

A Reflected Stochastic Heat Equation as Symmetric Dynamics with Respect to the 3-d Bessel Bridge

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We prove that a stochastic heat equation with reflection at 0, on the spatial interval [0, 1] with Dirichlet boundary conditions and additive white-noise, admits an explicit symmetrizing invariant measure on C([0, 1]): the 3-d Bessel Bridge, i.e., the law of the modulus of a 3-dimensional Brownian motion conditioned to be 0 at time 1, a classical measure in probability theory, also connected with the theory of excursions of Brownian motion. This is a non-trivial example of a Gibbs-type measure being singular with respect to the reference Gaussian measure and concentrated on the convex set of positive, continuous functions on [0, 1]. © 2001 Academic Press

1. INTRODUCTION

In [6], Nualart and Pardoux studied existence and uniqueness of a solution to a reflected stochastic heat equation, namely of a pair (u, η) , where *u* is a continuous function of $(t, \xi) \in \mathcal{O} := [0, +\infty) \times [0, 1]$ and η is a positive measure on \mathcal{O} , satisfying

$$\begin{cases} \frac{\partial u}{\partial t} = \frac{1}{2} \frac{\partial^2 u}{\partial \xi^2} - f(\xi, u(t, \xi)) + \frac{\partial^2 W}{\partial t} \frac{\eta(dt, d\xi)}{\partial t} \\ u(0, \xi) = x(\xi), & u(t, 0) = u(t, 1) = 0 \\ u \geqslant 0, & \int_{\mathcal{O}} u \, d\eta = 0. \end{cases}$$
(1)

where $x:[0,1] \mapsto [0,\infty)$ is continuous with x(0) = x(1) = 0, $\{W(t,\xi):$ $(t, \xi) \in \mathcal{O}$ is a Brownian sheet, and $f: [0, 1] \times \mathbb{R} \mapsto \mathbb{R}$.



The aim of this paper is to prove that Eq. (1) admits, on the space $C_0(0, 1)$ of continuous functions of $\xi \in [0, 1]$, satisfying Dirichlet boundary conditions, an explicit invariant and symmetrizing measure, given by

$$\exp\left\{-\int_{0}^{1} d\xi \int_{0}^{x(\xi)} 2f(\xi, s) ds\right\} v(dx), \qquad x \in C_{0}(0, 1), \tag{2}$$

where v is a well-known probability measure on $C_0(0, 1)$: the 3-d Bessel bridge, namely the law of the modulus of a 3-dimensional Brownian motion $(B_\tau)_{\tau \in [0, 1]}$, conditioned to be 0 at $\tau = 1$. This measure plays an important role in the study of Brownian motion (see [7]).

On the other hand, Da Prato proved in [2] the existence of a symmetric semigroup $(P_t)_{t\geq 0}$ on $L^2(H,(\int_H e^{-2U}d\mu)^{-1}e^{-2U}d\mu)$, associated with the stochastic differential inclusion

$$dX \in (AX - \partial U(X)) \ dt + dW, \qquad X(0) = x \in H, \tag{3}$$

where H is a separable Hilbert space, $A := D(A) \subset H \mapsto H$ is a strictly negative self-adjoint operator such that $Q := (-2A)^{-1}$ is trace-class, μ is the Gaussian measure $\mathcal{N}(0, Q)$ on H with 0 mean and covariance operator Q, and W is a cylindrical white-noise on H. Moreover, $U: H \mapsto \mathbb{R} \cup \{+\infty\}$ is a convex, lower semicontinuous function, satisfying suitable integrability conditions with respect to μ and

$$\mu(x: U(x) < +\infty \text{ and } \partial U(x) \neq \emptyset) = 1,$$

where $\partial U(x)$, the subdifferential of U at x, is defined as the subset of H:

$$\partial U(x) := \{ v \in H : U(x+h) \geqslant U(x) + \langle h, v \rangle, \forall h \in H \}.$$

Equation (1) can be interpreted as an example of (3), setting $H := L^2(0, 1)$, $A := (1/2) d^2/d\xi^2$ on H with Dirichlet boundary conditions,

$$U(x) := \begin{cases} \int_0^1 d\xi \int_0^{x(\xi)} f(\xi, s) \, ds & \text{if } x \ge 0 \\ +\infty & \text{otherwise} \end{cases}$$
 (4)

and defining, for all non-negative $x \in H$, $\partial U(x)$ as the subset of the dual space M of $C_0(0, 1)$, $M := \{\text{signed measures on } (0, 1)\}$,

$$\begin{split} \partial \, U(x) &:= \big\{ m \in M : \, U(x+z) \geqslant U(x) + \big\langle z, m \big\rangle, \, \forall z \in C_0(0,1) \big\} \\ &= f(\xi, x(\xi)) \, d\xi - \bigg\{ m \in M : m \geqslant 0, \int_{(0,1)} x(\xi) \, m(d\xi) = 0 \bigg\}. \end{split}$$

Then (1) can be written formally as a differential inclusion of measures:

$$\left(\frac{\partial u}{\partial t} - Au - \frac{\partial^2 W}{\partial t \ \partial \xi}\right) d\xi \in \partial U(u(t, \cdot)).$$

However, in this case $\mu(U=+\infty)=1$ (see Lemma 5 below) and the measure " $(\int_H e^{-2U} d\mu)^{-1} e^{-2U} d\mu$ " is not well defined. Our result shows that a natural Gibbs-type measure for (1) is provided by (2). Notice that ν is not Gaussian and is even singular with respect to the reference Gaussian measure μ . Moreover, the support of ν is a closed convex set having empty interior both in the topologies of $L^2(0,1)$ and C([0,1]).

The proof we give relies on the construction of solutions to (1) given by Nualart and Pardoux in [6] and on a result of Biane on a connection between the law of the Brownian Bridge and the law of the 3-d Bessel Bridge (see [1] and Theorem 4 below).

