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1 Reminder

1.1 Bug List

- 沒開 long long
- 陣列戳出界 / 開不夠大 / 開太大本地 compile 噴怪 error
- 傳之前先確定選對檔案
- 寫好的函式忘記呼叫
- 變數打錯
- 0-base / 1-base
- 忘記初始化
- == 打成 =
- <= 打成 <+
- dp[i] 從 dp[i-1] 轉移時忘記特判 i > 0
- std::sort 比較運算子寫成 < 或是讓 = 的情況為 true
- 漏 case / 分 case 要好好想
- 線段樹改值懶標初始值不能設為 0
- DFS 的時候不小心覆寫到全域變數
- 浮點數誤差
- 多筆測資不能沒讀完直接 return
- 記得刪 cerr

1.2 OwO

- 可以構造複雜點的測資幫助思考
- 真的卡太久請跳題
- Enjoy The Contest!

2 Basic

2.1 Vimrc

```

set number relativenumber ai t_Co=256 tabstop=4
set mouse=a shiftwidth=4 encoding=utf8
set bs=2 ruler laststatus=2 cmdheight=2
set clipboard=unnamedplus showcmd autoread
set belloff=all
filetype indent on
"set guifont Hack:h16
":set guifont?

inoremap ( (<Esc>i
inoremap " "<Esc>i
inoremap [ [<Esc>i
inoremap ' '<Esc>i
inoremap { {<CR><Esc>ko

vmap <C-c> "+y
inoremap <C-v> <Esc>p
nnoremap <C-v> p

nnoremap <tab> gt
nnoremap <S-tab> gT
inoremap <C-n> <Esc>:tabnew<CR>
nnoremap <C-n> :tabnew<CR>

inoremap <F9> <Esc>:w<CR>:!~/runcpp.sh %:p:t %:p:h<CR>
nnoremap <F9> :w<CR>:!~/runcpp.sh %:p:t %:p:h<CR>

syntax on
colorscheme desert
set filetype=cpp
set background=dark
hi Normal ctermfg=white ctermbg=black

```

2.2 Runcpp.sh

```

#!/bin/bash
clear
echo "Start compiling $1..."
echo
g++ -O2 -std=c++20 -Wall -Wextra -Wshadow $2/$1 -o $2/
out
if [ "$?" -ne 0 ]
then

```

```

8     exit 1
9 fi
10 echo
11 echo "Done compiling"
12 echo "=====
13 echo
14 echo "Input file:"
15 echo
16 cat $2/in.txt
17 echo
18 echo "=====
19 echo
20 declare startTime=`date +%s%N`
21 $2/out < $2/in.txt > $2/out.txt
22 declare endTime=`date +%s%N`
23 delta=`expr $endTime - $startTime`
24 delta=`expr $delta / 1000000`
25 cat $2/out.txt
26 echo
27 echo "time: $delta ms"

```

2.3 Stress

```

1 g++ gen.cpp -o gen.out
2 g++ ac.cpp -o ac.out
3 g++ wa.cpp -o wa.out
4 for ((i=0;;i++))
5 do
6     echo "$i"
7     ./gen.out > in.txt
8     ./ac.out < in.txt > ac.txt
9     ./wa.out < in.txt > wa.txt
10    diff ac.txt wa.txt || break
11 done

```

2.4 PBDS

```

1 #include <bits/extc++.h>
2 using namespace __gnu_pbds;
3
4 // map
5 tree<int, int, less<>, rb_tree_tag,
6     tree_order_statistics_node_update> tr;
7 tr.order_of_key(element);
8 tr.find_by_order(rank);
9
10 // set
11 tree<int, null_type, less<>, rb_tree_tag,
12     tree_order_statistics_node_update> tr;
13 tr.order_of_key(element);
14 tr.find_by_order(rank);
15
16 // hash table
17 gp_hash_table<int, int> ht;
18 ht.find(element);
19 ht.insert({key, value});
20 ht.erase(element);
21
22 // priority queue
23 __gnu_pbds::priority_queue<int, less<int>> big_q;
24 // Big First
25 __gnu_pbds::priority_queue<int, greater<int>> small_q;
26 // Small First
27 q1.join(q2);
28
29 // join

```

2.5 Random

```

1 mt19937 gen(chrono::steady_clock::now().
2     time_since_epoch().count());
3 uniform_int_distribution<int> dis(1, 100);
4 cout << dis(gen) << endl;
5 shuffle(v.begin(), v.end(), gen);

```

3 Data Structure

3.1 BIT

```

1 struct BIT {
2     int n;
3     long long bit[N];
4
5     void init(int x, vector<long long> &a) {
6         n = x;
7         for (int i = 1, j; i <= n; i++) {
8             bit[i] += a[i - 1], j = i + (i & -i);
9             if (j <= n) bit[j] += bit[i];
10        }
11    }
12
13    void update(int x, long long dif) {
14        while (x <= n) bit[x] += dif, x += x & -x;
15    }
16
17    long long query(int l, int r) {
18        if (l != 1) return query(1, r) - query(1, l -
19            1);
20
21        long long ret = 0;
22        while (l <= r) ret += bit[r], r -= r & -r;
23        return ret;
24    }
25 } bm;

```

3.2 DSU

```

1 struct DSU {
2     int h[N], s[N];
3
4     void init(int n) { iota(h, h + n + 1, 0), fill(s, s
5         + n + 1, 1); }
6
7     int fh(int x) { return (h[x] == x ? x : h[x] = fh(h
8         [x])); }
9
10    bool mer(int x, int y) {
11        x = fh(x), y = fh(y);
12        if (x == y) return 0;
13        if (s[x] < s[y]) swap(x, y);
14        s[x] += s[y], s[y] = 0;
15        h[y] = x;
16        return 1;
17    }
18 } bm;

```

3.3 Segment Tree

```

1 struct segtree {
2     int n, seg[1 << 19];
3
4     void init(int x) {
5         n = 1 << (lg(x) + 1);
6         for (int i = 1; i < 2 * n; i++)
7             seg[i] = inf;
8     }
9
10    void update(int x, int val) {
11        x += n;
12        seg[x] = val, x /= 2;
13        while (x)
14            seg[x] = min(seg[2 * x], seg[2 * x + 1]), x
15                /= 2;
16    }
17
18    int query(int l, int r) {
19        l += n, r += n;
20        int ret = inf;
21        while (l < r) {
22            if (l & 1)
23                ret = min(ret, seg[l++]);
24            if (r & 1)
25                ret = min(ret, seg[--r]);
26            l /= 2, r /= 2;
27        }
28        return ret;
29    }
30 } bm;

```

3.4 Treap

```

1 mt19937 rng(random_device{}());
2 struct Treap {
3     Treap *l, *r;
4     int val, num, pri;
5     Treap(int k) {
6         l = r = NULL;
7         val = k;
8         num = 1;
9         pri = rng();
10    }
11};
12 int siz(Treap *now) { return now ? now->num : 0; }
13 void pull(Treap *&now) {
14     now->num = siz(now->l) + siz(now->r) + 1;
15 }
16 Treap *merge(Treap *a, Treap *b) {
17     if (!a || !b)
18         return a ? a : b;
19     else if (a->pri > b->pri) {
20         a->r = merge(a->r, b);
21         pull(a);
22         return a;
23     } else {
24         b->l = merge(a, b->l);
25         pull(b);
26         return b;
27     }
28 }
29 void split_size(Treap *rt, Treap *&a, Treap *&b, int
    val) {
30     if (!rt) {
31         a = b = NULL;
32         return;
33     }
34     if (siz(rt->l) + 1 > val) {
35         b = rt;
36         split_size(rt->l, a, b->l, val);
37         pull(b);
38     } else {
39         a = rt;
40         split_size(rt->r, a->r, b, val - siz(a->l) - 1);
41         pull(a);
42     }
43 }
44 void split_val(Treap *rt, Treap *&a, Treap *&b, int val)
    {
45     if (!rt) {
46         a = b = NULL;
47         return;
48     }
49     if (rt->val <= val) {
50         a = rt;
51         split_val(rt->r, a->r, b, val);
52         pull(a);
53     } else {
54         b = rt;
55         split_val(rt->l, a, b->l, val);
56         pull(b);
57     }
58 }
59 void treap_dfs(Treap *now) {
60     if (!now) return;
61     treap_dfs(now->l);
62     cout << now->val << " ";
63     treap_dfs(now->r);
64 }

```

3.5 Persistent Treap

```

1 struct node {
2     node *l, *r;
3     char c;
4     int v, sz;
5     node(char x = '$') : c(x), v(mt()), sz(1) {
6         l = r = nullptr;
7     }
8     node(node* p) { *this = *p; }
9     void pull() {

```

```

10         sz = 1;
11         for (auto i : {l, r})
12             if (i) sz += i->sz;
13     }
14 } arr[maxn], *ptr = arr;
15 inline int size(node* p) { return p ? p->sz : 0; }
16 node* merge(node* a, node* b) {
17     if (!a || !b) return a ? a : b;
18     if (a->v < b->v) {
19         node* ret = new (ptr++) node(a);
20         ret->r = merge(ret->r, b);
21         ret->pull();
22         return ret;
23     } else {
24         node* ret = new (ptr++) node(b);
25         ret->l = merge(a, ret->l);
26         ret->pull();
27         return ret;
28     }
29 }
30 P<node*> split(node* p, int k) {
31     if (!p) return {nullptr, nullptr};
32     if (k >= size(p->l) + 1) {
33         auto [a, b] = split(p->r, k - size(p->l) - 1);
34         node* ret = new (ptr++) node(p);
35         ret->r = a;
36         ret->pull();
37         return {ret, b};
38     } else {
39         auto [a, b] = split(p->l, k);
40         node* ret = new (ptr++) node(p);
41         ret->l = b;
42         ret->pull();
43         return {a, ret};
44     }
45 }

```

3.6 Li Chao Tree

```

1 constexpr int maxn = 5e4 + 5;
2 struct line {
3     ld a, b;
4     ld operator()(ld x) { return a * x + b; }
5 } arr[(maxn + 1) << 2];
6 bool operator<(line a, line b) { return a.a < b.a; }
7 #define m ((l + r) >> 1)
8 void insert(line x, int i = 1, int l = 0, int r = maxn)
    {
9     if (r - l == 1) {
10         if (x(l) > arr[i](l))
11             arr[i] = x;
12         return;
13     }
14     line a = max(arr[i], x), b = min(arr[i], x);
15     if (a(m) > b(m))
16         arr[i] = a, insert(b, i << 1, l, m);
17     else
18         arr[i] = b, insert(a, i << 1 | 1, m, r);
19 }
20 ld query(int x, int i = 1, int l = 0, int r = maxn) {
21     if (x < l || r <= x) return -numeric_limits<ld>::
22         max();
23     if (r - l == 1) return arr[i](x);
24     return max({arr[i](x), query(x, i << 1, l, m),
25         query(x, i << 1 | 1, m, r)});
26 }
27 #undef m

```

3.7 Sparse Table

```

1 const int lgmx = 19;
2
3 int n, q;
4 int spt[lgmx][maxn];
5
6 void build() {
7     FOR(k, 1, lgmx, 1) {
8         for (int i = 0; i + (1 << k) - 1 < n; i++) {
9             spt[k][i] = min(spt[k - 1][i], spt[k - 1][i
10                 + (1 << (k - 1))]);
11         }
12     }
13 }

```

```

14 int query(int l, int r) {
15     int ln = len(l, r);
16     int lg = __lg(ln);
17     return min(spt[lg][l], spt[lg][r - (1 << lg) + 1]);
18 }

```

3.8 Time Segment Tree

```

1 constexpr int maxn = 1e5 + 5;
2 V<P<int>> arr[(maxn + 1) << 2];
3 V<int> dsu, sz;
4 V<tuple<int, int, int>> his;
5 int cnt, q;
6 int find(int x) {
7     return x == dsu[x] ? x : find(dsu[x]);
8 };
9 inline bool merge(int x, int y) {
10     int a = find(x), b = find(y);
11     if (a == b) return false;
12     if (sz[a] > sz[b]) swap(a, b);
13     his.emplace_back(a, b, sz[b]), dsu[a] = b, sz[b] +=
14         sz[a];
15     return true;
16 };
17 inline void undo() {
18     auto [a, b, s] = his.back();
19     his.pop_back();
20     dsu[a] = a, sz[b] = s;
21 };
22 #define m ((l + r) >> 1)
23 void insert(int ql, int qr, P<int> x, int i = 1, int l
24     = 0, int r = q) {
25     // debug(ql, qr, x); return;
26     if (qr <= l || r <= ql) return;
27     if (ql <= l && r <= qr) {
28         arr[i].push_back(x);
29         return;
30     }
31     if (qr <= m)
32         insert(ql, qr, x, i << 1, l, m);
33     else if (m <= ql)
34         insert(ql, qr, x, i << 1 | 1, m, r);
35     else {
36         insert(ql, qr, x, i << 1, l, m);
37         insert(ql, qr, x, i << 1 | 1, m, r);
38     }
39 }
40 void traversal(V<int>& ans, int i = 1, int l = 0, int r
41     = q) {
42     int opcnt = 0;
43     // debug(i, l, r);
44     for (auto [a, b] : arr[i])
45         if (merge(a, b))
46             opcnt++, cnt--;
47     if (r - l == 1)
48         ans[l] = cnt;
49     else {
50         traversal(ans, i << 1, l, m);
51         traversal(ans, i << 1 | 1, m, r);
52     }
53     while (opcnt--)
54         undo(), cnt++;
55     arr[i].clear();
56 }
57 #undef m
58 inline void solve() {
59     int n, m;
60     cin >> n >> m >> q, q++;
61     dsu.resize(cnt = n), sz.assign(n, 1);
62     iota(dsu.begin(), dsu.end(), 0);
63     // a, b, time, operation
64     unordered_map<ll, V<int>> s;
65     for (int i = 0; i < m; i++) {
66         int a, b;
67         cin >> a >> b;
68         if (a > b) swap(a, b);
69         s[((1ll)a << 32) | b].emplace_back(0);
70     }
71     for (int i = 1; i < q; i++) {
72         int op, a, b;
73         cin >> op >> a >> b;

