

# Simultaneous Clustering and Estimation of Multiple Sparse Networks

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# Outline

- 1 Introduction
  - Review of Clustering
  - Clustering for high-dimensional data
  - Review of Estimation for Graphical Model
  - Multiple Gaussian Graphical Model
- 2 Simultaneous Clustering and Estimation
  - Motivation
  - Joint Clustering and Graphical Lasso
  - EM algorithm
- 3 Theoretical Guarantee
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  - Several Conditions
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# Background for clustering

- Consider each  $p$ -dimensional observation  $x_i, i = 1, \dots, n$  is drawn from a Gaussian mixture model with

$$f(x) = \sum_{k=1}^K \pi_k f_k(x; \mu_k, \Sigma_k) \quad (1.1)$$

where  $\pi_k$  is the mixture weight and  $f_k(x; \mu_k, \Sigma_k)$  is a multivariate normal distribution.

- For classical clustering problem, we assume  $\Sigma_k = \Sigma = \text{diag}(\sigma_1^2, \dots, \sigma_p^2)$
- Output: cluster assignments and cluster means

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# Regularized Model-based Clustering

- Sun et al.(2012) proposed a high-dimensional cluster analysis via regularized model-based clustering.
- Regularized log-likelihood function for the observed data:

$$\sum_{i=1}^n \log \left( \sum_{k=1}^K \pi_k f_k(\mathbf{x}_i; \boldsymbol{\mu}_k, \sigma^2 \mathbf{I}_p) \right) - \lambda \sum_{j=1}^p \|\boldsymbol{\mu}_{(j)}\|_2 \quad (1.2)$$

with  $\boldsymbol{\mu}_{(j)}$  the  $j$ -th column of the center matrix  $(\boldsymbol{\mu}_1, \dots, \boldsymbol{\mu}_K)^T$ .

- An EM algorithm can be employed to maximize (1.2), where the cluster assignment  $L_{ik}$  is treated as missing data.

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# Single Gaussian Graphical model

- Suppose that the observation  $x_1, \dots, x_n \in \mathbb{R}^p$  are independent and identically distributed  $N(\mu, \Sigma)$ , where  $\mu \in \mathbb{R}^p$  and  $\Sigma$  is a positive definite  $p \times p$  matrix.
- Goal: Estimate the *precision* matrix  $\Omega = \Sigma^{-1}$
- Gaussian log-likelihood takes the form (up to a constant)

$$l(\Omega) = \frac{n}{2} [\log\{\det(\Sigma^{-1})\} - \text{tr}(S\Sigma^{-1})] \quad (1.3)$$

where  $S$  denotes the empirical covariance matrix.

- Method for estimating  $\Sigma^{-1}$  in high-dimensional setting

$$\max_{\Omega} [\log\{\det(\Omega)\} - \text{tr}(S\Omega) - \lambda \|\Omega\|_1] \quad (1.4)$$



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# Multiple Gaussian Graphical Model without Similarity

- Key assumption: **The cluster structure is known in advance.**
- Suppose that we are given K data set  $X^{(1)}, \dots, X^{(K)}$ , with K fixed.  $X^{(k)}$  is an  $n_k \times p$  matrix,  $x_1^{(k)}, \dots, x_{n_k}^{(k)} \sim N(\mu_k, \Sigma_k)$ .
- $\Omega_k = \Sigma_k^{-1}$ ,  $\Theta = (\Omega_1, \dots, \Omega_K)$ . We let  $S_k = (1/n_k)(X^{(k)})^T X^{(k)}$
- Similarly, the log-likelihood for the data takes the form(up to a constant)

$$l(\Theta) = \frac{1}{2} \sum_{k=1}^K n_k [\log\{\det(\Omega_k)\} - \text{tr}(S_k \Omega_k)] \quad (1.5)$$

- It is the same as to estimate each precision matrix separately.

# Multiple Gaussian Graphical Model with Similarity

- Multiple graphical models share certain characteristics, such as the locations or weights of non-zero edges.
- In high-dimensional setting, joint estimation of graphical models solves

$$\max_{\Omega} \sum_{k=1}^K n_k [\log\{\det(\Omega_k)\} - \text{tr}(S_k \Omega_k)] - \mathcal{P}(\Theta) \quad (1.6)$$

- The choice of  $\mathcal{P}(\Theta)$  could encourage estimators to share similar characteristics across classes and simultaneously encourage sparsity.