2. DEFINITIONS

Our aim is to find a symmetrizing invariant measure for the process $x \mapsto u(t, \cdot)$, $t \ge 0$, where (u, η) satisfies:

$$\begin{cases} \frac{\partial u}{\partial t} = \frac{1}{2} \frac{\partial^2 u}{\partial \xi^2} - f(\xi, u(t, \xi)) + \frac{\partial^2 W}{\partial t \partial \xi} + \frac{\eta(dt, d\xi)}{dt d\xi} \\ u(0, \xi) = x(\xi), & u(t, 0) = u(t, 1) = 0 \\ u + \alpha \geqslant 0, & \int_{\mathcal{O}} (u + \alpha) d\eta = 0, \end{cases}$$
 (5)

where $\alpha \geqslant 0$, $x: [0, 1] \mapsto [-\alpha, +\infty)$ is continuous and x(0) = x(1) = 0. We introduce the following notations: $(t, \xi) \in \mathcal{O} := [0, +\infty) \times [0, 1]$, $H := L^2(0, 1)$ with scalar product $\langle \cdot, \cdot \rangle$ and norm $\| \cdot \|$,

$$\langle h, k \rangle := \int_0^1 h(\xi) \, k(\xi) \, d\xi, \qquad ||h||^2 := \langle h, h \rangle,$$

$$C_0(0, 1) := \{ c : [0, 1] \mapsto \mathbb{R} \text{ continuous, } c(0) = c(1) = 0 \},$$

$$A : D(A) \subset H \mapsto H, \qquad D(A) := H^2 \cap H_0^1(0, 1), \qquad A := \frac{1}{2} \frac{d^2}{d\xi^2}.$$

We set $K_{\alpha} := \{h \in H : h \geqslant -\alpha\}$ with $\alpha \geqslant 0$, and we denote by $\Pi_{K_{\alpha}} : H \mapsto K_{\alpha}$ the projection from H onto the closed convex set $K_{\alpha} \subset H$. Recall that $\Pi_{K_{\alpha}}$ is 1-Lipschitz continuous. If $D \subseteq H$, we denote by $C_b(D)$ the space of all $\varphi : D \mapsto \mathbb{R}$ being bounded and uniformly continuous with respect to $\|\cdot\|$. If $D \subseteq H$ and $\varphi \in C_b(D)$, we denote by ω_{φ} the modulus of continuity of φ :

$$\omega_{\varphi} \colon [0, \infty) \mapsto [0, 1], \qquad \omega_{\varphi}(r) \colon = \sup \big\{ |\varphi(x) - \varphi(x')| \, \wedge \, 1 \colon \|x - x'\| \leqslant r \big\}.$$

We identify $C_b(K_\alpha)$ with a subspace of $C_b(H)$ by means of the injection: $C_b(K_\alpha) \ni \varphi \mapsto \varphi \circ \Pi_{K_\alpha} \in C_b(H)$. If $0 \leqslant \alpha \leqslant \beta$, then $C_b(K_\alpha) \subseteq C_b(K_\beta)$.

If $\{m_n\}_n \cup \{m\}$ is a sequence of probability measures on $(H, \mathcal{B}(H))$, where $\mathcal{B}(H)$ is the Borel σ -field of H, we say that m_n converges weakly to m, if:

$$\lim_{n\to\infty} \int_{H} \varphi \ dm_n = \int_{H} \varphi \ dm, \qquad \forall \varphi \in C_b(H).$$

Given a Markov process $\{Y(t, x): t \ge 0, x \in D\}$ on $D \subseteq H$, we say that a probability measure m on D is symmetrizing for Y, if, setting for all $\varphi \in C_b(D): R_t^Y \varphi(x) := \mathbb{E}[\varphi(Y(t, x))], x \in D$, we have:

$$\int_{D} \varphi \ R_{t}^{Y} \psi \ dm = \int_{D} \psi \ R_{t}^{Y} \varphi \ dm, \qquad \forall \varphi, \psi \in C_{b}(D).$$

A symmetrizing measure is in particular invariant; i.e.,

$$\int_{D} R_{t}^{Y} \varphi \ dm = \int_{D} \varphi \ dm, \qquad \forall \varphi \in C_{b}(D).$$

We denote by $1_D(\cdot)$ the characteristic function of a set D. We sometimes write $m(\varphi)$ for $\int_H \varphi \ dm$, $\varphi \in C_b(H)$.

By $W = \{W(t, \xi) : (t, \xi) \in \mathcal{O}\}$ we denote a two-parameter Wiener process defined on a complete probability space $(\Omega, \mathcal{F}, \mathbb{P})$, i.e., W is a Gaussian process with zero mean and covariance function

$$\mathbb{E}\left[W(t,\xi)\ W(t',\xi')\right] = (t \wedge t')(\xi \wedge \xi'), \qquad (t,\xi), (t',\xi') \in \mathcal{O}.$$

We denote by \mathscr{F}_t the σ -field generated by the random variables $\{W(s, \xi): (s, \xi) \in [0, t] \times [0, 1]\}$ and by $C_c^{\infty}(0, 1)$ the subset of $C_0(0, 1)$ of all C^{∞} functions with support being compact in (0, 1).

We always assume in the following that:

- (H1) $f = f_1 + f_2, f_1, f_2$: [0, 1] $\times \mathbb{R} \mapsto \mathbb{R}$ are jointly measurable.
- (H2) There exists c>0 such that $|f_1(\xi,y)-f_1(\xi,y')|\leqslant c\;|y-y'|$ for all $\xi\in[0,1],\;y,\;y'\in\mathbb{R}.$

(H3) $f_2(\xi, \cdot)$ is non-decreasing and continuous, for all $\xi \in [0, 1]$.

