

介绍性课程.

DFT 离散 Fourier 变换

FFT Fast Fourier Transform.

Cooley-Tukey 1965

Gauss 1805

IBM Princeton.

多项式乘法.

$$f(x) = a_0 + a_1 x + \dots + a_d x^d \quad \deg \leq d$$

$$g(x) = b_0 + b_1 x + \dots + b_d x^d \quad \deg \leq d.$$

$$f \cdot g = a_0 b_0 + (a_1 b_0 + b_1 a_0) x + \left(\sum_l \underline{a_l} \underline{b_{k-l}} \right) x^k + \dots$$

“复杂度” 乘法 \leftarrow 更关注.
(加法) 次数.

$$C \cdot d^2$$

$$\underline{O(d^2)}$$

FFT 降到 $O(d \log d)$

f 由 x_0, x_1, \dots, x_d 的取值唯一确定.

$$x_i \neq x_j, \forall i \neq j$$

$$\begin{pmatrix} f(x_0) \\ f(x_1) \\ \vdots \\ f(x_d) \end{pmatrix} = \begin{pmatrix} 1 & x_0 & x_0^2 & \dots & x_0^d \\ 1 & x_1 & x_1^2 & \dots & x_1^d \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_d & x_d^2 & \dots & x_d^d \end{pmatrix} \begin{pmatrix} a_0 \\ a_1 \\ \vdots \\ a_d \end{pmatrix}$$

矩阵 M 范德蒙矩阵.

$$|M| = \prod_{i < j} (x_j - x_i) \neq 0. \quad M \text{ 可逆.}$$

$$\text{有} \begin{pmatrix} a_0 \\ \vdots \\ a_d \end{pmatrix} = M^{-1} \begin{pmatrix} f(x_0) \\ \vdots \\ f(x_d) \end{pmatrix}$$

$$h(x) = f(x) \cdot g(x) \quad \deg \leq 2d.$$

$$(x_0, \dots, x_{2d})$$

$$h(x_i) = f(x_i) g(x_i)$$

$O(d)$ 次运算.

10) 题: 代入值 (Evaluation)

左乘 $M \cdot \begin{pmatrix} \end{pmatrix}$

$O(d^2)$

$\frac{(2d+1)}{n} \frac{(2d+1)}{2}$

$O(dn)$

$\begin{pmatrix} a_0 \\ \vdots \\ a_d \\ 0 \\ \vdots \\ 0 \end{pmatrix}$

恢复 (re-conv) h 系数

左乘 $M^{-1} \cdot \begin{pmatrix} \end{pmatrix}_{n \times n} \begin{pmatrix} \end{pmatrix}$

$O(d^2)$

Improve $O(d^2)$ $2/n$

取 $x_1, \dots, x_{n/2}, -x_1, \dots, -x_{n/2}$

$f(x)$ even function (偶函数)

$$f(x_i) = f(-x_i)$$

odd function (奇函数)

$$f(x_i) = -f(-x_i)$$

$$f(x) = x^4 + 3x^3 + 2x^2 + x + 1$$

$$= \frac{(x^4 + 2x^2 + 1)}{f_e(x^2)} + \frac{(3x^3 + x)}{x \cdot f_o(x^2)}$$

$$\deg f = d$$

$$\deg f_e, \deg f_o \leq \frac{d}{2}$$

$$f(x_i) = \frac{f_e(x_i^2)}{x_i^{\frac{n}{2} \cdot \frac{d}{2}}} + x_i \frac{f_o(x_i^2)}{x_i^{\frac{n}{2} \cdot \frac{d}{2}}}$$

$$f(-x_i) = \frac{f_e(x_i^2)}{x_i^{\frac{n}{2} \cdot \frac{d}{2}}} - x_i \frac{f_o(x_i^2)}{x_i^{\frac{n}{2} \cdot \frac{d}{2}}}$$

