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1 Reminder

1.1 Bug List

- 沒開 long long
- 陣列截出界 / 開不夠大 / 開太大本地 compile 噴怪 error
- 傳之前先確定選對檔案
- 寫好的函式忘記呼叫
- 變數打錯
- 0-base / 1-base
- 忘記初始化
- == 打成 =
- <= 打成 <+
- dp[i] 從 dp[i-1] 轉移時忘記特判 $i > 0$
- std::sort 比較運算子寫成 < 或是讓 = 的情況為 true
- 漏 case / 分 case 要好好想
- 線段樹改值懶標初始值不能設為 0
- DFS 的時候不小心覆寫到全域變數
- 浮點數誤差
- 多筆測資不能沒讀完直接 return
- 記得刪 cerr

1.2 OwO

- 可以構造複雜點的測資幫助思考
- 真的卡太久請跳題
- Enjoy The Contest!

2 Basic

2.1 Vimrc

```

set number relativenumber ai t_Co=256 tabstop=4
set mouse=a shiftwidth=4 encoding=utf8
set bs=2 ruler laststatus=2 cmdheight=2
set clipboard=unnamedplus showcmd autoread
set belloff=all
filetype indent on
"set guifont Hack:h16
":set guifont?

inoremap ( (<Esc>i
inoremap " "<Esc>i
inoremap [ [<Esc>i
inoremap ' '<Esc>i
inoremap { {<CR><Esc>ko

vmap <C-c> "+y
inoremap <C-v> <Esc>p
nnoremap <C-v> p

nnoremap <tab> gt
nnoremap <S-tab> gT
inoremap <C-n> <Esc>:tabnew<CR>
nnoremap <C-n> :tabnew<CR>

inoremap <F9> <Esc>:w<CR>:!~/runcpp.sh %:p:t %:p:h<CR>
nnoremap <F9> :w<CR>:!~/runcpp.sh %:p:t %:p:h<CR>

syntax on
colorscheme desert

set filetype=cpp
set background=dark
hi Normal ctermfg=white ctermbg=black

```

2.2 Runcpp.sh

```

#! /bin/bash
clear
echo "Start compiling $1..."

```

```

4 echo
5 g++ -O2 -std=c++20 -Wall -Wextra -Wshadow $2/$1 -o $2/
  out
6 if [ "$?" -ne 0 ]
7 then
8     exit 1
9 fi
10 echo
11 echo "Done compiling"
12 echo "=====
13 echo
14 echo "Input file:"
15 echo
16 cat $2/in.txt
17 echo
18 echo "=====
19 echo
20 declare startTime=`date +%s%N`
21 $2/out < $2/in.txt > $2/out.txt
22 declare endTime=`date +%s%N`
23 delta=`expr $endTime - $startTime`
24 delta=`expr $delta / 1000000`
25 cat $2/out.txt
26 echo
27 echo "time: $delta ms"

```

2.3 Stress

```

1 g++ gen.cpp -o gen.out
2 g++ ac.cpp -o ac.out
3 g++ wa.cpp -o wa.out
4 for ((i=0;;i++))
5 do
6     echo "$i"
7     ./gen.out > in.txt
8     ./ac.out < in.txt > ac.txt
9     ./wa.out < in.txt > wa.txt
10    diff ac.txt wa.txt || break
11 done

```

2.4 PBDS

```

1 #include <bits/extc++.h>
2 using namespace __gnu_pbds;
3
4 // map
5 tree<int, int, less<>, rb_tree_tag,
  tree_order_statistics_node_update> tr;
6 tr.order_of_key(element);
7 tr.find_by_order(rank);
8
9 // set
10 tree<int, null_type, less<>, rb_tree_tag,
  tree_order_statistics_node_update> tr;
11 tr.order_of_key(element);
12 tr.find_by_order(rank);
13
14 // priority queue
15 __gnu_pbds::priority_queue<int, less<int> > big_q; //
  Big First
16 __gnu_pbds::priority_queue<int, greater<int> > small_q;
  // Small First
17 q1.join(q2); // join

```

2.5 Random

```

1 mt19937 gen(chrono::steady_clock::now().
  time_since_epoch().count());
2 uniform_int_distribution<int> dis(1, 100);
3 cout << dis(gen) << endl;
4 shuffle(v.begin(), v.end(), gen);

```

3 Python

3.1 I/O

```

1 import sys
2 input = sys.stdin.readline
3
4 # Input
5 def readInt():
6     return int(input())
7 def readList():
8     return list(map(int, input().split()))
9 def readStr():
10    s = input()
11    return list(s[:len(s) - 1])
12 def readVars():
13    return map(int, input().split())
14
15 # Output
16 sys.stdout.write(string)
17
18 # faster
19 def main():
20     pass
21 main()

```

3.2 Decimal

```

1 from decimal import *
2 getcontext().prec = 2500000
3 getcontext().Emax = 2500000
4 a,b = Decimal(input()),Decimal(input())
5 a*=b
6 print(a)

```

4 Data Structure

4.1 BIT

```

1 struct BIT
2 {
3     int n;
4     long long bit[N];
5
6     void init(int x, vector<long long> &a)
7     {
8         n = x;
9         for(int i=1, j; i<=n; i++)
10            {
11                bit[i] += a[i-1], j = i + (i & -i);
12                if(j <= n) bit[j] += bit[i];
13            }
14    }
15
16    void update(int x, long long dif)
17    {
18        while(x <= n) bit[x] += dif, x += x & -x;
19    }
20
21    long long query(int l, int r)
22    {
23        if(l != 1) return query(1, r) - query(1, l-1);
24
25        long long ret = 0;
26        while(l <= r) ret += bit[r], r -= r & -r;
27        return ret;
28    }
29 }bm;

```

4.2 DSU

```

1 struct DSU
2 {
3     int h[N], s[N];
4
5     void init(int n)
6     { iota(h, h+n+1, 0), fill(s, s+n+1, 1); }
7
8     int fh(int x)
9     { return (h[x]==x? x: h[x]=fh(h[x])); }
10
11     bool mer(int x, int y)

```

```

12 {
13     x = fh(x), y = fh(y);
14     if(x == y) return 0;
15     if(s[x] < s[y]) swap(x, y);
16     s[x] += s[y], s[y] = 0;
17     h[y] = x;
18     return 1;
19 }
20 }bm;

```

4.3 Segment Tree

```

1 struct segtree
2 {
3     int n, seg[1<<19];
4
5     void init(int x)
6     {
7         n = 1<<((__lg(x) + 1));
8         for(int i=1; i<2*n; i++)
9             seg[i] = inf;
10    }
11
12    void update(int x, int val)
13    {
14        x += n;
15        seg[x] = val, x /= 2;
16        while(x)
17            seg[x] = min(seg[2*x], seg[2*x+1]), x /= 2;
18    }
19
20    int query(int l, int r)
21    {
22        l += n, r += n;
23        int ret = inf;
24        while(l < r)
25        {
26            if(l & 1)
27                ret = min(ret, seg[l++]);
28            if(r & 1)
29                ret = min(ret, seg[--r]);
30            l /= 2, r /= 2;
31        }
32        return ret;
33    }
34 }bm;

```

4.4 Merging on Seg-Tree

```

1 struct segtree
2 {
3     struct node
4     {
5         long long sum, pre;
6         node()
7         {
8             sum = pre = 0;
9         }
10    };
11
12    node mer(node x, node y)
13    {
14        node ret;
15        ret.sum = x.sum + y.sum;
16        ret.pre = max(x.pre, x.sum + y.pre);
17        return ret;
18    }
19
20    int n;
21    node seg[1<<19];
22
23    void init(int x)
24    {
25        n = 1<<((__lg(x) + 1));
26    }
27
28    void print()
29    {
30        for(int i=1, j=1; i<=__lg(n)+1; i++)
31        {

```

```

32            for(; j<(1<<i); j++)
33                cout << seg[j].sum << " ";
34            cout << "\n";
35        }
36        cout << "\n";
37    }
38
39    void update(int x, long long val)
40    {
41        x += n;
42        seg[x].sum = val, seg[x].pre = max(0LL, val);
43        x /= 2;
44        while(x)
45            seg[x] = mer(seg[2*x], seg[2*x+1]), x /= 2;
46    }
47
48    long long query(int l, int r)
49    {
50        l += n, r += n;
51        node retl, retr;
52        while(l < r)
53        {
54            if(l & 1)
55                retl = mer(retl, seg[l++]);
56            if(r & 1)
57                retr = mer(seg[--r], retr);
58            l /= 2, r /= 2;
59        }
60        return mer(retl, retr).pre;
61    }
62 }bm;

```

4.5 Heavy Light Decomposition

```

1 const int N=2e5+5;
2 int n,dfn[N],son[N],top[N],num[N],dep[N],p[N];
3 vector<int>path[N];
4 struct node
5 {
6     int mx,sum;
7 }seg[N<<2];
8 void update(int x,int l,int r,int qx,int val)
9 {
10     if(l==r)
11     {
12         seg[x].mx=seg[x].sum=val;
13         return;
14     }
15     int mid=(l+r)>>1;
16     if(qx<=mid)update(x<<1,l,mid,qx,val);
17     else update(x<<1|1,mid+1,r,qx,val);
18     seg[x].mx=max(seg[x<<1].mx,seg[x<<1|1].mx);
19     seg[x].sum=seg[x<<1].sum+seg[x<<1|1].sum;
20 }
21 int big(int x,int l,int r,int ql,int qr)
22 {
23     if(ql<=l&&r<=qr)return seg[x].mx;
24     int mid=(l+r)>>1;
25     int res=-INF;
26     if(ql<=mid)res=max(res,big(x<<1,l,mid,ql,qr));
27     if(mid<qr)res=max(res,big(x<<1|1,mid+1,r,ql,qr));
28     return res;
29 }
30 int ask(int x,int l,int r,int ql,int qr)
31 {
32     if(ql<=l&&r<=qr)return seg[x].sum;
33     int mid=(l+r)>>1;
34     int res=0;
35     if(ql<=mid)res+=ask(x<<1,l,mid,ql,qr);
36     if(mid<qr)res+=ask(x<<1|1,mid+1,r,ql,qr);
37     return res;
38 }
39 void dfs1(int now)
40 {
41     son[now]=-1;
42     num[now]=1;
43     for(auto i:path[now])
44     {
45         if(!dep[i])
46         {
47             dep[i]=dep[now]+1;

```

```

48     p[i]=now;
49     dfs1(i);
50     num[now]+=num[i];
51     if(son[now]==-1||num[i]>num[son[now]])son[
        now]=i;
52     }
53     }
54 }
55 int cnt;
56 void dfs2(int now,int t)
57 {
58     top[now]=t;
59     cnt++;
60     dfn[now]=cnt;
61     if(son[now]==-1)return;
62     dfs2(son[now],t);
63     for(auto i:path[now])
64         if(i!=p[now]&&i!=son[now])
65             dfs2(i,i);
66 }
67 int path_big(int x,int y)
68 {
69     int res=-INF;
70     while(top[x]!=top[y])
71     {
72         if(dep[top[x]]<dep[top[y]])swap(x,y);
73         res=max(res,big(1,1,n,dfn[top[x]],dfn[x]));
74         x=p[top[x]];
75     }
76     if(dfn[x]>dfn[y])swap(x,y);
77     res=max(res,big(1,1,n,dfn[x],dfn[y]));
78     return res;
79 }
80 int path_sum(int x,int y)
81 {
82     int res=0;
83     while(top[x]!=top[y])
84     {
85         if(dep[top[x]]<dep[top[y]])swap(x,y);
86         res+=ask(1,1,n,dfn[top[x]],dfn[x]);
87         x=p[top[x]];
88     }
89     if(dfn[x]>dfn[y])swap(x,y);
90     res+=ask(1,1,n,dfn[x],dfn[y]);
91     return res;
92 }
93 void buildTree()
94 {
95     FOR(i,0,n-1)
96     {
97         int a,b;cin>>a>>b;
98         path[a].pb(b);
99         path[b].pb(a);
100     }
101 }
102 void buildHLD(int root)
103 {
104     dep[root]=1;
105     dfs1(root);
106     dfs2(root,root);
107     FOR(i,1,n+1)
108     {
109         int now;cin>>now;
110         update(1,1,n,dfn[i],now);
111     }
112 }

```

4.6 Skew Heap

```

1 struct node{
2     node *l,*r;
3     int v;
4     node(int x):v(x){
5         l=r=nullptr;
6     }
7 };
8 node* merge(node* a,node* b){
9     if(!a||!b) return a?:b;
10    // min heap
11    if(a->v>b->v) swap(a,b);
12    a->r=merge(a->r,b);

```

```

13    swap(a->l,a->r);
14    return a;
15 }

```

4.7 Leftist Heap

```

1 struct node{
2     node *l,*r;
3     int d, v;
4     node(int x):d(1),v(x){
5         l=r=nullptr;
6     }
7 };
8 static inline int d(node* x){return x?x->d:0;}
9 node* merge(node* a,node* b){
10    if(!a||!b) return a?:b;
11    // min heap
12    if(a->v>b->v) swap(a,b);
13    a->r=merge(a->r,b);
14    if(d(a->l)<d(a->r))
15        swap(a->l,a->r);
16    a->d=d(a->r)+1;
17    return a;
18 }

