Problem 1:

$$f(x_1, x_2) = x_1^3 + 2x_1x_2 - 3x_1^2x_2^2$$

$$\frac{df}{dx_1} = 2x_1^2 + 2x_2 - 6x_1x_2^2$$

$$\frac{df}{dx_2} = 2x_1 - 6x_1^2x_2$$

$$f_{x_1x_1} = 4x_1 - 6x_2^2$$

$$f_{x_1x_2} = 2 - 12x_1x_2$$

$$f_{x_2x_1} = 2 - 12x_1x_2$$

$$f_{x_2x_2} = -6x_1^2$$

Tylor expansion:

$$f(\mathbf{x}) = f(\mathbf{x}^0) + (\mathbf{x} - \mathbf{x}^0)^T \nabla f(\mathbf{x}^0) + (\mathbf{x} - \mathbf{x}^0)^T H(\mathbf{x})(\mathbf{x} - \mathbf{x}^0)$$

where
$$\mathbf{x}^0 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

For linear approximation:

$$l(x_1, x_2) = f(\mathbf{x}^0) + (\mathbf{x} - \mathbf{x}^0)^T \nabla f(\mathbf{x}^0)$$
$$= f\left(\begin{bmatrix} 1\\1 \end{bmatrix}\right) + \begin{bmatrix} x_1 - 1 & x_2 - 1 \end{bmatrix} \begin{bmatrix} -1\\-4 \end{bmatrix}$$
$$= -x_1 - 4x_2 + 5$$

Hessian:

$$H = \begin{bmatrix} f_{x_1 x_1} & f_{x_1 x_2} \\ f_{x_2 x_1} & f_{x_2 x_2} \end{bmatrix}$$

For quadratic approximation:

$$f(\mathbf{x}) = f(\mathbf{x}^0) + (\mathbf{x} - \mathbf{x}^0)^T \nabla f(\mathbf{x}^0) + (\mathbf{x} - \mathbf{x}^0)^T H(\mathbf{x}) (\mathbf{x} - \mathbf{x}^0)$$

$$= -x_1 - 4x_2 + 5 + \begin{bmatrix} x_1 - 1 & x_2 - 1 \end{bmatrix} \begin{bmatrix} 4x_1 - 6x_2^2 & 2 - 12x_1x_2 \\ 2 - 12x_1x_2 & -6x_1^2 \end{bmatrix} \begin{bmatrix} x_1 - 1 \\ x_2 - 1 \end{bmatrix}$$

$$= -x_1 - 4x_2 + 5 + (2x_1 - 6x_1^2x_2)(x_1 - 1)^2 - 6x_1^2(x_2 - 1)^2 + (4 - 24x_1x_2)(x_1 - 1)(x_2 - 1)$$

Problem 2:

1.

$$f(\mathbf{x}) = \begin{bmatrix} x_1 & x_2 \end{bmatrix} \begin{bmatrix} 1 & 4 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} x_1//x_2 \end{bmatrix} - \begin{bmatrix} x_1 & x_2 \end{bmatrix} \begin{bmatrix} -2 \\ 1 \end{bmatrix} + \pi$$

$$= x_1^2 + 3x_2^2 + 6x_1x_2 + 2x_1 + x_2 + \pi$$

$$\frac{df}{dx_1} = 2x_1 + 6x_2 + 2$$

$$\frac{df}{dx_2} = 6x_2 + 6x_1 + 1$$

$$Df(\mathbf{x}) = \begin{bmatrix} \frac{df}{dx_1} & \frac{df}{dx_2} \end{bmatrix} = \begin{bmatrix} 2x_1 + 6x_2 + 2 & 6x_2 + 6x_1 + 1 \end{bmatrix}$$

2.

$$f(\mathbf{x}) = \frac{1}{2} \begin{bmatrix} x_1 & x_2 \end{bmatrix} \begin{bmatrix} 2 & 3 \\ 9 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} x_1 & x_2 \end{bmatrix} \begin{bmatrix} 2 \\ -3 \end{bmatrix} + \log 3$$

$$= x_1^2 + \frac{1}{2}x_2^2 + 6x_1x_2 + 2x_1 - 3x_2 + \log 3$$

$$\frac{df}{x_1} = 2x_1 + 6x_2 + 2$$

$$\frac{df}{x_2} = x_2 + 6x_1 - 3$$

$$f_{x_1x_1} = 2$$

$$f_{x_1x_2} = 6$$

$$f_{x_2x_1} = 6$$

$$f_{x_2x_2} = 1$$

Hessian:

$$H = \begin{bmatrix} 2 & 6 \\ 6 & 1 \end{bmatrix}$$

Problem 3:

$$f(x_1, x_2) = e^{3x_1 x_2^2}$$

1.

$$\frac{df}{x_1} = 3x_2^2 e^{3x_1 x_2^2}$$
$$\frac{df}{x_2} = 6x_1 x_2 e^{3x_1 x_2^2}$$

