## Math 221: LINEAR ALGEBRA

Chapter 5. Vector Space  $\mathbb{R}^n$  §5-3. Orthogonality

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The Dot Product

The Cauchy Inequality

Orthogonality

Orthogonality and Independence

## Linear Algebra with Applications Lecture Notes

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The Dot Product

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## The Dot Product

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## Dot Product

#### Definitions

Let 
$$\vec{\mathbf{x}} = \begin{bmatrix} \mathbf{x}_1 \\ \mathbf{x}_2 \\ \vdots \\ \mathbf{x}_n \end{bmatrix}$$
 and  $\vec{\mathbf{y}} = \begin{bmatrix} \mathbf{y}_1 \\ \mathbf{y}_2 \\ \vdots \\ \mathbf{y}_n \end{bmatrix}$  be vectors in  $\mathbb{R}^n$ .

1. The dot product of  $\vec{x}$  and  $\vec{y}$  is

$$\vec{x} \cdot \vec{y} = x_1 y_1 + x_2 y_2 + \cdots x_n y_n = \vec{x}^T \vec{y}.$$

2. The length or norm of  $\vec{x}$ , denoted  $||\vec{x}||$  is

$$||\vec{x}|| = \sqrt{x_1^2 + x_2^2 \cdots + x_n^2} = \sqrt{\vec{x} \cdot \vec{x}} = \sqrt{\vec{x}^T \vec{x}}.$$

3.  $\vec{x}$  is called a unit vector if  $||\vec{x}|| = 1$ .

Theorem (Properties of length and the dot product)

Let  $\vec{x}, \vec{y}, \vec{z} \in \mathbb{R}^n$ , and let  $a \in \mathbb{R}$ . Then 1.  $\vec{x} \cdot \vec{y} = \vec{y} \cdot \vec{x}$  (the dot product is commutative)

1. 
$$\mathbf{x} \cdot \mathbf{y} = \mathbf{y} \cdot \mathbf{x}$$
 (the dot product is commutative)  
2.  $\vec{\mathbf{z}} \cdot (\vec{\mathbf{z}} + \vec{\mathbf{z}}) = \vec{\mathbf{z}} \cdot \vec{\mathbf{z}} + \vec{\mathbf{z}} \cdot \vec{\mathbf{z}}$  (the dot product distributes ever addit

2. 
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 (the dot product distributes 3.  $(\vec{a} \vec{x}) \cdot \vec{v} = \vec{a} (\vec{x} \cdot \vec{v}) = \vec{x} \cdot (\vec{a} \vec{v})$ 

4. 
$$\|\vec{\mathbf{x}}\|^2 = \vec{\mathbf{x}} \cdot \vec{\mathbf{x}}$$
.

6.  $||a\vec{x}|| = |a| ||\vec{x}||$ .

## Example

Let  $\vec{x}, \vec{y} \in \mathbb{R}^n$ . Then

Let 
$$x,y \in \mathbb{R}$$
 . Then 
$$||\vec{x}+\vec{y}||^2 = (\vec{x}+\vec{y}) \cdot (\vec{x}+\vec{y})$$

 $= \vec{\mathbf{x}} \cdot \vec{\mathbf{x}} + \vec{\mathbf{x}} \cdot \vec{\mathbf{y}} + \vec{\mathbf{y}} \cdot \vec{\mathbf{x}} + \vec{\mathbf{y}} \cdot \vec{\mathbf{y}}$   $= \vec{\mathbf{x}} \cdot \vec{\mathbf{x}} + 2(\vec{\mathbf{x}} \cdot \vec{\mathbf{y}}) + |\vec{\mathbf{y}} \cdot \vec{\mathbf{y}}|$   $= ||\vec{\mathbf{x}}||^2 + 2(\vec{\mathbf{x}} \cdot \vec{\mathbf{y}}) + ||\vec{\mathbf{y}}||^2.$ 

#### Problem

Let  $\{\vec{f}_1, \vec{f}_2, \dots, \vec{f}_k\} \in \mathbb{R}^n$  and suppose  $\mathbb{R}^n = \operatorname{span}\{\vec{f}_1, \vec{f}_2, \dots, \vec{f}_k\}$ . Furthermore, suppose that there exists a vector  $\vec{x} \in \mathbb{R}^n$  for which  $\vec{x} \cdot \vec{f}_j = 0$  for all j,  $1 \leq j \leq k$ . Show that  $\vec{x} = \vec{0}_n$ .