$$\left(\frac{1}{2} n d \right)$$

$$\frac{f_e(x_i^2)}{x_1^2 \cdots x_{\frac{n}{2}}^2}$$

$$\frac{f_o(x_i^2)}{x_1^2 \cdots x_{\frac{n}{2}}^2}$$

$$f(x_i)$$

$$\pm x_1, \pm x_2 \cdots \pm x_{n/2}$$

± 配对
点的值

$$x_1^2, \cdots, x_{\frac{n}{2}}^2 \text{ 不是 } \pm \text{ 配对}$$

$$f$$

1

-1
 $-x_1$

$$\underline{\chi_1^2 = 1}$$

$$\frac{\sqrt{-1} = i}{x_2}$$

$$\frac{-\sqrt{-1} \pm i}{-x_2}$$

$$\underline{X_2^2 = -X_1^2 = -1}$$

3/ 入夏数 ①

$$\boxed{x_1^4} = 1.$$

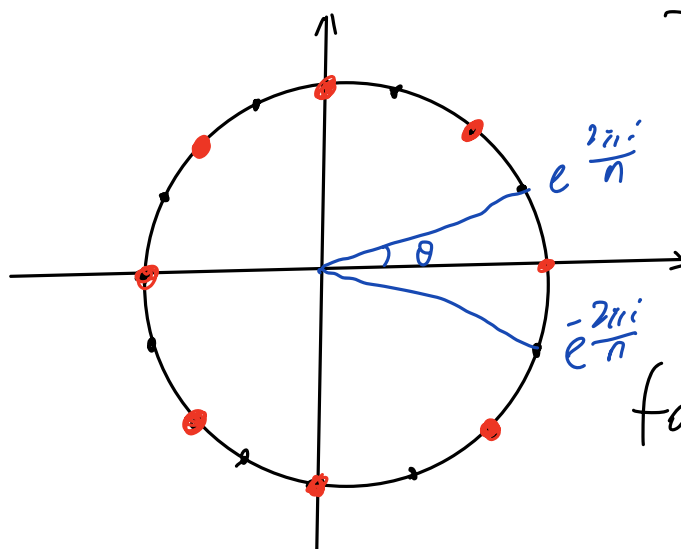
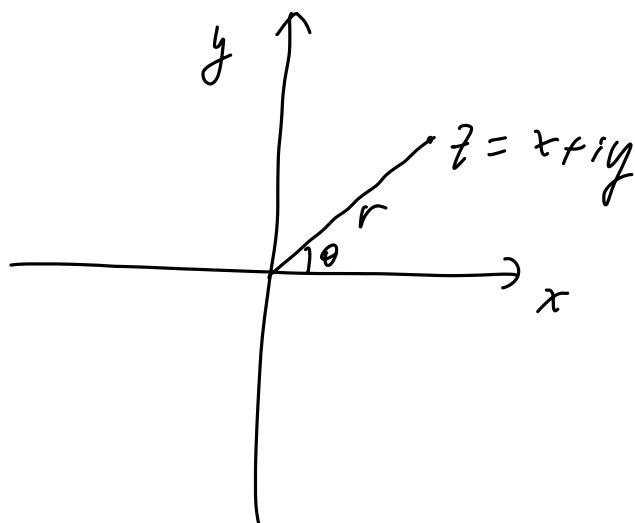
$$(f_0)_o, (f_1)_e$$

$$\underline{f(e)}, \underline{f(e)}_e$$

A handwritten diagram illustrating a sequence of operations on a 1D lattice. The top row shows a sequence of terms: $|$, -1 , $\sqrt{-1}$, $-\sqrt{-1}$, $e^{\frac{2\pi i}{8}}$, $-e^{\frac{2\pi i}{8}}$, $e^{-\frac{2\pi i}{8}}$, $-e^{\frac{2\pi i}{8}}$. The subsequent rows show how these terms are combined using diagonal lines representing multiplication or addition, leading to a final state at the bottom.

复数乘法.

$$z = r \cdot e^{i\theta} = r(\cos\theta + j\sin\theta)$$



f 16 个点

$$\boxed{e^{\frac{2\pi j}{16} \cdot k}}$$

$$0 \leq k \leq 16-1$$

for 8 个点.

