

Measures

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For Continuous Data

1. Central Tendency
2. Variability or Dispersion
3. Skewness
4. Kurtosis

Central Tendency

Common central tendency measures: mean, median, mode (the most frequent value)

Mean

Sample Mean:

$$\bar{x} = \frac{\sum x_i}{n}$$

Population Mean:

$$\mu = \frac{\sum X_i}{N}$$

Median

Sample Median: \tilde{x}

Population Median: η (eta)

Dispersion or Variability

4 common measures of dispersion:

1. Range: $R = \max - \min$
2. Variance: population $\sigma^2 = \frac{\sum (X_i - \mu)^2}{N}$, sample $s^2 = \frac{\sum (x_i - \bar{x})^2}{n-1} = \frac{\sum x_i^2 - \frac{(\sum x_i)^2}{n}}{n-1}$
3. Standard Deviation: population $\sigma = \sqrt{\sigma^2}$, sample $s = \sqrt{s^2}$

4. Coefficient of Variation (CV): population $CV = \frac{\sigma}{\mu} \times 100\%$, sample $CV = \frac{s}{\bar{x}} \times 100\%$
(no unit)

Remark. *Why use $n - 1$? because it is proved to be more accurate.*

Disadvantages of Range: sensitive to outliers

Variance represents the distance from the mean

Variance and Standard Deviation are absolute measures of dispersion (about mean), while Coefficient of Variation is a relative measure of dispersion (about mean).

Skewness

Aka. shape of the distribution

3 types of skewness:

1. Symmetrical: mean = median = mode
2. Right Skewness or Positive Skewness: mean \gg median
3. Left Skewness or Negative Skewness: mean \ll median

Skewness Coefficient (g_1): $g_1 = \frac{\frac{\sum(X_i - \bar{x})^3}{n-1}}{s^3}$

1. $g_1 = 0$: symmetrical
2. $g_1 > 0$: right skewness
3. $g_1 < 0$: left skewness

Kurtosis

$$g_2 = \frac{\frac{\sum(x_i - \bar{x})^4}{n-1}}{s^4} - 3$$

1. $g_2 = 0$: meso-kurtic
2. $g_2 > 0$: leptokurtic (more peaked)
3. $g_2 < 0$: platykurtic (less peaked)

Measures of Non-central Tendency

1. Quartiles: Q_1, Q_2, Q_3
2. Percentiles: P_1, P_2, \dots, P_{99} : E.g. $P_{20} \Rightarrow 20\%$ data $\leq P_{20}$
3. Interquartile Range (IQR): $Q_3 - Q_1$

How to find Quartiles

1. Arrange data in **ascending order**
2. Cal $Q_1 = 0.25 * (n + 1)$; $Q_3 = 0.75 * (n + 1)$;

3. If Q_1 or Q_3 is not an integer, take the average of the two values around it.