

Spring - Mass system. (Oscillations of a Mechanical system)

DDE : $y'' + \left(\frac{c}{m}\right) y' + \left(\frac{k}{m}\right) y = \frac{1}{m} F(t)$ (*)

$$y(t), \quad y(0) = y_0, \quad y'(0) = v_0.$$

Last time : external force $F(t) \equiv 0$.

Aux. poly : $r^2 + \frac{c}{m} r + \frac{k}{m} = 0$

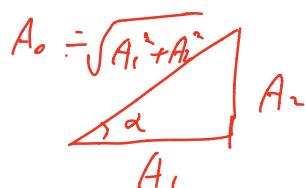
Case 1: No damping. $c = 0$.

$$y(t) = C_1 \cos \omega_0 t + C_2 \sin \omega_0 t.$$

$$\omega_0 = \sqrt{\frac{k}{m}}. \quad \rightarrow = A_0 \cos(\omega_0 t - \alpha)$$

Recall identifies from trig. $A_0 = \sqrt{C_1^2 + C_2^2}$

$$A_1 \cos \theta + A_2 \sin \theta.$$

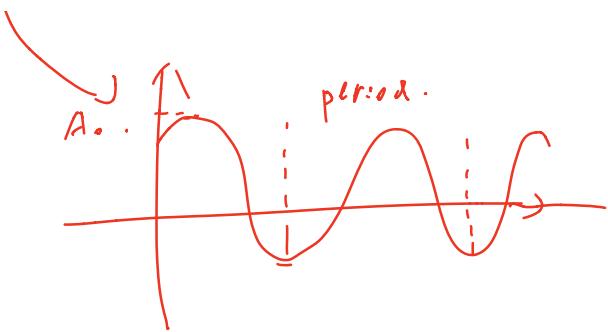


$$= A_0 (\cos \alpha \cos \theta + \sin \alpha \sin \theta)$$

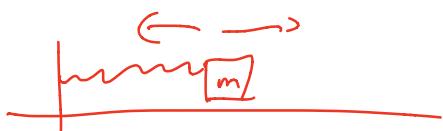
$$= A_0 \cdot \cos(\theta - \alpha).$$

$$\cos \alpha = \frac{A_1}{\sqrt{A_1^2 + A_2^2}} = \frac{A_1}{A_0}$$

$$\sin \alpha = \frac{A_2}{\sqrt{A_1^2 + A_2^2}}$$



$$\text{period} = \frac{2\pi}{\omega_0} = 2\pi \sqrt{\frac{m}{k}}.$$



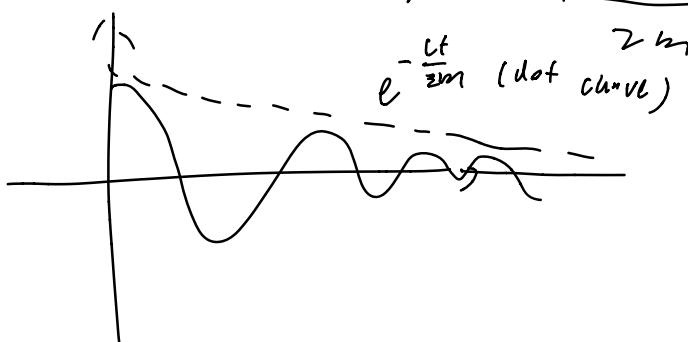
(ase 2) Damping $c > 0$.

2.a) Under damped $c^2 < 4km$. Aux. polynomial

complex roots

$$y(t) = e^{-\frac{ct}{2m}} (c_1 \cos(\mu t) + c_2 \sin(\mu t))$$

$$M = \sqrt{4km - c^2}$$



b) critically damped $c^2 = 4km$.

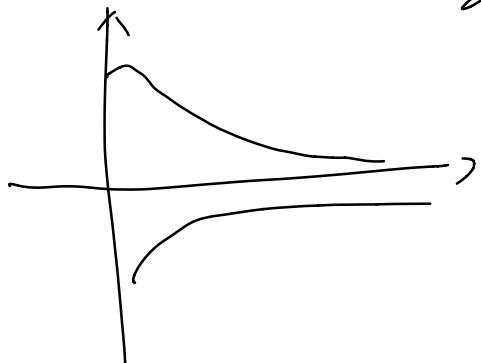
$$y(t) = e^{-\frac{ct}{2m}}(c_1 + c_2 t)$$

c) over damped $c^2 > 4km$.