#### Proof.

Write  $\vec{x} = t_1 \vec{f}_1 + t_2 \vec{f}_2 + \dots + t_k \vec{f}_k$  for some  $t_1, t_2, \dots, t_k \in \mathbb{R}$  (this is possible because  $\vec{f}_1, \vec{f}_2, \dots, \vec{f}_k$  span  $\mathbb{R}^n$ , is this representation unique?). Then

$$\begin{split} ||\vec{x}||^2 &= \vec{x} \cdot \vec{x} \\ &= \vec{x} \cdot (t_1 \vec{f}_1 + t_2 \vec{f}_2 + \dots + t_k \vec{f}_k) \\ &= \vec{x} \cdot (t_1 \vec{f}_1) + \vec{x} \cdot (t_2 \vec{f}_2) + \dots + \vec{x} \cdot (t_k \vec{f}_k) \\ &= t_1 (\vec{x} \cdot \vec{f}_1) + t_2 (\vec{x} \cdot \vec{f}_2) + \dots + t_k (\vec{x} \cdot \vec{f}_k) \\ &= t_1 (0) + t_2 (0) + \dots + t_k (0) = 0. \end{split}$$

Since  $||\vec{x}||^2 = 0$ ,  $||\vec{x}|| = 0$ . By the previous theorem,  $||\vec{x}|| = 0$  if and only if  $\vec{x} = \vec{0}_n$ . Therefore,  $\vec{x} = \vec{0}_n$ .

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## Cauchy-Schwartz Inequality

Theorem (Cauchy-Schwartz Inequality)

If  $\vec{x}, \vec{y} \in \mathbb{R}^n$ , then  $|\vec{x} \cdot \vec{y}| \le ||\vec{x}|| \ ||\vec{y}||$  with equality if and only if  $\{\vec{x}, \vec{y}\}$  is linearly dependent.



$$\left|\frac{\vec{x}}{||\vec{x}||} \cdot \frac{\vec{y}}{||\vec{y}||}\right| \le 1$$

$$\{\vec{x}, \vec{y}\}\$$
is linearly dependent  $\Leftrightarrow$   $\vec{x} = t\vec{y},$  for some  $t \in \mathbb{R}.$ 

#### Proof.

Let  $\vec{x}, \vec{y} \in \mathbb{R}^n$  and  $t \in \mathbb{R}$ . Then

$$\begin{split} 0 &\leq ||t\vec{x} + \vec{y}||^2 &= (t\vec{x} + \vec{y}) \cdot (t\vec{x} + \vec{y}) \\ &= t^2 \vec{x} \cdot \vec{x} + 2t\vec{x} \cdot \vec{y} + \vec{y} \cdot \vec{y} \\ &= t^2 ||\vec{x}||^2 + 2t(\vec{x} \cdot \vec{y}) + ||\vec{y}||^2. \end{split}$$

The quadratic  $t^2||\vec{x}||^2 + 2t(\vec{x} \cdot \vec{y}) + ||\vec{y}||^2$  in t is always nonnegative, so it does not have distinct real roots. Thus, if we use the quadratic formula to solve for t, the discriminant must be non-positive, i.e.,

$$\Delta = (2\vec{x} \cdot \vec{y})^2 - 4||\vec{x}||^2||\vec{y}||^2 \le 0$$

Therefore,  $(2\vec{x} \cdot \vec{y})^2 \le 4||\vec{x}||^2||\vec{y}||^2$ . Since both sides of the inequality are nonnegative, we can take (positive) square roots of both sides:

$$|2\vec{\mathbf{x}} \cdot \vec{\mathbf{y}}| \le 2||\vec{\mathbf{x}}|| \ ||\vec{\mathbf{y}}||$$

Therefore,  $|\vec{x} \cdot \vec{y}| \le ||\vec{x}|| \ ||\vec{y}||$ . What remains is to show that  $|\vec{x} \cdot \vec{y}| = ||\vec{x}|| \ ||\vec{y}||$  if and only if  $\{\vec{x}, \vec{y}\}$  is linearly dependent.