(H4) There exist a constant $\lambda < \pi^2$, $a \in H$ and a polynomial p of degree $N \in \mathbb{N}$, such that for all $\xi \in [0, 1]$, $y \in \mathbb{R}$:

$$-a(\xi) - \lambda |y| \leq 2f(\xi, y) \leq a(\xi) + p(|y|).$$

Following [6], we set the following:

DEFINITION 1. A pair (u, η) is said to be a solution of Eq. (5) with reflection in $-\alpha \le 0$ and initial value $x \in K_{\alpha} \cap C_0(0, 1)$, if:

- (i) $\{u(t,\xi): (t,\xi)\in\mathcal{O}\}$ is a continuous and adapted process, i.e., $u(t,\xi)$ is \mathscr{F}_t -measurable for all $(t,\xi)\in\mathcal{O}$, and a.s. $u(\cdot,\cdot)$ is continuous on \mathcal{O} , $u(t,\cdot)\in K_\alpha\cap C_0(0,1)$ for all $t\geqslant 0$, and $u(0,\cdot)=x$.
- (ii) $\eta(dt, d\xi)$ is a random positive measure on \mathcal{O} such that $\eta([0, T] \times [\delta, 1 \delta]) < +\infty$ for all $T, \delta > 0$, and η is adapted; i.e., $\eta(B)$ is \mathscr{F}_t -measurable for every Borel set $B \subset [0, t] \times [0, 1]$.
 - (iii) For all $t \ge 0$ and $\varphi \in C_c^{\infty}(0, 1)$, setting $u_s := u(s, \cdot)$,

$$\begin{split} \langle u_t, \varphi \rangle - \int_0^t \langle u_s, A\varphi \rangle \, ds + \int_0^t \langle f(\cdot, u_s), \varphi \rangle \, ds \\ \\ = \langle x, \varphi \rangle + \int_0^t \int_0^1 \varphi(\xi) \, dW_{s, \, \xi} + \int_0^t \int_0^1 \varphi(\xi) \, \eta(ds, d\xi). \end{split}$$

(iv)
$$\int_{\mathcal{O}} (u + \alpha) d\eta = 0.$$

Finally, we will use the following:

LEMMA 1. Let T be a Polish metric space, and let $\{m_n\}_n \cup \{m\}$, respectively $\{\varphi_n\}_n$, be a sequence of probability measures, resp. of real-valued continuous functions, on T, satisfying:

- m_n converges weakly to m.
- The family $\{\varphi_n\}_n$ is uniformly bounded and equicontinuous on T.
- $\varphi_n(x)$ has a limit $\varphi(x)$ as $n \to \infty$, for all $x \in S$, with $S \subseteq T$ Borel and m(S) = 1.

Then:

$$\lim_{n\to\infty} \int_T \varphi_n \, dm_n = \int_S \varphi \, dm.$$

Proof. We can suppose that $0 \le \varphi_n \le 1$ for all n. By Prokhorov's theorem, there exists for every $\delta > 0$ a compact set $Q_\delta \subset T$ such that eventually $m_n(Q_\delta) \ge 1 - \delta$. Let $\{\varphi_{n_k}\}_k$ be any subsequence of $\{\varphi_n\}_n$. On Q_δ we can apply the Ascoli–Arzelà theorem and obtain uniform convergence of a sub-subsequence $\{\varphi_{n_{k(l)}}\}_l$ to a continuous function $f: Q_\delta \mapsto \mathbb{R}$. Then:

$$\begin{split} \int_{T} \varphi_{n_{k(l)}} \, dm_{n_{k(l)}} - \int_{T} \varphi_{n_{k(l)}} \, dm &\leqslant m_{n_{k(l)}} (T - Q_{\delta}) + \int_{Q_{\delta}} \varphi_{n_{k(l)}} \big[\, dm_{n_{k(l)}} - dm \big] \\ &\leqslant \delta + 2\delta + \int_{Q_{\delta}} f \, \big[\, dm_{n_{k(l)}} - dm \big], \end{split}$$

where for $l \geqslant l_0$, $\sup_{Q_{\delta}} |\varphi_{n_{k(l)}} - f| \leqslant \delta$. Since m(T - S) = 0 and Q_{δ} is closed,

$$\lim_{n\to\infty} \int_T \varphi_n \, dm = \int_S \varphi \, dm,$$

 $\limsup_{n\to\infty} \int_{Q_{\delta}} f \, dm_n \leqslant \int_{Q_{\delta}} f \, dm, \quad \text{and therefore:}$

$$\limsup_{l\to\infty} \int_T \varphi_{n_{k(l)}} dm_{n_{k(l)}} \leqslant \int_S \varphi dm.$$

Changing φ_n with $1 - \varphi_n$, we obtain the thesis.

3. THE PROCESS X_{α} , $\alpha \geqslant 0$

In [6], the following theorem is proved:

THEOREM 1. Assume that f satisfies (H1), (H2), (H3), (H4) and let $x \in K_{\alpha} \cap C_0(0, 1)$. Then there exists a unique solution (u, η) to Eq. (5) with reflection in $-\alpha$ and initial value x.

We recall the strategy of the proof, given in [6], of the existence of solutions. First, the following approximating problem is introduced:

$$\begin{cases} \frac{\partial u_{\alpha}^{\varepsilon}}{\partial t} = \frac{1}{2} \frac{\partial^{2} u_{\alpha}^{\varepsilon}}{\partial \xi^{2}} - f(\cdot, u_{\alpha}^{\varepsilon}(t, \cdot)) + \frac{\partial^{2} W}{\partial t} \frac{\partial \xi}{\partial \xi} + \frac{(\alpha + u_{\alpha}^{\varepsilon})^{-}}{\varepsilon} \\ u_{\alpha}^{\varepsilon}(0, \cdot) = x \in H, \qquad u_{\alpha}^{\varepsilon}(t, 0) = u_{\alpha}^{\varepsilon}(t, 1) = 0, \quad \forall t \geqslant 0. \end{cases}$$

$$(6)$$

with $\varepsilon > 0$, $(r)^- := \sup\{-r, 0\}$, and $\alpha \ge 0$. This is now a SPDE in $L^2(0, 1)$ with additive noise and monotone or Lipschitz-continuous drift terms, for which existence and uniqueness of a solution are well known (see [3]). Then, if $x \in K_\alpha \cap C_0(0, 1)$, the following is proved:

