
Section 10: Advanced Regression + Geometry of Least Squares

TF: Reagan Rose (rrose@g.harvard.edu)

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Motivation

The methods we've used so far in this class provide techniques for analyzing data in *one dimension*. But in statistics, we're never interested in analyzing just one observation of data or just one variable. Statistics and data are inherently *multidimensional*. To deal with this, instead of applying our one-dimensional techniques to every single line of data or every single variable of interest, we use **multivariate notation** and **linear algebra** to make our lives easier and do analyses quickly and easily!

Review of Linear Algebra

First let's review some basic concepts from linear algebra.

Vectors

If we have two vectors p -dimensional vectors \mathbf{u} and \mathbf{v} , then we have the following **vector operations**:

- **Dot product:** $\mathbf{u} \cdot \mathbf{v} = \mathbf{u}^T \mathbf{v} = \sum_{i=1}^p u_i v_i$
- **Norm:** $\|\mathbf{u} - \mathbf{v}\|^2 = (\mathbf{u} - \mathbf{v}) \cdot (\mathbf{u} - \mathbf{v}) = \|\mathbf{u}\|^2 + \|\mathbf{v}\|^2 - 2\mathbf{u} \cdot \mathbf{v}$

and **vector properties**:

- **orthogonality:** $\mathbf{u} \perp \mathbf{v}$ if $\mathbf{u} \cdot \mathbf{v} = 0$.
- **decomposition:** for an arbitrary vector $\mathbf{y} \in \mathbb{R}^p$, $\mathbf{y} = \hat{\mathbf{y}} + \mathbf{y}^\perp$

Let's call $\hat{\mathbf{y}}$ the "best linear predictor of \mathbf{y} ", where "best" means that

$$\|\mathbf{y} - \hat{\mathbf{y}}\| < \|\mathbf{y} - \mathbf{v}\|^2$$

for every vector $\mathbf{v} \neq \hat{\mathbf{y}}$ in a subspace $V \subseteq \mathbb{R}^p$. Equivalently, we can write

$$\arg \min_{\mathbf{v} \in V} \|\mathbf{y} - \mathbf{v}\|^2 = \hat{\mathbf{y}}.$$

In other words, $\hat{\mathbf{y}}$ is the "closest" vector to \mathbf{y} in the subspace V .

Matrices

Matrices can be tricky to work with. So let's review some basic concepts and properties. Below is a list of important **matrix operations** that you'll need to remember when working with regression formulae. To get started, let \mathbf{a} be an arbitrary $p \times 1$ vector, \mathbf{b} an arbitrary $1 \times b$ vector, and \mathbf{M} an arbitrary $p \times p$ matrix. The following properties hold

- **Vector/Matrix equivalence:** Every vector is a matrix. The converse is not true.
- **Matrix multiplication:** Matrices can be multiplied if the *inner dimensions* match (i.e. $(p \times 1) \times (1 \times p)$ can be multiplied and will be a $p \times p$ matrix. $(p \times 1) \times (n \times 1)$ cannot be multiplied). Order does matter in matrix multiplication (i.e. $\mathbf{A} \times \mathbf{B} \neq \mathbf{B} \times \mathbf{A}$), and multiplication is done using *row by column* logic.
- **Addition/Subtraction:** Matrices of the same dimension can be added and subtracted pointwise
- **Column space:** $C(\mathbf{X}) = \text{Column space of } \mathbf{X} = \{\mathbf{X}\mathbf{a} : \text{all vectors } \mathbf{a} \in \mathbb{R}^p\}$
- **Inverse:** Only square matrices can be inverted. If $\mathbf{M} = \begin{pmatrix} m_{11} & m_{12} \\ m_{21} & m_{22} \end{pmatrix}$ then

$$\mathbf{M}^{-1} = \frac{1}{m_{11}m_{22} - m_{12}m_{21}} \begin{pmatrix} m_{22} & -m_{12} \\ -m_{21} & m_{11} \end{pmatrix}$$

Multiple Regression Framework

Now let's apply these linear algebra concepts to multiple linear regression. Recall that the general framework for regression assumes that we have data:

$$(Y_1, \mathbf{X}_1), \dots, (Y_n, \mathbf{X}_n)$$

where $Y_i, i = 1, \dots, n$ is the outcome variable for observation i and $\mathbf{X}_i = (X_{i1}, \dots, X_{ip})$ is a vector of p predictor variables for observation i . Usually we let $X_{i1} = 1$ for all i to represent the intercept term. This then allows us to write the **multiple regression model**

$$Y_i = \mathbf{X}_i\boldsymbol{\beta} + \epsilon_i,$$

where as usual $\epsilon_i \sim^{iid} \mathcal{N}(0, \sigma^2)$ represents the "noise" in the model and $\boldsymbol{\beta} = (\beta_0, \beta_1, \dots, \beta_p)$ is the coefficient vector. We can then compile this into a compact, matrix-form equation as follows:

$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\epsilon},$$

where $\mathbf{Y} = (Y_1, \dots, Y_n)^T$ is a vector of outcomes,

$$\mathbf{X} = \begin{pmatrix} \mathbf{X}_1 \\ \dots \mathbf{X}_n \end{pmatrix} = \begin{pmatrix} X_{11} & X_{12} & \dots & X_{1p} \\ \vdots & \vdots & \ddots & \vdots \\ X_{n1} & X_{n2} & \dots & X_{np} \end{pmatrix}$$

is a matrix of predictors and $\boldsymbol{\epsilon} = (\epsilon_1, \dots, \epsilon_n) \sim \mathcal{N}_p(\mathbf{0}, \sigma^2 I_p)$ is a random vector of "noise" drawn from a *multivariate normal distribution*. We call \mathbf{X} the **model matrix**, which is an extremely important concept in the theory of linear models.

