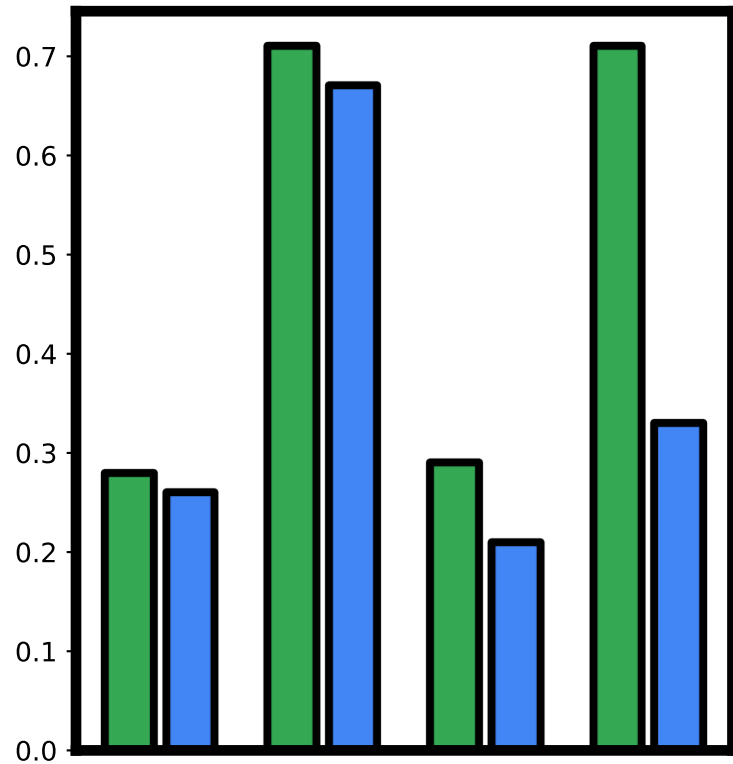
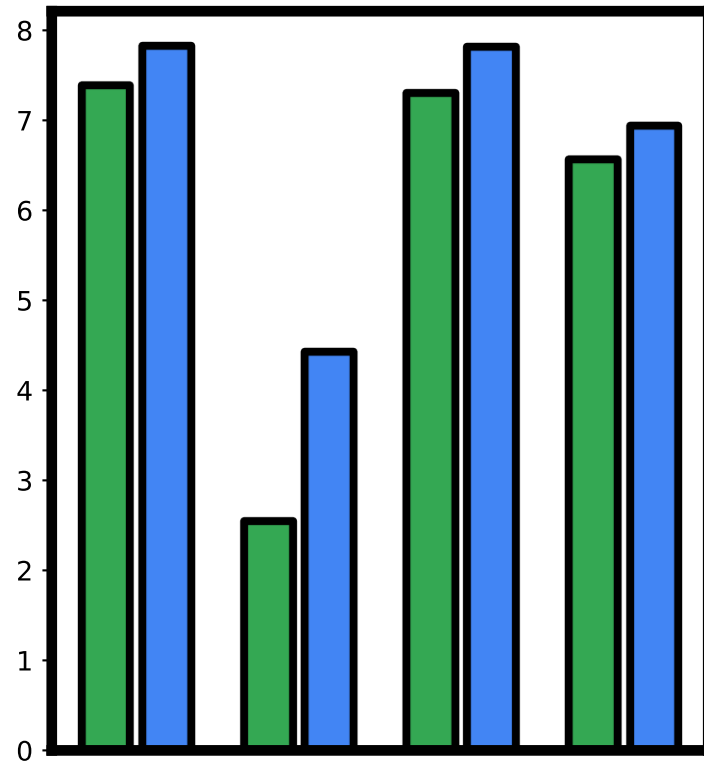


Success Rate ↑



Control Difference ↓



Min. Distance

