```
┌─────────────────────────────────────┐
│         view_frames Result          │
│                                     │
│  Recorded at time: 1736541044.3951333 │
└─────────────────────────────────────┘

                  robot1/map
                       │
        Broadcaster: default_authority
        Average rate: 5.208
        Buffer length: 4.8
        Most recent transform: 98.153
        Oldest transform: 93.353
                       │
                 robot1/odom
                       │
        Broadcaster: default_authority
        Average rate: 29.61
        Buffer length: 5.032
        Most recent transform: 97.355
        Oldest transform: 92.323
                       │
            robot1/base_footprint
                       │
        Broadcaster: default_authority
        Average rate: 10000.0
        Buffer length: 0.0
        Most recent transform: 0.0
        Oldest transform: 0.0
                       │
                robot1/base_link
```

- robot1/base_link → robot1/camera_link
  Broadcaster: default_authority
  Average rate: 10000.0
  Buffer length: 0.0
  Most recent transform: 0.0
  Oldest transform: 0.0

- robot1/base_link → robot1/caster_back_left_link
  Broadcaster: default_authority
  Average rate: 10000.0
  Buffer length: 0.0
  Most recent transform: 0.0
  Oldest transform: 0.0

- robot1/base_link → robot1/caster_back_right_link
  Broadcaster: default_authority
  Average rate: 10000.0
  Buffer length: 0.0
  Most recent transform: 0.0
  Oldest transform: 0.0

- robot1/base_link → robot1/imu_link
  Broadcaster: default_authority
  Average rate: 10000.0
  Buffer length: 0.0
  Most recent transform: 0.0
  Oldest transform: 0.0

- robot1/base_link → robot1/base_scan
  Broadcaster: default_authority
  Average rate: 10000.0
  Buffer length: 0.0
  Most recent transform: 0.0
  Oldest transform: 0.0

- robot1/base_link → robot1/wheel_left_link
  Broadcaster: default_authority
  Average rate: 19.608
  Buffer length: 4.998
  Most recent transform: 97.355
  Oldest transform: 92.357

- robot1/base_link → robot1/wheel_right_link
  Broadcaster: default_authority
  Average rate: 19.608
  Buffer length: 4.998
  Most recent transform: 97.355
  Oldest transform: 92.357

- robot1/camera_link → robot1/camera_rgb_frame
  Broadcaster: default_authority
  Average rate: 10000.0
  Buffer length: 0.0
  Most recent transform: 0.0
  Oldest transform: 0.0

- robot1/camera_rgb_frame → robot1/camera_rgb_optical_frame
  Broadcaster: default_authority
  Average rate: 10000.0
  Buffer length: 0.0
  Most recent transform: 0.0
  Oldest transform: 0.0