

Problem 0: Homework checklist

- ✓ I didn't talk with any one about this homework.
- ✓ Source-code are included at the end of this document.

Problem 1:

1. Function backsolve.m

```
1 function x = backsolve(A, b)
2     % Assume matrix A is n by n upper triangular matrix;
3     % Vector b is n by 1.
4     n = length(b) ;           %% Get the length of the vector b
5     x = zeros(n,1);           %% initiate solution Xl
6     x(n) = b(n)/A(n,n);       %% For the base case, x(n) = ...
                                b(n)/A(n,n);
7     for i=n-1:-1:1
8         temp = 0;
9         for j = i:n
10            temp = temp + A(i, j)*x(j);    %% Accumulate all ...
                                           the other terms
11        end
12        x(i) = (b(i)-temp)/A(i,i);    %% solve X(i)
13    end
14 end
```

Function forwardsolve.m:

```
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2     % Assume matrix A is n by n upper triangular matrix;
3     % Vector b is n by 1.
4     n = length(b) ;           %% Get the length of the vector b
5     x = zeros(n,1);           %% Initiate solution Xl
6     x(1) = b(1)/A(1,1);       %% For the base case, x(1) = ...
                                b(1)/A(1,1);
7     for i=2:n
8         temp = 0;
9         for j = 1:i
10            temp = temp + A(i, j)*x(j); %% Accumulate all ...
                                           the other terms
11        end
12        x(i) = (b(i)-temp)/A(i,i);    %% solve X(i)
13    end
14 end
```

2. I set $n = 1000$ and repeat the procedure for 100 times. The time elapses for Matlab backslash method is around 3.210974 seconds. My backsolve method will spend around 4.733596 seconds. Matlab backslash has better performance than mine.

For the accuracy:

$$\frac{\|X_{matlab} - X_{mine}\|}{\|X_{matlab}\|} = 7.2165e - 16 \quad (1)$$

3. My linear solver function:

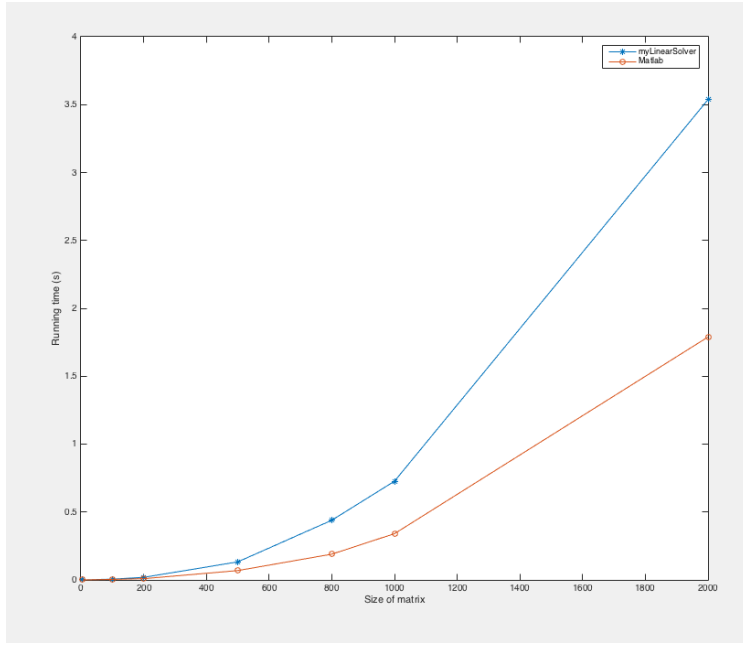


Figure 1: Time consumption for different size of matrix.

```

1 function x = linearSolver(A, b)
2     [L, U, P] = lu(A);
3     x1 = forwardsolve(L, P*b);
4     x = backsolve(U, x1);
5 end

```

Problem 2:

1. Base on

$$\frac{1}{h^2}(u(x_{i-1}, y_j) + u(x_i, y_{j-1}) - 4u(x_i, y_j) + u(x_{i+1}, y_j) + u(x_i, y_{j+1})) = f(x_i, y_j)$$