归纳算法.

$$n = 2^k$$

$$w = e^{-\frac{2\pi j}{n}}$$

$$\begin{pmatrix} f(1) \\ f(w) \\ f(w^2) \\ \vdots \\ f(w^{n-1}) \end{pmatrix}$$

$$= \underbrace{\begin{pmatrix} 1 & 1 & \dots & 1 \\ 1 & w & \dots & w^{n-1} \\ 1 & w^2 & w^4 & \dots & w^{2(n-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & w^{(n-1)/2} & \dots & \dots & w^{(n-1)(n-1)/2} \end{pmatrix}}_{F_n} \begin{pmatrix} a_0 \\ \vdots \\ a_{n-1} \end{pmatrix}$$

F_n 左乘 $\begin{pmatrix} a_0 \\ \vdots \\ a_{n-1} \end{pmatrix}$ 有 recursive 算法.

“复杂度” $O(n \log n)$

相对于直接算法
 $O(n^2)$

恢复系数

F_n^{-1} 左乘 $\begin{pmatrix} f(1) \\ \vdots \\ f(n-1) \end{pmatrix}$ 是否可以简化.

定理: $(\bar{F}_n)^T \cdot F_n = n \cdot I_n.$

\bar{F}_n 是 F_n 中每个元素作 ^复共轭

证明: $F_n = (v_0, \dots, v_{n-1})$

$$(\bar{F}_n)^T \cdot F_n = \begin{pmatrix} \bar{v}_0^T \\ \bar{v}_1^T \\ \vdots \\ \bar{v}_{n-1}^T \end{pmatrix} \begin{pmatrix} v_0 & \dots & v_{n-1} \end{pmatrix}$$

$$= \begin{pmatrix} \bar{V}_i^T \cdot V_j \end{pmatrix}$$

$$\bar{V}_i^T V_j = \sum_{k=0}^{n-1} (\bar{w}^i)^k \cdot (w^j)^k$$

$$= \sum_{k=0}^{n-1} (w^{-i} \cdot w^j)^k$$

$$\boxed{\bar{w} = w^{-1}} = \sum_{k=0}^{n-1} (w^{j-i})^k$$

$$\boxed{|w|^2 = \bar{w} \cdot w = 1}$$

① $j=i$, $\bar{V}_i^T \cdot V_j = n$.

② $j \neq i$, 如果 $\underline{(j-i, n)} = 1$, $j-i, n$ 互素
最大公因数.

$(w^{j-i})^k$, $k=0, \dots, n-1$, 互不相同.

是 $x^n - 1 = 0$ 所有根.

$$\sum_{k=0}^n (w^{j-i})^k = 0.$$

w^{j-i} 是 $X^{\frac{n}{(j-i, n)}} - 1$ 的根.

$$\sum_{k=0}^n (w^{j-i})^k = 0.$$

性质: $F_n^{-1} = \frac{1}{n} (\overline{F_n})^T$

$$F_n^{-1} \cdot \begin{pmatrix} f(1) \\ \vdots \\ f(w^{n-1}) \end{pmatrix} = \frac{1}{n} \begin{pmatrix} 1 & \overline{w} & (\overline{w})^2 & \dots & (\overline{w})^{n-1} \\ 1 & (\overline{w})^2 & & & \\ \vdots & & & & \\ 1 & & & & \end{pmatrix}$$

$\overline{w} = e^{\frac{2\pi i}{n}}$ Recursive 递归算法

$O(n \log n)$

矩阵角度.

$$F_{2n} \begin{pmatrix} a_0 \\ \vdots \\ a_{n-1} \end{pmatrix} = \underbrace{\begin{pmatrix} I_n & D_n \\ \overline{I_n} & -D_n \end{pmatrix}}_{O(n)} \underbrace{\begin{bmatrix} \tilde{F}_n \\ \tilde{F}_n \end{bmatrix}}_{O(n)} \begin{pmatrix} f_{\text{even}} \\ f_{\text{odd}} \end{pmatrix}$$

$$D_n = \begin{pmatrix} 1 & & \\ & w_{2n} & \\ & & \ddots \\ & & & w_{2n}^{n-1} \end{pmatrix}$$

$$w_{2n} = e^{-\frac{2\pi i}{2n}}$$

量換矩阵

$$F_{2n} = \begin{pmatrix} I_n & D_n \\ I_n & -D_n \end{pmatrix} \begin{pmatrix} F_n & \\ & F_n \end{pmatrix} \begin{pmatrix} P_{2n} \end{pmatrix}$$