## Proof. (continued)

First suppose that  $\{\vec{x}, \vec{y}\}\$  is dependent. Then by symmetry (of  $\vec{x}$  and  $\vec{y}$ ),  $\vec{x} = k\vec{y}$  for some  $k \in \mathbb{R}$ . Hence

$$\begin{split} |\vec{x} \cdot \vec{y}| &= |(k\vec{y}) \cdot \vec{y}| = |k| \, |\vec{y} \cdot \vec{y}| = |k| \, ||\vec{y}||^2, \quad \text{and} \quad ||\vec{x}|| \, ||\vec{y}|| = ||k\vec{y}|| \, ||\vec{y}|| = |k| \, ||\vec{y}||^2, \\ \text{so} \ |\vec{x} \cdot \vec{y}| &= ||\vec{x}|| \, ||\vec{y}||. \end{split}$$

Conversely, suppose  $\{\vec{x}, \vec{y}\}$  is independent; then  $t\vec{x} + \vec{y} \neq \vec{0}_n$  for all  $t \in \mathbb{R}$ , so  $||t\vec{x} + \vec{y}||^2 > 0$  for all  $t \in \mathbb{R}$ . Thus the quadratic

$$t^{2}||\vec{x}||^{2} + 2t(\vec{x} \cdot \vec{y}) + ||\vec{y}||^{2} > 0$$

so has no real roots. It follows that the discriminant is negative, i.e.,

$$(2\vec{x} \cdot \vec{y})^2 - 4||\vec{x}||^2||\vec{y}||^2 < 0.$$

Therefore,  $(2\vec{x} \cdot \vec{y})^2 < 4||\vec{x}||^2||\vec{y}||^2$ ; taking square roots of both sides (they are both nonnegative) and dividing by two gives us

$$|\vec{\mathbf{x}} \cdot \vec{\mathbf{y}}| < ||\vec{\mathbf{x}}|| \ ||\vec{\mathbf{y}}||,$$

showing that equality is impossible.

## Corollary (Triangle Inequality I)

If 
$$\vec{x}, \vec{y} \in \mathbb{R}^n$$
, then  $||\vec{x} + \vec{y}|| \le ||\vec{x}|| + ||\vec{y}||$ .

Proof.

$$\begin{split} ||\vec{x} + \vec{y}||^2 &= (\vec{x} + \vec{y}) \cdot (\vec{x} + \vec{y}) \\ &= \vec{x} \cdot \vec{x} + 2\vec{x} \cdot \vec{y} + \vec{y} \cdot \vec{y} \\ &= ||\vec{x}||^2 + 2\vec{x} \cdot \vec{y} + ||\vec{y}||^2 \\ &\leq ||\vec{x}||^2 + 2||\vec{x}|| \, ||\vec{y}|| + ||\vec{y}||^2 \text{ by the Cauchy Inequality} \\ &= (||\vec{x}|| + ||\vec{y}||)^2. \end{split}$$

