Measures

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For Continuous Data

- 1. Central Tendency
- 2. Variability or Dispersion
- 3. Skewness
- 4. Kurtosis

Central Tendency

Common central tendency measures: mean, median, mode (the most frequent value)

Mean

Sample Mean:

$$\bar{x} = \frac{\sum x_i}{n}$$

Population Mean:

$$\mu = \frac{\sum X_i}{N}$$

Median

Sample Median: \tilde{x}

Population Median: η (eta)

Dispersion or Variability

4 common measures of dispersion:

1. Range: $R = \max - \min$

2. Variance: population $\sigma^2 = \frac{\sum (X_i - \mu)^2}{N}$, sample $s^2 = \frac{\sum (x_i - \bar{x})^2}{n-1} = \frac{\sum x_i^2 - \frac{(\sum x_i)^2}{n}}{n-1}$

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3. Standard Deviation: population $\sigma = \sqrt{\sigma^2}$, sample $s = \sqrt{s^2}$

4. Coefficient of Variation (CV): population $CV = \frac{\sigma}{\mu} \times 100\%$, sample $CV = \frac{s}{\bar{x}} \times 100\%$ (no unit)

Remark. Why use n-1? because it is proved to be more accurate.

Disadvantages of Range: sensitive to outliers

Variance represents the distance from the mean

Variance and Standard Deviation are absolute measures of dispersion (about mean), while Coefficient of Variation is a relative measure of dispersion (about mean).

Skewness

Aka. shape of the distribution

3 types of skewness:

- 1. Symmetrical: mean = median = mode
- 2. Right Skewness or Positive Skewness: mean >> median
- 3. Left Skewness or Negative Skewness: mean << median

Skewness Coefficient (g_1) : $g_1 = \frac{\sum (X_i - \bar{x})^3}{s^3}$

- 1. $g_1 = 0$: symmetrical
- 2. $g_1 > 0$: right skewness
- 3. $g_1 < 0$: left skewness

Kurtosis

$$g_2 = \frac{\frac{\sum (x_i - \bar{x})^4}{n-1}}{s^4} - 3$$

- 1. $g_2 = 0$: meso-kurtic
- 2. $g_2 > 0$: lepto-kurtic (more peaked)
- 3. $g_2 < 0$: platy-kurtic (less peaked)

Measures of Non-central Tendency

- 1. Quartiles: Q1, Q2, Q3
- 2. Percentiles: P1, P2, ..., P99: E.g. $P_{20} \Rightarrow 20\%$ data $<= P_{20}$
- 3. Interquartile Range (IQR): $Q_3 Q_1$

How to find Quartiles

- 1. Arrange data in ascending order
- 2. Cal $Q_1 = 0.25 * (n+1); Q_3 = 0.5 * (n+1);$

3. If Q_1 or Q_3 is not an integer, take the average of the two values around it.