$$y(t) = e^{-\frac{ct}{2m}}(c_1 e^{ut} + c_2 e^{-ut})$$

$$M = \frac{\sqrt{c^2 - 4km}}{2m}$$

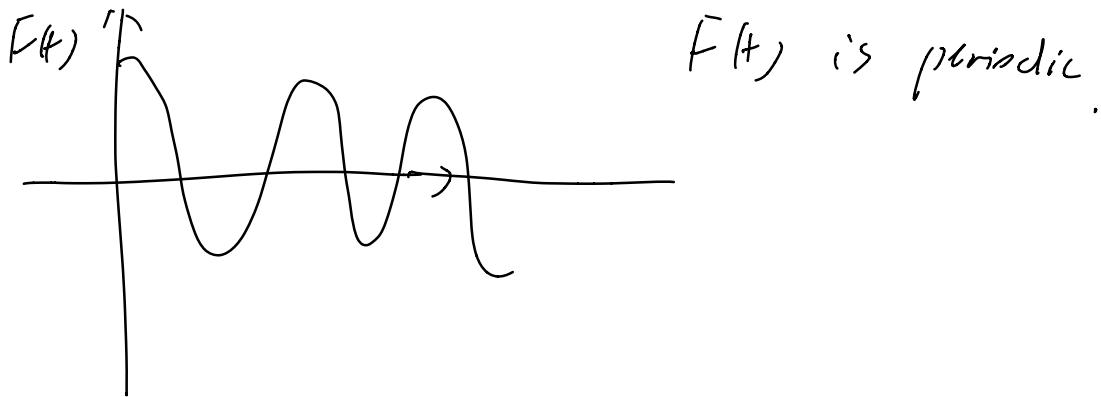
b). c)



$F(t) = 0$ homogeneous equation.

Today's class: we focus on

$F(t) = F_0 \cos \omega t$. F_0, ω are constants.



Case 1: No damping

homogeneous solutions:

$$y_c(t) = A_0 \cos(\omega_0 t - \phi)$$

$$y = y_c + y_p$$

Anni. of $F(t) = f_0 \cos \omega t$

$$A(D) = (D - \omega_i)(D + \omega_i)$$

$$= D^2 + \omega^2$$

$$P(D) = D^2 + \frac{c}{m} D + \frac{k}{m} = D^2 + \frac{k}{m}$$

$$\underline{A(D) P(D)}$$

If $w_0 \neq w$, i.e. $\frac{k}{m} \neq w^2$.

$$y_p = A_1 \cos wt + A_2 \sin wt.$$

$$= C_0 \cdot \cos(wt - \alpha)$$

$$y_p'' + \frac{k}{m} y_p = \frac{F_0}{m} \cos wt.$$

$$C_0 \left(-w^2 + \frac{k}{m} \right) \cos(wt - \alpha) = \frac{F_0}{m} \cos wt$$

$$C_0 = \frac{F_0}{m(w_0^2 - w^2)}, \quad \alpha = 0$$

$$y_p = \frac{F_0}{m(w_0^2 - w^2)} \cos wt$$

$$\text{General solution } y(x) = A_0 \cdot \cos(w_0 t - \phi)$$

$$+ \frac{F_0}{m(w_0^2 - w^2)} \cos wt.$$

Look at case: $y(0) = y'(0) = 0$.

$$\text{Get: } y(0) = 0 \Rightarrow A_0 \cos \phi + \frac{F_0}{m(w_0^2 - w^2)} = 0$$

$$y'(0) = 0 \Rightarrow A_0 w_0 - \sin(-\phi) + \frac{F_0 w}{m(w_0^2 - w^2)} \sin \phi = 0$$

$$\sin \phi = 0 \Rightarrow \phi = 0$$

$$A_0 + \frac{F_0}{m(w_0^2 - w^2)} = 0 \quad A_0 = -\frac{F_0}{m(w_0^2 - w^2)}$$

$$y(t) = \frac{F_0}{m(w_0^2 - w^2)} (\cos wt - \cos \omega_0 t)$$

w is related to $F(t)$ when $w = w_0$. resonance

ω_0 is related to Spring-Mass system itself.