$O(n)$

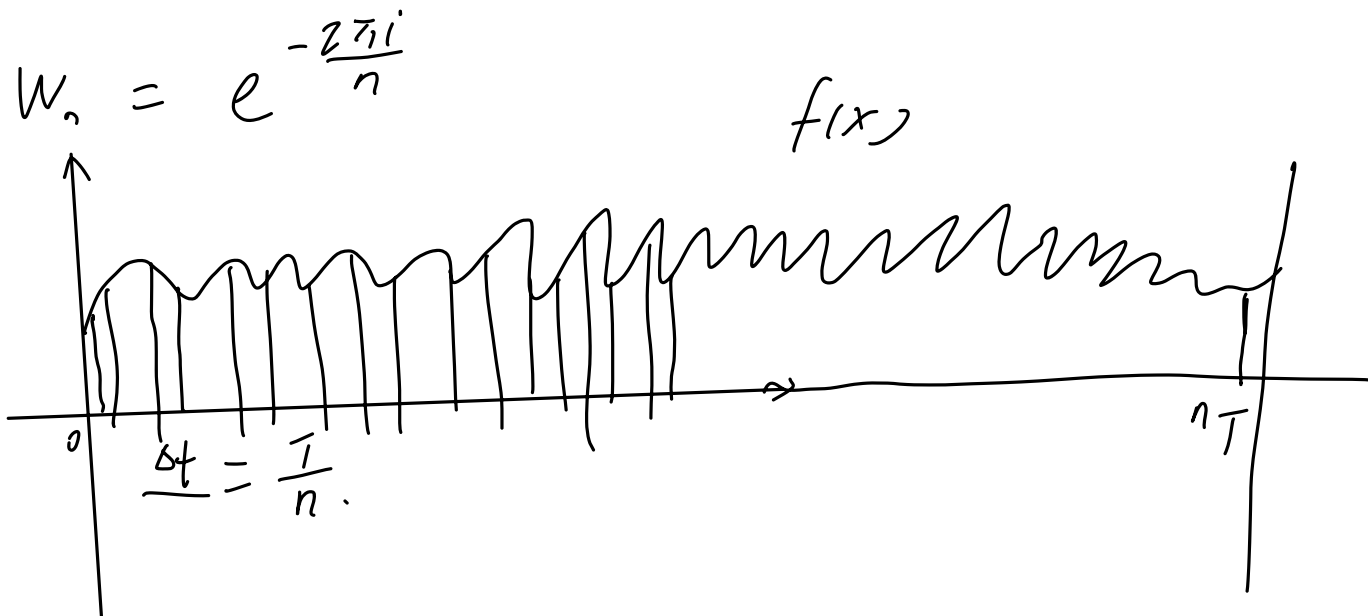
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1) 3) 4)

~~$2 \cdot O(\frac{n}{2})$~~
 $O(n)$

$O(n \log n)$

2) 常 DFT.

Discrete Fourier Transform



取 样 $f(x_k)$, $x_k = \frac{k \cdot T}{n}$

$k = 0, \dots, n-1.$

$\begin{pmatrix} f_0 \\ \vdots \\ f_{n-1} \end{pmatrix} \in \mathbb{R}^n, \quad (\mathbb{C}^n)$ 或 \mathbb{C}^n

DFT: $\mathbb{C}^n \rightarrow \mathbb{C}^n$

$\begin{pmatrix} f_0 \\ \vdots \\ f_{n-1} \end{pmatrix} \mapsto F_n \cdot \begin{pmatrix} f_0 \\ \vdots \\ f_{n-1} \end{pmatrix} = \begin{pmatrix} \hat{f}_0 \\ \vdots \\ \hat{f}_{n-1} \end{pmatrix}$

