Plant Leaf Meshes from RGB-D Sensors

Anonymous 3DV submission

Paper ID ****

4. Mesh Formulation

5. Results

6. Conclusion

References

[1] Z. Zhang. A flexible new technique for camera calibration. *Pattern Analysis and Machine Intelligence, IEEE Transactions on*, 22(11):1330–1334, Nov 2000. 1

Figure 1. Example caption of a leaf image with 3D projected points.

Abstract

1. Introduction

Introduction here including application description

2. Related Work

3. Data Modeling

An example citation [1].