- (a) $u_{\alpha}^{\varepsilon}(t, \cdot) \in C_0(0, 1)$ for all $t \ge 0$, and u_{α}^{ε} is continuous on \mathcal{O} .
- (b) The map $0 < \varepsilon \mapsto u_{\alpha}^{\varepsilon}(t, \xi)$ is non-decreasing for all $(t, \xi) \in \mathcal{O}$. The limit $\lim_{\varepsilon \downarrow 0} u_{\alpha}^{\varepsilon}(t, \xi) = \sup_{\varepsilon > 0} u_{\alpha}^{\varepsilon}(t, \xi) =: u_{\alpha}(t, \xi)$ is finite for all $(t, \xi) \in \mathcal{O}$, $u_{\alpha}(t, \cdot) \in K_{\alpha} \cap C_{0}(0, 1)$ for all $t \geqslant 0$, and u_{α} is continuous on \mathcal{O} .
- (c) The measure on \mathcal{O} , $\eta_{\alpha}^{\varepsilon}(dt, d\xi) := (1/\varepsilon)(\alpha + u_{\alpha}^{\varepsilon})^{-} dt d\xi$, converges distributionally to a measure $\eta_{\alpha}(dt, d\xi)$ on \mathcal{O} .
- (d) The pair $(u_{\alpha}, \eta_{\alpha})$ is the solution to (5) with reflection in $-\alpha$ and initial value $x \in K_{\alpha} \cap C_0(0, 1)$.

We set for all $t \ge 0$, $\alpha \ge 0$, $\varepsilon > 0$:

- $X_{\alpha}(t, x) \in C_0(0, 1), X_{\alpha}(t, x)(\xi) := u_{\alpha}(t, \xi), x \in K_{\alpha} \cap C_0(0, 1),$
- $X_{\alpha}^{\varepsilon}(t, x) \in H$, $X_{\alpha}^{\varepsilon}(t, x)(\xi) := u_{\alpha}^{\varepsilon}(t, \xi)$, $x \in H$.

LEMMA 2. For all $\alpha \ge 0$, $\varepsilon > 0$, $t \ge 0$, we have: $\forall x, x' \in C_0(0, 1)$,

$$||X_{\alpha}^{\varepsilon}(t,x) - X_{\alpha}^{\varepsilon}(t,x')|| \leq e^{ct} ||x - x'||, \tag{7}$$

where $\|\cdot\|$ denotes the norm in H and c>0 is the constant of (H2).

Proof. By the monotonicity properties of $(\cdot)^-$ and $f_2(\xi, \cdot)$ we have

$$\frac{1}{2}\frac{d}{dt}\left\|\boldsymbol{X}_{\alpha}^{\varepsilon}(t,\,\boldsymbol{x})-\boldsymbol{X}_{\alpha}^{\varepsilon}(t,\,\boldsymbol{x}')\right\|^{2}\leqslant c\,\left\|\boldsymbol{X}_{\alpha}^{\varepsilon}(t,\,\boldsymbol{x})-\boldsymbol{X}_{\alpha}^{\varepsilon}(t,\,\boldsymbol{x}')\right\|^{2}$$

and the thesis follows from Gronwall's lemma.

Therefore, the same estimate holds for X_{α} , $\alpha \ge 0$: $\forall x, x' \in K_{\alpha} \cap C_0(0, 1)$,

$$||X_{\alpha}(t,x) - X_{\alpha}(t,x')|| \le e^{ct} ||x - x'||$$
 (8)

and we can uniquely extend $X_{\alpha}^{\varepsilon}(t,\cdot)$, respectively $X_{\alpha}(t,\cdot)$, to maps from H to H, resp. from K_{α} to K_{α} , that we denote by the same symbols, satisfying (7) for all $x, x' \in H$, resp. (8) for all $x, x' \in K_{\alpha}$. We set for all $\alpha \geqslant 0$, $\varepsilon > 0$, $\varphi \in C_b(H)$, $t \geqslant 0$:

$$P_{\sigma}^{\varepsilon}(t) \varphi : H \mapsto \mathbb{R}, \qquad P_{\sigma}^{\varepsilon}(t) \varphi(x) := \mathbb{E}[\varphi(X_{\sigma}^{\varepsilon}(t, x))], \qquad x \in H, \qquad (9)$$

$$P_{\alpha}(t) \varphi \colon K_{\alpha} \mapsto \mathbb{R}, \qquad P_{\alpha}(t) \varphi(x) := \mathbb{E}[\varphi(X_{\alpha}(t, x))], \qquad x \in K_{\alpha}.$$
 (10)

LEMMA 3. For all $\alpha \ge 0$, $\varepsilon > 0$, $\varphi \in C_b(H)$, $t \ge 0$, we have:

$$P_{\alpha}^{\varepsilon}(t) \varphi \in C_{b}(H), \qquad \omega_{P_{\alpha}^{\varepsilon}(t) \varphi}(r) \leq \omega_{\varphi}(e^{ct}r) \qquad \forall r \geq 0, \tag{11}$$

$$P_{\alpha}(t) \ \varphi \in C_b(K_{\alpha}), \qquad \omega_{P_{\alpha}(t) \ \varphi}(r) \le \omega_{\varphi}(e^{ct}r) \qquad \forall r \ge 0,$$
 (12)

$$\lim_{\varepsilon \downarrow 0} P_{\alpha}^{\varepsilon}(t) \varphi(x) = P_{\alpha}(t) \varphi(x) \qquad \forall x \in K_{\alpha}, \tag{13}$$

$$P_{\alpha}(s) P_{\alpha}(t) \varphi(x) = P_{\alpha}(t+s) \varphi(x), \qquad \forall x \in K_{\alpha}. \tag{14}$$

In particular, $(P_{\alpha}(t))_{t\geq 0}$ is a Markov semigroup acting on $C_b(K_{\alpha})$.