```

```

71     if (a > b) swap(a, b);
72     switch (op) {
73     case 1:
74         s[((1ll)a << 32) | b].push_back(i);
75         break;
76     case 2:
77         auto tmp = s[((1ll)a << 32) | b].back();
78         s[((1ll)a << 32) | b].pop_back();
79         insert(tmp, i, P<int>{a, b});
80     }
81 }
82 for (auto [p, v] : s) {
83     int a = p >> 32, b = p & -1;
84     while (v.size()) {
85         insert(v.back(), q, P<int>{a, b});
86         v.pop_back();
87     }
88 }
89 V<int> ans(q);
90 traversal(ans);
91 for (auto i : ans)
92     cout << i << ' ';
93 cout << endl;
94 }

```

4 Flow / Matching

4.1 Dinic

```

1 struct Dinic {
2     int n, s, t, level[N], iter[N];
3     struct edge {
4         int to, cap, rev;
5     };
6     vector<edge> path[N];
7     void init(int _n, int _s, int _t) {
8         n = _n, s = _s, t = _t;
9         FOR(i, 0, n + 1)
10             path[i].clear();
11     }
12     void add(int a, int b, int c) {
13         edge now;
14         now.to = b, now.cap = c, now.rev = sz(path[b]);
15         path[a].pb(now);
16         now.to = a, now.cap = 0, now.rev = sz(path[a])
17             - 1;
18         path[b].pb(now);
19     }
20     void bfs() {
21         memset(level, -1, sizeof(level));
22         level[s] = 0;
23         queue<int> q;
24         q.push(s);
25         while (q.size()) {
26             int now = q.front();
27             q.pop();
28             for (edge e : path[now]) {
29                 if (e.cap > 0 && level[e.to] == -1) {
30                     level[e.to] = level[now] + 1;
31                     q.push(e.to);
32                 }
33             }
34         }
35     }
36     int dfs(int now, int flow) {
37         if (now == t) return flow;
38         for (int &i = iter[now]; i < sz(path[now]); i++) {
39             edge &e = path[now][i];
40             if (e.cap > 0 && level[e.to] == level[now]
41                 + 1) {
42                 int res = dfs(e.to, min(flow, e.cap));
43                 if (res > 0) {
44                     e.cap -= res;
45                     path[e.to][e.rev].cap += res;
46                     return res;
47                 }
48             }
49         }
50         return 0;
51     }
52 }

```

```

49     }
50     int dinic() {
51         int res = 0;
52         while (true) {
53             bfs();
54             if (level[t] == -1) break;
55             memset(iter, 0, sizeof(iter));
56             int now = 0;
57             while ((now = dfs(s, INF)) > 0) res += now;
58         }
59         return res;
60     }
61 };

```

4.2 MCMF

```

1 struct MCMF {
2     int n, s, t, par[N + 5], p_i[N + 5], dis[N + 5],
3         vis[N + 5];
4     struct edge {
5         int to, cap, rev, cost;
6     };
7     vector<edge> path[N];
8     void init(int _n, int _s, int _t) {
9         n = _n, s = _s, t = _t;
10        FOR(i, 0, 2 * n + 5)
11            par[i] = p_i[i] = vis[i] = 0;
12    }
13    void add(int a, int b, int c, int d) {
14        path[a].pb({b, c, sz(path[b]), d});
15        path[b].pb({a, 0, sz(path[a]) - 1, -d});
16    }
17    void spfa() {
18        FOR(i, 0, n * 2 + 5)
19            dis[i] = INF,
20            vis[i] = 0;
21        dis[s] = 0;
22        queue<int> q;
23        q.push(s);
24        while (!q.empty()) {
25            int now = q.front();
26            q.pop();
27            vis[now] = 0;
28            for (int i = 0; i < sz(path[now]); i++) {
29                edge e = path[now][i];
30                if (e.cap > 0 && dis[e.to] > dis[now] +
31                    e.cost) {
32                    dis[e.to] = dis[now] + e.cost;
33                    par[e.to] = now;
34                    p_i[e.to] = i;
35                    if (vis[e.to] == 0) {
36                        vis[e.to] = 1;
37                        q.push(e.to);
38                    }
39                }
40            }
41        }
42    }
43    pii flow() {
44        int flow = 0, cost = 0;
45        while (true) {
46            spfa();
47            if (dis[t] == INF)
48                break;
49            int mn = INF;
50            for (int i = t; i != s; i = par[i])
51                mn = min(mn, path[par[i]][p_i[i]].cap);
52            flow += mn;
53            cost += dis[t] * mn;
54            for (int i = t; i != s; i = par[i]) {
55                edge &now = path[par[i]][p_i[i]];
56                now.cap -= mn;
57                path[i][now.rev].cap += mn;
58            }
59            return mp(flow, cost);
60        }
61 };

```

4.3 KM

```

1 struct KM {
2     int n, mx[1005], my[1005], pa[1005];
3     int g[1005][1005], lx[1005], ly[1005], sy[1005];
4     bool vx[1005], vy[1005];
5     void init(int _n) {
6         n = _n;
7         FOR(i, 1, n + 1)
8             fill(g[i], g[i] + 1 + n, 0);
9     }
10    void add(int a, int b, int c) { g[a][b] = c; }
11    void augment(int y) {
12        for (int x, z; y; y = z)
13            x = pa[y], z = mx[x], my[y] = x, mx[x] = y;
14    }
15    void bfs(int st) {
16        FOR(i, 1, n + 1)
17            sy[i] = INF,
18            vx[i] = vy[i] = 0;
19        queue<int> q;
20        q.push(st);
21        for (;;) {
22            while (!q.empty()) {
23                int x = q.front();
24                q.pop();
25                vx[x] = 1;
26                FOR(y, 1, n + 1)
27                    if (!vy[y]) {
28                        int t = lx[x] + ly[y] - g[x][y];
29                        if (t == 0) {
30                            pa[y] = x;
31                            if (!my[y]) {
32                                augment(y);
33                                return;
34                            }
35                            vy[y] = 1, q.push(my[y]);
36                        } else if (sy[y] > t)
37                            pa[y] = x, sy[y] = t;
38                    }
39            }
40            int cut = INF;
41            FOR(y, 1, n + 1)
42                if (!vy[y] && cut > sy[y]) cut = sy[y];
43            FOR(j, 1, n + 1) {
44                if (vx[j]) lx[j] -= cut;
45                if (vy[j]) ly[j] += cut;
46            } else sy[j] -= cut;
47        }
48        FOR(y, 1, n + 1) {
49            if (!vy[y] && sy[y] == 0) {
50                if (!my[y]) {
51                    augment(y);
52                    return;
53                }
54                vy[y] = 1;
55                q.push(my[y]);
56            }
57        }
58    }
59 }
60
61 int solve() {
62     fill(mx, mx + n + 1, 0);
63     fill(my, my + n + 1, 0);
64     fill(ly, ly + n + 1, 0);
65     fill(lx, lx + n + 1, 0);
66     FOR(x, 1, n + 1)
67         FOR(y, 1, n + 1)
68             lx[x] = max(lx[x], g[x][y]);
69     bfs(x);
70     int ans = 0;
71     FOR(y, 1, n + 1)
72         ans += g[my[y]][y];
73     return ans;
74 }
75
76 };
77

```

4.4 Hopcroft-Karp

```

1 struct HopcroftKarp {

```

```

2 // id: X = [1, nx], Y = [nx+1, nx+ny]
3 int n, nx, ny, m, MXCNT;
4 vector<vector<int>> > g;
5 vector<int> mx, my, dis, vis;
6 void init(int nnx, int nny, int mm) {
7     nx = nnx, ny = nny, m = mm;
8     n = nx + ny + 1;
9     g.clear();
10    g.resize(n);
11 }
12 void add(int x, int y) {
13     g[x].emplace_back(y);
14     g[y].emplace_back(x);
15 }
16 bool dfs(int x) {
17     vis[x] = true;
18     Each(y, g[x]) {
19         int px = my[y];
20         if (px == -1 ||
21             (dis[px] == dis[x] + 1 &&
22              !vis[px] && dfs(px))) {
23             mx[x] = y;
24             my[y] = x;
25             return true;
26         }
27     }
28     return false;
29 }
30 void get() {
31     mx.clear();
32     mx.resize(n, -1);
33     my.clear();
34     my.resize(n, -1);
35
36     while (true) {
37         queue<int> q;
38         dis.clear();
39         dis.resize(n, -1);
40         for (int x = 1; x <= nx; x++) {
41             if (mx[x] == -1) {
42                 dis[x] = 0;
43                 q.push(x);
44             }
45         }
46         while (!q.empty()) {
47             int x = q.front();
48             q.pop();
49             Each(y, g[x]) {
50                 if (my[y] != -1 && dis[my[y]] ==
51                     -1) {
52                     dis[my[y]] = dis[x] + 1;
53                     q.push(my[y]);
54                 }
55             }
56         }
57         bool brk = true;
58         vis.clear();
59         vis.resize(n, 0);
60         for (int x = 1; x <= nx; x++)
61             if (mx[x] == -1 && dfs(x))
62                 brk = false;
63
64         if (brk) break;
65     }
66     MXCNT = 0;
67     for (int x = 1; x <= nx; x++)
68         if (mx[x] != -1) MXCNT++;
69 }
70 } hk;

```

4.5 Blossom

```

1 const int N=5e2+10;
2 struct Graph{
3     int to[N],bro[N],head[N],e;
4     int lnk[N],vis[N],stp,n;
5     void init(int _n){
6         stp=0;e=1;n=_n;
7         FOR(i,0,n+1)head[i]=lnk[i]=vis[i]=0;
8     }

```

```

9     void add(int u,int v){
10         to[e]=v,bro[e]=head[u],head[u]=e++;
11         to[e]=u,bro[e]=head[v],head[v]=e++;
12     }
13     bool dfs(int x){
14         vis[x]=stp;
15         for(int i=head[x];i;i=bro[i])
16             {
17                 int v=to[i];
18                 if(!lnk[v])
19                     {
20                         lnk[x]=v;lnk[v]=x;
21                         return true;
22                     }
23                 else if(vis[lnk[v]]<stp)
24                     {
25                         int w=lnk[v];
26                         lnk[x]=v,lnk[v]=x,lnk[w]=0;
27                         if(dfs(w))return true;
28                         lnk[w]=v,lnk[v]=w,lnk[x]=0;
29                     }
30             }
31         return false;
32     }
33     int solve(){
34         int ans=0;
35         FOR(i,1,n+1){
36             if(!lnk[i]){
37                 stp++;
38                 ans+=dfs(i);
39             }
40         }
41         return ans;
42     }
43     void print_matching(){
44         FOR(i,1,n+1)
45             if(i<graph.lnk[i])
46                 cout<<i<<" "<<graph.lnk[i]<<endl;
47     }
48 };

```

4.6 Weighted Blossom

```

1 struct WeightGraph { // 1-based
2     static const int inf = INT_MAX;
3     static const int maxn = 514;
4     struct edge {
5         int u, v, w;
6         edge() {}
7         edge(int u, int v, int w) : u(u), v(v), w(w) {}
8     };
9     int n, n_x;
10    edge g[maxn * 2][maxn * 2];
11    int lab[maxn * 2];
12    int match[maxn * 2], slack[maxn * 2], st[maxn * 2],
13        pa[maxn * 2];
14    int flo_from[maxn * 2][maxn + 1], S[maxn * 2], vis[
15        maxn * 2];
16    vector<int> flo[maxn * 2];
17    queue<int> q;
18    int e_delta(const edge &e) { return lab[e.u] + lab[
19        e.v] - g[e.u][e.v].w * 2; }
20    void update_slack(int u, int x) {
21        if (!slack[x] || e_delta(g[u][x]) < e_delta(g[
22            slack[x]][x])) slack[x] = u;
23    }
24    void set_slack(int x) {
25        slack[x] = 0;
26        for (int u = 1; u <= n; ++u)
27            if (g[u][x].w > 0 && st[u] != x && S[st[u]]
28                == 0)
29                update_slack(u, x);
30    }
31    void q_push(int x) {
32        if (x <= n)
33            q.push(x);
34        else
35            for (size_t i = 0; i < flo[x].size(); i++)
36                q_push(flo[x][i]);
37    }
38    void set_st(int x, int b) {