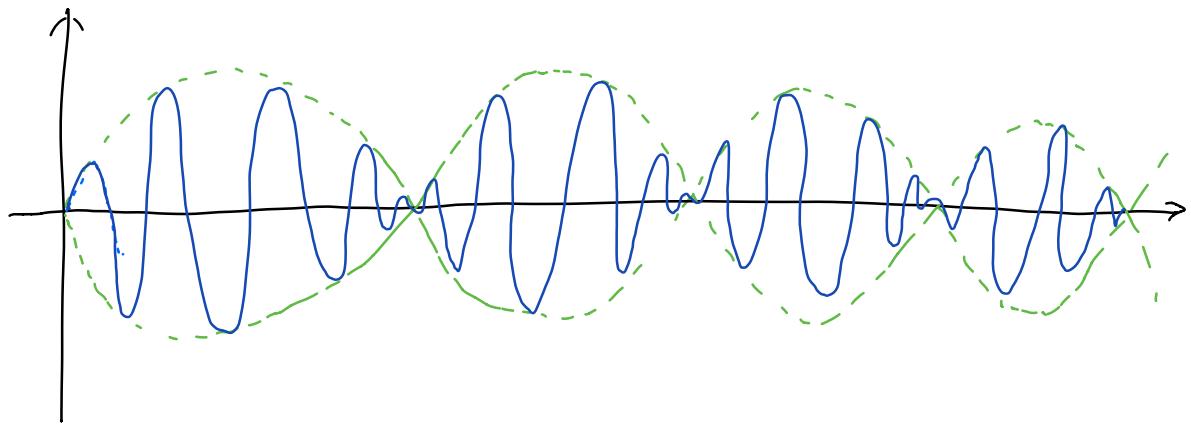
Recall trig identity: $\cos(A - B) - \cos(A + B)$

$$= 2 \sin A \sin B.$$

$$\begin{aligned} A - B &= wt. \\ A + B &= \omega_0 t \end{aligned} \Rightarrow \left\{ \begin{array}{l} A = \frac{1}{2}(\omega_0 + w)t \\ B = \frac{1}{2}(\omega_0 - w)t. \end{array} \right.$$

$$y(t) = \frac{2F_0}{m(\omega_0^2 - \omega^2)} \sin\left(\frac{\omega_0 - \omega}{2}t\right) \sin\left(\frac{\omega_0 + \omega}{2}t\right)$$

smaller
 longer period.
 not small
 shorter period.



Resonance: $\omega = \omega_0$, $y'' + \omega_0^2 y = \frac{F_0}{m} \cos \omega_0 t$.

$$A(D) = (D^2 + \omega_0^2)$$

$$P(D) = (D^2 + \omega_0^2)$$

$A(D)P(D)$ has repeated complex roots

$$\frac{i\omega_0, -i\omega_0}{J}$$

algebraic multiplicity 2.

$$\underline{y_p = t(A_1 \cos \omega_0 t + A_2 \sin \omega_0 t)}$$

$$(D^2 + \omega_0^2) y_p = \frac{F_0}{m} \cos \omega_0 t.$$

$$\Rightarrow A_1 = 0, \quad A_2 = \frac{F_0}{2m\omega_0}.$$

General solution $y(t) = y_c + y_p$

$$= A_0 \cos(\omega_0 t - \phi)$$

$\left(\frac{F_0}{2m\omega_0} + \sin \omega_0 t \right)$

$t \rightarrow +\infty$

Eventually, the spring will break.

Damping $c > 0$.

$$y'' + \frac{c}{m}y' + \frac{k}{m} = \frac{F_0}{m} \cos \omega t.$$

Anx poly $r^2 + \frac{c}{m}r + \frac{k}{m} = 0$ has not
root $\pm \omega_i$.

Plug in.

$$y_p(t) = A_1 \cos \omega t + A_2 \sin \omega t.$$

long calculation \Rightarrow

$$y_p(t) = \frac{F_0}{(k - m\omega^2)^2 + c^2\omega^2} \left[(k - m\omega^2) \cos \omega t + c\omega \sin \omega t \right]$$

general solution $y(t) = \underline{y_p} + \underline{y_c}$

$$c > 0 \Rightarrow \lim_{t \rightarrow \infty} y_c(t) \rightarrow 0$$

"transient part"

steady state.

only see the part caused by external force.

New topic chapter 3.9.

Reduction of order method to find solutions

to 2nd order ODE gives one (non-zero)

solution
to homo eqn.