# Multiple Gaussian Graphical Model with Similarity

- Guo et al. (2011) employed a non-convex penalty

$$P(\Theta) = \lambda \sum_{i \neq j} \left( \sum_{k=1}^K |\omega_{ij}^{(k)}| \right)^2, \quad (1.7)$$

where  $\omega_{ij}$  is the entry of precision matrix  $\Omega$ .

- Danaher et al. (2014) applied two convex penalties:  
fused graphical lasso

$$P(\Theta) = \lambda_1 \sum_{k=1}^K \sum_{i \neq j} |\omega_{ij}^{(k)}| + \lambda_2 \sum_{k < k'} \sum_{i,j} |\omega_{ij}^{(k)} - \omega_{ij}^{(k')}|. \quad (1.8)$$

group graphical lasso

$$P(\Theta) = \lambda_1 \sum_{k=1}^K \sum_{i \neq j} |\omega_{ij}^{(k)}| + \lambda_2 \sum_{i \neq j} \left( \sum_{k=1}^K \omega_{ij}^{(k)^2} \right)^{1/2}. \quad (1.9)$$

# Multiple Gaussian Graphical Model with Similarity

- Lee and Liu(2015) extend the joint estimation method to non-Gaussian cases.

All the literature above treat the cluster structure as known!

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# Motivation

- From a clustering point of view, we consider the dependencies among variables within clusters.
- From a perspective of joint estimation for precision matrix, we do not assume that the clustering structure is given in advance.

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# Some notations

- Let  $x_1, \dots, x_n \sim f(x) = \sum_{k=1}^K \pi_k f_k(x, \mu_k, \Sigma_k)$
- The set of parameters  $\Theta := \{(\mu_k, \Omega_k), k = 1, \dots, K\}$ , where  $\Omega_k = \Sigma_k^{-1}$
- Denote the  $K$  clusters as  $\mathcal{A}_1, \dots, \mathcal{A}_K$  and  $L$  as the cluster assignment matrix with  $L_{ik} = \mathcal{I}(x_i \in \mathcal{A}_k)$ . So  $\sum_{k=1}^K L_{ik} = 1$ .
- In EM algorithm,  $L$  can be treated as a latent variable.

# Joint Clustering and Graphical Lasso

- Our optimization problem is formulated as

$$\max_{\pi_k, \mu_k, \Omega_k} \sum_{i=1}^n \log \left( \sum_{k=1}^K \pi_k f_k(x_i; \mu_k, (\Omega_k)^{-1}) \right) - \mathcal{P}(\Theta) \quad (2.1)$$

where

$$\mathcal{P}(\Theta) = \lambda_1 \sum_{k=1}^K \sum_{j=1}^p |\mu_{kj}| + \lambda_2 \sum_{k=1}^K \sum_{i \neq j} |\omega_{kij}| + \lambda_3 \sum_{i \neq j} \left( \sum_{k=1}^K \omega_{kij}^2 \right)^{1/2} \quad (2.2)$$

- If  $L_{ik}$  is available, the regularized log-likelihood function for the complete data can be calculated as

$$\log L_c(\Theta) := \sum_{i=1}^n \sum_{k=1}^K L_{ik} [\log \pi_k + \log f_k(x_i; \Theta_k)] - P(\Theta)$$

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# Expectation Step

- Given the current estimator  $\hat{\Theta}^{(t)}$ , the conditional expectation of (18) is computed as

$$Q_m(\Theta|\hat{\Theta}^{(t)}) - P(\Theta) \quad (2.3)$$

where

$$Q_m(\Theta|\hat{\Theta}^{(t)}) := \sum_{i=1}^n \sum_{k=1}^K \hat{L}_{ik}^{(t)} [\log \pi_k + \log f_k(x_i; \Theta_k)] \quad (2.4)$$

$$\hat{L}_{ik}^{(t)} = \frac{\hat{\pi}_k^{(t)} f_k(x_i; \hat{\Theta}_k^{(t)})}{\sum_{k=1}^K \hat{\pi}_k^{(t)} f_k(x_i; \hat{\Theta}_k^{(t)})} \quad (2.5)$$