```

```

33     st[x] = b;
34     if (x > n)
35         for (size_t i = 0; i < flo[x].size(); ++i)
36             set_st(flo[x][i], b);
37 }
38 int get_pr(int b, int xr) {
39     int pr = find(flo[b].begin(), flo[b].end(), xr) - flo[b].begin();
40     if (pr % 2 == 1) {
41         reverse(flo[b].begin() + 1, flo[b].end());
42         return (int)flo[b].size() - pr;
43     }
44     return pr;
45 }
46 void set_match(int u, int v) {
47     match[u] = g[u][v].v;
48     if (u <= n) return;
49     edge e = g[u][v];
50     int xr = flo_from[u][e.u], pr = get_pr(u, xr);
51     for (int i = 0; i < pr; ++i) set_match(flo[u][i], flo[u][i ^ 1]);
52     set_match(xr, v);
53     rotate(flo[u].begin(), flo[u].begin() + pr, flo[u].end());
54 }
55 void augment(int u, int v) {
56     for (;;) {
57         int xnv = st[match[u]];
58         set_match(u, v);
59         if (!xnv) return;
60         set_match(xnv, st[pa[xnv]]);
61         u = st[pa[xnv]], v = xnv;
62     }
63 }
64 int get_lca(int u, int v) {
65     static int t = 0;
66     for (++t; u || v; swap(u, v)) {
67         if (u == 0) continue;
68         if (vis[u] == t) return u;
69         vis[u] = t;
70         u = st[match[u]];
71         if (u) u = st[pa[u]];
72     }
73     return 0;
74 }
75 void add_blossom(int u, int lca, int v) {
76     int b = n + 1;
77     while (b <= n_x && st[b]) ++b;
78     if (b > n_x) ++n_x;
79     lab[b] = 0, S[b] = 0;
80     match[b] = match[lca];
81     flo[b].clear();
82     flo[b].push_back(lca);
83     for (int x = u, y; x != lca; x = st[pa[y]])
84         flo[b].push_back(x), flo[b].push_back(y = st[match[x]]), q_push(y);
85     reverse(flo[b].begin() + 1, flo[b].end());
86     for (int x = v, y; x != lca; x = st[pa[y]])
87         flo[b].push_back(x), flo[b].push_back(y = st[match[x]]), q_push(y);
88     set_st(b, b);
89     for (int x = 1; x <= n_x; ++x) g[b][x].w = g[x][b].w = 0;
90     for (int x = 1; x <= n; ++x) flo_from[b][x] = 0;
91     for (size_t i = 0; i < flo[b].size(); ++i) {
92         int xs = flo[b][i];
93         for (int x = 1; x <= n_x; ++x)
94             if (g[b][x].w == 0 || e_delta(g[xs][x]) < e_delta(g[b][x]))
95                 g[b][x] = g[xs][x], g[x][b] = g[x][xs];
96         for (int x = 1; x <= n; ++x)
97             if (flo_from[xs][x]) flo_from[b][x] = xs;
98     }
99     set_slack(b);
100 }
101 void expand_blossom(int b) {
102     for (size_t i = 0; i < flo[b].size(); ++i)
103         set_st(flo[b][i], flo[b][i]);
104 }
105 int xr = flo_from[b][g[b][pa[b]].u], pr = get_pr(b, xr);
106 for (int i = 0; i < pr; i += 2) {
107     int xs = flo[b][i], xns = flo[b][i + 1];
108     pa[xs] = g[xns][xs].u;
109     S[xs] = 1, S[xns] = 0;
110     slack[xs] = 0, set_slack(xns);
111     q_push(xns);
112 }
113 S[xr] = 1, pa[xr] = pa[b];
114 for (size_t i = pr + 1; i < flo[b].size(); ++i) {
115     int xs = flo[b][i];
116     S[xs] = -1, set_slack(xs);
117 }
118 st[b] = 0;
119 }
120 bool on_found_edge(const edge &e) {
121     int u = st[e.u], v = st[e.v];
122     if (S[v] == -1) {
123         pa[v] = e.u, S[v] = 1;
124         int nu = st[match[v]];
125         slack[v] = slack[nu] = 0;
126         S[nu] = 0, q_push(nu);
127     } else if (S[v] == 0) {
128         int lca = get_lca(u, v);
129         if (!lca)
130             return augment(u, v), augment(v, u), true;
131         else
132             add_blossom(u, lca, v);
133     }
134     return false;
135 }
136 bool matching() {
137     memset(S + 1, -1, sizeof(int) * n_x);
138     memset(slack + 1, 0, sizeof(int) * n_x);
139     q = queue<int>();
140     for (int x = 1; x <= n_x; ++x)
141         if (st[x] == x && !match[x]) pa[x] = 0, S[x] = 0, q_push(x);
142     if (q.empty()) return false;
143     for (;;) {
144         while (q.size()) {
145             int u = q.front();
146             q.pop();
147             if (S[st[u]] == 1) continue;
148             for (int v = 1; v <= n; ++v)
149                 if (g[u][v].w > 0 && st[u] != st[v] && (e_delta(g[u][v]) == 0 || (on_found_edge(g[u][v]))))
150                     return true;
151             else
152                 update_slack(u, st[v]);
153         }
154     }
155     int d = inf;
156     for (int b = n + 1; b <= n_x; ++b)
157         if (st[b] == b && S[b] == 1) d = min(d, lab[b] / 2);
158     for (int x = 1; x <= n_x; ++x)
159         if (st[x] == x && slack[x]) {
160             if (S[x] == -1)
161                 d = min(d, e_delta(g[slack[x]](x)));
162             else if (S[x] == 0)
163                 d = min(d, e_delta(g[slack[x]](x)) / 2);
164         }
165     for (int u = 1; u <= n; ++u) {
166         if (S[st[u]] == 0) {
167             if (lab[u] <= d) return 0;
168             lab[u] -= d;
169         } else if (S[st[u]] == 1)
170             lab[u] += d;
171     }
172     for (int b = n + 1; b <= n_x; ++b)
173         if (st[b] == b) {
174             if (S[st[b]] == 0)
175                 lab[b] += d * 2;
176             else if (S[st[b]] == 1)

```



```

176         lab[b] -= d * 2;
177     }
178     q = queue<int>();
179     for (int x = 1; x <= n_x; ++x)
180         if (st[x] == x && slack[x] && st[slack[x]] != x && e_delta(g[slack[x]][x]) == 0)
181             if (on_found_edge(g[slack[x]][x]))
182                 return true;
183     for (int b = n + 1; b <= n_x; ++b)
184         if (st[b] == b && S[b] == 1 && lab[b] == 0) expand_blossom(b);
185     }
186     return false;
187 }
188 pair<long long, int> solve() {
189     memset(match + 1, 0, sizeof(int) * n);
190     n_x = n;
191     int n_matches = 0;
192     long long tot_weight = 0;
193     for (int u = 0; u <= n; ++u) st[u] = u, flo[u].clear();
194     int w_max = 0;
195     for (int u = 1; u <= n; ++u)
196         for (int v = 1; v <= n; ++v) {
197             flo_from[u][v] = (u == v ? u : 0);
198             w_max = max(w_max, g[u][v].w);
199         }
200     for (int u = 1; u <= n; ++u) lab[u] = w_max;
201     while (matching()) ++n_matches;
202     for (int u = 1; u <= n; ++u)
203         if (match[u] && match[u] < u)
204             tot_weight += g[u][match[u]].w;
205     return make_pair(tot_weight, n_matches);
206 }
207 void add_edge(int ui, int vi, int wi) { g[ui][vi].w = g[vi][ui].w = wi; }
208 void init(int _n) {
209     n = _n;
210     for (int u = 1; u <= n; ++u)
211         for (int v = 1; v <= n; ++v)
212             g[u][v] = edge(u, v, 0);
213 }

```

4.7 Cover / Independent Set

```

1 V(E) Cover: choose some V(E) to cover all E(V)
2 V(E) Independ: set of V(E) not adj to each other
3
4 M = Max Matching
5 Cv = Min V Cover
6 Ce = Min E Cover
7 Iv = Max V Ind
8 Ie = Max E Ind (equiv to M)
9
10 M = Cv (Konig Theorem)
11 Iv = V \ Cv
12 Ce = V - M
13
14 Construct Cv:
15 1. Run Dinic
16 2. Find s-t min cut
17 3. Cv = {X in T} + {Y in S}

```

5 Graph

5.1 Heavy-Light Decomposition

```

1 const int N = 2e5 + 5;
2 int n, dfn[N], son[N], top[N], num[N], dep[N], p[N];
3 vector<int> path[N];
4 struct node {
5     int mx, sum;
6 } seg[N << 2];
7 void update(int x, int l, int r, int qx, int val) {
8     if (l == r) {
9         seg[x].mx = seg[x].sum = val;
10        return;

```

```

11    }
12    int mid = (l + r) >> 1;
13    if (qx <= mid) update(x << 1, l, mid, qx, val);
14    else update(x << 1 | 1, mid + 1, r, qx, val);
15    seg[x].mx = max(seg[x << 1].mx, seg[x << 1 | 1].mx);
16    seg[x].sum = seg[x << 1].sum + seg[x << 1 | 1].sum;
17 }
18 int big(int x, int l, int r, int ql, int qr) {
19     if (ql <= l && r <= qr) return seg[x].mx;
20     int mid = (l + r) >> 1;
21     int res = -INF;
22     if (ql <= mid) res = max(res, big(x << 1, l, mid, ql, qr));
23     if (mid < qr) res = max(res, big(x << 1 | 1, mid + 1, r, ql, qr));
24     return res;
25 }
26 int ask(int x, int l, int r, int ql, int qr) {
27     if (ql <= l && r <= qr) return seg[x].sum;
28     int mid = (l + r) >> 1;
29     int res = 0;
30     if (ql <= mid) res += ask(x << 1, l, mid, ql, qr);
31     if (mid < qr) res += ask(x << 1 | 1, mid + 1, r, ql, qr);
32     return res;
33 }
34 void dfs1(int now) {
35     son[now] = -1;
36     num[now] = 1;
37     for (auto i : path[now]) {
38         if (!dep[i]) {
39             dep[i] = dep[now] + 1;
40             p[i] = now;
41             dfs1(i);
42             num[now] += num[i];
43             if (son[now] == -1 || num[i] > num[son[now]]) son[now] = i;
44         }
45     }
46 }
47 int cnt;
48 void dfs2(int now, int t) {
49     top[now] = t;
50     cnt++;
51     dfn[now] = cnt;
52     if (son[now] == -1) return;
53     dfs2(son[now], t);
54     for (auto i : path[now])
55         if (i != p[now] && i != son[now]) dfs2(i, i);
56 }
57 int path_big(int x, int y) {
58     int res = -INF;
59     while (top[x] != top[y]) {
60         if (dep[top[x]] < dep[top[y]]) swap(x, y);
61         res = max(res, big(1, 1, n, dfn[top[x]], dfn[x]));
62         x = p[top[x]];
63     }
64     if (dfn[x] > dfn[y]) swap(x, y);
65     res = max(res, big(1, 1, n, dfn[x], dfn[y]));
66     return res;
67 }
68 int path_sum(int x, int y) {
69     int res = 0;
70     while (top[x] != top[y]) {
71         if (dep[top[x]] < dep[top[y]]) swap(x, y);
72         res += ask(1, 1, n, dfn[top[x]], dfn[x]);
73         x = p[top[x]];
74     }
75     if (dfn[x] > dfn[y]) swap(x, y);
76     res += ask(1, 1, n, dfn[x], dfn[y]);
77     return res;
78 }
79 void buildTree() {
80     FOR(i, 0, n - 1) {
81         int a, b;
82         cin >> a >> b;
83         path[a].pb(b);
84         path[b].pb(a);
85     }
86 }

```



```

87 void buildHLD(int root) {
88     dep[root] = 1;
89     dfs1(root);
90     dfs2(root, root);
91     FOR(i, 1, n + 1) {
92         int now;
93         cin >> now;
94         update(1, 1, n, dfn[i], now);
95     }
96 }

```

5.2 Centroid Decomposition

```

1  #include <bits/stdc++.h>
2  using namespace std;
3  const int N = 1e5 + 5;
4  vector<int> a[N];
5  int sz[N], lv[N];
6  bool used[N];
7  int f_sz(int x, int p) {
8      sz[x] = 1;
9      for (int i : a[x])
10         if (i != p && !used[i])
11             sz[x] += f_sz(i, x);
12     return sz[x];
13 }
14 int f_cen(int x, int p, int total) {
15     for (int i : a[x]) {
16         if (i != p && !used[i] && 2 * sz[i] > total)
17             return f_cen(i, x, total);
18     }
19     return x;
20 }
21 void cd(int x, int p) {
22     int total = f_sz(x, p);
23     int cen = f_cen(x, p, total);
24     lv[cen] = lv[p] + 1;
25     used[cen] = 1;
26     // cout << "cd: " << x << " " << p << " " << cen <<
27     // "\n";
28     for (int i : a[cen]) {
29         if (!used[i])
30             cd(i, cen);
31     }
32 }
33 int main() {
34     ios_base::sync_with_stdio(0);
35     cin.tie(0);
36     int n;
37     cin >> n;
38     for (int i = 0, x, y; i < n - 1; i++) {
39         cin >> x >> y;
40         a[x].push_back(y);
41         a[y].push_back(x);
42     }
43     cd(1, 0);
44     for (int i = 1; i <= n; i++)
45         cout << (char)('A' + lv[i] - 1) << " ";
46     cout << "\n";
47 }

```

5.3 Bellman-Ford + SPFA

```

1  int n, m;
2
3  // Graph
4  vector<vector<pair<int, ll> > > g;
5  vector<ll> dis;
6  vector<bool> negCycle;
7
8  // SPFA
9  vector<int> rlx;
10 queue<int> q;
11 vector<bool> inq;
12 vector<int> pa;
13 void SPFA(vector<int>& src) {
14     dis.assign(n + 1, LINF);
15     negCycle.assign(n + 1, false);
16     rlx.assign(n + 1, 0);
17     while (!q.empty()) q.pop();

```

```

18     inq.assign(n + 1, false);
19     pa.assign(n + 1, -1);
20
21     for (auto& s : src) {
22         dis[s] = 0;
23         q.push(s);
24         inq[s] = true;
25     }
26
27     while (!q.empty()) {
28         int u = q.front();
29         q.pop();
30         inq[u] = false;
31         if (rlx[u] >= n) {
32             negCycle[u] = true;
33         } else
34             for (auto& e : g[u]) {
35                 int v = e.first;
36                 ll w = e.second;
37                 if (dis[v] > dis[u] + w) {
38                     dis[v] = dis[u] + w;
39                     rlx[v] = rlx[u] + 1;
40                     pa[v] = u;
41                     if (!inq[v]) {
42                         q.push(v);
43                         inq[v] = true;
44                     }
45                 }
46             }
47     }
48 }
49
50 // Bellman-Ford
51 queue<int> q;
52 vector<int> pa;
53 void BellmanFord(vector<int>& src) {
54     dis.assign(n + 1, LINF);
55     negCycle.assign(n + 1, false);
56     pa.assign(n + 1, -1);
57
58     for (auto& s : src) dis[s] = 0;
59
60     for (int rlx = 1; rlx <= n; rlx++) {
61         for (int u = 1; u <= n; u++) {
62             if (dis[u] == LINF) continue; // Important
63             !!
64             for (auto& e : g[u]) {
65                 int v = e.first;
66                 ll w = e.second;
67                 if (dis[v] > dis[u] + w) {
68                     dis[v] = dis[u] + w;
69                     pa[v] = u;
70                     if (rlx == n) negCycle[v] = true;
71                 }
72             }
73         }
74     }
75
76     // Negative Cycle Detection
77     void NegCycleDetect() {
78         /* No Neg Cycle: NO
79         Exist Any Neg Cycle:
80         YES
81         v0 v1 v2 ... vk v0 */
82
83         vector<int> src;
84         for (int i = 1; i <= n; i++)
85             src.emplace_back(i);
86
87         SPFA(src);
88         // BellmanFord(src);
89
90         int ptr = -1;
91         for (int i = 1; i <= n; i++)
92             if (negCycle[i]) {
93                 ptr = i;
94                 break;
95             }
96
97         if (ptr == -1) {
98             return cout << "NO" << endl, void();