Then all the linear equations:

$$\begin{aligned}
 (i = 0, j = 0) : f_{0,0} &= 0 \\
 (i = 0, j = 1) : f_{0,1} &= 0 \\
 (i = 0, j = 2) : f_{0,2} &= 0 \\
 (i = 0, j = 3) : f_{0,3} &= 0 \\
 (i = 1, j = 0) : f_{1,0} &= 0 \\
 (i = 1, j = 1) : f_{1,1} &= 0 \\
 (i = 1, j = 2) : f_{1,2} &= 0 \\
 (i = 1, j = 3) : f_{1,3} &= 0 \\
 (i = 2, j = 0) : f_{2,0} &= 0 \\
 (i = 2, j = 1) : f_{2,1} &= 0 \\
 (i = 3, j = 0) : f_{3,0} &= 0 \\
 (i = 3, j = 1) : f_{3,1} &= 0
 \end{aligned}$$

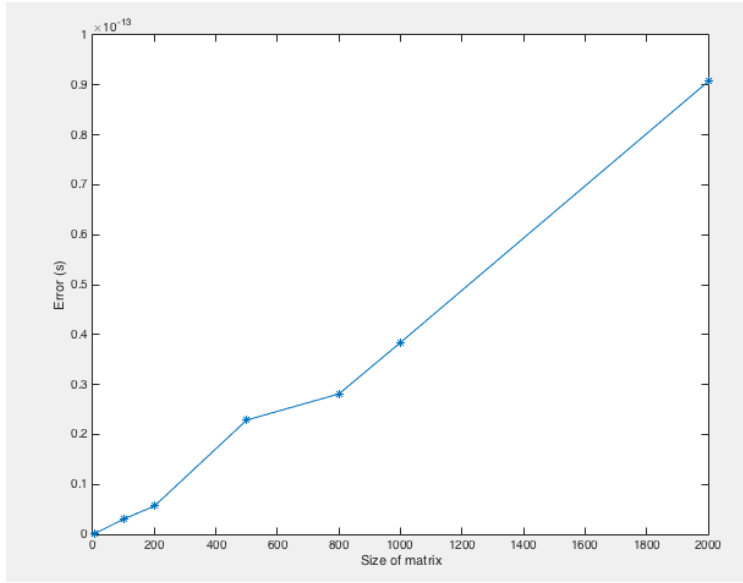


Figure 2: Error plot between Matlab backslash solver and my linear solver.

All the others:

$$(i = 2, j = 2) : f_{2,2} = \frac{1}{h^2} (u(x_1, y_2) + u(x_2, y_1) - 4u(x_2, y_2) + u(x_3, y_2) + u(x_2, y_3))$$

$$(i = 2, j = 3) : f_{2,3} = \frac{1}{h^2} (u(x_1, y_3) + u(x_2, y_2) - 4u(x_2, y_3) + u(x_3, y_3) + u(x_2, y_3))$$

$$(i = 3, j = 2) : f_{3,2} = \frac{1}{h^2} (u(x_2, y_2) + u(x_3, y_2) - 4u(x_3, y_2) + u(x_4, y_2) + u(x_3, y_3))$$

$$(i = 3, j = 3) : f_{3,3} = \frac{1}{h^2} (u(x_2, y_3) + u(x_2, y_2) - 4u(x_3, y_3) + u(x_4, y_3) + u(x_3, y_4))$$

2. The code is filled as below:

```

1  n = 10;
2  A = zeros((n+1)^2, (n+1)^2);
3  newA = zeros((n+1)^2-2, (n+1)^2-2);
4  f = zeros((n+1)^2, 1);
5  G = reshape(1:((n+1)^2), n+1, n+1)';
6  for i=0:n
7      for j=0:n
8          row = G(i+1, j+1);
9          if i==0 || j == 0 || i==n || j==n
10             % we are on a boundary
11             f(row) = 0;
12             A(row, row) = 1; % For boundary points, we set ...
                             % the diagonal term to be 1.
13
14         else
15             % we are NOT on a boundary
16             f(row) = 1/n^2;
17             A(row, G(i, j+1)) = 1; % Put the ...
                                     % coefficients to the corresponding entry of ...
                                     % matrix A.
18             A(row, G(i+1, j)) = 1;
19             A(row, G(i+1, j+1)) = -4;
20             A(row, G(i+2, j+1)) = 1;
21             A(row, G(i+1, j+2)) = 1;
22         % end
23

```

```

24     end
25 end
26 end
27 u = A\b;

