robotics Intuitive Physics Team

- · Studied imitation learning methods for contact-rich tasks
- · Built real-time control systems for robotics with GPU policy in-the-loop

Nuro Inc - Jan 2020 - Jan 2021

Software Engineer, Autonomy @ Mapping and Localization Team

• Developed mapping and localization system for Nuro's autonomous delivery vehicles

Apple Inc - May 2019 - Aug 2019

Engineering Intern @ Camera Architecture Team

• Developed software for simulating future camera systems

Uber Technologies - May 2018 - Jul 2018

Software Engineering Intern @ Maps Imagery Research Team

- · Developed an unsupervised learning algorithm to cluster and filter GPS trails
- Researched improving image-based SLAM with semantic segmentation

Services

Technical Paper Reviewer

- International Conference on Intelligent Robots and Systems (IROS)
- International Conference on Robotics and Automation (ICRA)