```

```

99     }
100
101     cout << "YES\n";
102     vector<int> ans;
103     vector<bool> vis(n + 1, false);
104
105     while (true) {
106         ans.emplace_back(ptr);
107         if (vis[ptr]) break;
108         vis[ptr] = true;
109         ptr = pa[ptr];
110     }
111     reverse(ans.begin(), ans.end());
112
113     vis.assign(n + 1, false);
114     for (auto& x : ans) {
115         cout << x << ' ';
116         if (vis[x]) break;
117         vis[x] = true;
118     }
119     cout << endl;
120 }
121
122 // Distance Calculation
123 void calcDis(int s) {
124     vector<int> src;
125     src.emplace_back(s);
126     SPFA(src);
127     // BellmanFord(src);
128
129     while (!q.empty()) q.pop();
130     for (int i = 1; i <= n; i++)
131         if (negCycle[i]) q.push(i);
132
133     while (!q.empty()) {
134         int u = q.front();
135         q.pop();
136         for (auto& e : g[u]) {
137             int v = e.first;
138             if (!negCycle[v]) {
139                 q.push(v);
140                 negCycle[v] = true;
141             }
142         }
143     }
144 }

```

5.4 BCC - AP

```

1 int n, m;
2 int low[maxn], dfn[maxn], instp;
3 vector<int> E, g[maxn];
4 bitset<maxn> isap;
5 bitset<maxn> vis;
6 stack<int> stk;
7 int bccnt;
8 vector<int> bcc[maxn];
9 inline void popout(int u) {
10     bccnt++;
11     bcc[bccnt].emplace_back(u);
12     while (!stk.empty()) {
13         int v = stk.top();
14         if (u == v) break;
15         stk.pop();
16         bcc[bccnt].emplace_back(v);
17     }
18 }
19 void dfs(int u, bool rt = 0) {
20     stk.push(u);
21     low[u] = dfn[u] = ++instp;
22     int kid = 0;
23     Each(e, g[u]) {
24         if (vis[e]) continue;
25         vis[e] = true;
26         int v = E[e] ^ u;
27         if (!dfn[v]) {
28             // tree edge
29             kid++;
30             dfs(v);
31             low[u] = min(low[u], low[v]);
32             if (!rt && low[v] >= dfn[u]) {

```

```

33             // bcc found: u is ap
34             isap[u] = true;
35             popout(u);
36         }
37     } else {
38         // back edge
39         low[u] = min(low[u], dfn[v]);
40     }
41 }
42 // special case: root
43 if (rt) {
44     if (kid > 1) isap[u] = true;
45     popout(u);
46 }
47 }
48 void init() {
49     cin >> n >> m;
50     fill(low, low + maxn, INF);
51     REP(i, m) {
52         int u, v;
53         cin >> u >> v;
54         g[u].emplace_back(i);
55         g[v].emplace_back(i);
56         E.emplace_back(u ^ v);
57     }
58 }
59 void solve() {
60     FOR(i, 1, n + 1, 1) {
61         if (!dfn[i]) dfs(i, true);
62     }
63     vector<int> ans;
64     int cnt = 0;
65     FOR(i, 1, n + 1, 1) {
66         if (isap[i]) cnt++, ans.emplace_back(i);
67     }
68     cout << cnt << endl;
69     Each(i, ans) cout << i << ' ';
70     cout << endl;
71 }

```

5.5 BCC - Bridge

```

1 int n, m;
2 vector<int> g[maxn], E;
3 int low[maxn], dfn[maxn], instp;
4 int bccnt, bccid[maxn];
5 stack<int> stk;
6 bitset<maxn> vis, isbrg;
7 void init() {
8     cin >> n >> m;
9     REP(i, m) {
10         int u, v;
11         cin >> u >> v;
12         E.emplace_back(u ^ v);
13         g[u].emplace_back(i);
14         g[v].emplace_back(i);
15     }
16     fill(low, low + maxn, INF);
17 }
18 void popout(int u) {
19     bccnt++;
20     while (!stk.empty()) {
21         int v = stk.top();
22         if (v == u) break;
23         stk.pop();
24         bccid[v] = bccnt;
25     }
26 }
27 void dfs(int u) {
28     stk.push(u);
29     low[u] = dfn[u] = ++instp;
30
31     Each(e, g[u]) {
32         if (vis[e]) continue;
33         vis[e] = true;
34
35         int v = E[e] ^ u;
36         if (dfn[v]) {
37             // back edge
38             low[u] = min(low[u], dfn[v]);
39         } else {

```

```

40         // tree edge
41         dfs(v);
42         low[u] = min(low[u], low[v]);
43         if (low[v] == dfn[v]) {
44             isbrg[e] = true;
45             popout(u);
46         }
47     }
48 }
49
50 void solve() {
51     FOR(i, 1, n + 1, 1) {
52         if (!dfn[i]) dfs(i);
53     }
54     vector<pii> ans;
55     vis.reset();
56     FOR(u, 1, n + 1, 1) {
57         Each(e, g[u]) {
58             if (!isbrg[e] || vis[e]) continue;
59             vis[e] = true;
60             int v = E[e] ^ u;
61             ans.emplace_back(mp(u, v));
62         }
63     }
64     cout << (int)ans.size() << endl;
65     Each(e, ans) cout << e.F << ' ' << e.S << endl;
66 }

```

5.6 SCC - Tarjan

```

1 // 2-SAT
2 vector<int> E, g[maxn]; // 1~n, n+1~2n
3 int low[maxn], in[maxn], instp;
4 int sccnt, sccid[maxn];
5 stack<int> stk;
6 bitset<maxn> ins, vis;
7 int n, m;
8 void init() {
9     cin >> m >> n;
10    E.clear();
11    fill(g, g + maxn, vector<int>());
12    fill(low, low + maxn, INF);
13    memset(in, 0, sizeof(in));
14    instp = 1;
15    sccnt = 0;
16    memset(sccid, 0, sizeof(sccid));
17    ins.reset();
18    vis.reset();
19 }
20 inline int no(int u) {
21     return (u > n ? u - n : u + n);
22 }
23 int ecnt = 0;
24 inline void clause(int u, int v) {
25     E.eb(no(u) ^ v);
26     g[no(u)].eb(ecnt++);
27     E.eb(no(v) ^ u);
28     g[no(v)].eb(ecnt++);
29 }
30 void dfs(int u) {
31     in[u] = instp++;
32     low[u] = in[u];
33     stk.push(u);
34     ins[u] = true;
35
36     Each(e, g[u]) {
37         if (vis[e]) continue;
38         vis[e] = true;
39
40         int v = E[e] ^ u;
41         if (ins[v])
42             low[u] = min(low[u], in[v]);
43         else if (!in[v]) {
44             dfs(v);
45             low[u] = min(low[u], low[v]);
46         }
47     }
48     if (low[u] == in[u]) {
49         sccnt++;
50         while (!stk.empty()) {
51             int v = stk.top();

```

```

52             stk.pop();
53             ins[v] = false;
54             sccid[v] = sccnt;
55             if (u == v) break;
56         }
57     }
58 }
59 int main() {
60     init();
61     REP(i, m) {
62         char su, sv;
63         int u, v;
64         cin >> su >> u >> sv >> v;
65         if (su == '-') u = no(u);
66         if (sv == '-') v = no(v);
67         clause(u, v);
68     }
69     FOR(i, 1, 2 * n + 1, 1) {
70         if (!in[i]) dfs(i);
71     }
72     FOR(u, 1, n + 1, 1) {
73         int du = no(u);
74         if (sccid[u] == sccid[du]) {
75             return cout << "IMPOSSIBLE\n", 0;
76         }
77     }
78     FOR(u, 1, n + 1, 1) {
79         int du = no(u);
80         cout << (sccid[u] < sccid[du] ? '+' : '-') << '
81         ';
82     }
83     cout << endl;
84 }

```

5.7 SCC - Kosaraju

```

1 const int N = 1e5 + 10;
2 vector<int> ed[N], ed_b[N]; // 反邊
3 vector<int> SCC(N); // 最後SCC的分組
4 bitset<N> vis;
5 int SCC_cnt;
6 int n, m;
7 vector<int> pre; // 後序遍歷
8
9 void dfs(int x) {
10     vis[x] = 1;
11     for (int i : ed[x]) {
12         if (vis[i]) continue;
13         dfs(i);
14     }
15     pre.push_back(x);
16 }
17
18 void dfs2(int x) {
19     vis[x] = 1;
20     SCC[x] = SCC_cnt;
21     for (int i : ed_b[x]) {
22         if (vis[i]) continue;
23         dfs2(i);
24     }
25 }
26
27 void kosaraju() {
28     for (int i = 1; i <= n; i++) {
29         if (!vis[i]) {
30             dfs(i);
31         }
32     }
33     SCC_cnt = 0;
34     vis = 0;
35     for (int i = n - 1; i >= 0; i--) {
36         if (!vis[pre[i]]) {
37             SCC_cnt++;
38             dfs2(pre[i]);
39         }
40     }
41 }

```

5.8 Eulerian Path - Undir

```

1 // from 1 to n
2 #define gg return cout << "IMPOSSIBLE\n", void();
3
4 int n, m;
5 vector<int> g[maxn];
6 bitset<maxn> inodd;
7
8 void init() {
9     cin >> n >> m;
10    inodd.reset();
11    for (int i = 0; i < m; i++) {
12        int u, v;
13        cin >> u >> v;
14        inodd[u] = inodd[u] ^ true;
15        inodd[v] = inodd[v] ^ true;
16        g[u].emplace_back(v);
17        g[v].emplace_back(u);
18    }
19 }
20 stack<int> stk;
21 void dfs(int u) {
22     while (!g[u].empty()) {
23         int v = g[u].back();
24         g[u].pop_back();
25         dfs(v);
26     }
27     stk.push(u);
28 }

```

5.9 Eulerian Path - Dir

```

1 // from node 1 to node n
2 #define gg return cout << "IMPOSSIBLE\n", 0
3
4 int n, m;
5 vector<int> g[maxn];
6 stack<int> stk;
7 int in[maxn], out[maxn];
8
9 void init() {
10    cin >> n >> m;
11    for (int i = 0; i < m; i++) {
12        int u, v;
13        cin >> u >> v;
14        g[u].emplace_back(v);
15        out[u]++, in[v]++;
16    }
17    for (int i = 1; i <= n; i++) {
18        if (i == 1 && out[i] - in[i] != 1) gg;
19        if (i == n && in[i] - out[i] != 1) gg;
20        if (i != 1 && i != n && in[i] != out[i]) gg;
21    }
22 }
23 void dfs(int u) {
24     while (!g[u].empty()) {
25         int v = g[u].back();
26         g[u].pop_back();
27         dfs(v);
28     }
29     stk.push(u);
30 }
31 void solve() {
32     dfs(1) for (int i = 1; i <= n; i++) if ((int)g[i].
33         size()) gg;
34     while (!stk.empty()) {
35         int u = stk.top();
36         stk.pop();
37         cout << u << ' ';
38     }
39 }

```

5.10 Hamilton Path

```

1 // top down DP
2 // Be Aware Of Multiple Edges
3 int n, m;
4 ll dp[maxn][1<<maxn];
5 int adj[maxn][maxn];
6
7 void init() {

```

```

8     cin >> n >> m;
9     fill(dp[0], dp[maxn-1]+(1<<maxn), -1);
10 }
11
12 void DP(int i, int msk) {
13     if (dp[i][msk] != -1) return;
14     dp[i][msk] = 0;
15     REP(j, n) if (j != i && (msk & (1<<j)) && adj[j][i]) {
16         int sub = msk ^ (1<<i);
17         if (dp[j][sub] == -1) DP(j, sub);
18         dp[i][msk] += dp[j][sub] * adj[j][i];
19         if (dp[i][msk] >= MOD) dp[i][msk] %= MOD;
20     }
21 }
22
23 int main() {
24     WiWiHorz
25     init();
26
27     REP(i, m) {
28         int u, v;
29         cin >> u >> v;
30         if (u == v) continue;
31         adj[--u][--v]++;
32     }
33
34     dp[0][1] = 1;
35     FOR(i, 1, n, 1) {
36         dp[i][1] = 0;
37         dp[i][1|(1<<i)] = adj[0][i];
38     }
39     FOR(msk, 1, (1<<n), 1) {
40         if (msk == 1) continue;
41         dp[0][msk] = 0;
42     }
43
44     DP(n-1, (1<<n)-1);
45     cout << dp[n-1][(1<<n)-1] << endl;
46
47     return 0;
48 }

```

5.11 Kth Shortest Path

```

1 // time: O(|E| \lg |E|+|V| \lg |V|+K)
2 // memory: O(|E| \lg |E|+|V|)
3 struct KSP{ // 1-base
4     struct nd{
5         int u,v; ll d;
6         nd(int ui=0,int vi=0,ll di=INF){ u=ui; v=vi; d=di;
7         }
8     };
9     struct heap{ nd* edge; int dep; heap* chd[4]; };
10    static int cmp(heap* a,heap* b)
11    { return a->edge->d > b->edge->d; }
12    struct node{
13        int v; ll d; heap* H; nd* E;
14        node(){
15            node(ll _d,int _v,nd* _E){ d=_d; v=_v; E=_E; }
16            node(heap* _H,ll _d){ H=_H; d=_d; }
17            friend bool operator<(node a,node b)
18            { return a.d>b.d; }
19        };
20    int n,k,s,t,dst[N]; nd *nxt[N];
21    vector<nd*> g[N],rg[N]; heap *nullNd,*head[N];
22    void init(int _n,int _k,int _s,int _t){
23        n=_n; k=_k; s=_s; t=_t;
24        for(int i=1;i<=n;i++){
25            g[i].clear(); rg[i].clear();
26            nxt[i]=NULL; head[i]=NULL; dst[i]=-1;
27        }
28    }
29    void addEdge(int ui,int vi,ll di){
30        nd* e=new nd(ui,vi,di);
31        g[ui].push_back(e); rg[vi].push_back(e);
32    }
33    queue<int> dfsQ;
34    void dijkstra(){