```

4.8 Treap

```

1 mt19937 rng(random_device{}());
2 struct Treap
3 {
4     Treap *l,*r;
5     int val,num,pri;
6     Treap(int k)
7     {
8         l=r=NULL;
9         val=k;
10        num=1;
11        pri=rng();
12    }
13 };
14 int siz(Treap *now){return now?now->num:0;}
15 void pull(Treap *&now)
16 {
17     now->num=siz(now->l)+siz(now->r)+1;
18 }
19 Treap* merge(Treap *a,Treap *b)
20 {
21     if(!a||!b)return a?:b;
22     else if(a->pri>b->pri)
23     {
24         a->r=merge(a->r,b);
25         pull(a);
26         return a;
27     }
28     else
29     {
30         b->l=merge(a,b->l);
31         pull(b);
32         return b;
33     }
34 }
35 void split_size(Treap *rt,Treap *&a,Treap *&b,int val)
36 {
37     if(!rt)
38     {
39         a=b=NULL;
40         return;
41     }
42     if(siz(rt->l)+1>val)
43     {
44         b=rt;
45         split_size(rt->l,a,b->l,val);
46         pull(b);
47     }
48     else
49     {
50         a=rt;
51         split_size(rt->r,a->r,b,val-siz(a->l)-1);
52         pull(a);
53     }

```

```

54 }
55 void split_val(Treap *rt, Treap *a, Treap *b, int val)
56 {
57     if(!rt)
58     {
59         a=b=NULL;
60         return;
61     }
62     if(rt->val<=val)
63     {
64         a=rt;
65         split_val(rt->r, a->r, b, val);
66         pull(a);
67     }
68     else
69     {
70         b=rt;
71         split_val(rt->l, a, b->l, val);
72         pull(b);
73     }
74 }
75 void treap_dfs(Treap *now)
76 {
77     if(!now) return;
78     treap_dfs(now->l);
79     cout<<now->val<<" ";
80     treap_dfs(now->r);
81 }

```

4.9 Persistent Treap

```

1 struct node {
2     node *l, *r;
3     char c; int v, sz;
4     node(char x = '$'): c(x), v(mt()), sz(1) {
5         l = r = nullptr;
6     }
7     node(node* p) { *this = *p; }
8     void pull() {
9         sz = 1;
10        for (auto i : {l, r})
11            if (i) sz += i->sz;
12    }
13 } arr[maxn], *ptr = arr;
14 inline int size(node* p) { return p ? p->sz : 0; }
15 node* merge(node* a, node* b) {
16     if (!a || !b) return a ? : b;
17     if (a->v < b->v) {
18         node* ret = new(ptr++) node(a);
19         ret->r = merge(ret->r, b); ret->pull();
20         return ret;
21     }
22     else {
23         node* ret = new(ptr++) node(b);
24         ret->l = merge(a, ret->l); ret->pull();
25         return ret;
26     }
27 }
28 P<node*> split(node* p, int k) {
29     if (!p) return {nullptr, nullptr};
30     if (k >= size(p->l) + 1) {
31         auto [a, b] = split(p->r, k - size(p->l) - 1);
32         node* ret = new(ptr++) node(p);
33         ret->r = a; ret->pull();
34         return {ret, b};
35     }
36     else {
37         auto [a, b] = split(p->l, k);
38         node* ret = new(ptr++) node(p);
39         ret->l = b; ret->pull();
40         return {a, ret};
41     }
42 }

```

4.10 Li Chao Tree

```

1 constexpr int maxn = 5e4 + 5;
2 struct line {
3     ld a, b;
4     ld operator()(ld x) { return a * x + b; }

```

```

5 } arr[(maxn + 1) << 2];
6 bool operator<(line a, line b) { return a.a < b.a; }
7 #define m ((l+r)>>1)
8 void insert(line x, int i = 1, int l = 0, int r = maxn)
9 {
10     if (r - l == 1) {
11         if (x(l) > arr[i](l))
12             arr[i] = x;
13         return;
14     }
15     line a = max(arr[i], x), b = min(arr[i], x);
16     if (a(m) > b(m))
17         arr[i] = a, insert(b, i << 1, l, m);
18     else
19         arr[i] = b, insert(a, i << 1 | 1, m, r);
20 }
21 ld query(int x, int i = 1, int l = 0, int r = maxn) {
22     if (x < l || r <= x) return -numeric_limits<ld>::
23         max();
24     if (r - l == 1) return arr[i](x);
25     return max({arr[i](x), query(x, i << 1, l, m),
26         query(x, i << 1 | 1, m, r)});
27 }
28 #undef m

```

4.11 Time Segment Tree

```

1 constexpr int maxn = 1e5 + 5;
2 V<P<int>> arr[(maxn + 1) << 2];
3 V<int> dsu, sz;
4 V<tuple<int, int, int>> his;
5 int cnt, q;
6 int find(int x) {
7     return x == dsu[x] ? x : find(dsu[x]);
8 }
9 inline bool merge(int x, int y) {
10     int a = find(x), b = find(y);
11     if (a == b) return false;
12     if (sz[a] > sz[b]) swap(a, b);
13     his.emplace_back(a, b, sz[b]), dsu[a] = b, sz[b] +=
14         sz[a];
15     return true;
16 }
17 inline void undo() {
18     auto [a, b, s] = his.back(); his.pop_back();
19     dsu[a] = a, sz[b] = s;
20 }
21 #define m ((l + r) >> 1)
22 void insert(int ql, int qr, P<int> x, int i = 1, int l
23     = 0, int r = q) {
24     // debug(ql, qr, x); return;
25     if (qr <= l || r <= ql) return;
26     if (ql <= l && r <= qr) { arr[i].push_back(x);
27         return; }
28     if (qr <= m)
29         insert(ql, qr, x, i << 1, l, m);
30     else if (m <= ql)
31         insert(ql, qr, x, i << 1 | 1, m, r);
32     else {
33         insert(ql, qr, x, i << 1, l, m);
34         insert(ql, qr, x, i << 1 | 1, m, r);
35     }
36 }
37 void traversal(V<int>& ans, int i = 1, int l = 0, int r
38     = q) {
39     int opcnt = 0;
40     // debug(i, l, r);
41     for (auto [a, b] : arr[i])
42         if (merge(a, b))
43             opcnt++, cnt--;
44     if (r - l == 1) ans[l] = cnt;
45     else {
46         traversal(ans, i << 1, l, m);
47         traversal(ans, i << 1 | 1, m, r);
48     }
49     while (opcnt--)
50         undo(), cnt++;
51     arr[i].clear();
52 }
53 #undef m
54 inline void solve() {

```

```

51 int n, m; cin>>n>>m>>q,q++;
52 dsu.resize(cnt = n), sz.assign(n, 1);
53 iota(dsu.begin(), dsu.end(), 0);
54 // a, b, time, operation
55 unordered_map<ll, V<int>> s;
56 for (int i = 0; i < m; i++) {
57     int a, b; cin>>a>>b;
58     if (a > b) swap(a, b);
59     s[((ll)a << 32) | b].emplace_back(0);
60 }
61 for (int i = 1; i < q; i++) {
62     int op,a, b;
63     cin>>op>>a>>b;
64     if (a > b) swap(a, b);
65     switch (op) {
66     case 1:
67         s[((ll)a << 32) | b].push_back(i);
68         break;
69     case 2:
70         auto tmp = s[((ll)a << 32) | b].back();
71         s[((ll)a << 32) | b].pop_back();
72         insert(tmp, i, P<int> {a, b});
73     }
74 }
75 for (auto [p, v] : s) {
76     int a = p >> 32, b = p & -1;
77     while (v.size()) {
78         insert(v.back(), q, P<int> {a, b});
79         v.pop_back();
80     }
81 }
82 V<int> ans(q);
83 traversal(ans);
84 for (auto i : ans)
85     cout<<i<<' ';
86 cout<<endl;
87 }

```

5 DP

5.1 Aliens

```

1 int n; ll k;
2 vector<ll> a;
3 vector<pll> dp[2];
4 void init() {
5     cin >> n >> k;
6     Each(i, dp) i.clear(), i.resize(n);
7     a.clear(); a.resize(n);
8     Each(i, a) cin >> i;
9 }
10 pll calc(ll p) {
11     dp[0][0] = mp(0, 0);
12     dp[1][0] = mp(-a[0], 0);
13     FOR(i, 1, n, 1) {
14         if (dp[0][i-1].F > dp[1][i-1].F + a[i] - p) {
15             dp[0][i] = dp[0][i-1];
16         } else if (dp[0][i-1].F < dp[1][i-1].F + a[i] - p) {
17             dp[0][i] = mp(dp[1][i-1].F + a[i] - p, dp[1][i-1].S+1);
18         } else {
19             dp[0][i] = mp(dp[0][i-1].F, min(dp[0][i-1].S, dp[1][i-1].S+1));
20         }
21         if (dp[0][i-1].F - a[i] > dp[1][i-1].F) {
22             dp[1][i] = mp(dp[0][i-1].F - a[i], dp[0][i-1].S);
23         } else if (dp[0][i-1].F - a[i] < dp[1][i-1].F) {
24             dp[1][i] = dp[1][i-1];
25         } else {
26             dp[1][i] = mp(dp[1][i-1].F, min(dp[0][i-1].S, dp[1][i-1].S));
27         }
28     }
29     return dp[0][n-1];
30 }
31 void solve() {
32     ll l = 0, r = 1e7;

```

```

33     pll res = calc(0);
34     if (res.S <= k) return cout << res.F << endl, void();
35     while (l < r) {
36         ll mid = (l+r)>>1;
37         res = calc(mid);
38         if (res.S <= k) r = mid;
39         else l = mid+1;
40     }
41     res = calc(l);
42     cout << res.F + k*1 << endl;
43 }

```

6 Graph

6.1 Bellman-Ford + SPFA

```

1 int n, m;
2
3 // Graph
4 vector<vector<pair<int, ll> > > g;
5 vector<ll> dis;
6 vector<bool> negCycle;
7
8 // SPFA
9 vector<int> rlx;
10 queue<int> q;
11 vector<bool> inq;
12 vector<int> pa;
13 void SPFA(vector<int>& src) {
14     dis.assign(n+1, LINF);
15     negCycle.assign(n+1, false);
16     rlx.assign(n+1, 0);
17     while (!q.empty()) q.pop();
18     inq.assign(n+1, false);
19     pa.assign(n+1, -1);
20
21     for (auto& s : src) {
22         dis[s] = 0;
23         q.push(s); inq[s] = true;
24     }
25
26     while (!q.empty()) {
27         int u = q.front();
28         q.pop(); inq[u] = false;
29         if (rlx[u] >= n) {
30             negCycle[u] = true;
31         }
32         else for (auto& e : g[u]) {
33             int v = e.first;
34             ll w = e.second;
35             if (dis[v] > dis[u] + w) {
36                 dis[v] = dis[u] + w;
37                 rlx[v] = rlx[u] + 1;
38                 pa[v] = u;
39                 if (!inq[v]) {
40                     q.push(v);
41                     inq[v] = true;
42                 }
43             }
44         }
45     }
46
47 // Bellman-Ford
48 queue<int> q;
49 vector<int> pa;
50 void BellmanFord(vector<int>& src) {
51     dis.assign(n+1, LINF);
52     negCycle.assign(n+1, false);
53     pa.assign(n+1, -1);
54
55     for (auto& s : src) dis[s] = 0;
56
57     for (int rlx = 1; rlx <= n; rlx++) {
58         for (int u = 1; u <= n; u++) {
59             if (dis[u] == LINF) continue; // Important
60             !!
61             for (auto& e : g[u]) {
62                 int v = e.first; ll w = e.second;
63                 if (dis[v] > dis[u] + w) {
64                     dis[v] = dis[u] + w;
65                     pa[v] = u;
66                 }
67             }
68         }
69     }

```

```

63         if (rlx == n) negCycle[v] = true;
64     } } } }
65
66 // Negative Cycle Detection
67 void NegCycleDetect() {
68     /* No Neg Cycle: NO
69     Exist Any Neg Cycle:
70     YES
71     v0 v1 v2 ... vk v0 */
72
73     vector<int> src;
74     for (int i = 1; i <= n; i++)
75         src.emplace_back(i);
76
77     SPFA(src);
78     // BellmanFord(src);
79
80     int ptr = -1;
81     for (int i = 1; i <= n; i++) if (negCycle[i])
82         { ptr = i; break; }
83
84     if (ptr == -1) { return cout << "NO" << endl, void
85         (); }
86
87     cout << "YES\n";
88     vector<int> ans;
89     vector<bool> vis(n+1, false);
90
91     while (true) {
92         ans.emplace_back(ptr);
93         if (vis[ptr]) break;
94         vis[ptr] = true;
95         ptr = pa[ptr];
96     }
97     reverse(ans.begin(), ans.end());
98
99     vis.assign(n+1, false);
100    for (auto& x : ans) {
101        cout << x << ' ';
102        if (vis[x]) break;
103        vis[x] = true;
104    }
105    cout << endl;
106}
107
108 // Distance Calculation
109 void calcDis(int s) {
110     vector<int> src;
111     src.emplace_back(s);
112     SPFA(src);
113     // BellmanFord(src);
114
115     while (!q.empty()) q.pop();
116     for (int i = 1; i <= n; i++)
117         if (negCycle[i]) q.push(i);
118
119     while (!q.empty()) {
120         int u = q.front(); q.pop();
121         for (auto& e : g[u]) {
122             int v = e.first;
123             if (!negCycle[v]) {
124                 q.push(v);
125                 negCycle[v] = true;
126             }
127         }
128     }