Proof. For (12), notice that, by (8), for all $x, x' \in K_{\alpha}$:

$$\begin{split} |P_{\mathbf{a}}(t) \; \varphi(x) - P_{\mathbf{a}}(t) \; \varphi(x')| &\leqslant \mathbb{E} \big[\left| \varphi(X_{\mathbf{a}}(t, \, x)) - \varphi(X_{\mathbf{a}}(t, \, x')) \right| \big] \\ &\leqslant \mathbb{E} \big[\left. \omega_{\varphi}(\|X_{\mathbf{a}}(t, \, x) - X_{\mathbf{a}}(t, \, x')\|) \big] \\ &\leqslant \omega_{\varphi}(e^{ct} \; \|x - x'\|), \end{split}$$

and (11) follows analogously. Equation (13) is a consequence of (b) in the proof of Theorem 1 and (11). It is well known that $(P_{\alpha}^{\epsilon}(t))_{t\geq 0}$ is a semi-group acting on $C_b(H)$: since the family of probability measures $\{m^{\epsilon}\}_{\epsilon>0}$, where m^{ϵ} is the law of $X_{\alpha}^{\epsilon}(s,x)$, and the family of functions $\{P_{\alpha}^{\epsilon}(t),\varphi\}_{\epsilon>0}$ satisfy the Hypothesis of Lemma 1; Eq. (14) follows.

Lemma 4. For all $\varphi \in C_b(H)$, $\lim_{\alpha \downarrow 0} P_{\alpha}(t) \varphi(x) = P_0(t) \varphi(x)$, $t \geqslant 0$, $x \in K_0$.

Proof. If $x \in K_0 \cap C_0(0, 1)$, then the map $0 < \alpha \mapsto X_{\alpha}^{\varepsilon}(t, x)(\xi)$ is non-decreasing for all $(t, \xi) \in \mathcal{O}$, $\varepsilon > 0$. Therefore,

$$\begin{split} \lim_{\alpha\downarrow 0} X_{\alpha}(t,\,x)(\xi) &= \sup_{\alpha>0} X_{\alpha}(t,\,x)(\xi) = \sup_{\alpha>0} \sup_{\varepsilon>0} X_{\alpha}^{\varepsilon}(t,\,x)(\xi) \\ &= \sup_{\varepsilon>0} \sup_{\alpha>0} X_{\alpha}^{\varepsilon}(t,\,x)(\xi) = \sup_{\varepsilon>0} X_{0}^{\varepsilon}(t,\,x)(\xi) \\ &= X_{0}(t,\,x)(\xi), \end{split}$$

since $\sup_{\alpha>0} X^{\varepsilon}_{\alpha}(t,x)(\cdot) = X^{\varepsilon}_{0}(t,x)(\cdot)$ by the uniqueness of solutions to (6). The general case follows by (12) and a density argument.

4. THE BROWNIAN BRIDGE RESTRICTED TO K_{α} AS SYMMETRIZING MEASURE FOR X_{α} , $\alpha > 0$

Recall that the Ornstein-Uhlenbeck process

$$Z(t, x) := e^{tA}x + \int_0^t e^{(t-s)A} dW_s \qquad t \ge 0, \qquad x \in H,$$

is, under our assumptions, a continuous Markov process with values in H, admitting as symmetrizing measure $\mu := \mathcal{N}(0, (-2A)^{-1})$, i.e., the Gaussian measure on H with 0 mean and covariance operator $(-2A)^{-1}$.

Our next lemma identifies μ with a well-known probability measure on $C_0(0, 1)$: the law of the Brownian bridge. Recall that the Brownian bridge is defined as a linear Brownian motion $(w_\tau)_{\tau \in [0, 1]}$, conditioned to be 0 at $\tau = 1$, and can be realized as $[0, 1] \ni \tau \mapsto w_\tau - \tau w_1$. The law of the Brownian bridge is concentrated on $C_0(0, 1)$ and is the unique Gaussian measure on $\mathbb{R}^{[0, 1]}$ with 0 mean and covariance function: $\Gamma(\tau, \sigma) = \tau \wedge \sigma - \tau \sigma$, σ , $\tau \in [0, 1]$, (see [7, Chap. I]).

LEMMA 5. The measure μ coincides with the law of the Brownian bridge.

Proof. Recall that the measure μ is concentrated on $C([0, 1]) \subset H$. By definition of Gaussian measures, the following holds for all $h, k \in H$:

$$\int_{H} \langle x, h \rangle \langle x, k \rangle \, \mathcal{N}(0, (-2A)^{-1})(dx) = \langle (-2A)^{-1} \, h, k \rangle. \tag{15}$$

Since the operator $(-2A)^{-1}$ can be expressed as an integral operator with kernel: $\xi \wedge \sigma - \xi \sigma$, $\xi, \sigma \in [0, 1]$, then setting in (19) $h = \chi_{[0, t]}$, $k = \chi_{[0, s]}$, $s, t \in [0, 1]$, and differentiating with respect to t and s, we obtain:

$$\int_{C([0,1])} x(t) x(s) d\mu(x) = t \wedge s - ts. \quad \blacksquare$$

Lemma 5 allows us to calculate explicitly $\mu(K_{\alpha})$:

$$\mu(K_{\alpha}) = 1 - \exp\{-2\alpha^2\}, \qquad \alpha \geqslant 0, \tag{16}$$