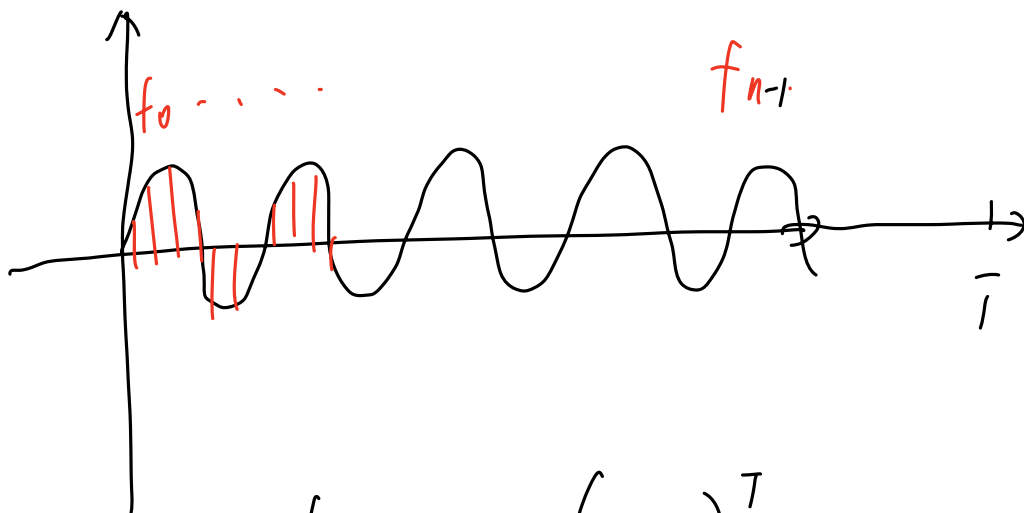
Inverse: iDFT: $\mathbb{C}^n \rightarrow \mathbb{C}^n$

$\begin{pmatrix} \hat{f}_0 \\ \vdots \\ \hat{f}_{n-1} \end{pmatrix} \mapsto \underbrace{(F_n^{-1})}_{\frac{1}{n} (\overline{F_n})^T} \begin{pmatrix} \hat{f}_0 \\ \vdots \\ \hat{f}_{n-1} \end{pmatrix}$

$f = \sin(2\pi a t)$

$= \frac{e^{2\pi i a t} - e^{-2\pi i a t}}{2i}$

$a \frac{1}{T} \text{ 的 数.}$



$$\underline{DFT} (f_0 \dots f_{n-1})^T$$

研究 $e^{2\pi i a t} = f(x)$

$$f_k = e^{2\pi i a \left(k \frac{T}{n}\right)}$$

$$DFT (f_0, \dots, f_{n-1})^T$$

$$= (\hat{f}_0 \dots \hat{f}_{n-1})$$

$$\hat{f}_a = \sum_{l=0}^{n-1} (w^k)^l \cdot e^{2\pi i \left(\frac{aT}{n} \cdot l\right)}$$

$$= \sum_{l=0}^{n-1} e^{2\pi i \left(\frac{aT}{n} - \frac{k}{n}\right) \cdot l}$$

$$= \sum_{l=0}^{n-1} e^{2\pi i \frac{(aT-k)l}{n}}$$

aT 整数.

$$\frac{k = aT \pmod{n}}{k \neq aT \pmod{n}} = n$$

$$= 0.$$

$|\hat{f}_n|$ 大的 k .

$$\frac{k}{T} = a$$

$$a > 0$$

$$f(t) = e^{-2\pi i a t}$$

$$k = n - aT$$

如果 $f(t) = \overline{f(t)}$,

$\hat{f}_0 \dots \hat{f}_{n-1}$ 有 "对称性"