```

3. Using Matlab's backslash solver, I can get the result for u :

```

0      0      0      0      0      0      0      0      0      0      0
0 -0.0128 -0.0206 -0.0254 -0.0280 -0.0288 -0.0280 -0.0254 -0.0206 -0.0128 0
0 -0.0206 -0.0343 -0.0430 -0.0478 -0.0493 -0.0478 -0.0430 -0.0343 -0.0206 0
0 -0.0254 -0.0430 -0.0544 -0.0608 -0.0629 -0.0608 -0.0544 -0.0430 -0.0254 0
0 -0.0280 -0.0478 -0.0608 -0.0682 -0.0706 -0.0682 -0.0608 -0.0478 -0.0280 0
0 -0.0288 -0.0493 -0.0629 -0.0706 -0.0731 -0.0706 -0.0629 -0.0493 -0.0288 0
0 -0.0280 -0.0478 -0.0608 -0.0682 -0.0706 -0.0682 -0.0608 -0.0478 -0.0280 0
0 -0.0254 -0.0430 -0.0544 -0.0608 -0.0629 -0.0608 -0.0544 -0.0430 -0.0254 0
0 -0.0206 -0.0343 -0.0430 -0.0478 -0.0493 -0.0478 -0.0430 -0.0343 -0.0206 0
0 -0.0128 -0.0206 -0.0254 -0.0280 -0.0288 -0.0280 -0.0254 -0.0206 -0.0128 0
0      0      0      0      0      0      0      0      0      0      0

```

Problem 3: The Schur Complement

1.

$$\begin{aligned}
 C\mathbf{x}_1 + D\mathbf{x}_2 &= \mathbf{b}_2 \\
 D\mathbf{x}_2 &= \mathbf{b}_2 - C\mathbf{x}_1 \\
 \mathbf{x}_2 &= D^{-1}(\mathbf{b}_2 - C\mathbf{x}_1)
 \end{aligned}$$

It is possible when the block matrix D is invertible because we need the inverse of matrix D .

2.

$$\begin{aligned}
 A\mathbf{x}_1 + B\mathbf{x}_2 &= \mathbf{b}_1 \\
 C\mathbf{x}_1 + D\mathbf{x}_2 &= \mathbf{b}_2
 \end{aligned}$$

Now we know that D is invertible. So multiply BD^{-1} on the second equation:

$$\begin{aligned}
 A\mathbf{x}_1 + B\mathbf{x}_2 &= \mathbf{b}_1 \\
 BD^{-1}C\mathbf{x}_1 + B\mathbf{x}_2 &= BD^{-1}\mathbf{b}_2 \\
 (BD^{-1}C - A)\mathbf{x}_1 &= (BD^{-1}\mathbf{b}_2 - \mathbf{b}_1)
 \end{aligned}$$

So if we can get inverse of $BD^{-1}C - A$, then we can solve \mathbf{x}_1 .

3. Then we can solve

$$\mathbf{x}_1 = (BD^{-1}C - A)^{-1}(BD^{-1}\mathbf{b}_2 - \mathbf{b}_1)$$

Problem 4: Ranking with Linear Systems

Questions:

I am a little confuse why we need r_1, r_2, \dots, r_n to be the indicate the performance of each team, instead of S_1, S_2, \dots, S_n ?

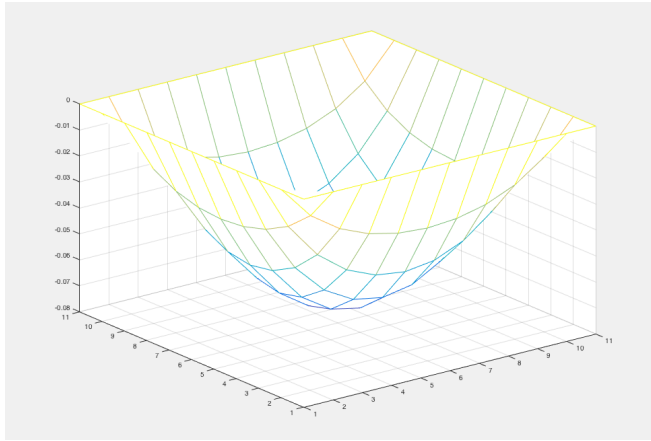


Figure 3: Surface plot of μ .