(see [7, Chap. III, Exercise (3.14)]). We introduce the functions

$$F: L^{N+1}(0,1) \subset H \mapsto \mathbb{R}, \qquad F(x) := \int_0^1 d\xi \int_0^{x(\xi)} f(\xi, s) \, ds,$$

$$V_{\alpha}: H \mapsto [0, +\infty),$$

$$V_{\alpha}(x) := \frac{1}{2} \int_0^1 [(\alpha + x(\xi))^-]^2 \, d\xi = \frac{1}{2} [d(x, K_{\alpha})]^2,$$

where N is the degree of p in (H4) and $d(x, K_{\alpha})$ denotes the distance in H of x from the closed convex set K_{α} , $\alpha \ge 0$. Notice that $\mu(L^{N+1}(0, 1)) = 1$,

and by (H2), (H3), and (H4), $\exp(-F)$ is well defined and satisfies for all $x \in H$,

$$\exp(-2F(x)) \leqslant \exp\left(\langle a, x \rangle + \frac{\lambda}{2} \|x\|^2\right) \leqslant \exp(C \|a\|^2) \exp\left(\frac{\rho}{2} \|x\|^2\right) \quad (17)$$

for some $\lambda < \rho < \pi^2$, C > 0. Since $-2A \ge \pi^2 > \rho$, we have:

$$\int_{H} \exp(-2F(x)) \, \mu(dx) \leq e^{C \|a\|^{2}} \int_{H} \exp\left(\frac{\rho}{2} \|x\|^{2}\right) \mathcal{N}(0, (-2A)^{-1})$$

$$= e^{C \|a\|^{2}} \frac{1}{\sqrt{\det(I + \rho(2A)^{-1})}} < \infty. \tag{18}$$

 V_{α} is Fréchet differentiable on H with Lipschitz-continuous gradient $\nabla V_{\alpha}(x) = -(\alpha + x(\cdot))^-$, $x \in H$. F belongs to the Sobolev space $W^{1,\,p}(H,\mu)$ for all $p \in [1,\,\infty[$, with gradient $\nabla F(x) = f(\cdot,x(\cdot))$, $x \in L^{2N}(0,1)$, and $\mu(L^{2N}(0,1)) = 1$. Equation (6) can now be written in the following form:

$$\begin{cases} dX_{\varepsilon}^{\alpha} = \left(AX_{\varepsilon}^{\alpha} - \nabla F(X_{\varepsilon}^{\alpha}) - \frac{1}{\varepsilon} \nabla V_{\alpha}(X_{\varepsilon}^{\alpha})\right) dt + dW \\ X_{\varepsilon}^{\alpha}(0, x) = x \in H \end{cases}$$
(19)

If $\varepsilon > 0$, (19) is a gradient system, namely (see [4, Sect. 8.6], and [5, Chap. 2]):

Proposition 1. If $\varepsilon > 0$, then $\forall \alpha \ge 0$, setting

$$Z_{\alpha,\,\varepsilon} := \int_{\mathcal{U}} e^{-2F - (2V_{\alpha}/\varepsilon)} \, d\mu > 0,$$

the probability measure on H,

$$v_{\alpha,\,\varepsilon}^{F}(dx) := \frac{1}{Z_{\alpha,\,\varepsilon}} \exp\left\{-2F(x) - \frac{2}{\varepsilon} V_{\alpha}(x)\right\} \mu(dx),$$

is symmetrizing for the process $\{X_{\sigma}^{\varepsilon}(t,x): t \geq 0, x \in H\}$.

By (16), if $\alpha > 0$ then $\mu(K_{\alpha}) > 0$, and we can introduce the probability measures v_{α} and v_{α}^{F} on K_{α} , with $Z_{\alpha} := \int_{K} e^{-2F} d\mu > 0$:

$$dv_{\alpha} := \frac{1}{\mu(K_{\alpha})} 1_{K_{\alpha}} d\mu, \qquad dv_{\alpha}^{F} := \frac{1}{Z_{\alpha}} 1_{K_{\alpha}} e^{-2F} d\mu.$$
 (20)

THEOREM 2. If $\alpha > 0$, v_{α}^F is a symmetrizing measure for the processes $\{X_{\alpha}(t,x): t \geq 0, x \in K_{\alpha}\}$ and $\{X_{\alpha}(t,x): t \geq 0, x \in K_{\alpha} \cap C_0(0,1)\}$.

Proof. First, we have:

$$\frac{1}{Z_{\alpha}} 1_{K_{\alpha}}(x) e^{-2F(x)} = \lim_{\varepsilon \downarrow 0} \frac{1}{Z_{\alpha, \varepsilon}} \exp\left\{-2F(x) - \frac{2}{\varepsilon} V_{\alpha}(x)\right\} \quad \forall x \in H,$$

$$\frac{1}{Z_{\alpha, \varepsilon}} \exp\left\{-2F - \frac{2}{\varepsilon} V_{\alpha}\right\} \leqslant \frac{1}{Z_{\alpha, 1}} \exp\left\{\left\langle a, x \right\rangle + \frac{\lambda}{2} \|x\|^{2}\right\} \qquad \forall \varepsilon \in]0, 1].$$

Then, by (13), (17), and (18) and by the dominated convergence theorem, we obtain:

$$v_{\alpha}^F\!(\psi\;P_{\alpha}(t)\;\varphi) = \lim_{\varepsilon \downarrow 0} v_{\alpha,\,\varepsilon}^F(\psi\;P_{\alpha}^\varepsilon(t)\;\varphi) = \lim_{\varepsilon \downarrow 0} v_{\alpha,\,\varepsilon}^F(\varphi\;P_{\alpha}^\varepsilon(t)\;\psi) = v_{\alpha}^F(\varphi\;P_{\alpha}(t)\;\psi)$$

for all $\varphi, \psi \in C_b(H)$. Therefore, v_α^F is symmetrizing measure for $\{X_\alpha(t,x): t \geq 0, x \in K_\alpha\}$. Finally, $v_\alpha^F(K_\alpha \cap C_0(0,1)) = 1$ and, by Theorem 1, the set $K_\alpha \cap C_0(0,1)$ is invariant for $\{X_\alpha(t,\cdot): t \geq 0\}$, i.e., $x \in K_\alpha \cap C_0(0,1)$ implies $X_\alpha(t,x) \in K_\alpha \cap C_0(0,1)$ for all $t \geq 0$, a.s.