Note that $\mathbf{X}\boldsymbol{\beta}$ is matrix multiplication, so we can think of this as

$$\mathbf{X}\boldsymbol{\beta} = \begin{pmatrix} X_{11} & X_{12} & \dots & X_{1p} \\ \vdots & \vdots & \ddots & \vdots \\ X_{n1} & X_{n2} & \dots & X_{np} \end{pmatrix} \begin{pmatrix} \beta_1 \\ \vdots \\ \beta_p \end{pmatrix} = \beta_1 \begin{pmatrix} X_{11} \\ \vdots \\ X_{n1} \end{pmatrix} + \dots + \beta_p \begin{pmatrix} X_{1p} \\ \vdots \\ X_{np} \end{pmatrix} = \beta_1 \mathbf{X}_{\cdot 1} + \dots + \beta_p \mathbf{X}_{\cdot p}.$$

The Least Squares Problem

Note that we can define the **residuals** as:

$$e_i = Y_i - \mathbf{X}_i \hat{\boldsymbol{\beta}}$$

in matrix/vector form, this becomes

$$\mathbf{e} = \mathbf{Y} - \mathbf{X}\boldsymbol{\beta}.$$

The **least squares problem** then can be expressed as:

$$\min_{\boldsymbol{\beta}} \|\mathbf{e}\|^2 = \min_{\boldsymbol{\beta}} \|\mathbf{Y} - \mathbf{X}\boldsymbol{\beta}\|^2.$$

Differentiating this and setting equal to zero yields the least squares estimator

$$\hat{\boldsymbol{\beta}} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{Y}.$$

Geometry of Least Squares

A important decomposition used in linear regression is

$$\mathbf{y} = \hat{\mathbf{y}} + \mathbf{y}^\perp,$$

where $\hat{\mathbf{y}} = \mathbf{X}\hat{\boldsymbol{\beta}}$ is the predicted value of \mathbf{y} and $\mathbf{y}^\perp = \mathbf{Y} - \mathbf{X}\hat{\boldsymbol{\beta}}$ is the orthogonal component of \mathbf{y} . Thus, somewhat obviously:

$$\mathbf{Y} = \mathbf{X}\hat{\boldsymbol{\beta}} + (\mathbf{Y} - \mathbf{X}\hat{\boldsymbol{\beta}}) = \mathbf{X}\hat{\boldsymbol{\beta}} + \mathbf{e}.$$

But this is important because of what we know about the Pythagorean Theorem: when $\mathbf{u} \perp \mathbf{v}$, $\|\mathbf{u} + \mathbf{v}\|^2 = \|\mathbf{u}\|^2 + \|\mathbf{v}\|^2$. Thus we have

$$\mathbf{X}\hat{\boldsymbol{\beta}} \perp \mathbf{e} \implies \|\mathbf{Y}\|^2 = \|\mathbf{X}\hat{\boldsymbol{\beta}}\|^2 + \|\mathbf{e}\|^2$$

so that if everything is centered around 0, we have derived:

$$SST = SSR + SSE.$$

Also recall from linear algebra that if we consider $\mathbf{x} - \bar{\mathbf{x}}$ and $\mathbf{Y} - \bar{\mathbf{Y}}$ as vectors, and consider the angle, θ , between them, then we can write:

$$\cos(\theta) = \frac{(\mathbf{x} - \bar{\mathbf{x}}) \cdot (\mathbf{Y} - \bar{\mathbf{Y}})}{\|\mathbf{x} - \bar{\mathbf{x}}\| \|\mathbf{Y} - \bar{\mathbf{Y}}\|}$$

then plugging in what we know about these terms will tell us that

$$\cos(\theta) = \frac{S_{XY}}{S_X S_Y} = \hat{\beta}_1 \frac{S_X}{S_Y} = R.$$

So the angle between the (centered) predictors and the (centered) outcome vector tells us exactly the correlation coefficient!. It is also possible to prove that

$$\cos^2(\theta) = R^2,$$

where R^2 is the coefficient of determination for the regression. This makes sense, since when \mathbf{Y} and $\mathbf{X}\hat{\beta}$ are close, then \mathbf{X} gives us a lot of information to get a good estimate for \mathbf{Y} , so $\cos(\theta)$ is high, and so is R^2 .

Exercises

Question 1. Regression 3 Ways

Suppose we have the following dataset, with one outcome variable Y , one predictor variable X and two observations:

$$\mathbf{Y} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \quad \mathbf{X} = \begin{pmatrix} 2.5 \\ 1.1 \end{pmatrix}.$$

- (a) Find β_0 and β_1 for the regression model for this data: $\hat{Y}_i = \hat{\beta}_0 + \hat{\beta}_1 X_i$, using the **univariate formulas** you know.
- (b) Solve for $\hat{\beta} = (\beta_0, \beta_1)^T$ **by hand** using the **matrix/vector formulas** you know.
- (c) Now solve for β_0 and β_1 using the **lm function** in R.
- (d) Finally, solve for $\hat{\beta} = (\beta_0, \beta_1)^T$ using **matrix multiplication** in R.

Question 2. Download the HEIGHT.CSV dataset we worked with last week. We're interested in modeling child height based on all of the other variables.

- (a) Construct the model matrix \mathbf{X} for this model.
- (b) Use matrix multiplication to calculate the regression coefficients.
- (c) Use matrix multiplication to find the standard errors of the regression coefficients, and use these to find the t -statistics for each of the coefficients.
- (d) Report the final model, including only the significant predictors.