view_frames Result

Recorded at time: 1735001635.1983316

robot1/map

Broadcaster: default_authority
Average rate: 5.208
Buffer length: 4.8
Most recent transform: 47.894
Oldest transform: 43.094

robot1/odom

Broadcaster: default_authority
Average rate: 29.612
Buffer length: 4.998
Most recent transform: 45.994
Oldest transform: 40.996

robot1/base_footprint

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot1/base_link

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 19.675
Buffer length: 4.93
Most recent transform: 45.96
Oldest transform: 41.03

Broadcaster: default_authority
Average rate: 19.675
Buffer length: 4.93
Most recent transform: 45.96
Oldest transform: 41.03

robot1/camera_link

robot1/caster_back_left_link

robot1/caster_back_right_link

robot1/imu_link

robot1/base_scan

robot1/wheel_left_link

robot1/wheel_right_link

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot1/camera_rgb_frame

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot1/camera_rgb_optical_frame