## **Backpropgation is Just Steepest Descent with Automatic Differentiation**

https://idontgetoutmuch.wordpress.com/2013/10/13/backpropogation-is-just-steepest-descent-with-automatic-differentiation-2/

How to calculate partial derivative

$$rac{\partial E(...,w,...)}{\partial w}pprox rac{(...,w+arepsilon,...)-E(...,w,...)}{arepsilon}$$

But this will get numerical errors when the  $\varepsilon$  gets smaller

Backpropgation comes to rescue

$$(g \circ f)'(a) = g'(f(a)).f'(a)$$

in alternative notation

$$rac{\mathrm{d}(g\circ f)}{\mathrm{d}x}(a) = rac{\mathrm{d}g}{\mathrm{d}y}(f(a))rac{\mathrm{d}f}{\mathrm{d}x}(a)$$

where y = f(x). or

$$\frac{\mathrm{d}g}{\mathrm{d}x} = \frac{\mathrm{d}g}{\mathrm{d}u}\frac{\mathrm{d}y}{\mathrm{d}x}$$

example:

$$rac{\mathrm{d}}{\mathrm{d}x}\sqrt{3\sin(x)} = rac{\mathrm{d}}{\mathrm{d}x}(3\sin(x))\cdotrac{\mathrm{d}}{\mathrm{d}y}\sqrt{y} = 3\cos(x)\cdotrac{1}{2\sqrt{y}} = rac{3\cos(x)}{2\sqrt{3\sin(x)}}$$

Neural Network

$$egin{aligned} a_i^{(1)} &= \sum_{j=0}^{N^{(1)}} w_{ij}^{(1)} x_j \ z_i^{(1)} &= anh(a_i^{(1)}) \ a_i^{(2)} &= \sum_{j=0}^{N^{(2)}} w_{ij}^{(2)} z_j^{(1)} \ \dots &= \dots \ a_i^{(L-1)} &= \sum_{j=0}^{N^{(L-1)}} w_{ij}^{(L-1)} z_j^{(L-2)} \ z_j^{(L-1)} &= anh(a_j^{(L-1)}) \ \hat{y}_i &= \sum_{j=0}^{N^{(L)}} w_{ij}^{(L)} z_j^{(L-1)} \end{aligned}$$

cost function

gradient decent

chain rule

$$E(oldsymbol{w};oldsymbol{x},oldsymbol{y}) = rac{1}{2} \|(\hat{oldsymbol{y}}-oldsymbol{y})\|^2$$

$$\Delta w_{ij} = rac{\partial E}{\partial w_{ij}}$$

$$\Delta w_{ij} = rac{\partial E}{\partial w_{ij}} = rac{\partial E}{\partial a_i} rac{\partial a_i}{\partial w_{ij}}$$

since

$$a_j^{(l)} = \sum_{i=0}^N w_{ij}^{(l)} z_i^{(l-1)}$$

thus

$$rac{\partial a_i^{(l)}}{\partial w_{ij}^{(l)}} = rac{\sum_{k=0}^M w_{kj}^{(l)} z_k^{(l-1)}}{\partial w_{ij}^{(l)}} = z_i^{(l-1)}$$

define

$$\delta_j^{(l)} \equiv rac{\partial E}{\partial a_j^{(l)}}$$

thus

$$\Delta w_{ij}^{(l)} = rac{\partial E}{\partial w_{ij}^{(l)}} = \delta_j^{(l)} z_i^{(l-1)}$$

output layer

$$\delta_j = rac{\partial E}{\partial a_j} = rac{\partial E}{\partial y_j} = rac{\partial}{\partial y_j}igg(rac{1}{2}\sum_{i=0}^M(\hat{y}_i-y_i)^2igg) = \hat{y}_j-y_j$$

a hidden layer using the chain rule

$$\delta_j^{(l-1)} = rac{\partial E}{\partial a_j^{(l-1)}} = \sum_k rac{\partial E}{\partial a_k^{(l)}} rac{\partial a_k^{(l)}}{\partial a_j^{(l-1)}}$$

now

$$a_k^{(l)} = \sum_i w_{ki}^{(l)} z_i^{(l-1)} = \sum_i w_{ki}^{(l)} f(a_i^{(l-1)})$$

thus

$$rac{\partial a_k^{(l)}}{\partial a_j^{(l-1)}} = rac{\sum_i w_{ki}^{(l)} f(a_i^{(l-1)})}{\partial a_j^{(l-1)}} = w_{kj}^{(l)} \, f'(a_j^{(l-1)})$$

then

$$\delta_j^{(l-1)} = \sum_k rac{\partial E}{\partial a_k^{(l)}} rac{\partial a_k^{(l)}}{\partial a_j^{(l-1)}} = \sum_k \delta_k^{(l)} w_{kj}^{(l)} \, f'(a_j^{(l-1)}) = f'(a_j^{(l-1)}) \sum_k \delta_k^{(l)} w_{kj}^{(l)}$$

## Summary:

- 1. forward calculation for  $a_j$  and  $z_j$  for each layer
- 2. evaluate output layer  $\delta_j^{(L)}$  using  $\delta_j = \hat{y}_j y_j$
- 3. backward evaluate  $\delta_j$  in each layer using  $\delta_j^{(l-1)} = f'(a_j^{(l-1)}) \sum_k \delta_k^{(l)} w_{kj}^{(l)}$
- 4. use  $\partial E/\partial w_{ij}^{(l)}=\delta_j^{(l)}z_i^{(l-1)}$  to calculate  $\Delta w_{ij}^{(l)}$  in each layer
- 5. for activation function  $\tanh$ ,  $f'(a) = \tanh'(a) = 1 \tanh^2(a)$
- 6. thus  $w' = w \gamma \nabla E(w)$