5. CONVERGENCE OF v_{α} TO v

Let $(B_{\tau})_{\tau \in [0,1]}$ be a 3-dimensional Brownian motion. We denote by ν the law of the 3-d Bessel Bridge, namely of the modulus of B, conditioned to be equal to 0 at $\tau = 1$. The probability measure ν is concentrated on $K_0 \cap C_0(0,1)$. In this section we prove the following:

Theorem 3. The measures $dv_{\alpha} = (1/\mu(K_{\alpha})) 1_{K_{\alpha}} d\mu$, $\alpha > 0$, converge weakly as $\alpha \downarrow 0$ to the law v of the 3-d Bessel bridge.

We recall the following result from [1]:

THEOREM 4. Let $(e_{\tau})_{\tau \in [0,1]}$ be a 3-d Bessel bridge, and let ζ be a random variable with uniform distribution on [0,1] and independent of e. Then the process:

$$(\beta_{\tau})_{\tau \in [0,1]}, \qquad \beta_{\tau} := e_{\tau \oplus \zeta} - e_{\zeta},$$

where \oplus denotes the sum mod 1, is a Brownian bridge.

Theorem 3 was proved in [8]. We give here a proof, based on Theorem 4, which seems to be promising for further developments.

We set e_{τ} : $C_0(0, 1) \mapsto \mathbb{R}$, $e_{\tau}(x) := x(\tau)$, $\tau \in [0, 1]$. Then $(e_{\tau})_{\tau \in [0, 1]}$ is a 3-d Bessel bridge under ν . By Theorem 4 and (16), we have for $\alpha > 0$, $\varphi \in C_b(H)$,

$$v_{\alpha}(\varphi) = \frac{1}{1 - \exp\{-2\alpha^2\}} \int_0^1 v(\varphi(e_{(\cdot \oplus r)} - e_r) \, 1_{(e_r \leqslant \alpha)}) \, dr, \tag{21}$$

since $\{e_{(\cdot \oplus r)} - e_r \geqslant -\alpha\} = \{e_r \leqslant \alpha\}.$

LEMMA 6. For all $r \in [0, 1]$, there exists a regular conditional distribution $\{v(\cdot | e_r = y) : y \ge 0\}$ of v given e_r , such that, setting

$$\delta_{\omega}(r, y) := v(\varphi(e_{(\cdot, \oplus, r)} - e_r) \mid e_r = y), \qquad \varphi \in C_b(H), \quad r \in [0, 1[, y \geqslant 0, y]]$$

we have for all $y \ge 0$:

$$\lim_{r\downarrow 0} \delta_{\varphi}(r,\sqrt{r(1-r)}\;y) = \lim_{r\uparrow 1} \delta_{\varphi}(r,\sqrt{r(1-r)}\;y) = v(\varphi).$$

Proof. Let $(B_{\tau})_{\tau \in [0, \infty)}$ and $(\hat{B}_{\tau})_{\tau \in [0, \infty)}$ be two independent 3-d Brownian motions and $r \in]0, 1[$. Denoting by $|\cdot|$ the euclidean norm in \mathbb{R}^3 , we set b := |B|, $\hat{b} := |\hat{B}|$,

$$\begin{split} \beta(z)(\tau) := B_{\tau} - \tau B_{1} + \tau z, & \hat{\beta}(z)(\tau) := \hat{B}_{\tau} - \tau \hat{B}_{1} + \tau z, \quad \tau \in [\,0,\,1\,], \quad z \in \mathbb{R}^{3}, \\ \pi_{r}, \hat{\pi}_{r} \colon L^{2}(0,\,\infty) \times L^{2}(0,\,\infty) \mapsto L^{2}(0,\,1), \\ \pi_{r}(c,\,d)(\tau) := \mathbf{1}_{[\,0,\,r\,]}(\tau) \, c(\tau) + \mathbf{1}_{\,]\,r,\,1\,]}(\tau) \, d(1-\tau), \\ \hat{\pi}_{r}(c,\,d)(\tau) := \mathbf{1}_{[\,0,\,1-r\,]}(\tau) \, d(1-r-\tau) + \mathbf{1}_{\,]1-r,\,1\,]}(\tau) \, c(\tau+r-1). \end{split}$$

(22)

For all $\varphi \in C_b(H)$, we set

$$v(\varphi(e) | e_r = y) := \mathbb{E}[\varphi(\pi_r(b, \hat{b})) | b_r = y = \hat{b}_{1-r}], \quad y \geqslant 0,$$
 (23)

$$\mathbb{E}[\varphi(b) \mid b(1) = y] := \int_{\mathcal{S}^2} \sigma(dn) \, \mathbb{E}[\varphi(|\beta(yn)|)], \qquad y \geqslant 0, \tag{24}$$

where S^2 is the unitary sphere in \mathbb{R}^3 and $\sigma(dn)$ is the normalized uniform distribution on S^2 . Then (23), respectively (24), is a regular conditional distribution of ν given e_r , resp. of $\mathbb{P}(b \in \cdot)$ given b(1). In particular, the law of $|\beta(0)|$ is equal to ν . By (22) and (23) we have:

$$v(\varphi(e_{(\cdot \oplus r)} - e_r) \mid e_r = y) = \mathbb{E}[\varphi(\hat{\pi}_r(b, \hat{b}) - y) \mid b_r = y = \hat{b}_{1-r}]. \tag{25}$$

Identifying $h \in L^2(0, 1)$ with $h1_{[0,1]} \in L^2(0, \infty)$, we set $\varphi_r: H \times H \mapsto \mathbb{R}$,

$$\varphi_r(h, k) := \varphi(\hat{\pi}_r(\sqrt{r} \, h(\ \cdot\ /r), \sqrt{1-r} \, k(\cdot/(1-r))) - \sqrt{r(1-r)} \, y).$$