Since both sides of the inequality are nonnegative, we take (positive) square roots of both sides:

$$||\vec{x} + \vec{y}|| \le ||\vec{x}|| + ||\vec{y}||.$$

#### Definition

If  $\vec{x}, \vec{y} \in \mathbb{R}^n$ , then the distance between  $\vec{x}$  and  $\vec{y}$  is defined as

$$d(\vec{x}, \vec{y}) = ||\vec{x} - \vec{y}||$$

## Theorem (Properties of the distance function)

Let  $\vec{x}, \vec{y}, \vec{z} \in \mathbb{R}^n$ . Then

- 1.  $d(\vec{x}, \vec{y}) \ge 0$ .
- 2.  $d(\vec{x}, \vec{y}) = 0$  if and only if  $\vec{x} = \vec{y}$ .
- 3.  $d(\vec{x}, \vec{y}) = d(\vec{y}, \vec{x})$ .
- 4.  $d(\vec{x}, \vec{z}) \leq d(\vec{x}, \vec{y}) + d(\vec{y}, \vec{z})$  (Triangle Inequality II).

## Proof. (Proof of the Triangle Inequality II)

$$\begin{split} d(\vec{x},\vec{z}) &= ||\vec{x} - \vec{z}|| &= ||(\vec{x} - \vec{y}) + (\vec{y} - \vec{z})|| \\ &\leq ||\vec{x} - \vec{y}|| + ||\vec{y} - \vec{z}|| \text{ by Triangle Inequality I} \\ &= d(\vec{x},\vec{y}) + d(\vec{y},\vec{z}). \end{split}$$

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## Orthogonality

#### Definitions

- Let  $\vec{x}, \vec{y} \in \mathbb{R}^n$ . We say that two vectors  $\vec{x}$  and  $\vec{y}$  are orthogonal if  $\vec{x} \cdot \vec{y} = 0$ .
- ▶ More generally,  $X = \{\vec{x}_1, \vec{x}_2, \dots, \vec{x}_k\} \subseteq \mathbb{R}^n$  is an orthogonal set if each  $\vec{x_i}$  is nonzero, and every pair of distinct vectors of X is orthogonal, i.e.,  $\vec{x}_i \cdot \vec{x}_j = 0$  for all  $i \neq j, 1 \leq i, j \leq k$ .
- ▶ A set  $X = \{\vec{x}_1, \vec{x}_2, \dots, \vec{x}_k\} \subseteq \mathbb{R}^n$  is an orthonormal set if X is an orthogonal set of unit vectors, i.e.,  $||\vec{x}_i|| = 1$  for all i,  $1 \le i \le k$ .

### Examples

1. The standard basis  $\{\vec{e}_1, \cdots, \vec{e}_n\}$  of  $\mathbb{R}^n$  is an orthonormal set (and hence an orthogonal set).

2.

$$\left\{ \begin{bmatrix} 1\\1\\1\\1 \end{bmatrix}, \begin{bmatrix} 1\\1\\-1\\-1 \end{bmatrix}, \begin{bmatrix} 1\\-1\\1\\-1 \end{bmatrix} \right\}$$

is an orthogonal (but not orthonormal) subset of  $\mathbb{R}^4$ .

- 3. If  $\{\vec{x}_1, \vec{x}_2, \dots, \vec{x}_k\}$  is an orthogonal subset of  $\mathbb{R}^n$  and  $p \neq 0$ , then  $\{p\vec{x}_1, p\vec{x}_2, \dots, p\vec{x}_k\}$  is an orthogonal subset of  $\mathbb{R}^n$ .
- 4.

$$\left\{ \frac{1}{2} \begin{bmatrix} 1\\1\\1\\1 \end{bmatrix}, \frac{1}{2} \begin{bmatrix} 1\\1\\-1\\-1 \end{bmatrix}, \frac{1}{2} \begin{bmatrix} 1\\-1\\1\\-1 \end{bmatrix} \right\}$$

is an orthonormal subset of  $\mathbb{R}^4$ .

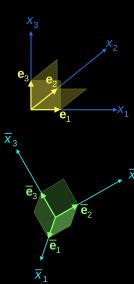
#### Definition

# Normalizing an orthogonal set is the process of turning an orthogonal (but not orthonormal) set into an orthonormal set. If $\{\vec{x}_1, \vec{x}_2, \dots, \vec{x}_k\}$ is an

orthogonal subset of  $\mathbb{R}^n$ , then

$$\left\{\frac{1}{||\vec{x}_1||}\vec{x}_1, \frac{1}{||\vec{x}_2||}\vec{x}_2, \dots, \frac{1}{||\vec{x}_k||}\vec{x}_k\right\}$$

is an orthonormal set.