```

6.2 BCC - AP

```

1 int n, m;
2 int low[maxn], dfn[maxn], instp;
3 vector<int> E, g[maxn];
4 bitset<maxn> isap;
5 bitset<maxn> vis;
6 stack<int> stk;
7 int bccnt;
8 vector<int> bcc[maxn];
9 inline void popout(int u) {
10     bccnt++;
11     bcc[bccnt].emplace_back(u);
12     while (!stk.empty()) {
13         int v = stk.top();

```

```

14         if (u == v) break;
15         stk.pop();
16         bcc[bccnt].emplace_back(v);
17     }
18 }
19 void dfs(int u, bool rt = 0) {
20     stk.push(u);
21     low[u] = dfn[u] = ++instp;
22     int kid = 0;
23     Each(e, g[u]) {
24         if (vis[e]) continue;
25         vis[e] = true;
26         int v = E[e]^u;
27         if (!dfn[v]) {
28             // tree edge
29             kid++; dfs(v);
30             low[u] = min(low[u], low[v]);
31             if (!rt && low[v] >= dfn[u]) {
32                 // bcc found: u is ap
33                 isap[u] = true;
34                 popout(u);
35             }
36         } else {
37             // back edge
38             low[u] = min(low[u], dfn[v]);
39         }
40     }
41     // special case: root
42     if (rt) {
43         if (kid > 1) isap[u] = true;
44         popout(u);
45     }
46 }
47 void init() {
48     cin >> n >> m;
49     fill(low, low+maxn, INF);
50     REP(i, m) {
51         int u, v;
52         cin >> u >> v;
53         g[u].emplace_back(i);
54         g[v].emplace_back(i);
55         E.emplace_back(u^v);
56     }
57 }
58 void solve() {
59     FOR(i, 1, n+1, 1) {
60         if (!dfn[i]) dfs(i, true);
61     }
62     vector<int> ans;
63     int cnt = 0;
64     FOR(i, 1, n+1, 1) {
65         if (isap[i]) cnt++, ans.emplace_back(i);
66     }
67     cout << cnt << endl;
68     Each(i, ans) cout << i << ' ';
69     cout << endl;
70 }

```

6.3 BCC - Bridge

```

1 int n, m;
2 vector<int> g[maxn], E;
3 int low[maxn], dfn[maxn], instp;
4 int bccnt, bccid[maxn];
5 stack<int> stk;
6 bitset<maxn> vis, isbrg;
7 void init() {
8     cin >> n >> m;
9     REP(i, m) {
10         int u, v;
11         cin >> u >> v;
12         E.emplace_back(u^v);
13         g[u].emplace_back(i);
14         g[v].emplace_back(i);
15     }
16     fill(low, low+maxn, INF);
17 }
18 void popout(int u) {
19     bccnt++;
20     while (!stk.empty()) {
21         int v = stk.top();

```



```

22     if (v == u) break;
23     stk.pop();
24     bccid[v] = bccnt;
25 }
26 }
27 void dfs(int u) {
28     stk.push(u);
29     low[u] = dfn[u] = ++instp;
30
31     Each(e, g[u]) {
32         if (vis[e]) continue;
33         vis[e] = true;
34
35         int v = E[e]^u;
36         if (dfn[v]) {
37             // back edge
38             low[u] = min(low[u], dfn[v]);
39         } else {
40             // tree edge
41             dfs(v);
42             low[u] = min(low[u], low[v]);
43             if (low[v] == dfn[v]) {
44                 isbrg[e] = true;
45                 popout(u);
46             }
47         }
48     }
49 }
50 void solve() {
51     FOR(i, 1, n+1, 1) {
52         if (!dfn[i]) dfs(i);
53     }
54     vector<pii> ans;
55     vis.reset();
56     FOR(u, 1, n+1, 1) {
57         Each(e, g[u]) {
58             if (!isbrg[e] || vis[e]) continue;
59             vis[e] = true;
60             int v = E[e]^u;
61             ans.emplace_back(mp(u, v));
62         }
63     }
64     cout << (int)ans.size() << endl;
65     Each(e, ans) cout << e.F << ' ' << e.S << endl;
66 }

```

6.4 SCC - Tarjan

```

1 // 2-SAT
2 vector<int> E, g[maxn]; // 1~n, n+1~2n
3 int low[maxn], in[maxn], instp;
4 int sccnt, sccid[maxn];
5
6 stack<int> stk;
7 bitset<maxn> ins, vis;
8
9 int n, m;
10
11 void init() {
12     cin >> m >> n;
13     E.clear();
14     fill(g, g+maxn, vector<int>());
15     fill(low, low+maxn, INF);
16     memset(in, 0, sizeof(in));
17     instp = 1;
18     sccnt = 0;
19     memset(sccid, 0, sizeof(sccid));
20     ins.reset();
21     vis.reset();
22 }
23
24 inline int no(int u) {
25     return (u > n ? u-n : u+n);
26 }
27
28 int ecnt = 0;
29 inline void clause(int u, int v) {
30     E.eb(no(u)^v);
31     g[no(u)].eb(ecnt++);
32     E.eb(no(v)^u);
33     g[no(v)].eb(ecnt++);

```

```

34 }
35
36 void dfs(int u) {
37     in[u] = instp++;
38     low[u] = in[u];
39     stk.push(u);
40     ins[u] = true;
41
42     Each(e, g[u]) {
43         if (vis[e]) continue;
44         vis[e] = true;
45
46         int v = E[e]^u;
47         if (ins[v]) low[u] = min(low[u], in[v]);
48         else if (!in[v]) {
49             dfs(v);
50             low[u] = min(low[u], low[v]);
51         }
52     }
53
54     if (low[u] == in[u]) {
55         sccnt++;
56         while (!stk.empty()) {
57             int v = stk.top();
58             stk.pop();
59             ins[v] = false;
60             sccid[v] = sccnt;
61             if (u == v) break;
62         }
63     }
64 }
65
66 int main() {
67     WiWiHorz
68     init();
69
70     REP(i, m) {
71         char su, sv;
72         int u, v;
73         cin >> su >> u >> sv >> v;
74         if (su == '-') u = no(u);
75         if (sv == '-') v = no(v);
76         clause(u, v);
77     }
78
79     FOR(i, 1, 2*n+1, 1) {
80         if (!in[i]) dfs(i);
81     }
82
83     FOR(u, 1, n+1, 1) {
84         int du = no(u);
85         if (sccid[u] == sccid[du]) {
86             return cout << "IMPOSSIBLE\n", 0;
87         }
88     }
89
90     FOR(u, 1, n+1, 1) {
91         int du = no(u);
92         cout << (sccid[u] < sccid[du] ? '+' : '-') << '
93             ' << ' ';
94     }
95     cout << endl;
96
97     return 0;
98 }

```

6.5 SCC - Kosaraju

```

1 const int N = 1e5 + 10;
2 vector<int> ed[N], ed_b[N]; // 反邊
3 vector<int> SCC(N); // 最後SCC的分組
4 bitset<N> vis;
5 int SCC_cnt;
6 int n, m;
7 vector<int> pre; // 後序遍歷
8
9 void dfs(int x)
10 {
11     vis[x] = 1;
12     for(int i : ed[x]) {

```



```

13     if(vis[i]) continue;
14     dfs(i);
15 }
16 pre.push_back(x);
17 }
18
19 void dfs2(int x)
20 {
21     vis[x] = 1;
22     SCC_cnt = SCC_cnt;
23     for(int i : ed_b[x]) {
24         if(vis[i]) continue;
25         dfs2(i);
26     }
27 }
28
29 void kosaraju()
30 {
31     for(int i = 1; i <= n; i++) {
32         if(!vis[i]) {
33             dfs(i);
34         }
35     }
36     SCC_cnt = 0;
37     vis = 0;
38     for(int i = n - 1; i >= 0; i--) {
39         if(!vis[pre[i]]) {
40             SCC_cnt++;
41             dfs2(pre[i]);
42         }
43     }
44 }

```

6.6 Eulerian Path - Undir

```

1 // from 1 to n
2 #define gg return cout << "IMPOSSIBLE\n", void();
3
4 int n, m;
5 vector<int> g[maxn];
6 bitset<maxn> inodd;
7
8 void init() {
9     cin >> n >> m;
10    inodd.reset();
11    for (int i = 0; i < m; i++) {
12        int u, v; cin >> u >> v;
13        inodd[u] = inodd[u] ^ true;
14        inodd[v] = inodd[v] ^ true;
15        g[u].emplace_back(v);
16        g[v].emplace_back(u);
17    }
18    stack<int> stk;
19    void dfs(int u) {
20        while (!g[u].empty()) {
21            int v = g[u].back();
22            g[u].pop_back();
23            dfs(v);
24        }
25        stk.push(u);
26    }
27 }

```

6.7 Eulerian Path - Dir

```

1 // from node 1 to node n
2 #define gg return cout << "IMPOSSIBLE\n", 0
3
4 int n, m;
5 vector<int> g[maxn];
6 stack<int> stk;
7 int in[maxn], out[maxn];
8
9 void init() {
10    cin >> n >> m;
11    for (int i = 0; i < m; i++) {
12        int u, v; cin >> u >> v;
13        g[u].emplace_back(v);
14        out[u]++, in[v]++;
15    }
16    for (int i = 1; i <= n; i++) {
17        if (i == 1 && out[i]-in[i] != 1) gg;

```

```

18        if (i == n && in[i]-out[i] != 1) gg;
19        if (i != 1 && i != n && in[i] != out[i]) gg;
20    }
21    void dfs(int u) {
22        while (!g[u].empty()) {
23            int v = g[u].back();
24            g[u].pop_back();
25            dfs(v);
26        }
27        stk.push(u);
28    }
29    void solve() {
30        dfs(1);
31        for (int i = 1; i <= n; i++)
32            if ((int)g[i].size()) gg;
33        while (!stk.empty()) {
34            int u = stk.top();
35            stk.pop();
36            cout << u << ' ';
37        }
38    }
39 }

```

6.8 Hamilton Path

```

1 // top down DP
2 // Be Aware Of Multiple Edges
3 int n, m;
4 ll dp[maxn][1<<maxn];
5 int adj[maxn][maxn];
6
7 void init() {
8     cin >> n >> m;
9     fill(dp[0], dp[maxn-1]+(1<<maxn), -1);
10 }
11
12 void DP(int i, int msk) {
13     if (dp[i][msk] != -1) return;
14     dp[i][msk] = 0;
15     REP(j, n) if (j != i && (msk & (1<<j)) && adj[j][i]) {
16         int sub = msk ^ (1<<i);
17         if (dp[j][sub] == -1) DP(j, sub);
18         dp[i][msk] += dp[j][sub] * adj[j][i];
19         if (dp[i][msk] >= MOD) dp[i][msk] %= MOD;
20     }
21 }
22
23 int main() {
24     WiWiHorz
25     init();
26
27     REP(i, m) {
28         int u, v;
29         cin >> u >> v;
30         if (u == v) continue;
31         adj[--u][--v]++;
32     }
33
34     dp[0][1] = 1;
35     FOR(i, 1, n, 1) {
36         dp[i][1] = 0;
37         dp[i][1|(1<<i)] = adj[0][i];
38     }
39     FOR(msk, 1, (1<<n), 1) {
40         if (msk == 1) continue;
41         dp[0][msk] = 0;
42     }
43
44     DP(n-1, (1<<n)-1);
45     cout << dp[n-1][(1<<n)-1] << endl;
46
47     return 0;
48 }

```

6.9 Kth Shortest Path

```

1 // time: O(|E| \lg |E|+|V| \lg |V|+K)
2 // memory: O(|E| \lg |E|+|V|)
3 struct KSP{ // 1-base