```

```

34 while(dfsQ.size()) dfsQ.pop();
35 priority_queue<node> Q; Q.push(node(0,t,NULL));
36 while (!Q.empty()){
37     node p=Q.top(); Q.pop(); if(dst[p.v]!=-1)continue;
38     dst[p.v]=p.d; nxt[p.v]=p.E; dfsQ.push(p.v);
39     for(auto e:rg[p.v]) Q.push(node(p.d+e->d,e->u,e));
40 }
41 heap* merge(heap* curNd,heap* newNd){
42     if(curNd==nullNd) return newNd;
43     heap* root=new heap;memcpy(root,curNd,sizeof(heap))
44     ;
45     if(newNd->edge->d<curNd->edge->d){
46         root->edge=newNd->edge;
47         root->chd[2]=newNd->chd[2];
48         root->chd[3]=newNd->chd[3];
49         newNd->edge=curNd->edge;
50         newNd->chd[2]=curNd->chd[2];
51         newNd->chd[3]=curNd->chd[3];
52     }
53     if(root->chd[0]->dep<root->chd[1]->dep)
54         root->chd[0]=merge(root->chd[0],newNd);
55     else root->chd[1]=merge(root->chd[1],newNd);
56     root->dep=max(root->chd[0]->dep,
57                 root->chd[1]->dep)+1;
58     return root;
59 }
60 vector<heap*> V;
61 void build(){
62     nullNd=new heap; nullNd->dep=0; nullNd->edge=new nd
63     ;
64     fill(nullNd->chd,nullNd->chd+4,nullNd);
65     while(not dfsQ.empty()){
66         int u=dfsQ.front(); dfsQ.pop();
67         if(!nxt[u]) head[u]=nullNd;
68         else head[u]=head[nxt[u]->v];
69         V.clear();
70         for(auto&& e:g[u]){
71             int v=e->v;
72             if(dst[v]==-1) continue;
73             e->d+=dst[v]-dst[u];
74             if(nxt[u]!=e){
75                 heap* p=new heap;fill(p->chd,p->chd+4,nullNd)
76                 ;
77                 p->dep=1; p->edge=e; V.push_back(p);
78             }
79             if(V.empty()) continue;
80             make_heap(V.begin(),V.end(),cmp);
81 #define L(X) ((X<<1)+1)
82 #define R(X) ((X<<1)+2)
83             for(size_t i=0;i<V.size();i++){
84                 if(L(i)<V.size()) V[i]->chd[2]=V[L(i)];
85                 else V[i]->chd[2]=nullNd;
86                 if(R(i)<V.size()) V[i]->chd[3]=V[R(i)];
87                 else V[i]->chd[3]=nullNd;
88             }
89             head[u]=merge(head[u],V.front());
90         }
91     }
92     vector<ll> ans;
93     void first_K(){
94         ans.clear(); priority_queue<node> Q;
95         if(dst[s]==-1) return;
96         ans.push_back(dst[s]);
97         if(head[s]!=nullNd)
98             Q.push(node(head[s],dst[s]+head[s]->edge->d));
99         for(int _=1;_<k and not Q.empty();_++){
100             node p=Q.top(); Q.pop(); ans.push_back(p.d);
101             if(head[p.H->edge->v]!=nullNd){
102                 q.H=head[p.H->edge->v]; q.d=p.d+q.H->edge->d;
103                 Q.push(q);
104             }
105             for(int i=0;i<4;i++){
106                 if(p.H->chd[i]!=nullNd){
107                     q.H=p.H->chd[i];
108                     q.d=p.d-p.H->edge->d+p.H->chd[i]->edge->d;
109                     Q.push(q);
110                 }
111             }
112         }
113     }
114     void solve(){ // ans[i] stores the i-th shortest path

```

```

111     dijkstra(); build();
112     first_K(); // ans.size() might less than k
113 }
114 } solver;

```

5.12 System of Difference Constraints

```

1 vector<vector<pair<int, ll>>> G;
2 void add(int u, int v, ll w) {
3     G[u].emplace_back(make_pair(v, w));
4 }

```

- $x_u - x_v \leq c \Rightarrow \text{add}(v, u, c)$
- $x_u - x_v \geq c \Rightarrow \text{add}(u, v, -c)$
- $x_u - x_v = c \Rightarrow \text{add}(v, u, c), \text{add}(u, v, -c)$
- $x_u \geq c \Rightarrow \text{add super vertex } x_0 = 0, \text{ then } x_u - x_0 \geq c \Rightarrow \text{add}(u, 0, -c)$
- Don't forget non-negative constraints for every variable if specified implicitly.
- Interval sum \Rightarrow Use prefix sum to transform into differential constraints. Don't forget $S_{i+1} - S_i \geq 0$ if x_i needs to be non-negative.
- $\frac{x_u}{x_v} \leq c \Rightarrow \log x_u - \log x_v \leq \log c$

6 String

6.1 Rolling Hash

```

1 const ll C = 27;
2 inline int id(char c) { return c - 'a' + 1; }
3 struct RollingHash {
4     string s;
5     int n;
6     ll mod;
7     vector<ll> Cexp, hs;
8     RollingHash(string& _s, ll _mod) : s(_s), n((int)_s
9     .size()), mod(_mod) {
10         Cexp.assign(n, 0);
11         hs.assign(n, 0);
12         Cexp[0] = 1;
13         for (int i = 1; i < n; i++) {
14             Cexp[i] = Cexp[i - 1] * C;
15             if (Cexp[i] >= mod) Cexp[i] %= mod;
16         }
17         hs[0] = id(s[0]);
18         for (int i = 1; i < n; i++) {
19             hs[i] = hs[i - 1] * C + id(s[i]);
20             if (hs[i] >= mod) hs[i] %= mod;
21         }
22     }
23     inline ll query(int l, int r) {
24         ll res = hs[r] - (l ? hs[l - 1] * Cexp[r - l +
25         1] : 0);
26         res = (res % mod + mod) % mod;
27         return res;
28     }
29 };

```

6.2 Trie

```

1 pii a[N][26];
2
3 void build(string &s) {
4     static int idx = 0;
5     int n = s.size();
6     for (int i = 0, v = 0; i < n; i++) {
7         pii &now = a[v][s[i] - 'a'];
8         if (now.first != -1)
9             v = now.first;
10        else

```

```

11     v = now.first = ++idx;
12     if (i == n - 1)
13         now.second++;
14 }
15 }

```

6.3 KMP

```

1 int n, m;
2 string s, p;
3 vector<int> f;
4 void build() {
5     f.clear(); f.resize(m, 0);
6     int ptr = 0; for (int i = 1; i < m; i++) {
7         while (ptr && p[i] != p[ptr]) ptr = f[ptr-1];
8         if (p[i] == p[ptr]) ptr++;
9         f[i] = ptr;
10    }
11    void init() {
12        cin >> s >> p;
13        n = (int)s.size();
14        m = (int)p.size();
15        build(); }
16    void solve() {
17        int ans = 0, pi = 0;
18        for (int si = 0; si < n; si++) {
19            while (pi && s[si] != p[pi]) pi = f[pi-1];
20            if (s[si] == p[pi]) pi++;
21            if (pi == m) ans++, pi = f[pi-1];
22        }
23    cout << ans << endl; }

```

6.4 Z Value

```

1 string is, it, s;
2 int n; vector<int> z;
3 void init() {
4     cin >> is >> it;
5     s = it+'0'+is;
6     n = (int)s.size();
7     z.resize(n, 0); }
8 void solve() {
9     int ans = 0; z[0] = n;
10    for (int i = 1, l = 0, r = 0; i < n; i++) {
11        if (i <= r) z[i] = min(z[i-l], r-i+1);
12        while (i+z[i] < n && s[z[i]] == s[i+z[i]]) z[i]++;
13        if (i+z[i]-1 > r) l = i, r = i+z[i]-1;
14        if (z[i] == (int)it.size()) ans++;
15    }
16    cout << ans << endl; }

```

6.5 Manacher

```

1 int n; string S, s;
2 vector<int> m;
3 void manacher() {
4     s.clear(); s.resize(2*n+1, '.');
5     for (int i = 0, j = 1; i < n; i++, j += 2) s[j] = S[i];
6     m.clear(); m.resize(2*n+1, 0);
7     // m[i] := max k such that s[i-k, i+k] is palindrome
8     int mx = 0, mxk = 0;
9     for (int i = 1; i < 2*n+1; i++) {
10        if (mx-(i-mx) >= 0) m[i] = min(m[mx-(i-mx)], mx+mxk-1);
11        while (0 <= i-m[i]-1 && i+m[i]+1 < 2*n+1 && s[i-m[i]-1] == s[i+m[i]+1]) m[i]++;
12        if (i+m[i] > mx+mxk) mx = i, mxk = m[i];
13    } }
14 void init() { cin >> S; n = (int)S.size(); }
15 void solve() {
16     manacher();
17     int mx = 0, ptr = 0;
18     for (int i = 0; i < 2*n+1; i++) if (mx < m[i]) {
19         mx = m[i]; ptr = i; }
20     for (int i = ptr-mx; i <= ptr+mx; i++)
21         if (s[i] != '.') cout << s[i];
22    cout << endl; }

```

6.6 Suffix Array

```

1 #define F first
2 #define S second
3 struct SuffixArray { // don't forget s += "$";
4     int n; string s;
5     vector<int> suf, lcp, rk;
6     vector<int> cnt, pos;
7     vector<pair<pii, int>> buc[2];
8     void init(string _s) {
9         s = _s; n = (int)s.size();
10        // resize(n): suf, rk, cnt, pos, lcp, buc[0~1]
11    }
12    void radix_sort() {
13        for (int t : {0, 1}) {
14            fill(cnt.begin(), cnt.end(), 0);
15            for (auto& i : buc[t]) cnt[(t ? i.F.F : i.F.S) ]++;
16            for (int i = 0; i < n; i++)
17                pos[i] = (!i ? 0 : pos[i-1] + cnt[i-1]);
18            for (auto& i : buc[t])
19                buc[t^1][pos[(t ? i.F.F : i.F.S) ]++] = i;
20        }
21    bool fill_suf() {
22        bool end = true;
23        for (int i = 0; i < n; i++) suf[i] = buc[0][i].S;
24        rk[suf[0]] = 0;
25        for (int i = 1; i < n; i++) {
26            int dif = (buc[0][i].F != buc[0][i-1].F);
27            end &= dif;
28            rk[suf[i]] = rk[suf[i-1]] + dif;
29        } return end;
30    }
31    void sa() {
32        for (int i = 0; i < n; i++)
33            buc[0][i] = make_pair(make_pair(s[i], s[i]), i);
34        sort(buc[0].begin(), buc[0].end());
35        if (fill_suf()) return;
36        for (int k = 0; (1<<k) < n; k++) {
37            for (int i = 0; i < n; i++)
38                buc[0][i] = make_pair(make_pair(rk[i], rk[(i + (1<<k)) % n]), i);
39            radix_sort();
40            if (fill_suf()) return;
41        }
42    void LCP() { int k = 0;
43        for (int i = 0; i < n-1; i++) {
44            if (rk[i] == 0) continue;
45            int pi = rk[i];
46            int j = suf[pi-1];
47            while (i+k < n && j+k < n && s[i+k] == s[j+k]) k++;
48            lcp[pi] = k;
49            k = max(k-1, 0);
50        } }
51    };
52    SuffixArray suffixarray;

```

6.7 SA-IS

```

1 const int N=300010;
2 struct SA{
3     #define REP(i,n) for(int i=0;i<int(n);i++)
4     #define REP1(i,a,b) for(int i=(a);i<=int(b);i++)
5     bool _t[N*2]; int _s[N*2], _sa[N*2];
6     int _c[N*2], x[N], _p[N], _q[N*2], hei[N], r[N];
7     int operator [](int i){ return _sa[i]; }
8     void build(int *s, int n, int m){
9         memcpy(_s, s, sizeof(int)*n);
10        sais(_s, _sa, _p, _q, _t, _c, n, m); mkhei(n);
11    }
12    void mkhei(int n){
13        REP(i,n) r[_sa[i]]=i;
14        hei[0]=0;
15        REP(i,n) if(r[i]) {
16            int ans=i>0?max(hei[r[i-1]]-1,0):0;
17            while(_s[i+ans]==_s[_sa[r[i]-1]+ans]) ans++;