## Problem

Verify that

$$\left\{ \begin{bmatrix} 1\\-1\\2 \end{bmatrix}, \begin{bmatrix} 0\\2\\1 \end{bmatrix}, \begin{bmatrix} 5\\1\\-2 \end{bmatrix} \right\}$$

is an orthogonal set, and normalize this set.  $\,$ 

#### Solution

$$\begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix} = 0 - 2 + 2 = 0,$$

$$\begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 5 \\ 1 \\ -2 \end{bmatrix} = 0 + 2 - 2 = 0,$$

$$\begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} \cdot \begin{bmatrix} 5 \\ 1 \\ -2 \end{bmatrix} = 5 - 1 - 4 = 0,$$

proving that the set is orthogonal. Normalizing gives us the orthonormal set

$$\left\{ \frac{1}{\sqrt{6}} \begin{bmatrix} 1\\ -1\\ 2 \end{bmatrix}, \frac{1}{\sqrt{5}} \begin{bmatrix} 0\\ 2\\ 1 \end{bmatrix}, \frac{1}{\sqrt{30}} \begin{bmatrix} 5\\ 1\\ -2 \end{bmatrix} \right\}.$$

## Theorem (Pythagoras' Theorem)

If  $\{\vec{x}_1, \vec{x}_2, \dots, \vec{x}_k\} \subseteq \mathbb{R}^n$  is orthogonal, then

$$||\vec{\mathbf{x}}_1 + \vec{\mathbf{x}}_2 + \dots + \vec{\mathbf{x}}_k||^2 = ||\vec{\mathbf{x}}_1||^2 + ||\vec{\mathbf{x}}_2||^2 + \dots + ||\vec{\mathbf{x}}_k||^2.$$

#### Proof.

Start with

$$\begin{split} ||\vec{x}_{1} + \vec{x}_{2} + \cdots + \vec{x}_{k}||^{2} &= (\vec{x}_{1} + \vec{x}_{2} + \cdots + \vec{x}_{k}) \cdot (\vec{x}_{1} + \vec{x}_{2} + \cdots + \vec{x}_{k}) \\ &= (\vec{x}_{1} \cdot \vec{x}_{1} + \vec{x}_{1} \cdot \vec{x}_{2} + \cdots + \vec{x}_{1} \cdot \vec{x}_{k}) \\ &+ (\vec{x}_{2} \cdot \vec{x}_{1} + \vec{x}_{2} \cdot \vec{x}_{2} + \cdots + \vec{x}_{2} \cdot \vec{x}_{k}) \\ &\vdots &\vdots &\vdots \\ &+ (\vec{x}_{k} \cdot \vec{x}_{1} + \vec{x}_{k} \cdot \vec{x}_{2} + \cdots + \vec{x}_{k} \cdot \vec{x}_{k}) \\ &= \vec{x}_{1} \cdot \vec{x}_{1} + \vec{x}_{2} \cdot \vec{x}_{2} + \cdots + \vec{x}_{k} \cdot \vec{x}_{k} \\ &= ||\vec{x}_{1}||^{2} + ||\vec{x}_{2}||^{2} + \cdots + ||\vec{x}_{k}||^{2}. \end{split}$$

The second last equality follows from the fact that the set is orthogonal, so for all i and j,  $i \neq j$  and  $1 \leq i, j \leq k$ ,  $\vec{x}_i \cdot \vec{x}_j = 0$ . Thus, the only nonzero terms are the ones of the form  $\vec{x}_i \cdot \vec{x}_i$ ,  $1 \leq i \leq k$ .

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## Orthogonality and Independence

#### Theorem

If  $S=\{\vec{x}_1,\vec{x}_2,\ldots,\vec{x}_k\}\subseteq\mathbb{R}^n$  is an orthogonal set, then S is independent.