# Maximization Step

- Update of  $\pi_k$ :

$$\hat{\pi}_k^{(t+1)} = \sum_{i=1}^n \frac{\hat{L}_{ik}^{(t)}}{n} \quad (2.6)$$

- Update of  $\mu_{kj}$  (follows KKT condition):

$$\text{If } \left| \sum_{i=1}^n \hat{L}_{ik}^{(t)} \left( \sum_{l=1, l \neq j}^p (x_{il} - \hat{\mu}_{kl}^{(t)}) \hat{\omega}_{klj}^{(t)} + x_{ij} \hat{\omega}_{kjj}^{(t)} \right) \right| \leq \lambda_1, \text{ then } \hat{\mu}_{kj}^{(t+1)} = 0; \quad (2.7)$$

$$\begin{aligned} \text{Else } \hat{\mu}_{kj}^{(t+1)} = & \left( \hat{\omega}_{kjj}^{(t)} \sum_{i=1}^n \hat{L}_{ik}^{(t)} \right)^{-1} \left\{ \sum_{i=1}^n \hat{L}_{ik}^{(t)} \left( \sum_{l=1}^p x_{il} \hat{\omega}_{klj}^{(t)} \right) \right. \\ & \left. - \left( \sum_{i=1}^n \hat{L}_{ik}^{(t)} \right) \left( \sum_{l=1}^p \hat{\mu}_{kl}^{(t)} \hat{\omega}_{klj}^{(t)} - \hat{\mu}_{kj}^{(t)} \hat{\omega}_{kjj}^{(t)} \right) - \lambda_1 \text{sign}(\hat{\mu}_{kj}^{(t)}) \right\} \quad (2.8) \end{aligned}$$

# Maximization Step

- Update of  $\Omega_k$ : Note that maximize (2.3) with respect to  $\Omega_k$  is equivalent to solve the following maximization problem.

$$\max_{\Omega_k} \sum_{k=1}^K n_k [\log \det(\Omega_k) - \text{trace}(\tilde{S}_k \Omega_k)] - P(\Omega), \quad (2.9)$$

where

$$\tilde{S}_k := \frac{\sum_{i=1}^n \hat{L}_{ik}^{(t)} (x_i - \mu_k)^T (x_i - \mu_k)}{\sum_{i=1}^n \hat{L}_{ik}^{(t)}} \quad (2.10)$$

- This optimization problem can be solved efficiently via the ADMM algorithm in Danaher et al. (2014).

# EM algorithm

Table: Outline of Our Algorithm

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**Input:** Training data  $x_1, \dots, x_n$  and Number of clusters  $K$ .

**Output:** Cluster assignment  $L_{ik}$  and graph  $\Omega_k$ .

---

**Step 1:** Initialize cluster centers by the k-means++ clustering and set  $\pi_k^{(0)} = \frac{1}{K}$ .

**Step 2:** Until the termination condition is met, for  $t = 1, 2, \dots$

(a) E-step. Find the cluster assignment  $L_{ik}^{(t)}$  as in (2.5).

(b) M-step. Given  $L_{ik}^{(t)}$ , update  $\pi_k^{(t+1)}$  as in (2.6),  $\mu_k^{(t+1)}$  as in (2.7), and the precision matrix  $\Omega_k^{(t+1)}$  in (2.9) via JGL algorithm.

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## Some previous work

- Balakrishnan et al.(2014) first considered both the statistical error and optimization error for the guarantee of EM algorithm.
- Wang et al.(2014) proposed high-dimensional EM algorithm based on truncation step.
- Yi et al.(2015) used regularization method for high-dimensional EM.

# Decomposable Regularizer

## Definition (Decomposability)

Regularizer  $\mathcal{P} : \mathbb{R}^p \rightarrow \mathbb{R}^+$  is decomposable with respect to  $(\mathcal{S}, \bar{\mathcal{S}})$  if

$$\mathcal{P}(u + v) = \mathcal{P}(u) + \mathcal{P}(v), \text{ for any } u \in \mathcal{S}, v \in \bar{\mathcal{S}}^\perp \quad (3.1)$$

where  $\mathcal{S} \subseteq \bar{\mathcal{S}}$ .