```



```

18     hei[r[i]]=ans;
19 }
20 }
21 void sais(int *s,int *sa,int *p,int *q,bool *t,int *c
    ,int n,int z){
22     bool uniq=t[n-1]=true,neq;
23     int nn=0,nmxz=-1,*nsa=sa+n,*ns=s+n,lst=-1;
24 #define MS0(x,n) memset((x),0,n*sizeof(*(x)))
25 #define MAGIC(XD) MS0(sa,n);\
26 memcpy(x,c,sizeof(int)*z); XD;\
27 memcpy(x+1,c,sizeof(int)*(z-1));\
28 REP(i,n) if(sa[i]&&!t[sa[i]-1]) sa[x[s[sa[i]-1]]++] = sa[
    i]-1;\
29 memcpy(x,c,sizeof(int)*z);\
30 for(int i=n-1;i>=0;i--) if(sa[i]&&t[sa[i]-1]) sa[--x[s[
    sa[i]-1]]]=sa[i]-1;
31     MS0(c,z); REP(i,n) uniq&=++c[s[i]]<2;
32     REP(i,z-1) c[i+1]+=c[i];
33     if(uniq) { REP(i,n) sa[--c[s[i]]]=i; return; }
34     for(int i=n-2;i>=0;i--)
35         t[i]=(s[i]==s[i+1]?t[i+1]:s[i]<s[i+1]);
36     MAGIC(REP1(i,1,n-1) if(t[i]&&!t[i-1]) sa[--x[s[i
        ]]] = p[q[i]=nn++] = i);
37     REP(i,n) if(sa[i]&&t[sa[i]]&&t[sa[i]-1]){
38         neq=lst<0||memcmp(s+sa[i],s+lst,(p[q[sa[i]]+1]-sa
            [i])*sizeof(int));
39         ns[q[lst=sa[i]]]=nmxz+=neq;
40     }
41     sais(ns,nsa,p+nn,q+n,t+n,c+z,nn,nmxz+1);
42     MAGIC(for(int i=nn-1;i>=0;i--) sa[--x[s[p[nsa[i
        ]]]]=p[nsa[i]]]);
43 }
44 }sa;
45 int H[N],SA[N],RA[N];
46 void suffix_array(int* ip,int len){
47     // should padding a zero in the back
48     // ip is int array, len is array length
49     // ip[0..n-1] != 0, and ip[len]=0
50     ip[len++]=0; sa.build(ip,len,128);
51     memcpy(H,sa.hei+1,len<<2); memcpy(SA,sa._sa+1,len<<2)
    ;
52     for(int i=0;i<len;i++) RA[i]=sa.r[i]-1;
53     // resulting height, sa array \in [0,len)
54 }

```

6.8 Minimum Rotation

```

1 //rotate(begin(s), begin(s)+minRotation(s), end(s))
2 int minRotation(string s) {
3     int a = 0, n = s.size(); s += s;
4     for(int b = 0; b < n; b++) for(int k = 0; k < n; k++) {
5         if(a + k == b || s[a + k] < s[b + k]) {
6             b += max(0, k - 1);
7             break; }
8         if(s[a + k] > s[b + k]) {
9             a = b;
10            break;
11        } }
12     return a; }

```

6.9 Aho Corasick

```

1 struct ACautomata{
2     struct Node{
3         int cnt;
4         Node *go[26], *fail, *dic;
5         Node(){
6             cnt = 0; fail = 0; dic=0;
7             memset(go,0,sizeof(go));
8         }
9     }pool[1048576],*root;
10    int nMem;
11    Node* new_Node(){
12        pool[nMem] = Node();
13        return &pool[nMem++];
14    }
15    void init() { nMem = 0; root = new_Node(); }
16    void add(const string &str) { insert(root,str,0); }
17    void insert(Node *cur, const string &str, int pos){
18        for(int i=pos;i<str.size();i++){

```

```

19         if(!cur->go[str[i]-'a'])
20             cur->go[str[i]-'a'] = new_Node();
21         cur=cur->go[str[i]-'a'];
22     }
23     cur->cnt++;
24 }
25 void make_fail(){
26     queue<Node*> que;
27     que.push(root);
28     while (!que.empty()){
29         Node* fr=que.front(); que.pop();
30         for (int i=0; i<26; i++){
31             if (fr->go[i]){
32                 Node *ptr = fr->fail;
33                 while (ptr && !ptr->go[i]) ptr = ptr->fail;
34                 fr->go[i]->fail=ptr=(ptr?ptr->go[i]:root);
35                 fr->go[i]->dic=(ptr->cnt?ptr:ptr->dic);
36                 que.push(fr->go[i]);
37             } } }
38 }AC;

```

7 Geometry

7.1 Basic Operations

```

1 typedef long long T;
2 // typedef long double T;
3 const long double eps = 1e-8;
4
5 short sgn(T x) {
6     if (abs(x) < eps) return 0;
7     return x < 0 ? -1 : 1;
8 }
9
10 struct Pt {
11     T x, y;
12     Pt(T _x=0, T _y=0):x(_x), y(_y) {}
13     Pt operator+(Pt a) { return Pt(x+a.x, y+a.y); }
14     Pt operator-(Pt a) { return Pt(x-a.x, y-a.y); }
15     Pt operator*(T a) { return Pt(x*a, y*a); }
16     Pt operator/(T a) { return Pt(x/a, y/a); }
17     T operator*(Pt a) { return x*a.x + y*a.y; }
18     T operator^(Pt a) { return x*a.y - y*a.x; }
19     bool operator<(Pt a)
20         { return x < a.x || (x == a.x && y < a.y); }
21     //return sgn(x-a.x) < 0 || (sgn(x-a.x) == 0 && sgn(y-a.
        y) < 0); }
22     bool operator==(Pt a)
23         { return sgn(x-a.x) == 0 && sgn(y-a.y) == 0; }
24 };
25
26 Pt mv(Pt a, Pt b) { return b-a; }
27 T len2(Pt a) { return a*a; }
28 T dis2(Pt a, Pt b) { return len2(b-a); }
29
30 short ori(Pt a, Pt b) { return ((a^b)>0) - ((a^b)<0); }
31 bool onseg(Pt p, Pt l1, Pt l2) {
32     Pt a = mv(p, l1), b = mv(p, l2);
33     return ((a^b) == 0) && ((a*b) <= 0);
34 }

```

7.2 InPoly

```

1 short inPoly(Pt p) {
2     // 0=Bound 1=In -1=Out
3     REP(i, n) if (onseg(p, E[i], E[(i+1)%n])) return 0;
4     int cnt = 0;
5     REP(i, n) if (banana(p, Pt(p.x+1, p.y+2e9),
        E[i], E[(i+1)%n])) cnt ^= 1;
6     return (cnt ? 1 : -1);
7 }

```

7.3 Sort by Angle

```

1 int ud(Pt a) { // up or down half plane
2     if (a.y > 0) return 0;
3     if (a.y < 0) return 1;
4     return (a.x >= 0 ? 0 : 1);

```



```

5 }
6 sort(ALL(E), [&](const Pt& a, const Pt& b){
7     if (ud(a) != ud(b)) return ud(a) < ud(b);
8     return (a^b) > 0;
9 });

```

7.4 Line Intersect Check

```

1 inline bool banana(Pt p1, Pt p2, Pt q1, Pt q2) {
2     if (onseg(p1, q1, q2) || onseg(p2, q1, q2) ||
3         onseg(q1, p1, p2) || onseg(q2, p1, p2)) {
4         return true;
5     }
6     Pt p = mv(p1, p2), q = mv(q1, q2);
7     return (ori(p, mv(p1, q1)) * ori(p, mv(p1, q2)) < 0 &&
8         ori(q, mv(q1, p1)) * ori(q, mv(q1, p2)) < 0);
9 }

```

7.5 Line Intersection

```

1 // T: long double
2 Pt bananaPoint(Pt p1, Pt p2, Pt q1, Pt q2) {
3     if (onseg(q1, p1, p2)) return q1;
4     if (onseg(q2, p1, p2)) return q2;
5     if (onseg(p1, q1, q2)) return p1;
6     if (onseg(p2, q1, q2)) return p2;
7     double s = abs(mv(p1, p2) ^ mv(p1, q1));
8     double t = abs(mv(p1, p2) ^ mv(p1, q2));
9     return q2 * (s/(s+t)) + q1 * (t/(s+t));
10 }

```

7.6 Convex Hull

```

1 vector<Pt> hull;
2 void convexHull() {
3     hull.clear(); sort(ALL(E));
4     REP(t, 2) {
5         int b = SZ(hull);
6         Each(ei, E) {
7             while (SZ(hull) - b >= 2 &&
8                 ori(mv(hull[SZ(hull)-2], hull.back()),
9                     mv(hull[SZ(hull)-2], ei)) == -1) {
10                 hull.pop_back();
11             }
12             hull.eb(ei);
13         }
14         hull.pop_back();
15         reverse(ALL(E));
16     } }

```

7.7 Lower Concave Hull

```

1 struct Line {
2     mutable ll m, b, p;
3     bool operator<(const Line& o) const { return m < o.m; }
4     bool operator<(ll x) const { return p < x; }
5 };
6
7 struct LineContainer : multiset<Line, less<>> {
8     // (for doubles, use inf = 1/.0, div(a,b) = a/b)
9     const ll inf = LLONG_MAX;
10    ll div(ll a, ll b) { // floored division
11        return a / b - ((a ^ b) < 0 && a % b); }
12    bool isect(iterator x, iterator y) {
13        if (y == end()) { x->p = inf; return false; }
14        if (x->m == y->m) x->p = x->b > y->b ? inf : -inf;
15        else x->p = div(y->b - x->b, x->m - y->m);
16        return x->p >= y->p;
17    }
18    void add(ll m, ll b) {
19        auto z = insert({m, b, 0}), y = z++, x = y;
20        while (isect(y, z)) z = erase(z);
21        if (x != begin() && isect(--x, y)) isect(x, y =
22            erase(y));
23        while ((x = x) != begin() && (--x)->p >= y->p)
24            isect(x, erase(y));
25    }

```

```

25 ll query(ll x) {
26     assert(!empty());
27     auto l = *lower_bound(x);
28     return l.m * x + l.b;
29 }
30 };

```

7.8 Polygon Area

```

1 T dbarea(vector<Pt>& e) {
2     ll res = 0;
3     REP(i, SZ(e)) res += e[i]^e[(i+1)%SZ(e)];
4     return abs(res);
5 }

```

7.9 Pick's Theorem

Consider a polygon which vertices are all lattice points.

Let i = number of points inside the polygon.

Let b = number of points on the boundary of the polygon.

Then we have the following formula:

$$Area = i + \frac{b}{2} - 1$$

7.10 Minimum Enclosing Circle

```

1 Pt circumcenter(Pt A, Pt B, Pt C) {
2     // a1(x-A.x) + b1(y-A.y) = c1
3     // a2(x-A.x) + b2(y-A.y) = c2
4     // solve using Cramer's rule
5     T a1 = B.x-A.x, b1 = B.y-A.y, c1 = dis2(A, B)/2.0;
6     T a2 = C.x-A.x, b2 = C.y-A.y, c2 = dis2(A, C)/2.0;
7     T D = Pt(a1, b1) ^ Pt(a2, b2);
8     T Dx = Pt(c1, b1) ^ Pt(c2, b2);
9     T Dy = Pt(a1, c1) ^ Pt(a2, c2);
10    if (D == 0) return Pt(-INF, -INF);
11    return A + Pt(Dx/D, Dy/D);
12 }
13 Pt center; T r2;
14 void minEncloseCircle() {
15     mt19937 gen(chrono::steady_clock::now().
16         time_since_epoch().count());
17     shuffle(ALL(E), gen);
18     center = E[0], r2 = 0;
19     for (int i = 0; i < n; i++) {
20         if (dis2(center, E[i]) <= r2) continue;
21         center = E[i], r2 = 0;
22         for (int j = 0; j < i; j++) {
23             if (dis2(center, E[j]) <= r2) continue;
24             center = (E[i] + E[j]) / 2.0;
25             r2 = dis2(center, E[i]);
26             for (int k = 0; k < j; k++) {
27                 if (dis2(center, E[k]) <= r2) continue;
28                 center = circumcenter(E[i], E[j], E[k]);
29                 r2 = dis2(center, E[i]);
30             }
31         }
32     } }

```

7.11 PolyUnion

```

1 struct PY{
2     int n; Pt pt[5]; double area;
3     Pt& operator[](const int x){ return pt[x]; }
4     void init(){ //n,pt[0~n-1] must be filled
5         area=pt[n-1]^pt[0];
6         for(int i=0;i<n-1;i++) area+=pt[i]^pt[i+1];
7         if((area/=2)<0)reverse(pt,pt+n),area=-area;
8     }
9 };
10 PY py[500]; pair<double,int> c[5000];
11 inline double segP(Pt &p,Pt &p1,Pt &p2){
12     if(dcmp(p1.x-p2.x)==0) return (p.y-p1.y)/(p2.y-p1.y);
13     return (p.x-p1.x)/(p2.x-p1.x);
14 }

```

```

15 double polyUnion(int n){ //py[0~n-1] must be filled
16 int i,j,ii,jj,ta,tb,r,d; double z,w,s,sum=0,tc,td;
17 for(i=0;i<n;i++) py[i][py[i].n]=py[i][0];
18 for(i=0;i<n;i++){
19     for(ii=0;ii<py[i].n;ii++){
20         r=0;
21         c[r++]=make_pair(0.0,0); c[r++]=make_pair(1.0,0);
22         for(j=0;j<n;j++){
23             if(i==j) continue;
24             for(jj=0;jj<py[j].n;jj++){
25                 ta=dcmp(tri(py[i][ii],py[i][ii+1],py[j][jj]))
26                 ;
27                 tb=dcmp(tri(py[i][ii],py[i][ii+1],py[j][jj
28                 +1]));
29                 if(ta==0 && tb==0){
30                     if((py[j][jj+1]-py[j][jj])*(py[i][ii+1]-py[
31                     i][ii])>0&&<i){
32                         c[r++]=make_pair(segP(py[j][jj],py[i][ii
33                         ],py[i][ii+1]),1);
34                         c[r++]=make_pair(segP(py[j][jj+1],py[i][
35                         ii],py[i][ii+1]),-1);
36                     }
37                     }else if(ta>0 && tb<0){
38                         tc=tri(py[j][jj],py[j][jj+1],py[i][ii]);
39                         td=tri(py[j][jj],py[j][jj+1],py[i][ii+1]);
40                         c[r++]=make_pair(tc/(tc-td),1);
41                     }else if(ta<0 && tb>=0){
42                         tc=tri(py[j][jj],py[j][jj+1],py[i][ii]);
43                         td=tri(py[j][jj],py[j][jj+1],py[i][ii+1]);
44                         c[r++]=make_pair(tc/(tc-td),-1);
45                     } } }
46     sort(c,c+r);
47     z=min(max(c[0].first,0.0),1.0); d=c[0].second; s
48     =0;
49     for(j=1;j<r;j++){
50         w=min(max(c[j].first,0.0),1.0);
51         if(!d) s+=w-z;
52         d+=c[j].second; z=w;
53     }
54     sum+=(py[i][ii]^py[i][ii+1])*s;
55 }
56 return sum/2;
57 }