#### Proof.

Form the linear equation:  $t_1\vec{x}_1 + t_2\vec{x}_2 + \dots + t_k\vec{x}_k = \vec{0}$ . We need to check whether there is only trivial solution. Notice that for all  $i, 1 \le i \le k$ ,

$$0 = (t_1 \vec{x}_1 + t_2 \vec{x}_2 + \dots + t_k \vec{x}_k) \cdot \vec{x}_i = t_i \vec{x}_i \cdot \vec{x}_i = t_i ||\vec{x}_i||^2,$$

since  $t_j \vec{x}_j \cdot \vec{x}_i = 0$  for all  $j, 1 \leq j \leq k$  where  $j \neq i$ . Since  $\vec{x}_i \neq \vec{0}_n$  and  $t_i ||\vec{x}_i||^2 = 0$ , it follows that  $t_i = 0$  for all  $i, 1 \leq i \leq k$ . Therefore, S is linearly independent.

## Example

Given an arbitrary vector

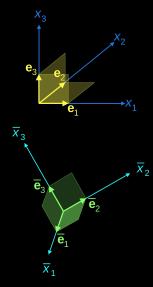
$$ec{\mathrm{x}} = \left| egin{array}{c} \mathrm{a}_1 \ \mathrm{a}_2 \ \mathrm{\vdots} \ \mathrm{a}_n \end{array} 
ight| \in \mathbb{R}^n$$

it is trivial to express  $\vec{x}$  as a linear combination of the standard basis vectors of  $\mathbb{R}^n$ ,  $\{\vec{e}_1, \vec{e}_2, \dots, \vec{e}_n\}$ :

$$\vec{x} = a_1 \vec{e}_1 + a_2 \vec{e}_2 + \dots + a_n \vec{e}_n.$$

#### Problem

Given any orthogonal basis B of  $\mathbb{R}^n$  (so not necessarily the standard basis), and an arbitrary vector  $\vec{x} \in \mathbb{R}^n$ , how do we express  $\vec{x}$  as a linear combination of the vectors in B?



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## Fourier Expansion

## Theorem (Fourier Expansion)

Let  $\{\vec{f}_1,\vec{f}_2,\ldots,\vec{f}_m\}$  be an orthogonal basis of a subspace U of  $\mathbb{R}^n$ . Then for any  $\vec{x}\in U$ ,

$$\vec{x} = \left(\frac{\vec{x} \cdot \vec{f}_1}{||\vec{f}_1||^2}\right) \vec{f}_1 + \left(\frac{\vec{x} \cdot \vec{f}_2}{||\vec{f}_2||^2}\right) \vec{f}_2 + \dots + \left(\frac{\vec{x} \cdot \vec{f}_m}{||\vec{f}_m||^2}\right) \vec{f}_m.$$

This expression is called the Fourier expansion of  $\vec{x}$ , and

$$\frac{\vec{\mathbf{x}} \cdot \vec{\mathbf{f}}_{j}}{||\vec{\mathbf{f}}_{i}||^{2}}, \quad j = 1, 2, \dots, m$$

are called the Fourier coefficients.

#### Example

Let 
$$\vec{f}_1 = \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix}$$
,  $\vec{f}_2 = \begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix}$ , and  $\vec{f}_3 = \begin{bmatrix} 5 \\ 1 \\ -2 \end{bmatrix}$ , and let  $\vec{x} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ .

We have seen that  $B = \{\vec{f}_1, \vec{f}_2, \vec{f}_3\}$  is an orthogonal subset of  $\mathbb{R}^3$ .

It follows that B is an orthogonal basis of  $\mathbb{R}^3$ . (Why?)