```

```

4 struct nd{
5     int u,v; ll d;
6     nd(int ui=0,int vi=0,ll di=INF){ u=ui; v=vi; d=di;
7     }
8 };
9 struct heap{ nd* edge; int dep; heap* chd[4]; };
10 static int cmp(heap* a,heap* b)
11 { return a->edge->d > b->edge->d; }
12 struct node{
13     int v; ll d; heap* H; nd* E;
14     node(){
15         node(ll _d,int _v,nd* _E){ d=_d; v=_v; E=_E; }
16         node(heap* _H,ll _d){ H=_H; d=_d; }
17         friend bool operator<(node a,node b)
18         { return a.d>b.d; }
19 };
20 int n,k,s,t,dst[N]; nd *nxt[N];
21 vector<nd*> g[N],rg[N]; heap *nullNd,*head[N];
22 void init(int _n,int _k,int _s,int _t){
23     n=_n; k=_k; s=_s; t=_t;
24     for(int i=1;i<=n;i++){
25         g[i].clear(); rg[i].clear();
26         nxt[i]=NULL; head[i]=NULL; dst[i]=-1;
27     }
28 void addEdge(int ui,int vi,ll di){
29     nd* e=new nd(ui,vi,di);
30     g[ui].push_back(e); rg[vi].push_back(e);
31 }
32 queue<int> dfsQ;
33 void dijkstra(){
34     while(dfsQ.size()) dfsQ.pop();
35     priority_queue<node> Q; Q.push(node(0,t,NULL));
36     while (!Q.empty()){
37         node p=Q.top(); Q.pop(); if(dst[p.v]!=-1)continue;
38         dst[p.v]=p.d; nxt[p.v]=p.E; dfsQ.push(p.v);
39         for(auto e:rg[p.v]) Q.push(node(p.d+e->d,e->u,e));
40     }
41 }
42 heap* merge(heap* curNd,heap* newNd){
43     if(curNd==nullNd) return newNd;
44     heap* root=new heap; memcpy(root,curNd,sizeof(heap));
45     if(newNd->edge->d<curNd->edge->d){
46         root->edge=newNd->edge;
47         root->chd[2]=newNd->chd[2];
48         root->chd[3]=newNd->chd[3];
49         newNd->edge=curNd->edge;
50         newNd->chd[2]=curNd->chd[2];
51         newNd->chd[3]=curNd->chd[3];
52     }
53     if(root->chd[0]->dep<root->chd[1]->dep)
54         root->chd[0]=merge(root->chd[0],newNd);
55     else root->chd[1]=merge(root->chd[1],newNd);
56     root->dep=max(root->chd[0]->dep,
57         root->chd[1]->dep)+1;
58     return root;
59 }
60 vector<heap*> V;
61 void build(){
62     nullNd=new heap; nullNd->dep=0; nullNd->edge=new nd
63     ;
64     fill(nullNd->chd,nullNd->chd+4,nullNd);
65     while(not dfsQ.empty()){
66         int u=dfsQ.front(); dfsQ.pop();
67         if(!nxt[u]) head[u]=nullNd;
68         else head[u]=head[nxt[u]->v];
69         V.clear();
70         for(auto&& e:g[u]){
71             int v=e->v;
72             if(dst[v]==-1) continue;
73             e->d+=dst[v]-dst[u];
74             if(nxt[u]!=e){
75                 heap* p=new heap; fill(p->chd,p->chd+4,nullNd);
76                 p->dep=1; p->edge=e; V.push_back(p);
77             }
78         }
79         if(V.empty()) continue;
80         make_heap(V.begin(),V.end(),cmp);
81     }
82 }
83 #define L(X) ((X<<1)+1)
84 #define R(X) ((X<<1)+2)
85 for(size_t i=0;i<V.size();i++){
86     if(L(i)<V.size()) V[i]->chd[2]=V[L(i)];
87     else V[i]->chd[2]=nullNd;
88     if(R(i)<V.size()) V[i]->chd[3]=V[R(i)];
89     else V[i]->chd[3]=nullNd;
90 }
91 head[u]=merge(head[u],V.front());
92 }
93 vector<ll> ans;
94 void first_K(){
95     ans.clear(); priority_queue<node> Q;
96     if(dst[s]==-1) return;
97     ans.push_back(dst[s]);
98     if(head[s]!=nullNd)
99         Q.push(node(head[s],dst[s]+head[s]->edge->d));
100     for(int _=1;_<k and not Q.empty();_++){
101         node p=Q.top(); q=Q.pop(); ans.push_back(p.d);
102         if(head[p.H->edge->v]!=nullNd){
103             q.H=head[p.H->edge->v]; q.d=p.d+q.H->edge->d;
104             Q.push(q);
105         }
106     }
107     for(int i=0;i<4;i++){
108         if(p.H->chd[i]!=nullNd){
109             q.H=p.H->chd[i];
110             q.d=p.d-p.H->edge->d+p.H->chd[i]->edge->d;
111             Q.push(q);
112         }
113     }
114 }
115 void solve(){ // ans[i] stores the i-th shortest path
116     dijkstra(); build();
117     first_K(); // ans.size() might less than k
118 }
119 } solver;

```

6.10 System of Difference Constraints

```

1 vector<vector<pair<int, ll>>> G;
2 void add(int u, int v, ll w) {
3     G[u].emplace_back(make_pair(v, w));
4 }

```

- $x_u - x_v \leq c \Rightarrow \text{add}(v, u, c)$
- $x_u - x_v \geq c \Rightarrow \text{add}(u, v, -c)$
- $x_u - x_v = c \Rightarrow \text{add}(v, u, c), \text{add}(u, v, -c)$
- $x_u \geq c \Rightarrow \text{add super vertex } x_0 = 0, \text{ then } x_u - x_0 \geq c \Rightarrow \text{add}(u, 0, -c)$
- Don't forget non-negative constraints for every variable if specified implicitly.
- Interval sum \Rightarrow Use prefix sum to transform into differential constraints. Don't forget $S_{i+1} - S_i \geq 0$ if x_i needs to be non-negative.
- $\frac{x_u}{x_v} \leq c \Rightarrow \log x_u - \log x_v \leq \log c$

7 String

7.1 Rolling Hash

```

1 const ll C = 27;
2 inline int id(char c) {return c-'a'+1;}
3 struct RollingHash {
4     string s; int n; ll mod;
5     vector<ll> Cexp, hs;
6     RollingHash(string& _s, ll _mod):
7         s(_s), n((_int)_s.size()), mod(_mod)
8     {
9         Cexp.assign(n, 0);
10        hs.assign(n, 0);
11        Cexp[0] = 1;
12        for (int i = 1; i < n; i++) {

```

```

13     Cexp[i] = Cexp[i-1] * C;
14     if (Cexp[i] >= mod) Cexp[i] %= mod;
15 }
16 hs[0] = id(s[0]);
17 for (int i = 1; i < n; i++) {
18     hs[i] = hs[i-1] * C + id(s[i]);
19     if (hs[i] >= mod) hs[i] %= mod;
20 }
21 inline ll query(int l, int r) {
22     ll res = hs[r] - (l ? hs[l-1] * Cexp[r-l+1] :
23         0);
24     res = (res % mod + mod) % mod;
25     return res; }
};

```

7.2 Trie

```

1 struct node {
2     int c[26]; ll cnt;
3     node(): cnt(0) {memset(c, 0, sizeof(c));}
4     node(ll x): cnt(x) {memset(c, 0, sizeof(c));}
5 };
6 struct Trie {
7     vector<node> t;
8     void init() {
9         t.clear();
10        t.emplace_back(node());
11    }
12    void insert(string s) { int ptr = 0;
13        for (auto& i : s) {
14            if (!t[ptr].c[i-'a']) {
15                t.emplace_back(node());
16                t[ptr].c[i-'a'] = (int)t.size()-1; }
17            ptr = t[ptr].c[i-'a']; }
18        t[ptr].cnt++; }
19 } trie;

```

7.3 KMP

```

1 int n, m;
2 string s, p;
3 vector<int> f;
4 void build() {
5     f.clear(); f.resize(m, 0);
6     int ptr = 0; for (int i = 1; i < m; i++) {
7         while (ptr && p[i] != p[ptr]) ptr = f[ptr-1];
8         if (p[i] == p[ptr]) ptr++;
9         f[i] = ptr;
10    }
11    void init() {
12        cin >> s >> p;
13        n = (int)s.size();
14        m = (int)p.size();
15        build(); }
16    void solve() {
17        int ans = 0, pi = 0;
18        for (int si = 0; si < n; si++) {
19            while (pi && s[si] != p[pi]) pi = f[pi-1];
20            if (s[si] == p[pi]) pi++;
21            if (pi == m) ans++, pi = f[pi-1];
22        }
23        cout << ans << endl; }

```

7.4 Z Value

```

1 string is, it, s;
2 int n; vector<int> z;
3 void init() {
4     cin >> is >> it;
5     s = it+'0'+is;
6     n = (int)s.size();
7     z.resize(n, 0); }
8 void solve() {
9     int ans = 0; z[0] = n;
10    for (int i = 1, l = 0, r = 0; i < n; i++) {
11        if (i <= r) z[i] = min(z[i-l], r-i+1);
12        while (i+z[i] < n && s[z[i]] == s[i+z[i]]) z[i]++;
13        if (i+z[i]-1 > r) l = i, r = i+z[i]-1;

```

```

14        if (z[i] == (int)it.size()) ans++;
15    }
16    cout << ans << endl; }

```

7.5 Manacher

```

1 int n; string S, s;
2 vector<int> m;
3 void manacher() {
4     s.clear(); s.resize(2*n+1, '.');
5     for (int i = 0, j = 1; i < n; i++, j += 2) s[j] = S[i];
6     m.clear(); m.resize(2*n+1, 0);
7     // m[i] := max k such that s[i-k, i+k] is palindrome
8     int mx = 0, mxk = 0;
9     for (int i = 1; i < 2*n+1; i++) {
10        if (mx-(i-mx) >= 0) m[i] = min(m[mx-(i-mx)], mx+mxk-i);
11        while (0 <= i-m[i]-1 && i+m[i]+1 < 2*n+1 &&
12            s[i-m[i]-1] == s[i+m[i]+1]) m[i]++;
13        if (i+m[i] > mx+mxk) mx = i, mxk = m[i];
14    } }
15 void init() { cin >> S; n = (int)S.size(); }
16 void solve() {
17     manacher();
18     int mx = 0, ptr = 0;
19     for (int i = 0; i < 2*n+1; i++) if (mx < m[i])
20         { mx = m[i]; ptr = i; }
21     for (int i = ptr-mx; i <= ptr+mx; i++)
22         if (s[i] != '.') cout << s[i];
23     cout << endl; }

```

7.6 Suffix Array

```

1 #define F first
2 #define S second
3 struct SuffixArray { // don't forget s += "$";
4     int n; string s;
5     vector<int> suf, lcp, rk;
6     vector<int> cnt, pos;
7     vector<pair<pii, int>> buc[2];
8     void init(string _s) {
9         s = _s; n = (int)s.size();
10        // resize(n): suf, rk, cnt, pos, lcp, buc[0~1]
11    }
12    void radix_sort() {
13        for (int t : {0, 1}) {
14            fill(cnt.begin(), cnt.end(), 0);
15            for (auto& i : buc[t]) cnt[ (t ? i.F.F : i.F.S) ]++;
16            for (int i = 0; i < n; i++)
17                pos[i] = (!i ? 0 : pos[i-1] + cnt[i-1]);
18            for (auto& i : buc[t])
19                buc[t^1][pos[ (t ? i.F.F : i.F.S) ]++] = i;
20        } }
21    bool fill_suf() {
22        bool end = true;
23        for (int i = 0; i < n; i++) suf[i] = buc[0][i].S;
24        rk[suf[0]] = 0;
25        for (int i = 1; i < n; i++) {
26            int dif = (buc[0][i].F != buc[0][i-1].F);
27            end &= dif;
28            rk[suf[i]] = rk[suf[i-1]] + dif;
29        } return end;
30    }
31    void sa() {
32        for (int i = 0; i < n; i++)
33            buc[0][i] = make_pair(make_pair(s[i], s[i]), i);
34        sort(buc[0].begin(), buc[0].end());
35        if (fill_suf()) return;
36        for (int k = 0; (1<<k) < n; k++) {
37            for (int i = 0; i < n; i++)
38                buc[0][i] = make_pair(make_pair(rk[i], rk[(i + (1<<k)) % n]), i);
39            radix_sort();
40            if (fill_suf()) return;
41        } }

```

```

42 void LCP() { int k = 0;
43   for (int i = 0; i < n-1; i++) {
44     if (rk[i] == 0) continue;
45     int pi = rk[i];
46     int j = suf[pi-1];
47     while (i+k < n && j+k < n && s[i+k] == s[j+k]) k++;
48     lcp[pi] = k;
49     k = max(k-1, 0);
50   }
51 };
52 SuffixArray suffixarray;