$$\hat{f}_n = \overline{\hat{f}_{n-n}}$$

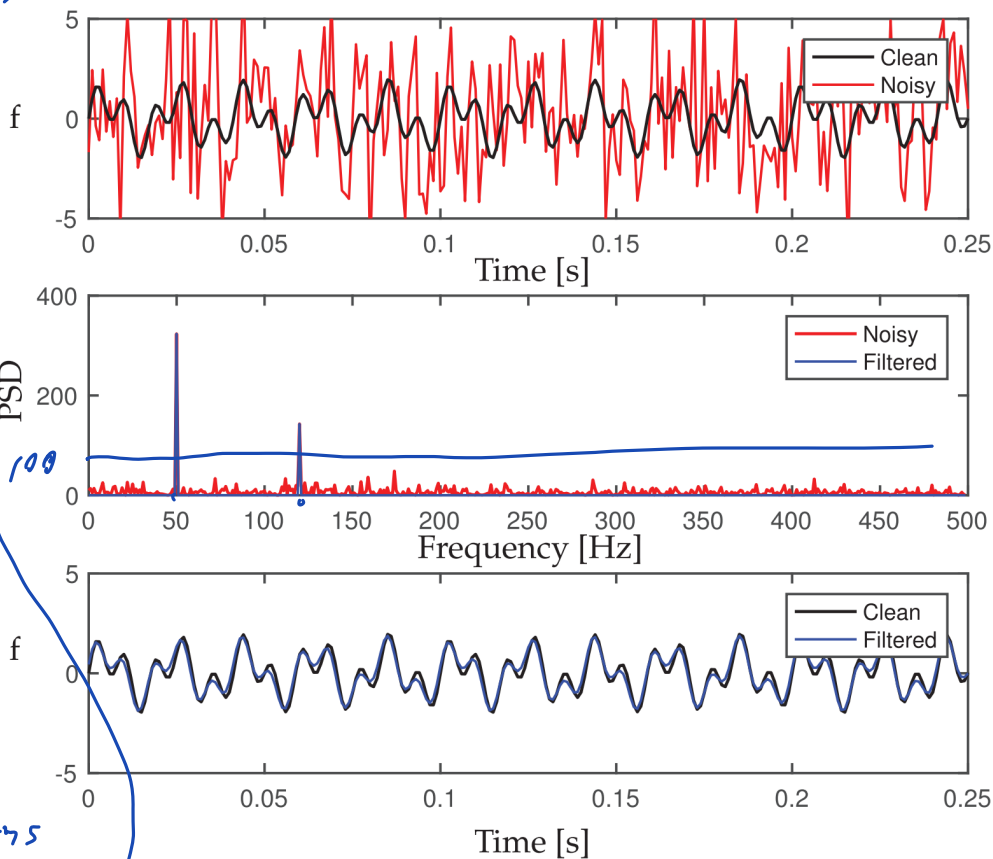
$$f = \sin(2\pi f_1 t) + \sin(2\pi f_2 t)$$

$$f_1 = 50, \quad f_2 = 120$$

$$f + \text{Noise}, \quad T = 1, \quad n = 1000$$

This part is
from
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Data-Driven
Science and
Engineering
Machine Learning
Dynamical Systems
and Control



$\frac{k}{T}$ 5-1

$$\text{PSD} = \frac{|\hat{f}_k|^2}{n}$$

by S.L. Bruntos and J.V. Katz

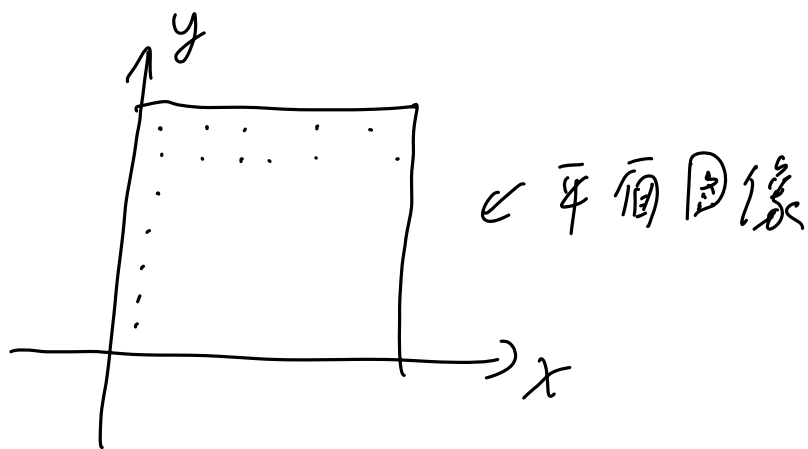
$$\text{filtered } f = \text{IDFT} \left(\hat{f}_k \cdot \{ \text{PSD} > 100 \} \right)$$

↓
示性函数

← f 不加 noise 有非0值
 $|\hat{f}_k|^2$ 在 50, 120.
 $\frac{1000 \cdot 50, 1000 \cdot 120}{-120}$

① De noise

② compress



(x_k, y_l) 对 $f(x_k, y_l)$ 二维 DFT.

去掉 $|f(k, l)|$ 小的值.