```

7.12 Minkowski Sum

```

1 /* convex hull Minkowski Sum*/
2 #define INF 10000000000000LL
3 int pos( const Pt& tp ){
4     if( tp.Y == 0 ) return tp.X > 0 ? 0 : 1;
5     return tp.Y > 0 ? 0 : 1;
6 }
7 #define N 300030
8 Pt pt[ N ], qt[ N ], rt[ N ];
9 LL Lx,Rx;
10 int dn,un;
11 inline bool cmp( Pt a, Pt b ){
12     int pa=pos( a ),pb=pos( b );
13     if(pa==pb) return (a^b)>0;
14     return pa<pb;
15 }
16 int minkowskiSum(int n,int m){
17     int i,j,r,p,q,fi,fj;
18     for(i=1,p=0;i<n;i++){
19         if( pt[i].Y<pt[p].Y ||
20             (pt[i].Y==pt[p].Y && pt[i].X<pt[p].X) ) p=i; }
21     for(i=1,q=0;i<m;i++){
22         if( qt[i].Y<qt[q].Y ||
23             (qt[i].Y==qt[q].Y && qt[i].X<qt[q].X) ) q=i; }
24     rt[0]=pt[p]+qt[q];
25     r=1; i=p; j=q; fi=fj=0;
26     while(1){
27         if((fj&&j==q) ||
28             ( (!fi||i!=p) &&
29               cmp(pt[(p+1)%n]-pt[p],qt[(q+1)%m]-qt[q]) ) ){
30             rt[r]=rt[r-1]+pt[(p+1)%n]-pt[p];
31             p=(p+1)%n;
32             fi=1;
33         }else{
34             rt[r]=rt[r-1]+qt[(q+1)%m]-qt[q];
35             q=(q+1)%m;
36             fj=1;
37         }
38         if(r<=1 || ((rt[r]-rt[r-1])^(rt[r-1]-rt[r-2]))
39             !=0) r++;
40         else rt[r-1]=rt[r];
41         if(i==p && j==q) break;
42     }
43     return r-1;
44 }
45 void initInConvex(int n){
46     int i,p,q;
47     LL Ly,Ry;
48     Lx=INF; Rx=-INF;
49     for(i=0;i<n;i++){
50         if(pt[i].X<Lx) Lx=pt[i].X;
51         if(pt[i].X>Rx) Rx=pt[i].X;
52     }
53     Ly=Ry=INF;
54     for(i=0;i<n;i++){
55         if(pt[i].X==Lx && pt[i].Y<Ly){ Ly=pt[i].Y; p=i;
56         }
57         if(pt[i].X==Rx && pt[i].Y>Ry){ Ry=pt[i].Y; q=i;
58         }
59     }
60     for(dn=0,i=p;i!=q;i=(i+1)%n){ qt[dn++]=pt[i]; }
61     qt[dn]=pt[q]; Ly=Ry=-INF;
62     for(i=0;i<n;i++){
63         if(pt[i].X==Lx && pt[i].Y>Ly){ Ly=pt[i].Y; p=i;
64         }
65         if(pt[i].X==Rx && pt[i].Y>Ry){ Ry=pt[i].Y; q=i;
66         }
67     }
68     for(un=0,i=p;i!=q;i=(i+n-1)%n){ rt[un++]=pt[i]; }
69     rt[un]=pt[q];
70 }
71 inline int inConvex(Pt p){
72     int L,R,M;
73     if(p.X<Lx || p.X>Rx) return 0;
74     L=0;R=dn;
75     while(L<R-1){ M=(L+R)/2;
76         if(p.X<qt[M].X) R=M; else L=M; }
77     if(tri(qt[L],qt[R],p)<0) return 0;
78     L=0;R=un;
79     while(L<R-1){ M=(L+R)/2;
80         if(p.X<rt[M].X) R=M; else L=M; }
81     if(tri(rt[L],rt[R],p)>0) return 0;
82     return 1;
83 }
84 int main(){
85     int n,m,i;
86     Pt p;
87     scanf("%d",&n);
88     for(i=0;i<n;i++) scanf("%lld%lld",&pt[i].X,&pt[i].Y
89     );
90     scanf("%d",&m);
91     for(i=0;i<m;i++) scanf("%lld%lld",&qt[i].X,&qt[i].Y
92     );
93     n=minkowskiSum(n,m);
94     for(i=0;i<n;i++) pt[i]=rt[i];
95     initInConvex(n);
96     scanf("%d",&m);
97     for(i=0;i<m;i++) scanf("%lld%lld",&qt[i].X,&qt[i].Y
98     );
99     n=minkowskiSum(n,m);
100    for(i=0;i<n;i++) pt[i]=rt[i];
101    initInConvex(n);
102    scanf("%d",&m);
103    for(i=0;i<m;i++){
104        scanf("%lld %lld",&p.X,&p.Y);
105        p.X*=3; p.Y*=3;
106        puts(inConvex(p)?"YES":"NO");
107    }
108 }

```

8 Number Theory

8.1 FFT

```

1 typedef complex<double> cp;
2

```

```

3 const double pi = acos(-1);
4 const int NN = 131072;
5
6 struct FastFourierTransform{
7     /*
8         Iterative Fast Fourier Transform
9         How this works? Look at this
10         0th recursion 0(000) 1(001) 2(010) 3(011)
11             4(100) 5(101) 6(110) 7(111)
12         1th recursion 0(000) 2(010) 4(100) 6(110)
13             | 1(011) 3(011) 5(101) 7(111)
14         2th recursion 0(000) 4(100) | 2(010) 6(110)
15             | 1(011) 5(101) | 3(011) 7(111)
16         3th recursion 0(000) | 4(100) | 2(010) | 6(110)
17             | 1(011) | 5(101) | 3(011) | 7(111)
18         All the bits are reversed => We can save the
19         reverse of the numbers in an array!
20     */
21     int n, rev[NN];
22     cp omega[NN], iomega[NN];
23     void init(int n_){
24         n = n_;
25         for(int i = 0; i < n; i++){
26             //Calculate the nth roots of unity
27             omega[i] = cp(cos(2*pi*i/n), sin(2*pi*i/n));
28             iomega[i] = conj(omega[i]);
29         }
30         int k = __lg(n);
31         for(int i = 0; i < n; i++){
32             int t = 0;
33             for(int j = 0; j < k; j++){
34                 if(i & (1<<j)) t |= (1<<(k-j-1));
35             }
36             rev[i] = t;
37         }
38     }
39
40     void transform(vector<cp> &a, cp* xomega){
41         for(int i = 0; i < n; i++){
42             if(i < rev[i]) swap(a[i], a[rev[i]]);
43         }
44         for(int len = 2; len <= n; len <= 1){
45             int mid = len >> 1;
46             int r = n/len;
47             for(int j = 0; j < n; j += len){
48                 for(int i = 0; i < mid; i++){
49                     cp tmp = xomega[r*i] * a[j+mid+i];
50                     a[j+mid+i] = a[j+i] - tmp;
51                     a[j+i] = a[j+i] + tmp;
52                 }
53             }
54         }
55     }
56
57     void fft(vector<cp> &a){ transform(a, omega); }
58     void ifft(vector<cp> &a){ transform(a, iomega); }
59     for(int i = 0; i < n; i++) a[i] /= n;
60 } FFT;
61
62 const int MAXN = 262144;
63 // (must be 2^k)
64 // 262144, 524288, 1048576, 2097152, 4194304
65 // before any usage, run pre_fft() first
66 typedef long double ld;
67 typedef complex<ld> cplx; //real() ,imag()
68 const ld PI = acos(-1);
69 const cplx I(0, 1);
70 cplx omega[MAXN+1];
71 void pre_fft(){
72     for(int i=0; i<=MAXN; i++) {
73         omega[i] = exp(i * 2 * PI / MAXN * I);
74     }
75 }
76 // n must be 2^k
77 void fft(int n, cplx a[], bool inv=false){
78     int basic = MAXN / n;
79     int theta = basic;
80     for (int m = n; m >= 2; m >= 1) {
81         int mh = m >> 1;
82         for (int i = 0; i < mh; i++) {
83             cplx w = omega[inv ? MAXN - (i * theta %
84                 MAXN) : i * theta % MAXN];
85
86             for (int j = i; j < n; j += m) {
87                 int k = j + mh;
88                 cplx x = a[j] - a[k];
89                 a[j] += a[k];
90                 a[k] = w * x;
91             }
92             theta = (theta * 2) % MAXN;
93         }
94     }
95     int i = 0;
96     for (int j = 1; j < n - 1; j++) {
97         for (int k = n >> 1; k > (i ^= k); k >>= 1);
98         if (j < i) swap(a[i], a[j]);
99     }
100     if(inv) {
101         for (i = 0; i < n; i++) a[i] /= n;
102     }
103 }
104 cplx arr[MAXN + 1];
105 inline void mul(int _n, long long a[], int _m, long long b
106     [], long long ans[]){
107     int n=1, sum = _n + _m - 1;
108     while(n < sum) n <= 1;
109     for(int i = 0; i < n; i++) {
110         double x = (i < _n ? a[i] : 0), y = (i < _m ? b[i]
111             : 0);
112         arr[i] = complex<double>(x + y, x - y);
113     }
114     fft(n, arr);
115     for(int i = 0; i < n; i++) arr[i]=arr[i]*arr[i];
116     fft(n, arr, true);
117     for(int i=0; i<sum; i++) ans[i]=(long long int)(arr[i
118         ].real() / 4 + 0.5);
119 }
120
121 long long a[MAXN];
122 long long b[MAXN];
123 long long ans[MAXN];
124 int a_length;
125 int b_length;

```

8.2 Pollard's rho

```

1 ll add(ll x, ll y, ll p) {
2     return (x + y) % p;
3 }
4 ll qMul(ll x, ll y, ll mod){
5     ll ret = x * y - (ll)((long double)x / mod * y) *
6     mod;
7     return ret<0?ret+mod:ret;
8 }
9 ll f(ll x, ll mod) { return add(qMul(x,x,mod),1,mod); }
10 ll pollard_rho(ll n) {
11     if(!(n & 1)) return 2;
12     while(true) {
13         ll y = 2, x = rand() % (n - 1) + 1, res = 1;
14         for(int sz = 2; res == 1; sz *= 2) {
15             for(int i = 0; i < sz && res <= 1; i++) {
16                 x = f(x, n);
17                 res = __gcd(llabs(x - y), n);
18             }
19             y = x;
20         }
21         if (res != 0 && res != n) return res;
22     }
23 }
24 vector<ll> ret;
25 void fact(ll x) {
26     if(miller_rabin(x)) {
27         ret.push_back(x);
28         return;
29     }
30     ll f = pollard_rho(x);
31     fact(f); fact(x / f);

```

8.3 Miller Rabin

```

1 // n < 4,759,123,141      3 : 2, 7, 61
2 // n < 1,122,004,669,633 4 : 2, 13, 23, 1662803

```

```

3 // n < 3,474,749,660,383      6 : pirmes <= 13
4 // n < 2^64                  7 :
5 // 2, 325, 9375, 28178, 450775, 9780504, 1795265022
6 bool witness(ll a, ll n, ll u, int t){
7     if(!(a%n)) return 0;
8     ll x=myspow(a,u,n);
9     for(int i=0; i<t; i++) {
10         ll nx=mul(x,x,n);
11         if(nx==1&&x!=1&&x!=n-1) return 1;
12         x=nx;
13     }
14     return x!=1;
15 }
16 bool miller_rabin(ll n, int s=100) {
17     // iterate s times of witness on n
18     // return 1 if prime, 0 otherwise
19     if(n<2) return 0;
20     if(!(n&1)) return n == 2;
21     ll u=n-1; int t=0;
22     while(!(u&1)) u>>=1, t++;
23     while(s--){
24         ll a=randll()%(n-1)+1;
25         if(witness(a,n,u,t)) return 0;
26     }
27     return 1;
28 }

```

8.4 Fast Power

Note: $a^n \equiv a^{(n \bmod (p-1))} \pmod{p}$

8.5 Extend GCD

```

1 ll GCD;
2 pll extgcd(ll a, ll b) {
3     if (b == 0) {
4         GCD = a;
5         return pll{1, 0};
6     }
7     pll ans = extgcd(b, a % b);
8     return pll{ans.S, ans.F - a/b * ans.S};
9 }
10 pll bezout(ll a, ll b, ll c) {
11     bool negx = (a < 0), negy = (b < 0);
12     pll ans = extgcd(abs(a), abs(b));
13     if (c % GCD != 0) return pll{-LLINF, -LLINF};
14     return pll{ans.F * c/GCD * (negx ? -1 : 1),
15                ans.S * c/GCD * (negy ? -1 : 1)};
16 }
17 ll inv(ll a, ll p) {
18     if (p == 1) return -1;
19     pll ans = bezout(a % p, -p, 1);
20     if (ans == pll{-LLINF, -LLINF}) return -1;
21     return (ans.F % p + p) % p;
22 }

```

8.6 Mu + Phi

```

1 const int maxn = 1e6 + 5;
2 ll f[maxn];
3 vector<int> lpf, prime;
4 void build() {
5     lpf.clear(); lpf.resize(maxn, 1);
6     prime.clear();
7     f[1] = ...; /* mu[1] = 1, phi[1] = 1 */
8     for (int i = 2; i < maxn; i++) {
9         if (lpf[i] == 1) {
10             lpf[i] = i; prime.emplace_back(i);
11             f[i] = ...; /* mu[i] = 1, phi[i] = i-1 */
12         }
13         for (auto& j : prime) {
14             if (i*j >= maxn) break;
15             lpf[i*j] = j;
16             if (i % j == 0) f[i*j] = ...; /* 0, phi[i]*j */
17             else f[i*j] = ...; /* -mu[i], phi[i]*phi[j] */
18             if (j >= lpf[i]) break;
19         }
20     }
21 }