```

7.7 SA-IS

```

1  const int N=300010;
2  struct SA{
3    #define REP(i,n) for(int i=0;i<int(n);i++)
4    #define REP1(i,a,b) for(int i=(a);i<=int(b);i++)
5    bool _t[N*2]; int _s[N*2], _sa[N*2];
6    int _c[N*2], x[N], _p[N], _q[N*2], hei[N], r[N];
7    int operator [](int i){ return _sa[i]; }
8    void build(int *s, int n, int m){
9      memcpy(_s, s, sizeof(int)*n);
10     sais(_s, _sa, _p, _q, _t, _c, n, m); mkhei(n);
11   }
12   void mkhei(int n){
13     REP(i, n) r[_sa[i]] = i;
14     hei[0] = 0;
15     REP(i, n) if(r[i]) {
16       int ans = i > 0 ? max(hei[r[i-1]]-1, 0) : 0;
17       while(_s[i+ans] == _s[_sa[r[i]-1]+ans]) ans++;
18       hei[r[i]] = ans;
19     }
20   }
21   void sais(int *s, int *sa, int *p, int *q, bool *t, int *c,
22     int n, int z){
23     bool uniq = t[n-1] = true, neq;
24     int nn = 0, nmzx = -1, *nsa = sa+n, *ns = s+n, lst = -1;
25     #define MS0(x, n) memset((x), 0, n*sizeof(*(x)))
26     #define MAGIC(XD) MS0(sa, n); \
27     memcpy(x, c, sizeof(int)*z); XD; \
28     memcpy(x+1, c, sizeof(int)*(z-1)); \
29     REP(i, n) if(sa[i] && !t[sa[i]-1]) sa[x[s[sa[i]-1]]++] = sa[i]-1; \
30     memcpy(x, c, sizeof(int)*z); \
31     for(int i = n-1; i >= 0; i--) if(sa[i] && t[sa[i]-1]) sa[--x[s[sa[i]-1]]] = sa[i]-1;
32     MS0(c, z); REP(i, n) uniq &= ++c[s[i]] < 2;
33     REP(i, z-1) c[i+1] += c[i];
34     if(uniq) { REP(i, n) sa[--c[s[i]]] = i; return; }
35     for(int i = n-2; i >= 0; i--)
36       t[i] = (s[i] == s[i+1] ? t[i+1] : s[i] < s[i+1]);
37     MAGIC(REP1(i, 1, n-1) if(t[i] && !t[i-1]) sa[--x[s[i]]] = p[q[i]=nn++] = i);
38     REP(i, n) if(sa[i] && t[sa[i]] && !t[sa[i]-1]){
39       neq = lst < 0 || memcmp(s+sa[i], s+lst, (p[q[sa[i]]+1]-sa[i])*sizeof(int));
40       ns[q[lst=sa[i]]] = nmzx += neq;
41     }
42     sais(ns, nsa, p+nn, q+n, t+n, c+z, nn, nmzx+1);
43     MAGIC(for(int i = nn-1; i >= 0; i--) sa[--x[s[p[nsa[i]]]]] = p[nsa[i]]);
44   }
45   int H[N], SA[N], RA[N];
46   void suffix_array(int* ip, int len){
47     // should padding a zero in the back
48     // ip is int array, len is array length
49     // ip[0..n-1] != 0, and ip[len]=0
50     ip[len++] = 0; sa.build(ip, len, 128);
51     memcpy(H, sa.hei+1, len<<2); memcpy(SA, sa._sa+1, len<<2);
52     for(int i=0; i<len; i++) RA[i] = sa.r[i]-1;
53     // resulting height, sa array \in [0, len)
54   }

```

7.8 Minimum Rotation

```

1 //rotate(begin(s), begin(s)+minRotation(s), end(s))

```

```

2 int minRotation(string s) {
3   int a = 0, n = s.size(); s += s;
4   for(int b = 0; b < n; b++) for(int k = 0; k < n; k++) {
5     if(a + k == b || s[a + k] < s[b + k]) {
6       b += max(0, k - 1);
7       break; }
8     if(s[a + k] > s[b + k]) {
9       a = b;
10      break;
11    } }
12   return a; }

```

7.9 Aho Corasick

```

1 struct ACautomata{
2   struct Node{
3     int cnt;
4     Node *go[26], *fail, *dic;
5     Node(){
6       cnt = 0; fail = 0; dic = 0;
7       memset(go, 0, sizeof(go));
8     }
9   } pool[1048576], *root;
10  int nMem;
11  Node* new_Node(){
12    pool[nMem] = Node();
13    return &pool[nMem++];
14  }
15  void init() { nMem = 0; root = new_Node(); }
16  void add(const string &str) { insert(root, str, 0); }
17  void insert(Node *cur, const string &str, int pos){
18    for(int i = pos; i < str.size(); i++){
19      if(!cur->go[str[i]-'a'])
20        cur->go[str[i]-'a'] = new_Node();
21      cur = cur->go[str[i]-'a'];
22    }
23    cur->cnt++;
24  }
25  void make_fail(){
26    queue<Node*> que;
27    que.push(root);
28    while (!que.empty()){
29      Node* fr = que.front(); que.pop();
30      for (int i = 0; i < 26; i++){
31        if (fr->go[i]){
32          Node *ptr = fr->fail;
33          while (ptr && !ptr->go[i]) ptr = ptr->fail;
34          fr->go[i]->fail = ptr = (ptr ? ptr->go[i] : root);
35          fr->go[i]->dic = (ptr->cnt ? ptr : ptr->dic);
36          que.push(fr->go[i]);
37        } } }
38  } AC;

```

8 Geometry

8.1 Basic Operations

```

1 typedef long long T;
2 // typedef long double T;
3 const long double eps = 1e-8;
4
5 short sgn(T x) {
6   if (abs(x) < eps) return 0;
7   return x < 0 ? -1 : 1;
8 }
9
10 struct Pt {
11   T x, y;
12   Pt(T _x=0, T _y=0):x(_x), y(_y) {}
13   Pt operator+(Pt a) { return Pt(x+a.x, y+a.y); }
14   Pt operator-(Pt a) { return Pt(x-a.x, y-a.y); }
15   Pt operator*(T a) { return Pt(x*a, y*a); }
16   Pt operator/(T a) { return Pt(x/a, y/a); }
17   T operator*(Pt a) { return x*a.x + y*a.y; }
18   T operator^(Pt a) { return x*a.y - y*a.x; }
19   bool operator<(Pt a) {
20     { return x < a.x || (x == a.x && y < a.y); }
21     //return sgn(x-a.x) < 0 || (sgn(x-a.x) == 0 && sgn(y-a.y) < 0); }

```

```

22 bool operator==(Pt a)
23     { return sgn(x-a.x) == 0 && sgn(y-a.y) == 0; }
24 };
25
26 Pt mv(Pt a, Pt b) { return b-a; }
27 T len2(Pt a) { return a*a; }
28 T dis2(Pt a, Pt b) { return len2(b-a); }
29
30 short ori(Pt a, Pt b) { return ((a^b)>0) - ((a^b)<0); }
31 bool onseg(Pt p, Pt l1, Pt l2) {
32     Pt a = mv(p, l1), b = mv(p, l2);
33     return ((a^b) == 0) && ((a*b) <= 0);
34 }

```

8.2 InPoly

```

1 short inPoly(Pt p) {
2     // 0=Bound 1=In -1=Out
3     REP(i, n) if (onseg(p, E[i], E[(i+1)%n])) return 0;
4     int cnt = 0;
5     REP(i, n) if (banana(p, Pt(p.x+1, p.y+2e9),
6         E[i], E[(i+1)%n])) cnt ^= 1;
7     return (cnt ? 1 : -1);
8 }

```

8.3 Sort by Angle

```

1 int ud(Pt a) { // up or down half plane
2     if (a.y > 0) return 0;
3     if (a.y < 0) return 1;
4     return (a.x >= 0 ? 0 : 1);
5 }
6 sort(ALL(E), [&](const Pt& a, const Pt& b){
7     if (ud(a) != ud(b)) return ud(a) < ud(b);
8     return (a^b) > 0;
9 });

```

8.4 Line Intersect Check

```

1 inline bool banana(Pt p1, Pt p2, Pt q1, Pt q2) {
2     if (onseg(p1, q1, q2) || onseg(p2, q1, q2) ||
3         onseg(q1, p1, p2) || onseg(q2, p1, p2)) {
4         return true;
5     }
6     Pt p = mv(p1, p2), q = mv(q1, q2);
7     return (ori(p, mv(p1, q1)) * ori(p, mv(p1, q2)) < 0 &&
8         ori(q, mv(q1, p1)) * ori(q, mv(q1, p2)) < 0);
9 }

```

8.5 Line Intersection

```

1 // T: long double
2 Pt bananaPoint(Pt p1, Pt p2, Pt q1, Pt q2) {
3     if (onseg(q1, p1, p2)) return q1;
4     if (onseg(q2, p1, p2)) return q2;
5     if (onseg(p1, q1, q2)) return p1;
6     if (onseg(p2, q1, q2)) return p2;
7     double s = abs(mv(p1, p2) ^ mv(p1, q1));
8     double t = abs(mv(p1, p2) ^ mv(p1, q2));
9     return q2 * (s/(s+t)) + q1 * (t/(s+t));
10 }

```

8.6 Convex Hull

```

1 vector<Pt> hull;
2 void convexHull() {
3     hull.clear(); sort(ALL(E));
4     REP(t, 2) {
5         int b = SZ(hull);
6         Each(ei, E) {
7             while (SZ(hull) - b >= 2 &&
8                 ori(mv(hull[SZ(hull)-2], hull.back()),
9                 mv(hull[SZ(hull)-2], ei)) == -1) {
10                 hull.pop_back();
11             }
12             hull.pb(ei);
13         }
14     }
15 }

```

```

14 hull.pop_back();
15 reverse(ALL(E));
16 } }

```

8.7 Lower Concave Hull

```

1 struct Line {
2     mutable ll m, b, p;
3     bool operator<(const Line& o) const { return m < o.m; }
4     bool operator<(ll x) const { return p < x; }
5 };
6
7 struct LineContainer : multiset<Line, less<>> {
8     // (for doubles, use inf = 1/.0, div(a,b) = a/b)
9     const ll inf = LLONG_MAX;
10     ll div(ll a, ll b) { // floored division
11         return a / b - ((a ^ b) < 0 && a % b); }
12     bool isect(iterator x, iterator y) {
13         if (y == end()) { x->p = inf; return false; }
14         if (x->m == y->m) x->p = x->b > y->b ? inf : -inf;
15         else x->p = div(y->b - x->b, x->m - y->m);
16         return x->p >= y->p;
17     }
18     void add(ll m, ll b) {
19         auto z = insert({m, b, 0}), y = z++, x = y;
20         while (isect(y, z)) z = erase(z);
21         if (x != begin() && isect(--x, y)) isect(x, y =
22             erase(y));
23         while ((y = x) != begin() && (--x)->p >= y->p)
24             isect(x, erase(y));
25     }
26     ll query(ll x) {
27         assert(!empty());
28         auto l = *lower_bound(x);
29         return l.m * x + l.b;
30     }
31 };

```

8.8 Polygon Area

```

1 T dbarea(vector<Pt>& e) {
2     ll res = 0;
3     REP(i, SZ(e)) res += e[i]^e[(i+1)%SZ(e)];
4     return abs(res);
5 }

```

8.9 Pick's Theorem

Consider a polygon which vertices are all lattice points.
 Let i = number of points inside the polygon.
 Let b = number of points on the boundary of the polygon.

Then we have the following formula:

$$Area = i + \frac{b}{2} - 1$$

8.10 Minimum Enclosing Circle

```

1 Pt circumcenter(Pt A, Pt B, Pt C) {
2     // a1(x-A.x) + b1(y-A.y) = c1
3     // a2(x-A.x) + b2(y-A.y) = c2
4     // solve using Cramer's rule
5     T a1 = B.x-A.x, b1 = B.y-A.y, c1 = dis2(A, B)/2.0;
6     T a2 = C.x-A.x, b2 = C.y-A.y, c2 = dis2(A, C)/2.0;
7     T D = Pt(a1, b1) ^ Pt(a2, b2);
8     T Dx = Pt(c1, b1) ^ Pt(c2, b2);
9     T Dy = Pt(a1, c1) ^ Pt(a2, c2);
10    if (D == 0) return Pt(-INF, -INF);
11    return A + Pt(Dx/D, Dy/D);
12 }
13 Pt center; T r2;
14 void minEncloseCircle() {
15     mt19937 gen(chrono::steady_clock::now().
16         time_since_epoch().count());
17     shuffle(ALL(E), gen);
18     center = E[0], r2 = 0;

```

```

18 for (int i = 0; i < n; i++) {
19     if (dis2(center, E[i]) <= r2) continue;
20     center = E[i], r2 = 0;
21     for (int j = 0; j < i; j++) {
22         if (dis2(center, E[j]) <= r2) continue;
23         center = (E[i] + E[j]) / 2.0;
24         r2 = dis2(center, E[i]);
25         for (int k = 0; k < j; k++) {
26             if (dis2(center, E[k]) <= r2) continue;
27             center = circumcenter(E[i], E[j], E[k]);
28             r2 = dis2(center, E[i]);
29         }
30     }
31 }
32 }

```

8.11 PolyUnion

```

1 struct PY{
2     int n; Pt pt[5]; double area;
3     Pt& operator[](const int x){ return pt[x]; }
4     void init(){ //n,pt[0~n-1] must be filled
5         area=pt[n-1]^pt[0];
6         for(int i=0;i<n-1;i++) area+=pt[i]^pt[i+1];
7         if((area/=2)<0)reverse(pt,pt+n),area=-area;
8     }
9 };
10 PY py[500]; pair<double,int> c[5000];
11 inline double segP(Pt &p,Pt &p1,Pt &p2){
12     if(dcmp(p1.x-p2.x)==0) return (p.y-p1.y)/(p2.y-p1.y);
13     return (p.x-p1.x)/(p2.x-p1.x);
14 }
15 double polyUnion(int n){ //py[0~n-1] must be filled
16     int i,j,ii,jj,ta,tb,r,d; double z,w,s,sum=0,tc,td;
17     for(i=0;i<n;i++) py[i][py[i].n]=py[i][0];
18     for(i=0;i<n;i++){
19         for(ii=0;ii<py[i].n;ii++){
20             r=0;
21             c[r++]=make_pair(0.0,0); c[r++]=make_pair(1.0,0);
22             for(j=0;j<n;j++){
23                 if(i==j) continue;
24                 for(jj=0;jj<py[j].n;jj++){
25                     ta=dcmp(tri(py[i][ii],py[i][ii+1],py[j][jj]))
26                     ;
27                     tb=dcmp(tri(py[i][ii],py[i][ii+1],py[j][jj
28                     +1]));
29                     if(ta==0 && tb==0){
30                         if((py[j][jj+1]-py[j][jj])*(py[i][ii+1]-py[
31                         i][ii])>0&&j<i){
32                             c[r++]=make_pair(segP(py[j][jj],py[i][ii
33                             ],py[i][ii+1]),1);
34                             c[r++]=make_pair(segP(py[j][jj+1],py[i][
35                             ii],py[i][ii+1]),-1);
36                         }
37                     }else if(ta>0 && tb<0){
38                         tc=tri(py[j][jj],py[j][jj+1],py[i][ii]);
39                         td=tri(py[j][jj],py[j][jj+1],py[i][ii+1]);
40                         c[r++]=make_pair(tc/(tc-td),1);
41                     }else if(ta<0 && tb>0){
42                         tc=tri(py[j][jj],py[j][jj+1],py[i][ii]);
43                         td=tri(py[j][jj],py[j][jj+1],py[i][ii+1]);
44                         c[r++]=make_pair(tc/(tc-td),-1);
45                     }
46                 }
47             }
48             sort(c,c+r);
49             z=min(max(c[0].first,0.0),1.0); d=c[0].second; s
50             =0;
51             for(j=1;j<r;j++){
52                 w=min(max(c[j].first,0.0),1.0);
53                 if(!d) s+=w-z;
54                 d+=c[j].second; z=w;
55             }
56             sum+=(py[i][ii]^py[i][ii+1])*s;
57         }
58     }
59     return sum/2;
60 }