Study (1) $y'' + a_1(x)y' + a_2(x)y = f(x).$

and suppose $y_1(x)$ solves the homogeneous

equation

$$\underline{y'' + a_1(x)y' + a_2(x)y = 0}.$$

We know general solution

$$y(x) = \underbrace{y_c}_{\substack{\downarrow \\ c_1 y_1 + c_2 y_2}} + y_p \quad \text{we need } y_c$$

$$c_1 y_1 + c_2 y_2 \quad \text{and } y_p$$

Ansatz: $y(x) = u(x) \cdot y_1(x)$ is a solution to

(*)

Start to compute: $y' = u'y_1 + uy_1'$.

$$y'' = u''y_1 + 2u'y_1' + uy_1''.$$

Substitute y into (F)

$$\begin{aligned} & u''y_1 + 2u'y_1' + \underline{uy_1''} + \underline{a_1(x)}(u'y_1 + \underline{uy_1'}) \\ & + \underline{a_2(x)uy_1} = f(x). \end{aligned}$$

$$\begin{aligned} & u(\underbrace{y_1'' + a_1(x)y_1' + a_2(x)y_1}_{\stackrel{(1)}{=}}) + u''y_1 + 2u'y_1' + a_2(x)uy_1 \\ & = f(x) \end{aligned}$$

$$u''y_1 + u'(2y_1' + a_2(x)y_1) = f(x).$$

$$(u')'y_1 + u'(2y_1' + a_2(x)y_1) = f(x)$$

Note: This is a 1st order ODE for u' .

Call $w = u'$.

$$w'y_1 + w(2y_1' + a_2(x)y_1) = f(x).$$

$$w' + w \cdot \left(\frac{2y_1'}{y_1} + a_1(x) \right) = \frac{F(x)}{y_1}$$

Integration factor. $e^{\int_x^x (\frac{2y_1'(s)}{y_1(s)} + a_1(s)) ds}$. (multiply on both sides)

$$\left(w \cdot e^{\int_x^x (\frac{2y_1'(s)}{y_1(s)} + a_1(s)) ds} \right)' =$$

$$\frac{F(x)}{y_1} \cdot e^{\int_x^x (\frac{2y_1'(s)}{y_1(s)} + a_1(s)) ds}$$

$$\text{Notation } I(x) = e^{\int_x^x \frac{2y_1'(s)}{y_1(s)} + a_1(s) ds}.$$

$$\frac{d}{dx} (w \cdot I) = \frac{F(x)}{y_1(x)} \cdot I(x)$$

$$w(x) = \frac{1}{I(x)} \left(\underbrace{\int_x^x \frac{I(s) F(s)}{y_1(s)} ds}_{+ C_1} + C_1 \right)$$

$$U(x) = w \Rightarrow$$

$$U(x) = \int_x^x \left(\frac{1}{I(t)} \int_t^x \frac{I(s) F(s)}{y_1(s)} ds \right) dt + C_1 \int_x^x \frac{1}{I(s)} ds$$

$$+ \underline{C_2} .$$

general solution

$$y(x) = u(x) \cdot y_1(x)$$

$$= \underline{C_2 y_1(x)} + C_1 \int^x \frac{1}{I(s)} ds$$

$$+ \underline{\int_0^x \left(\frac{1}{I(t)} \int^t + \frac{I(s)F(s)}{y_1(s)} ds \right) dt}.$$

solution to homogeneous
equation.

use $F(s) = 0$ to find $y_c(x)$

Do Not memorize the preceding formula

Just use the idea $y(x) = u(x) y_1(x)$

and start computing.

Ex: Find the general solution to

$$xy'' - 2y' + (2-x)y = 0 \quad (x > 0)$$

given one solution $y_1(x) = e^x$.

$$\text{Look for } y(x) = u(x) \cdot e^x$$

$$y' = u' \cdot e^x + u \cdot e^x$$

$$\begin{aligned} y'' &= \underline{u''e^x + 2u'e^x + ue^x} \\ x \cdot (u''e^x + 2u'e^x + ue^x) - 2(u'e^x + ue^x) \\ + (2-x) \cdot u \cdot e^x &= 0 \end{aligned}$$

$$\Rightarrow x \cdot u'' + 2u'(x-1) = 0.$$

$$w = u', \quad x \cdot w' + 2w(x-1) = 0.$$

$$w' + \frac{2(x-1)}{x} w = 0.$$

$$\begin{aligned} \text{Integration factor } I(x) &= e^{2 \int 1 - \frac{1}{x}} = e^{2(x - \log x)} \\ &= e^{2x} \cdot e^{-2\log x} \\ &= \frac{1}{x^2} \cdot e^{2x} \end{aligned}$$

$$(w \cdot \frac{1}{x^2} e^{2x})' = 0.$$

$$w = C_1 \cdot x^2 e^{-2x} = u'.$$

$$u(x) = C_1 \cdot \int x^2 e^{-2x} dx + C_2$$

$$y_1(x) = e^x, \quad = -\frac{1}{4} C_1 \cdot (1+2x+x^2) \cdot e^{-2x} + C_2$$

$$y_1(x) = C_1 e^{-x} (1+2x+x^2) + C_2 e^x$$