```

8.7 Other Formulas

- Inversion:**
 $aa^{-1} \equiv 1 \pmod{m}$. a^{-1} exists iff $\gcd(a, m) = 1$.
- Linear inversion:**
 $a^{-1} \equiv (m - \lfloor \frac{m}{a} \rfloor) \times (m \bmod a)^{-1} \pmod{m}$
- Fermat's little theorem:**
 $a^p \equiv a \pmod{p}$ if p is prime.
- Euler function:**
 $\phi(n) = n \prod_{p|n} \frac{p-1}{p}$
- Euler theorem:**
 $a^{\phi(n)} \equiv 1 \pmod{n}$ if $\gcd(a, n) = 1$.
- Extended Euclidean algorithm:**
 $ax + by = \gcd(a, b) = \gcd(b, a \bmod b) = \gcd(b, a - \lfloor \frac{a}{b} \rfloor b) = bx_1 + (a - \lfloor \frac{a}{b} \rfloor b)y_1 = ay_1 + b(x_1 - \lfloor \frac{a}{b} \rfloor y_1)$
- Divisor function:**
 $\sigma_x(n) = \sum_{d|n} d^x$. $n = \prod_{i=1}^r p_i^{a_i}$.
 $\sigma_x(n) = \prod_{i=1}^r \frac{p_i^{(a_i+1)x} - 1}{p_i^x - 1}$ if $x \neq 0$. $\sigma_0(n) = \prod_{i=1}^r (a_i + 1)$.
- Chinese remainder theorem (Coprime Moduli):**
 $x \equiv a_i \pmod{m_i}$.
 $M = \prod m_i$. $M_i = M/m_i$. $t_i = M_i^{-1}$.
 $x = kM + \sum a_i t_i M_i$, $k \in \mathbb{Z}$.
- Chinese remainder theorem:**
 $x \equiv a_1 \pmod{m_1}, x \equiv a_2 \pmod{m_2} \Rightarrow x = m_1 p + a_1 = m_2 q + a_2 \Rightarrow m_1 p - m_2 q = a_2 - a_1$
Solve for (p, q) using ExtGCD.
 $x \equiv m_1 p + a_1 \equiv m_2 q + a_2 \pmod{\text{lcm}(m_1, m_2)}$
- Avoiding Overflow:** $ca \bmod cb = c(a \bmod b)$
- Dirichlet Convolution:** $(f * g)(n) = \sum_{d|n} f(d)g(n/d)$
- Important Multiplicative Functions + Properties:**
 - $\epsilon(n) = [n = 1]$
 - $1(n) = 1$
 - $id(n) = n$
 - $\mu(n) = 0$ if n has squared prime factor
 - $\mu(n) = (-1)^k$ if $n = p_1 p_2 \cdots p_k$
 - $\epsilon = \mu * 1$
 - $\phi = \mu * id$
 - $[n = 1] = \sum_{d|n} \mu(d)$
 - $[gcd = 1] = \sum_{d|gcd} \mu(d)$
- Möbius inversion:** $f = g * 1 \Leftrightarrow g = f * \mu$

8.8 Polynomial

```

1 const int maxk = 20;
2 const int maxn = 1<<maxk;
3 const ll LINF = 1e18;
4
5 /* P = r*2^k + 1
6 P      r      k      g
7 998244353      119 23   3
8 1004535809      479 21   3
9
10 P      r      k      g
11 3      1      1      2
12 5      1      2      2
13 17     1      4      3
14 97     3      5      5
15 193    3      6      5
16 257    1      8      3
17 7681   15     9      17

```

```

18 12289          3 12 11
19 40961          5 13 3
20 65537          1 16 3
21 786433         3 18 10
22 5767169        11 19 3
23 7340033         7 20 3
24 23068673        11 21 3
25 104857601       25 22 3
26 167772161       5 25 3
27 469762049       7 26 3
28 1004535809      479 21 3
29 2013265921      15 27 31
30 2281701377      17 27 3
31 3221225473      3 30 5
32 75161927681     35 31 3
33 77309411329     9 33 7
34 206158430209    3 36 22
35 2061584302081   15 37 7
36 2748779069441   5 39 3
37 6597069766657   3 41 5
38 39582418599937   9 42 5
39 79164837199873   9 43 5
40 263882790666241 15 44 7
41 1231453023109121 35 45 3
42 1337006139375617 19 46 3
43 3799912185593857 27 47 5
44 4222124650659841 15 48 19
45 7881299347898369 7 50 6
46 31525197391593473 7 52 3
47 180143985094819841 5 55 6
48 1945555039024054273 27 56 5
49 4179340454199820289 29 57 3
50 9097271247288401921 505 54 6 */
51
52 const int g = 3;
53 const ll MOD = 998244353;
54
55 ll pw(ll a, ll n) { /* fast pow */ }
56
57 #define siz(x) (int)x.size()
58
59 template<typename T>
60 vector<T>& operator+=(vector<T>& a, const vector<T>& b) {
61     if (siz(a) < siz(b)) a.resize(siz(b));
62     for (int i = 0; i < min(siz(a), siz(b)); i++) {
63         a[i] += b[i];
64         a[i] -= a[i] >= MOD ? MOD : 0;
65     }
66     return a;
67 }
68
69 template<typename T>
70 vector<T>& operator-=(vector<T>& a, const vector<T>& b) {
71     if (siz(a) < siz(b)) a.resize(siz(b));
72     for (int i = 0; i < min(siz(a), siz(b)); i++) {
73         a[i] -= b[i];
74         a[i] += a[i] < 0 ? MOD : 0;
75     }
76     return a;
77 }
78
79 template<typename T>
80 vector<T> operator-(const vector<T>& a) {
81     vector<T> ret(siz(a));
82     for (int i = 0; i < siz(a); i++) {
83         ret[i] = -a[i] < 0 ? -a[i] + MOD : -a[i];
84     }
85     return ret;
86 }
87
88 vector<ll> X, iX;
89 vector<int> rev;
90
91 void init_ntt() {
92     X.clear(); X.resize(maxn, 1); // x1 = g^((p-1)/n)
93     iX.clear(); iX.resize(maxn, 1);
94
95     ll u = pw(g, (MOD-1)/maxn);
96     ll iu = pw(u, MOD-2);
97
98     for (int i = 1; i < maxn; i++) {
99         X[i] = X[i-1] * u;
100         iX[i] = iX[i-1] * iu;
101         if (X[i] >= MOD) X[i] %= MOD;
102         if (iX[i] >= MOD) iX[i] %= MOD;
103     }
104
105     rev.clear(); rev.resize(maxn, 0);
106     for (int i = 1, hb = -1; i < maxn; i++) {
107         if (!(i & (i-1))) hb++;
108         rev[i] = rev[i ^ (1<<hb)] | (1<<(maxk-hb-1));
109     } }
110
111 template<typename T>
112 void NTT(vector<T>& a, bool inv=false) {
113
114     int _n = (int)a.size();
115     int k = __lg(_n) + ((1<<__lg(_n)) != _n);
116     int n = 1<<k;
117     a.resize(n, 0);
118
119     short shift = maxk-k;
120     for (int i = 0; i < n; i++)
121         if (i > (rev[i]>>shift))
122             swap(a[i], a[rev[i]>>shift]);
123
124     for (int len = 2, half = 1, div = maxn>>1; len <= n
125         ; len<=1, half<=1, div>=1) {
126         for (int i = 0; i < n; i += len) {
127             for (int j = 0; j < half; j++) {
128                 T u = a[i+j];
129                 T v = a[i+j+half] * (inv ? iX[j*div] :
130                     X[j*div]) % MOD;
131                 a[i+j] = (u+v >= MOD ? u+v-MOD : u+v);
132                 a[i+j+half] = (u-v < 0 ? u-v+MOD : u-v);
133             } } }
134
135     if (inv) {
136         T dn = pw(n, MOD-2);
137         for (auto& x : a) {
138             x *= dn;
139             if (x >= MOD) x %= MOD;
140         } } }
141
142 template<typename T>
143 inline void resize(vector<T>& a) {
144     int cnt = (int)a.size();
145     for (; cnt > 0; cnt--) if (a[cnt-1]) break;
146     a.resize(max(cnt, 1));
147 }
148
149 template<typename T>
150 vector<T>& operator*=(vector<T>& a, vector<T> b) {
151     int na = (int)a.size();
152     int nb = (int)b.size();
153     a.resize(na + nb - 1, 0);
154     b.resize(na + nb - 1, 0);
155
156     NTT(a); NTT(b);
157     for (int i = 0; i < (int)a.size(); i++) {
158         a[i] *= b[i];
159         if (a[i] >= MOD) a[i] %= MOD;
160     }
161     NTT(a, true);
162
163     resize(a);
164     return a;
165 }
166
167 template<typename T>
168 void inv(vector<T>& ia, int N) {
169     vector<T> _a(move(ia));
170     ia.resize(1, pw(_a[0], MOD-2));
171     vector<T> a(1, -_a[0] + (-_a[0] < 0 ? MOD : 0));
172
173     for (int n = 1; n < N; n<=1) {
174         // n -> 2*n
175         // ia' = ia(2-a*ia);
176
177         for (int i = n; i < min(siz(_a), (n<<1)); i++)

```

```

176         a.emplace_back(-a[i] + (-a[i] < 0 ? MOD :
177             0));
178     vector<T> tmp = ia;
179     ia *= a;
180     ia.resize(n<<1);
181     ia[0] = ia[0] + 2 >= MOD ? ia[0] + 2 - MOD : ia
182         [0] + 2;
183     ia *= tmp;
184     ia.resize(n<<1);
185 }
186 }
187
188 template<typename T>
189 void mod(vector<T>& a, vector<T>& b) {
190     int n = (int)a.size()-1, m = (int)b.size()-1;
191     if (n < m) return;
192
193     vector<T> ra = a, rb = b;
194     reverse(ra.begin(), ra.end()); ra.resize(min(n+1, n
195         -m+1));
196     reverse(rb.begin(), rb.end()); rb.resize(min(m+1, n
197         -m+1));
198
199     inv(rb, n-m+1);
200
201     vector<T> q = move(ra);
202     q *= rb;
203     q.resize(n-m+1);
204     reverse(q.begin(), q.end());
205
206     q *= b;
207     a -= q;
208     resize(a);
209 }
210
211 /* Kitamasa Method (Fast Linear Recurrence):
212 Find a[K] (Given a[j] = c[0]a[j-N] + ... + c[N-1]a[j
213     -1])
214 Let B(x) = x^N - c[N-1]x^(N-1) - ... - c[1]x^1 - c[0]
215 Let R(x) = x^K mod B(x) (get x^K using fast pow and
216     use poly mod to get R(x))
217 Let r[i] = the coefficient of x^i in R(x)
218 => a[K] = a[0]r[0] + a[1]r[1] + ... + a[N-1]r[N-1] */

```

9 Linear Algebra

9.1 Gaussian-Jordan Elimination

```

1 int n; vector<vector<ll>> > v;
2 void gauss(vector<vector<ll>>& v) {
3     int r = 0;
4     for (int i = 0; i < n; i++) {
5         bool ok = false;
6         for (int j = r; j < n; j++) {
7             if (v[j][i] == 0) continue;
8             swap(v[j], v[r]);
9             ok = true; break;
10        }
11        if (!ok) continue;
12        ll div = inv(v[r][i]);
13        for (int j = 0; j < n+1; j++) {
14            v[r][j] *= div;
15            if (v[r][j] >= MOD) v[r][j] %= MOD;
16        }
17        for (int j = 0; j < n; j++) {
18            if (j == r) continue;
19            ll t = v[j][i];
20            for (int k = 0; k < n+1; k++) {
21                v[j][k] -= v[r][k] * t % MOD;
22                if (v[j][k] < 0) v[j][k] += MOD;
23            }
24        }
25    }
26 }

```

9.2 Determinant

1. Use GJ Elimination, if there's any row consists of only

0, then det = 0, otherwise det = product of diagonal elements.

2. Properties of det:

- Transpose: Unchanged
- Row Operation 1 - Swap 2 rows: $-det$
- Row Operation 2 - $k\vec{r}_i$: $k \times det$
- Row Operation 3 - $k\vec{r}_i$ add to \vec{r}_j : Unchanged

10 Combinatorics

10.1 Catalan Number

$$C_0 = 1, C_n = \sum_{i=0}^{n-1} C_i C_{n-1-i}, C_n = C_n^{2n} - C_{n-1}^{2n}$$

0	1	1	2	5
4	14	42	132	429
8	1430	4862	16796	58786
12	208012	742900	2674440	9694845

10.2 Burnside's Lemma

Let X be the original set.

Let G be the group of operations acting on X .

Let X^g be the set of x not affected by g .

Let X/G be the set of orbits.

Then the following equation holds:

$$|X/G| = \frac{1}{|G|} \sum_{g \in G} |X^g|$$

11 Special Numbers

11.1 Fibonacci Series

1	1	1	2	3
5	5	8	13	21
9	34	55	89	144
13	233	377	610	987
17	1597	2584	4181	6765
21	10946	17711	28657	46368
25	75025	121393	196418	317811
29	514229	832040	1346269	2178309
33	3524578	5702887	9227465	14930352

$$f(45) \approx 10^9, f(88) \approx 10^{18}$$

11.2 Prime Numbers

- First 50 prime numbers:

1	2	3	5	7	11
6	13	17	19	23	29
11	31	37	41	43	47
16	53	59	61	67	71
21	73	79	83	89	97
26	101	103	107	109	113
31	127	131	137	139	149
36	151	157	163	167	173
41	179	181	191	193	197
46	199	211	223	227	229

- Very large prime numbers:

1000001333	1000500889	2500001909
2000000659	900004151	850001359

- $\pi(n) \equiv \text{Number of primes } \leq n \approx n/((\ln n) - 1)$
 $\pi(100) = 25, \pi(200) = 46$
 $\pi(500) = 95, \pi(1000) = 168$
 $\pi(2000) = 303, \pi(4000) = 550$
 $\pi(10^4) = 1229, \pi(10^5) = 9592$
 $\pi(10^6) = 78498, \pi(10^7) = 664579$