```

8.12 Minkowski Sum

```
1 /* convex hull Minkowski Sum*/
```

```

2 #define INF 10000000000000LL
3 int pos( const Pt& tp ){
4     if( tp.Y == 0 ) return tp.X > 0 ? 0 : 1;
5     return tp.Y > 0 ? 0 : 1;
6 }
7 #define N 300030
8 Pt pt[ N ], qt[ N ], rt[ N ];
9 LL Lx,Rx;
10 int dn,un;
11 inline bool cmp( Pt a, Pt b ){
12     int pa=pos( a ),pb=pos( b );
13     if(pa==pb) return (a^b)>0;
14     return pa<pb;
15 }
16 int minkowskiSum(int n,int m){
17     int i,j,r,p,q,fi,fj;
18     for(i=1,p=0;i<n;i++){
19         if( pt[i].Y<pt[p].Y ||
20             (pt[i].Y==pt[p].Y && pt[i].X<pt[p].X) ) p=i; }
21     for(i=1,q=0;i<m;i++){
22         if( qt[i].Y<qt[q].Y ||
23             (qt[i].Y==qt[q].Y && qt[i].X<qt[q].X) ) q=i; }
24     rt[0]=pt[p]+qt[q];
25     r=1; i=p; j=q; fi=fj=0;
26     while(1){
27         if((fj&&j==q) ||
28             ( (!fi||i!=p) &&
29               cmp(pt[(p+1)%n]-pt[p],qt[(q+1)%n]-qt[q]) ) ){
30             rt[r]=rt[r-1]+pt[(p+1)%n]-pt[p];
31             p=(p+1)%n;
32             fi=1;
33         }else{
34             rt[r]=rt[r-1]+qt[(q+1)%n]-qt[q];
35             q=(q+1)%m;
36             fj=1;
37         }
38         if(r<=1 || ((rt[r]-rt[r-1])^(rt[r-1]-rt[r-2]))
39             !=0) r++;
40         else rt[r-1]=rt[r];
41         if(i==p && j==q) break;
42     }
43     return r-1;
44 }
45 void initInConvex(int n){
46     int i,p,q;
47     LL Ly,Ry;
48     Lx=INF; Rx=-INF;
49     for(i=0;i<n;i++){
50         if(pt[i].X<Lx) Lx=pt[i].X;
51         if(pt[i].X>Rx) Rx=pt[i].X;
52     }
53     Ly=Ry=INF;
54     for(i=0;i<n;i++){
55         if(pt[i].X==Lx && pt[i].Y<Ly){ Ly=pt[i].Y; p=i; }
56         if(pt[i].X==Rx && pt[i].Y>Ry){ Ry=pt[i].Y; q=i; }
57     }
58     for(dn=0,i=p;i!=(i+1)%n){ qt[dn++]=pt[i]; }
59     qt[dn]=pt[q]; Ly=Ry=-INF;
60     for(i=0;i<n;i++){
61         if(pt[i].X==Lx && pt[i].Y>Ly){ Ly=pt[i].Y; p=i; }
62         if(pt[i].X==Rx && pt[i].Y<Ry){ Ry=pt[i].Y; q=i; }
63     }
64     for(un=0,i=p;i!=(i+n-1)%n){ rt[un++]=pt[i]; }
65     rt[un]=pt[q];
66 }
67 inline int inConvex(Pt p){
68     int L,R,M;
69     if(p.X<Lx || p.X>Rx) return 0;
70     L=0;R=dn;
71     while(L<R-1){ M=(L+R)/2;
72         if(p.X<qt[M].X) R=M; else L=M; }
73     if(tri(qt[L],qt[R],p)<0) return 0;
74     L=0;R=un;
75     while(L<R-1){ M=(L+R)/2;
76         if(p.X<rt[M].X) R=M; else L=M; }
77     if(tri(rt[L],rt[R],p)>0) return 0;
78     return 1;
79 }

```



```

79 int main(){
80     int n,m,i;
81     Pt p;
82     scanf("%d",&n);
83     for(i=0;i<n;i++) scanf("%lld%lld",&pt[i].X,&pt[i].Y
84     );
85     scanf("%d",&m);
86     for(i=0;i<m;i++) scanf("%lld%lld",&qt[i].X,&qt[i].Y
87     );
88     n=minkowskiSum(n,m);
89     for(i=0;i<n;i++) pt[i]=rt[i];
90     scanf("%d",&m);
91     for(i=0;i<m;i++) scanf("%lld%lld",&qt[i].X,&qt[i].Y
92     );
93     n=minkowskiSum(n,m);
94     for(i=0;i<n;i++) pt[i]=rt[i];
95     initInConvex(n);
96     scanf("%d",&m);
97     for(i=0;i<m;i++){
98         scanf("%lld %lld",&p.X,&p.Y);
99         p.X*=3; p.Y*=3;
100         puts(inConvex(p)?"YES":"NO");
101     }
102 }

```

9 Number Theory

9.1 FFT

```

1 typedef complex<double> cp;
2
3 const double pi = acos(-1);
4 const int NN = 131072;
5
6 struct FastFourierTransform{
7     /*
8      Iterative Fast Fourier Transform
9      How this works? Look at this
10      0th recursion 0(000) 1(001) 2(010) 3(011)
11      4(100) 5(101) 6(110) 7(111)
12      1th recursion 0(000) 2(010) 4(100) 6(110)
13      | 1(011) 3(011) 5(101) 7(111)
14      2th recursion 0(000) 4(100) | 2(010) 6(110)
15      | 1(011) 5(101) | 3(011) 7(111)
16      3th recursion 0(000) | 4(100) | 2(010) | 6(110)
17      | 1(011) | 5(101) | 3(011) | 7(111)
18      All the bits are reversed => We can save the
19      reverse of the numbers in an array!
20      */
21     int n, rev[NN];
22     cp omega[NN], iomega[NN];
23     void init(int n_){
24         n = n_;
25         for(int i = 0; i < n; i++){
26             //Calculate the nth roots of unity
27             omega[i] = cp(cos(2*pi*i/n_), sin(2*pi*i/n_));
28             iomega[i] = conj(omega[i]);
29         }
30         int k = __lg(n_);
31         for(int i = 0; i < n; i++){
32             int t = 0;
33             for(int j = 0; j < k; j++){
34                 if(i & (1<<j)) t |= (1<<(k-j-1));
35             }
36             rev[i] = t;
37         }
38     }
39
40     void transform(vector<cp> &a, cp* xomega){
41         for(int i = 0; i < n; i++){
42             if(i < rev[i]) swap(a[i], a[rev[i]]);
43         }
44         for(int len = 2; len <= n; len <= 1){
45             int mid = len >> 1;
46             int r = n/len;
47             for(int j = 0; j < n; j += len)
48                 for(int i = 0; i < mid; i++){
49                     cp tmp = xomega[r*i] * a[j+mid+i];
50                     a[j+mid+i] = a[j+i] - tmp;
51                     a[j+i] = a[j+i] + tmp;
52                 }
53         }
54     }
55 }
56
57 void fft(vector<cp> &a){ transform(a, omega); }
58 void ifft(vector<cp> &a){ transform(a, iomega); for(
59     int i = 0; i < n; i++) a[i] /= n; }
60 } FFT;
61
62 const int MAXN = 262144;
63 // (must be 2^k)
64 // 262144, 524288, 1048576, 2097152, 4194304
65 // before any usage, run pre_fft() first
66 typedef long double ld;
67 typedef complex<ld> cplx; //real() ,imag()
68 const ld PI = acos(-1);
69 const cplx I(0, 1);
70 cplx omega[MAXN+1];
71 void pre_fft(){
72     for(int i=0; i<=MAXN; i++) {
73         omega[i] = exp(i * 2 * PI / MAXN * I);
74     }
75 }
76 // n must be 2^k
77 void fft(int n, cplx a[], bool inv=false){
78     int basic = MAXN / n;
79     int theta = basic;
80     for (int m = n; m >= 2; m >= 1) {
81         int mh = m >> 1;
82         for (int i = 0; i < mh; i++) {
83             cplx w = omega[inv ? MAXN - (i * theta %
84                 MAXN) : i * theta % MAXN];
85             for (int j = i; j < n; j += m) {
86                 int k = j + mh;
87                 cplx x = a[j] - a[k];
88                 a[j] += a[k];
89                 a[k] = w * x;
90             }
91             theta = (theta * 2) % MAXN;
92         }
93     }
94     int i = 0;
95     for (int j = 1; j < n - 1; j++) {
96         for (int k = n >> 1; k > (i ^ k); k >= 1);
97         if (j < i) swap(a[i], a[j]);
98     }
99     if(inv) {
100         for (i = 0; i < n; i++) a[i] /= n;
101     }
102 }
103 cplx arr[MAXN + 1];
104 inline void mul(int _n, long long a[], int _m, long long b
105     [], long long ans[]){
106     int n=1, sum = _n + _m - 1;
107     while(n < sum) n <= 1;
108     for(int i = 0; i < n; i++) {
109         double x = (i < _n ? a[i] : 0), y = (i < _m ? b[i]
110             : 0);
111         arr[i] = complex<double>(x + y, x - y);
112     }
113     fft(n, arr);
114     for(int i = 0; i < n; i++) arr[i]=arr[i]*arr[i];
115     fft(n, arr, true);
116     for(int i=0; i<sum; i++) ans[i]=(long long int)(arr[i
117         ].real() / 4 + 0.5);
118 }
119
120 long long a[MAXN];
121 long long b[MAXN];
122 long long ans[MAXN];
123 int a_length;
124 int b_length;

```

9.2 Pollard's rho

```

1 ll add(ll x, ll y, ll p) {
2     return (x + y) % p;
3 }
4 ll qMul(ll x, ll y, ll mod){

```



```

5  ll ret = x * y - (ll)((long double)x / mod * y) *
   mod;
6  return ret<0?ret+mod:ret;
7  }
8  ll f(ll x, ll mod) { return add(qMul(x,x,mod),1,mod); }
9  ll pollard_rho(ll n) {
10     if(!(n & 1)) return 2;
11     while(true) {
12         ll y = 2, x = rand() % (n - 1) + 1, res = 1;
13         for(int sz = 2; res == 1; sz *= 2) {
14             for(int i = 0; i < sz && res <= 1; i++) {
15                 x = f(x, n);
16                 res = __gcd(llabs(x - y), n);
17             }
18             y = x;
19         }
20         if (res != 0 && res != n) return res;
21     }
22 }
23 vector<ll> ret;
24 void fact(ll x) {
25     if(miller_rabin(x)) {
26         ret.push_back(x);
27         return;
28     }
29     ll f = pollard_rho(x);
30     fact(f); fact(x / f);
31 }

```

9.3 Miller Rabin

```

1  // n < 4,759,123,141      3 : 2, 7, 61
2  // n < 1,122,004,669,633  4 : 2, 13, 23, 1662803
3  // n < 3,474,749,660,383  6 : pimes <= 13
4  // n < 2^64              7 :
5  // 2, 325, 9375, 28178, 450775, 9780504, 1795265022
6  bool witness(ll a,ll n,ll u,int t){
7      if(!(a%n)) return 0;
8      ll x=mypow(a,u,n);
9      for(int i=0;i<t;i++) {
10         ll nx=mul(x,x,n);
11         if(nx==1&&x!=1&&x!=n-1) return 1;
12         x=nx;
13     }
14     return x!=1;
15 }
16 bool miller_rabin(ll n,int s=100) {
17     // iterate s times of witness on n
18     // return 1 if prime, 0 otherwise
19     if(n<2) return 0;
20     if(!(n&1)) return n == 2;
21     ll u=n-1; int t=0;
22     while(!(u&1)) u>>=1, t++;
23     while(s--){
24         ll a=randll()%n-1+1;
25         if(witness(a,n,u,t)) return 0;
26     }
27     return 1;
28 }