- Example

$$\|\theta + \gamma\|_1 = \|(\theta_{\mathcal{S}}, 0) + (0, \gamma_{\mathcal{S}^c})\|_1 = \|\theta\|_1 + \|\gamma\|_1$$

where  $\mathcal{S}$  is the support of  $\theta$ .

# Subspace compatibility constant

## Definition (Subspace compatibility constant)

For any subspace  $\mathcal{S}$  of  $\mathbb{R}^p$ , the subspace compatibility constant with respect to the pair  $(\mathcal{P}, \|\cdot\|)$  is given by

$$\psi(\mathcal{S}) := \sup_{u \in \mathcal{S} \setminus \{0\}} \frac{\mathcal{P}(u)}{\|u\|} \quad (3.2)$$

- Example: If  $\mathcal{S}$  is a  $s$ -dimensional coordinate subspace, with regularizer  $\mathcal{P}(u) = \|u\|_1$  and error norm  $\|u\| = \|u\|_2$ , then we have  $\Psi(\mathcal{S}) = \sqrt{s}$

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# Population version vs. Sample version

- Sample version  $Q$  function

$$Q_n(\Theta'|\Theta) := \frac{1}{n} \sum_{i=1}^n \sum_{k=1}^K L_{ik}(\mathbf{x}_i) [\log \pi'_k + \log f_k(\mathbf{x}_i; \Theta'_k)] \quad (3.3)$$

- Population version of  $Q$  function

$$Q(\Theta'|\Theta) := E \left[ \sum_{k=1}^K L_{ik}(\mathbf{X}) [\log \pi'_k + \log f_k(\mathbf{X}; \Theta'_k)] \right] \quad (3.4)$$

# Condition for Population version

## Condition (Strong Concavity and Smoothness)

$$Q(\Theta_2|\Theta^*) - Q(\Theta_1|\Theta^*) - \langle \nabla Q(\Theta_1|\Theta^*), \Theta_2 - \Theta_1 \rangle \leq -\frac{\gamma}{2} \|\Theta_2 - \Theta_1\|_2^2,$$

$$Q(\Theta_2|\Theta) - Q(\Theta_1|\Theta) - \langle \nabla Q(\Theta_1|\Theta), \Theta_2 - \Theta_1 \rangle \geq -\frac{\mu}{2} \|\Theta_2 - \Theta_1\|_2^2, \quad (3.5)$$

for any  $\Theta_1, \Theta_2 \in \mathcal{B}_\alpha(\Theta^*)$ .

- We will focus on the Euclidean ball of radius  $\alpha > 0$  for the basin of attraction space. That is,

$$\mathcal{B}_\alpha(\Theta^*) := \{\Theta \in \mathbb{R}^{K(p^2+p)} : \|\Theta - \Theta^*\|_2 \leq \alpha\}. \quad (3.6)$$

# Condition for Population version

## Condition ( $\tau$ -Lipschitz-Gradient)

The function  $\nabla_{\Theta'} Q(\bar{\mu}, \bar{\Omega} | \cdot)$  satisfies,

$$\|\nabla_{\Theta'} Q(\bar{\mu}, \bar{\Omega} | \Theta) - \nabla_{\Theta'} Q(\bar{\mu}, \bar{\Omega} | \Theta^*)\|_2 \leq \tau \cdot \|\Theta - \Theta^*\|_2, \quad (3.7)$$

for any  $\Theta \in \mathcal{B}_\alpha(\Theta^*)$ .

- Recall that  $(\bar{\mu}_k, \bar{\Omega}_k)$ ,  $k = 1, \dots, K$  is the true maximizer of the population objective function  $Q(\Theta' | \Theta)$ .

# Condition for Sample version

## Condition (Restricted Strong Concavity)

For any fixed  $\Theta \in \mathcal{B}(\alpha; \Theta^*)$ , with probability at least  $1-\delta$ , we have that for all  $\Theta' - \Theta^* \in \Omega \cap \mathcal{C}(\mathcal{S}, \bar{\mathcal{S}}; \mathcal{P})$ ,

$$Q_n(\Theta'|\Theta) - Q_n(\Theta^*|\Theta) - \langle \nabla Q_n(\Theta^*|\Theta), \Theta' - \Theta^* \rangle \leq -\frac{\gamma_n}{2} \|\Theta' - \Theta^*\|^2 \quad (3.8)$$

where  $\mathcal{C}(\mathcal{S}, \bar{\mathcal{S}}; \mathcal{P})$  is a particular set.



