## **Plant Leaf Meshes from RGB-D Sensors**

Daniel Morris

Saif Imran

Vincent Zickefoose

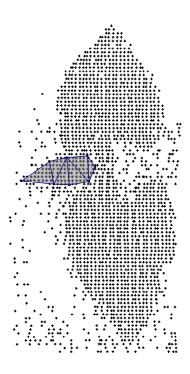
Jin Chen

David Kramer

Department of Electrical and Computer Engineering

Department of Energy Plant Research Laboratory

Michigan State University, East Lansing, MI 48824, USA



- 4. Mesh Formulation
- 5. Results
- 6. Conclusion

## References

[1] Z. Zhang. A flexible new technique for camera calibration. *Pattern Analysis and Machine Intelligence, IEEE Transactions on*, 22(11):1330–1334, Nov 2000. 1

Figure 1. Example caption of a leaf image with 3D projected points.

## **Abstract**

## 1. Introduction

Introduction here including application description

- 2. Related Work
- 3. Data Modeling

An example citation [1].