```

9.4 Fast Power

Note: $a^n \equiv a^{(n \bmod (p-1))} \pmod{p}$

9.5 Extend GCD

```

1  ll GCD;
2  pll extgcd(ll a, ll b) {
3      if (b == 0) {
4          GCD = a;
5          return pll{1, 0};
6      }
7      pll ans = extgcd(b, a % b);
8      return pll{ans.S, ans.F - a/b * ans.S};
9  }
10 pll bezout(ll a, ll b, ll c) {
11     bool negx = (a < 0), negy = (b < 0);
12     pll ans = extgcd(abs(a), abs(b));
13     if (c % GCD != 0) return pll{-LLINF, -LLINF};
14     return pll{ans.F * c/GCD * (negx ? -1 : 1),

```

```

15     ans.S * c/GCD * (negy ? -1 : 1)};
16 }
17 ll inv(ll a, ll p) {
18     if (p == 1) return -1;
19     pll ans = bezout(a % p, -p, 1);
20     if (ans == pll{-LLINF, -LLINF}) return -1;
21     return (ans.F % p + p) % p;
22 }

```

9.6 Mu + Phi

```

1  const int maxn = 1e6 + 5;
2  ll f[maxn];
3  vector<int> lpf, prime;
4  void build() {
5      lpf.clear(); lpf.resize(maxn, 1);
6      prime.clear();
7      f[1] = ...; /* mu[1] = 1, phi[1] = 1 */
8      for (int i = 2; i < maxn; i++) {
9          if (lpf[i] == 1) {
10             lpf[i] = i; prime.emplace_back(i);
11             f[i] = ...; /* mu[i] = 1, phi[i] = i-1 */
12         }
13         for (auto& j : prime) {
14             if (i*j >= maxn) break;
15             lpf[i*j] = j;
16             if (i % j == 0) f[i*j] = ...; /* 0, phi[i]*j */
17             else f[i*j] = ...; /* -mu[i], phi[i]*phi[j] */
18             if (j >= lpf[i]) break;
19         }
20     }
21 }

```

9.7 Other Formulas

- Inversion:**
 $aa^{-1} \equiv 1 \pmod{m}$. a^{-1} exists iff $\gcd(a, m) = 1$.
- Linear inversion:**
 $a^{-1} \equiv (m - \lfloor \frac{m}{a} \rfloor) \times (m \bmod a)^{-1} \pmod{m}$
- Fermat's little theorem:**
 $a^p \equiv a \pmod{p}$ if p is prime.
- Euler function:**
 $\phi(n) = n \prod_{p|n} \frac{p-1}{p}$
- Euler theorem:**
 $a^{\phi(n)} \equiv 1 \pmod{n}$ if $\gcd(a, n) = 1$.
- Extended Euclidean algorithm:**
 $ax + by = \gcd(a, b) = \gcd(b, a \bmod b) = \gcd(b, a - \lfloor \frac{a}{b} \rfloor b) = bx_1 + (a - \lfloor \frac{a}{b} \rfloor b)y_1 = ay_1 + b(x_1 - \lfloor \frac{a}{b} \rfloor y_1)$
- Divisor function:**
 $\sigma_x(n) = \sum_{d|n} d^x$. $n = \prod_{i=1}^r p_i^{a_i}$.
 $\sigma_x(n) = \prod_{i=1}^r \frac{p_i^{(a_i+1)x} - 1}{p_i^x - 1}$ if $x \neq 0$. $\sigma_0(n) = \prod_{i=1}^r (a_i + 1)$.
- Chinese remainder theorem (Coprime Moduli):**
 $x \equiv a_i \pmod{m_i}$.
 $M = \prod m_i$. $M_i = M/m_i$. $t_i = M_i^{-1}$.
 $x = kM + \sum a_i t_i M_i$, $k \in \mathbb{Z}$.
- Chinese remainder theorem:**
 $x \equiv a_1 \pmod{m_1}, x \equiv a_2 \pmod{m_2} \Rightarrow x = m_1 p + a_1 = m_2 q + a_2 \Rightarrow m_1 p - m_2 q = a_2 - a_1$
Solve for (p, q) using ExtGCD.
 $x \equiv m_1 p + a_1 \equiv m_2 q + a_2 \pmod{\text{lcm}(m_1, m_2)}$
- Avoiding Overflow:** $ca \bmod cb = c(a \bmod b)$
- Dirichlet Convolution:** $(f * g)(n) = \sum_{d|n} f(n)g(n/d)$
- Important Multiplicative Functions + Properties:**
1. $\epsilon(n) = [n = 1]$

2. $1(n) = 1$
3. $id(n) = n$
4. $\mu(n) = 0$ if n has squared prime factor
5. $\mu(n) = (-1)^k$ if $n = p_1 p_2 \cdots p_k$
6. $\epsilon = \mu * 1$
7. $\phi = \mu * id$
8. $[n = 1] = \sum_{d|n} \mu(d)$
9. $[gcd = 1] = \sum_{d|gcd} \mu(d)$

• Möbius inversion: $f = g * 1 \Leftrightarrow g = f * \mu$

9.8 Polynomial

```

1 const int maxk = 20;
2 const int maxn = 1<<maxk;
3 const ll LINF = 1e18;
4
5 /* P = r*2^k + 1
6 P          r    k    g
7 998244353  119  23    3
8 1004535809 479  21    3
9
10 P          r    k    g
11 3          1    1    2
12 5          1    2    2
13 17         1    4    3
14 97         3    5    5
15 193        3    6    5
16 257        1    8    3
17 7681       15    9   17
18 12289      3   12   11
19 40961      5   13    3
20 65537      1   16    3
21 786433     3   18   10
22 5767169    11  19    3
23 7340033    7   20    3
24 23068673   11  21    3
25 104857601  25  22    3
26 167772161  5   25    3
27 469762049  7   26    3
28 1004535809 479  21    3
29 2013265921 15  27   31
30 2281701377 17  27    3
31 3221225473 3   30    5
32 75161927681 35  31    3
33 77309411329 9   33    7
34 206158430209 3   36   22
35 2061584302081 15  37    7
36 2748779069441 5   39    3
37 6597069766657 3   41    5
38 39582418599937 9   42    5
39 79164837199873 9   43    5
40 263882790666241 15  44    7
41 1231453023109121 35  45    3
42 1337006139375617 19  46    3
43 3799912185593857 27  47    5
44 4222124650659841 15  48   19
45 7881299347898369 7   50    6
46 31525197391593473 7   52    3
47 180143985094819841 5   55    6
48 1945555039024054273 27  56    5
49 4179340454199820289 29  57    3
50 9097271247288401921 505  54    6 */
51
52 const int g = 3;
53 const ll MOD = 998244353;
54
55 ll pw(ll a, ll n) { /* fast pow */ }
56
57 #define siz(x) (int)x.size()
58
59 template<typename T>
60 vector<T>& operator+=(vector<T>& a, const vector<T>& b)
61 {
62     if (siz(a) < siz(b)) a.resize(siz(b));
63     for (int i = 0; i < min(siz(a), siz(b)); i++) {
64         a[i] += b[i];
65         a[i] -= a[i] >= MOD ? MOD : 0;
66     }
67 }

```

```

66     return a;
67 }
68
69 template<typename T>
70 vector<T>& operator--(vector<T>& a, const vector<T>& b)
71 {
72     if (siz(a) < siz(b)) a.resize(siz(b));
73     for (int i = 0; i < min(siz(a), siz(b)); i++) {
74         a[i] -= b[i];
75         a[i] += a[i] < 0 ? MOD : 0;
76     }
77     return a;
78 }
79
80 template<typename T>
81 vector<T> operator-(const vector<T>& a) {
82     vector<T> ret(siz(a));
83     for (int i = 0; i < siz(a); i++) {
84         ret[i] = -a[i] < 0 ? -a[i] + MOD : -a[i];
85     }
86     return ret;
87 }
88
89 vector<ll> X, iX;
90 vector<int> rev;
91
92 void init_ntt() {
93     X.clear(); X.resize(maxn, 1); // x1 = g^((p-1)/n)
94     iX.clear(); iX.resize(maxn, 1);
95
96     ll u = pw(g, (MOD-1)/maxn);
97     ll iu = pw(u, MOD-2);
98
99     for (int i = 1; i < maxn; i++) {
100         X[i] = X[i-1] * u;
101         iX[i] = iX[i-1] * iu;
102         if (X[i] >= MOD) X[i] %= MOD;
103         if (iX[i] >= MOD) iX[i] %= MOD;
104     }
105
106     rev.clear(); rev.resize(maxn, 0);
107     for (int i = 1, hb = -1; i < maxn; i++) {
108         if (!(i & (i-1))) hb++;
109         rev[i] = rev[i ^ (1<<hb)] | (1<<(maxk-hb-1));
110     }
111 }
112
113 template<typename T>
114 void NTT(vector<T>& a, bool inv=false) {
115
116     int _n = (int)a.size();
117     int k = __lg(_n) + ((1<<__lg(_n)) != _n);
118     int n = 1<<k;
119     a.resize(n, 0);
120
121     short shift = maxk-k;
122     for (int i = 0; i < n; i++)
123         if (i > (rev[i]>>shift))
124             swap(a[i], a[rev[i]>>shift]);
125
126     for (int len = 2, half = 1, div = maxn>>1; len <= n; len<=1, half<=1, div>=1) {
127         for (int i = 0; i < n; i += len) {
128             for (int j = 0; j < half; j++) {
129                 T u = a[i+j];
130                 T v = a[i+j+half] * (inv ? iX[j*div] : X[j*div]) % MOD;
131                 a[i+j] = (u+v >= MOD ? u+v-MOD : u+v);
132                 a[i+j+half] = (u-v < 0 ? u-v+MOD : u-v);
133             }
134         }
135     }
136
137     if (inv) {
138         T dn = pw(n, MOD-2);
139         for (auto& x : a) {
140             x *= dn;
141             if (x >= MOD) x %= MOD;
142         }
143     }
144 }
145
146 template<typename T>
147 inline void resize(vector<T>& a) {
148     int cnt = (int)a.size();
149     for (; cnt > 0; cnt--) if (a[cnt-1]) break;
150 }

```

```

144     a.resize(max(cnt, 1));
145 }
146
147 template<typename T>
148 vector<T>& operator*=(vector<T>& a, vector<T> b) {
149     int na = (int)a.size();
150     int nb = (int)b.size();
151     a.resize(na + nb - 1, 0);
152     b.resize(na + nb - 1, 0);
153
154     NTT(a); NTT(b);
155     for (int i = 0; i < (int)a.size(); i++) {
156         a[i] *= b[i];
157         if (a[i] >= MOD) a[i] %= MOD;
158     }
159     NTT(a, true);
160
161     resize(a);
162     return a;
163 }
164
165 template<typename T>
166 void inv(vector<T>& ia, int N) {
167     vector<T> _a(move(ia));
168     ia.resize(1, pw(_a[0], MOD-2));
169     vector<T> a(1, _a[0] + (-_a[0] < 0 ? MOD : 0));
170
171     for (int n = 1; n < N; n<=1) {
172         // n -> 2*n
173         // ia' = ia(2-a*ia);
174
175         for (int i = n; i < min(siz(_a), (n<<1)); i++)
176             a.emplace_back(-_a[i] + (-_a[i] < 0 ? MOD : 0));
177
178         vector<T> tmp = ia;
179         ia *= a;
180         ia.resize(n<<1);
181         ia[0] = ia[0] + 2 >= MOD ? ia[0] + 2 - MOD : ia[0] + 2;
182         ia *= tmp;
183         ia.resize(n<<1);
184     }
185     ia.resize(N);
186 }
187
188 template<typename T>
189 void mod(vector<T>& a, vector<T>& b) {
190     int n = (int)a.size()-1, m = (int)b.size()-1;
191     if (n < m) return;
192
193     vector<T> ra = a, rb = b;
194     reverse(ra.begin(), ra.end()); ra.resize(min(n+1, n-m+1));
195     reverse(rb.begin(), rb.end()); rb.resize(min(m+1, n-m+1));
196
197     inv(rb, n-m+1);
198
199     vector<T> q = move(ra);
200     q *= rb;
201     q.resize(n-m+1);
202     reverse(q.begin(), q.end());
203
204     q *= b;
205     a -= q;
206     resize(a);
207 }
208
209 /* Kitamasa Method (Fast Linear Recurrence):
210 Find a[K] (Given a[j] = c[0]a[j-N] + ... + c[N-1]a[j-1])
211 Let B(x) = x^N - c[N-1]x^(N-1) - ... - c[1]x^1 - c[0]
212 Let R(x) = x^K mod B(x) (get x^K using fast pow and use poly mod to get R(x))
213 Let r[i] = the coefficient of x^i in R(x)
214 => a[K] = a[0]r[0] + a[1]r[1] + ... + a[N-1]r[N-1] */

```

10 Linear Algebra

10.1 Gaussian-Jordan Elimination

```

1 int n; vector<vector<ll>> > v;
2 void gauss(vector<vector<ll>>& v) {
3     int r = 0;
4     for (int i = 0; i < n; i++) {
5         bool ok = false;
6         for (int j = r; j < n; j++) {
7             if (v[j][i] == 0) continue;
8             swap(v[j], v[r]);
9             ok = true; break;
10        }
11        if (!ok) continue;
12        ll div = inv(v[r][i]);
13        for (int j = 0; j < n+1; j++) {
14            v[r][j] *= div;
15            if (v[r][j] >= MOD) v[r][j] %= MOD;
16        }
17        for (int j = 0; j < n; j++) {
18            if (j == r) continue;
19            ll t = v[j][i];
20            for (int k = 0; k < n+1; k++) {
21                v[j][k] -= v[r][k] * t % MOD;
22                if (v[j][k] < 0) v[j][k] += MOD;
23            }
24            r++;
25        }