# Condition for Sample version

## Condition (Statistical Error( $\epsilon_n, \alpha, \delta$ ))

For any fixed  $\Theta \in \mathcal{B}_\alpha(\Theta^*)$ , with probability at least  $1 - \delta$ , we have

$$\|\nabla Q_n(\Theta^*|\Theta) - \nabla Q(\Theta^*|\Theta)\|_{\mathcal{P}^*} \leq \epsilon_n \quad (3.9)$$

- $\|\cdot\|_{\mathcal{P}^*}$  is the dual norm of  $\mathcal{P}$
- There is *no sparsity* here for statistical error.

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# Main Result

## Theorem

Assume the model parameter  $\Theta^* \in \mathcal{S}$  and regularizer  $\mathcal{P}$  is decomposable with respect to  $(\mathcal{S}, \bar{\mathcal{S}})$ . Given  $n$  samples and  $T$  iterations, we let  $m := n/T$ . Further, assume  $Q(\cdot|\cdot)$  and  $Q_m(\cdot|\cdot)$  satisfy the conditions above. If  $\Theta^{(t-1)} \in \mathcal{B}_\alpha(\Theta^*)$  and

$$\lambda_m^{(t)} \geq 3\epsilon_m + \frac{\alpha\mu\tau}{\gamma} \|\Theta^{(t-1)} - \Theta^*\| \frac{1}{\Psi(S)} \quad (3.10)$$

then we have

$$\|\Theta^{(t)} - \Theta^*\| \leq 5\Psi(S) \frac{\lambda_m^{(t)}}{\gamma_m} \quad (3.11)$$

# Main Result

## Remark

Here we focus on the analysis of solution  $\Theta^{(t)}$  directly from the algorithm instead of the optimal solution

$$\hat{\Theta} \in \arg \max_{\Theta} \sum_{i=1}^n \log \left( \sum_{k=1}^K \pi_k f_k(x_i; \mu_k, (\Omega_k)^{-1}) \right) - \mathcal{P}(\Theta)$$

# Main Result

## Corollary

*Under certain condition and careful choice of  $\lambda_m$ , we have*

$$\begin{aligned} \|\Theta^{(t+1)} - \Theta^*\|_2 &\lesssim \underbrace{\frac{1 - \kappa^t}{\gamma_m(1 - \kappa)} (\sqrt{d + Ks} + \sqrt{Kp}) \sqrt{\frac{\log(Kp^2 - Kp)}{n}}}_{\text{statistical error}} \\ &\quad + \underbrace{\kappa^t \|\Theta^{(0)} - \Theta^*\|_2}_{\text{optimization error}} \end{aligned}$$

*with high probability.*

- Denote the number of non-zero entries in  $\mu_k^*$  as  $d_k := \|\mu_k^*\|_0$ , and let  $d = \sum_k d_k$ ,  $s$  is the sparsity of precision matrix  $\Omega_k$
- $K$  is the number of cluster and  $1/2 \leq \kappa \leq 3/4$

## Comparison with Another Result

- Similar result is derived by Martin J. Wainwright(2014). If we assume  $\Theta^*$  is exactly group-sparse, say, supported on a group subset  $S_{\mathcal{G}} \subseteq \{1, 2, \dots, N_{\mathcal{G}}\}$  of cardinality  $s_{\mathcal{G}}$ , then

$$\|\hat{\Theta} - \Theta^*\|_2 \lesssim \sqrt{s_{\mathcal{G}} \left( \frac{m}{n} + \frac{\log |\mathcal{G}|}{n} \right)} \quad (3.12)$$

where  $m = \max_{t=1, \dots, N_{\mathcal{G}}} |G_t|$ .

- In this paper, we propose a regularized Gaussian mixture model with a joint graphical lasso penalty to borrow strength across various clusters in estimating multiple graphical models which share some common structures.
- For theory, we consider the potential gap between statistical and computational guarantees in application of our algorithm.
- The statistical rate is nearly mini-max rate.

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