Then the gradient at $\mathbf{x} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ is:

$$\begin{bmatrix} 3e^3 \\ 6e^3 \end{bmatrix}$$

2. Rate of increase of f at the point $\mathbf{x} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ in the direction \mathbf{d}

$$\frac{Df(\mathbf{x}) \cdot \mathbf{d}}{\|\mathbf{d}\|} = \frac{15e^3}{\sqrt{5}}$$

3. In the direction $\mathbf{d} = \begin{bmatrix} 3 \\ 6 \end{bmatrix}$, we can have the maximum rate of increase $3\sqrt{5}e^3$

Problem 4:

$$f(x_1, x_2, x_3) = -(x_1^2 + 4\epsilon x_2^2 + 5x_3^2 - 2x_1x_3 + 2\epsilon x_1x_2 + 4x_2x_3)$$
$$= -\begin{bmatrix} x_1 & x_2 & x_3 \end{bmatrix} \begin{bmatrix} 1 & \epsilon & -1 \\ \epsilon & 4\epsilon & 2 \\ -1 & 2 & 5 \end{bmatrix}$$

Using principal minor method:

$$k = 1:$$

$$D_{1} = 20\epsilon - 4 > 0$$

$$D_{2} = 7$$

$$D_{3} = 4\epsilon - \epsilon^{2} > 0$$

$$k = 2:$$

$$D_{1} = 1$$

$$D_{2} = 4\epsilon > 0$$

$$D_{3} = 5$$

$$k = 3:$$

$$D = 12\epsilon - 4 - 5\epsilon^{2} > 0$$

To make the function be negative semi-definite, the range of ϵ is $0.4 \le \epsilon \le 2$

Problem 5:

1.

$$f(x_1, x_2) = \frac{1}{3}x_2^3 + \frac{1}{2}x_2^2 + 2x_1x_2 + \frac{1}{2}x_1^2 - x_1 + 10$$
$$\frac{df}{dx_1} = 2x_2 + x_1 - 1 = 0$$
$$\frac{df}{dx_2} = x_2^2 + x_2 + 2x_1 = 0$$

We can get two points (-1,1) and (-3,2) which satisfy the first-order necessary conditions for the extremum.

2.

$$\begin{aligned} \frac{df}{dx_1dx_1} &= 1\\ \frac{df}{dx_1dx_2} &= 2\\ \frac{df}{dx_2dx_1} &= 2\\ \frac{df}{dx_2dx_2} &= 2x_2 + 1 \end{aligned}$$

Then Hessian is:

$$\begin{bmatrix} 1 & 2 \\ 2 & 2x_2 + 1 \end{bmatrix}$$

For point (-1,1), $H = \begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix}$ is indefinite For point (-3,2), $H = \begin{bmatrix} 1 & 2 \\ 2 & 5 \end{bmatrix}$ is positive definite Then the point (-3,2) is a strict local minimizer.

Problem 6:

$$f(\mathbf{x}) = \mathbf{x}^T \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \mathbf{x}$$
$$= x_1^2 + x_1 x_2 + x_2^2$$

The direction of travel is:

$$\mathbf{d} = -\mathbf{g} = -\frac{df}{d\mathbf{x}} = (\mathbf{A} + \mathbf{A}^T)\mathbf{x} = -\begin{bmatrix} 2 & 1\\ 1 & 2 \end{bmatrix}\mathbf{x} = \begin{bmatrix} -2x_1 - x_2\\ -x_1 - 2x_2 \end{bmatrix}$$

when $\epsilon_1 = 0.1; f(x^{(0)}) = 1.065$

$$\mathbf{x}^{(1)} = \mathbf{x}^{(0)} + \epsilon_1 \cdot \mathbf{d}$$
$$= \begin{bmatrix} 0.55 \\ 0.55 \end{bmatrix}$$

when $\epsilon_2 = 0.2$; $f(x^{(1)}) = 1.65$

$$\mathbf{x}^{(2)} = \mathbf{x}^{(1)} + \epsilon_2 \cdot \mathbf{d}$$
$$= \begin{bmatrix} -0.11 \\ -0.11 \end{bmatrix}$$

Problem 7:

Problem 8:

Problem 9:

```
1 [X, Y] = meshgrid(-1:0.1:1, -1:0.1:1);
2 Z = (X-Y).^4 + 12*X.*Y - Y + X + 5;
3 mesh(X, Y, Z);
4 contour(X, Y, Z, 20);
5 %xlabel(X1);
6 %ylabel(X2);
7 box on;
```

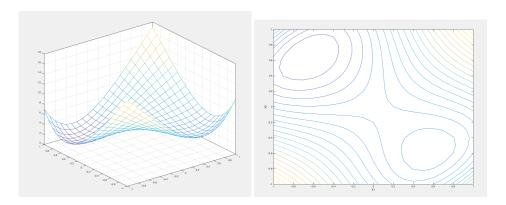


Figure 1: Left: Problem 9(a) Mesh plot . Right: Problem 9(b) Contour plot.