```

10.2 Determinant

1. Use GJ Elimination, if there's any row consists of only 0, then $\det = 0$, otherwise $\det = \text{product of diagonal elements}$.
2. Properties of \det :
 - Transpose: Unchanged
 - Row Operation 1 - Swap 2 rows: $-\det$
 - Row Operation 2 - $k\vec{r}_i$: $k \times \det$
 - Row Operation 3 - $k\vec{r}_i$ add to \vec{r}_j : Unchanged

11 Flow / Matching

11.1 Dinic

```

1 struct Dinic
2 {
3     int n,s,t,level[N],iter[N];
4     struct edge{int to,cap,rev;};
5     vector<edge>path[N];
6     void init(int _n,int _s,int _t)
7     {
8         n=_n,s=_s,t=_t;
9         FOR(i,0,n+1)path[i].clear();
10    }
11    void add(int a,int b,int c)
12    {
13        edge now;
14        now.to=b,now.cap=c,now.rev=sz(path[b]);
15        path[a].pb(now);
16        now.to=a,now.cap=0,now.rev=sz(path[a])-1;
17        path[b].pb(now);
18    }
19    void bfs()
20    {
21        memset(level,-1,sizeof(level));
22        level[s]=0;
23        queue<int>q;q.push(s);
24        while(q.size())
25        {
26            int now=q.front();q.pop();
27            for(edge e:path[now])
28            {
29                if(e.cap>0&&level[e.to]==-1)

```

```

30         {
31             level[e.to]=level[now]+1;
32             q.push(e.to);
33         }
34     }
35 }
36
37 int dfs(int now,int flow)
38 {
39     if(now==t)return flow;
40     for(int &i=iter[now];i<sz(path[now]);i++)
41     {
42         edge &e=path[now][i];
43         if(e.cap>0&&level[e.to]==level[now]+1)
44         {
45             int res=dfs(e.to,min(flow,e.cap));
46             if(res>0)
47             {
48                 e.cap-=res;
49                 path[e.to][e.rev].cap+=res;
50                 return res;
51             }
52         }
53     }
54     return 0;
55 }
56 int dinic()
57 {
58     int res=0;
59     while(true)
60     {
61         bfs();
62         if(level[t]==-1)break;
63         memset(iter,0,sizeof(iter));
64         int now=0;
65         while((now=dfs(s,INF))>0)res+=now;
66     }
67     return res;
68 }
69 };

```

11.2 ISAP

```

1 #define SZ(c) ((int)(c).size())
2 struct Maxflow{
3     static const int MAXV=50010;
4     static const int INF =1000000;
5     struct Edge{
6         int v,c,r;
7         Edge(int _v,int _c,int _r):v(_v),c(_c),r(_r){}
8     };
9     int s,t; vector<Edge> G[MAXV];
10    int iter[MAXV],d[MAXV],gap[MAXV],tot;
11    void init(int n,int _s,int _t){
12        tot=n,s=_s,t=_t;
13        for(int i=0;i<=tot;i++){
14            G[i].clear(); iter[i]=d[i]=gap[i]=0;
15        }
16    }
17    void addEdge(int u,int v,int c){
18        G[u].push_back(Edge(v,c,SZ(G[v])));
19        G[v].push_back(Edge(u,0,SZ(G[u])-1));
20    }
21    int DFS(int p,int flow){
22        if(p==t) return flow;
23        for(int &i=iter[p];i<SZ(G[p]);i++){
24            Edge &e=G[p][i];
25            if(e.c>0&&d[p]==d[e.v]+1){
26                int f=DFS(e.v,min(flow,e.c));
27                if(f){ e.c-=f; G[e.v][e.r].c+=f; return f; }
28            }
29        }
30        if(--gap[d[p]]==0) d[s]=tot;
31        else{ d[p]++; iter[p]=0; ++gap[d[p]]; }
32        return 0;
33    }
34    int flow(){
35        int res=0;
36        for(res=0,gap[0]=tot;d[s]<tot;res+=DFS(s,INF));
37        return res;
38    } // reset: set iter,d,gap to 0

```

```
39 } flow;
```

11.3 MCMF

```

1 struct MCMF
2 {
3     int n,s,t,par[N+5],p_i[N+5],dis[N+5],vis[N+5];
4     struct edge{int to,cap,rev,cost;};
5     vector<edge>path[N];
6     void init(int _n,int _s,int _t)
7     {
8         n=_n,s=_s,t=_t;
9         FOR(i,0,2*n+5)par[i]=p_i[i]=vis[i]=0;
10    }
11    void add(int a,int b,int c,int d)
12    {
13        path[a].pb({b,c,sz(path[b]),d});
14        path[b].pb({a,0,sz(path[a])-1,-d});
15    }
16    void spfa()
17    {
18        FOR(i,0,n*2+5)dis[i]=INF,vis[i]=0;
19        dis[s]=0;
20        queue<int>q;q.push(s);
21        while(!q.empty())
22        {
23            int now=q.front();
24            q.pop();
25            vis[now]=0;
26            for(int i=0;i<sz(path[now]);i++)
27            {
28                edge e=path[now][i];
29                if(e.cap>0&&dis[e.to]>dis[now]+e.cost)
30                {
31                    dis[e.to]=dis[now]+e.cost;
32                    par[e.to]=now;
33                    p_i[e.to]=i;
34                    if(vis[e.to]==0)
35                    {
36                        vis[e.to]=1;
37                        q.push(e.to);
38                    }
39                }
40            }
41        }
42    }
43    pii flow()
44    {
45        int flow=0,cost=0;
46        while(true)
47        {
48            spfa();
49            if(dis[t]==INF)break;
50            int mn=INF;
51            for(int i=t;i!=s;i=par[i])
52                mn=min(mn,path[par[i]][p_i[i]].cap);
53            flow+=mn;cost+=dis[t]*mn;
54            for(int i=t;i!=s;i=par[i])
55            {
56                edge &now=path[par[i]][p_i[i]];
57                now.cap-=mn;
58                path[i][now.rev].cap+=mn;
59            }
60        }
61        return mp(flow,cost);
62    }
63 };

```

11.4 Hopcroft-Karp

```

1 struct HopcroftKarp {
2     // id: X = [1, nx], Y = [nx+1, nx+ny]
3     int n, nx, ny, m, MXCNT;
4     vector<vector<int>> > g;
5     vector<int> mx, my, dis, vis;
6     void init(int nnx, int nny, int mm) {
7         nx = nnx, ny = nny, m = mm;
8         n = nx + ny + 1;
9         g.clear(); g.resize(n);
10    }

```

```

11 void add(int x, int y) {
12     g[x].emplace_back(y);
13     g[y].emplace_back(x);
14 }
15 bool dfs(int x) {
16     vis[x] = true;
17     Each(y, g[x]) {
18         int px = my[y];
19         if (px == -1 ||
20             (dis[px] == dis[x]+1 &&
21              !vis[px] && dfs(px))) {
22             mx[x] = y;
23             my[y] = x;
24             return true;
25         }
26     }
27     return false;
28 }
29 void get() {
30     mx.clear(); mx.resize(n, -1);
31     my.clear(); my.resize(n, -1);
32
33     while (true) {
34         queue<int> q;
35         dis.clear(); dis.resize(n, -1);
36         for (int x = 1; x <= nx; x++){
37             if (mx[x] == -1) {
38                 dis[x] = 0;
39                 q.push(x);
40             }
41         }
42         while (!q.empty()) {
43             int x = q.front(); q.pop();
44             Each(y, g[x]) {
45                 if (my[y] != -1 && dis[my[y]] ==
46                     -1) {
47                     dis[my[y]] = dis[x] + 1;
48                     q.push(my[y]);
49                 }
50             }
51         }
52         bool brk = true;
53         vis.clear(); vis.resize(n, 0);
54         for (int x = 1; x <= nx; x++)
55             if (mx[x] == -1 && dfs(x))
56                 brk = false;
57
58         if (brk) break;
59     }
60     MXCNT = 0;
61     for (int x = 1; x <= nx; x++) if (mx[x] != -1)
62         MXCNT++;
63 } hk;

```

11.5 Cover / Independent Set

1 V(E) Cover: choose some V(E) to cover all E(V)
2 V(E) Independ: set of V(E) not adj to each other

3
4 M = Max Matching
5 Cv = Min V Cover
6 Ce = Min E Cover
7 Iv = Max V Ind
8 Ie = Max E Ind (equiv to M)

9
10 M = Cv (Konig Theorem)
11 Iv = V \ Cv
12 Ce = V - M

13
14 Construct Cv:
15 1. Run Dinic
16 2. Find s-t min cut
17 3. Cv = {X in T} + {Y in S}

11.6 KM

```

1 struct KM
2 {

```

```

3 int n,mx[1005],my[1005],pa[1005];
4 int g[1005][1005],lx[1005],ly[1005],sy[1005];
5 bool vx[1005],vy[1005];
6 void init(int _n)
7 {
8     n=_n;
9     FOR(i,1,n+1)fill(g[i],g[i]+1+n,0);
10 }
11 void add(int a,int b,int c){g[a][b]=c;}
12 void augment(int y)
13 {
14     for(int x,z;y;y=z)
15         x=pa[y],z=mx[x],my[y]=x,mx[x]=y;
16 }
17 void bfs(int st)
18 {
19     FOR(i,1,n+1)sy[i]=INF,vx[i]=vy[i]=0;
20     queue<int>q;q.push(st);
21     for(;;)
22     {
23         while(!q.empty())
24         {
25             int x=q.front();q.pop();
26             vx[x]=1;
27             FOR(y,1,n+1)if(!vy[y])
28             {
29                 int t=lx[x]+ly[y]-g[x][y];
30                 if(t==0)
31                 {
32                     pa[y]=x;
33                     if(!my[y]){augment(y);return;}
34                     vy[y]=1, q.push(my[y]);
35                 }
36                 else if(sy[y]>t)pa[y]=x,sy[y]=t;
37             }
38         }
39         int cut=INF;
40         FOR(y,1,n+1)if(!vy[y]&&cut>sy[y])cut=sy[y];
41         FOR(j,1,n+1)
42         {
43             if(vx[j])lx[j]-=cut;
44             if(vy[j])ly[j]+=cut;
45             else sy[j]-=cut;
46         }
47         FOR(y,1,n+1)
48         {
49             if(!vy[y]&&sy[y]==0)
50             {
51                 if(!my[y]){augment(y);return;}
52                 vy[y]=1;q.push(my[y]);
53             }
54         }
55     }
56 }
57 int solve()
58 {
59     fill(mx,mx+n+1,0);fill(my,my+n+1,0);
60     fill(ly,ly+n+1,0);fill(lx,lx+n+1,0);
61     FOR(x,1,n+1)FOR(y,1,n+1)
62         lx[x]=max(lx[x],g[x][y]);
63     FOR(x,1,n+1)bfs(x);
64     int ans=0;
65     FOR(y,1,n+1)ans+=g[my[y]][y];
66     return ans;
67 }
68 };

```

12 Combinatorics

12.1 Catalan Number

$$C_0 = 1, C_n = \sum_{i=0}^{n-1} C_i C_{n-1-i}, C_n = C_n^{2n} - C_{n-1}^{2n}$$

0	1	1	2	5
4	14	42	132	429
8	1430	4862	16796	58786
12	208012	742900	2674440	9694845

12.2 Burnside's Lemma

Let X be the original set.

Let G be the group of operations acting on X .

Let X^g be the set of x not affected by g .

Let X/G be the set of orbits.

Then the following equation holds:

$$|X/G| = \frac{1}{|G|} \sum_{g \in G} |X^g|$$

13 Special Numbers

13.1 Fibonacci Series

1	1	1	2	3
5	5	8	13	21
9	34	55	89	144
13	233	377	610	987
17	1597	2584	4181	6765
21	10946	17711	28657	46368
25	75025	121393	196418	317811
29	514229	832040	1346269	2178309
33	3524578	5702887	9227465	14930352

$$f(45) \approx 10^9, f(88) \approx 10^{18}$$

13.2 Prime Numbers

- First 50 prime numbers:

1	2	3	5	7	11
6	13	17	19	23	29
11	31	37	41	43	47
16	53	59	61	67	71
21	73	79	83	89	97
26	101	103	107	109	113
31	127	131	137	139	149
36	151	157	163	167	173
41	179	181	191	193	197
46	199	211	223	227	229

- Very large prime numbers:

1000001333 1000500889 2500001909
2000000659 900004151 850001359

- $\pi(n) \equiv$ Number of primes $\leq n \approx n/((\ln n) - 1)$

$$\pi(100) = 25, \pi(200) = 46$$

$$\pi(500) = 95, \pi(1000) = 168$$

$$\pi(2000) = 303, \pi(4000) = 550$$

$$\pi(10^4) = 1229, \pi(10^5) = 9592$$

$$\pi(10^6) = 78498, \pi(10^7) = 664579$$