To express  $\vec{x}$  as a linear combination of the vectors of B, apply the Fourier Expansion Theorem. Assume  $\vec{x} = t_1 \vec{f}_1 + t_2 \vec{f}_2 + t_3 \vec{f}_3$ . Then

$$\mathbf{t}_1 = \frac{\vec{\mathbf{x}} \cdot \vec{\mathbf{f}}_1}{||\vec{\mathbf{f}}_1|||2} = \frac{2}{6}, \;\; \mathbf{t}_2 = \frac{\vec{\mathbf{x}} \cdot \vec{\mathbf{f}}_2}{||\vec{\mathbf{f}}_2|||2} = \frac{3}{5}, \;\; ext{ and } \;\; \mathbf{t}_3 = \frac{\vec{\mathbf{x}} \cdot \vec{\mathbf{f}}_3}{||\vec{\mathbf{f}}_2|||2} = \frac{4}{30}.$$

Therefore,

$$\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} + \frac{3}{5} \begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix} + \frac{2}{15} \begin{bmatrix} 5 \\ 1 \\ -2 \end{bmatrix}.$$

## Proof. (Fourier Expansion)

Let  $\vec{x} \in U$ . Since  $\{\vec{f}_1, \vec{f}_2, \dots, \vec{f}_m\}$  is a basis of U,  $\vec{x} = t_1 \vec{f}_1 + t_2 \vec{f}_2 + \dots + t_m \vec{f}_m$  for some  $t_1, t_2, \dots, t_m \in \mathbb{R}$ . Notice that for any  $i, 1 \leq i \leq m$ ,

$$\begin{split} \vec{x} \cdot \vec{f}_i &= (t_1 \vec{f}_1 + t_2 \vec{f}_2 + \dots + t_m \vec{f}_m) \cdot \vec{f}_i \\ &= t_i \vec{f}_i \cdot \vec{f}_i \quad \text{since } \{\vec{f}_1, \vec{f}_2, \dots, \vec{f}_m\} \text{ is orthogonal} \\ &= t_i ||\vec{f}_i||^2. \end{split}$$

Since  $\vec{f}_i$  is nonzero, we obtain

$$t_i = \frac{\vec{x} \cdot \vec{f}_i}{||\vec{f}_i||^2}.$$

The result now follows.

#### Remark

If  $\{\vec{f}_1, \vec{f}_2, \dots, \vec{f}_m\}$  is an orthonormal basis, then the Fourier coefficients are simply  $t_j = \vec{x} \cdot \vec{f}_j$ ,  $j = 1, 2, \dots, m$ .

Problem

Let 
$$\vec{\mathbf{f}}_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \quad \vec{\mathbf{f}}_2 = \begin{bmatrix} 1 \\ -1 \\ 0 \\ 0 \end{bmatrix}, \quad \vec{\mathbf{f}}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \end{bmatrix}, \quad \vec{\mathbf{f}}_4 = \begin{bmatrix} 0 \\ 0 \\ 1 \\ -1 \end{bmatrix}.$$

Show that  $B = \{\vec{f}_1, \vec{f}_2, \vec{f}_3, \vec{f}_4\}$  is an orthogonal basis of  $\mathbb{R}^4$ , and express  $\vec{x} = \begin{bmatrix} a & b & c & d \end{bmatrix}^T$  as a linear combination of  $\vec{f}_1, \vec{f}_2, \vec{f}_3$  and  $\vec{f}_4$ .

#### Solution

Computing  $\vec{f}_i \cdot \vec{f}_j$  for  $1 \le i < j \le 4$  gives us

Hence, B is an orthogonal set. It follows that B is independent, and since  $|B| = 4 = \dim(\mathbb{R}^4)$ , B also spans  $\mathbb{R}^4$ . Therefore, B is an orthogonal basis of  $\mathbb{R}^4$ . By the Fourier Expansion Theorem,

$$\vec{x} = \left(\frac{a+b}{2}\right)\vec{f}_1 + \left(\frac{a-b}{2}\right)\vec{f}_2 + \left(\frac{c+d}{2}\right)\vec{f}_3 + \left(\frac{c-d}{2}\right)\vec{f}_4.$$