Since for $\gamma > 0$, $\sqrt{\gamma} B_{(\cdot/\gamma)}$ is still a 3-d Brownian motion, we obtain by (25):

$$\begin{split} \delta_{\varphi}(r, \sqrt{r(1-r)} \, y) \\ &= \nu(\varphi(e_{(\cdot \oplus r)} - e_r) \mid e_r = \sqrt{r(1-r)} \, y) \\ &= \mathbb{E}[\, \varphi(\hat{\pi}_r(b, \hat{b}) - \sqrt{r(1-r)} \, y) \mid b_r = \sqrt{r(1-r)} \, y = \hat{b}_{1-r}] \\ &= \mathbb{E}[\, \varphi_r(b, \hat{b}) \mid b_1 = \sqrt{1-r} \, y, \, \hat{b}_1 = \sqrt{r} \, y \,]. \end{split} \tag{26}$$

Since for all $n \in S^2$ and $y \ge 0$,

$$\lim_{r\downarrow 0} \varphi_r(|\beta(\sqrt{1-r}\ yn)|, |\hat{\beta}(\sqrt{r}\ yn)|) = \varphi(|\hat{\beta}(0)(1-\cdot)|),$$

$$\lim_{r\uparrow 1} \varphi_r(|\beta(\sqrt{1-r}\ yn)|, |\hat{\beta}(\sqrt{r}\ yn)|) = \varphi(|\beta(0)|),$$

and since ν is invariant by the time-change $\tau \mapsto 1 - \tau$, the thesis follows by (24)–(26) and by the dominated convergence theorem.

Proof of Theorem 3. We split the integral on [0, 1] in (21) into two integrals on [0, 1/2] and [1/2, 1], respectively. Conditioning with respect to e_r and setting $c_{\alpha} := (1 - \exp\{-2\alpha^2\})$, we obtain

$$\begin{split} &\frac{1}{c_{\alpha}} \int_{0}^{1/2} dr \, v(\varphi(e_{(\cdot \oplus r)} - e_{r}) \, \mathbf{1}_{(e_{r} \leqslant \alpha)}) \\ &= \frac{1}{c_{\alpha}} \int_{0}^{1/2} dr \int_{0}^{\alpha} dy \, \sqrt{\frac{2}{\pi [r(1-r)]^{3}}} \, y^{2} \exp \left\{ -\frac{y^{2}}{2r(1-r)} \right\} \delta_{\varphi}(r, y) \\ &= \frac{1}{c_{\alpha}} \int_{0}^{1/2} dr \int_{0}^{\alpha/\sqrt{r(1-r)}} dy \, \sqrt{\frac{2}{\pi}} \, y^{2} \exp \left\{ -\frac{y^{2}}{2} \right\} \delta_{\varphi}(r, \sqrt{r(1-r)} \, y) \\ &= \frac{1}{c_{\alpha}} \sqrt{\frac{2}{\pi}} \int_{0}^{2\alpha} dy \exp \left\{ -\frac{y^{2}}{2} \right\} y^{2} \int_{0}^{1/2} dr \, \delta_{\varphi}(r, \sqrt{r(1-r)} \, y) \\ &+ \frac{\alpha^{2}}{c_{\alpha}} \sqrt{\frac{2}{\pi}} \int_{2\alpha}^{+\infty} dy \exp \left\{ -\frac{y^{2}}{2} \right\} \left(\frac{y}{\alpha} \right)^{2} \int_{0}^{\rho(\alpha, y)} dr \, \delta_{\varphi}(r, \sqrt{r(1-r)} \, y) \\ &=: I_{1}(\alpha) + I_{2}(\alpha), \qquad \rho(\alpha, y) := \frac{1}{2} \left(1 - \sqrt{1 - \left(\frac{2\alpha}{y} \right)^{2}} \right) \sim \left(\frac{\alpha}{y} \right)^{2} \end{split}$$

as $\alpha \downarrow 0$, y > 0. It is easy to see that $\lim_{\alpha \downarrow 0} I_1(\alpha) = 0$, while $I_2(\alpha)$ tends to $(1/2) \nu(\varphi)$ by Lemma 6 and the dominated convergence theorem. Since analogous computations hold for the integral on [1/2, 1], we obtain that $\nu_{\alpha}(\varphi)$ converges to $\nu(\varphi)$ and Theorem 3 is proved.

6. 3-D BESSEL BRIDGE AS SYMMETRIZING MEASURE FOR X_0

In this section we prove that the probability measure on K_0 :

$$dv^{F} := \frac{1}{\int_{K_{0}} \exp\{-2F\} \ dv} \exp\{-2F\} \ dv, \tag{27}$$

is well defined, that v_{α}^{F} , defined in (20), converges weakly to v^{F} as $\alpha \downarrow 0$, and that X_{0} is symmetric with respect to v^{F} . The difficulty is that $\exp(-2F)$ is not bounded, so that we cannot apply directly Theorem 3.

LEMMA 7. $v(e^{-2F}) \in]0, \infty[$ and v_{α}^{F} converges weakly to v^{F} as $\alpha \downarrow 0$.

Proof. We retain the notations of the proof of Lemma 6. Moreover, we set for all $\varphi \in C_b(H)$, $\varphi^F := \varphi e^{-2F}$. By Lemma 5 the law of $\beta(0)$ on $H \times H \times H$ is $\mu \otimes \mu \otimes \mu = \mathcal{N}(0, Q)$, $Q := (-2A)^{-1} \oplus (-2A)^{-1} \oplus (-2A)^{-1}$. Since $-2A \geqslant \pi^2 > \lambda$, we have by (17), (H4) and by $\mu(L^{N+1}(0, 1)) = 1$:

$$\int \exp\{-2F\} \ dv = \mathbb{E}[\exp\{-2F(|\beta(0)|)\}]$$

$$= \int_{H^3} \exp\{-2F(|z|)\} \ \mathcal{N}(0, Q)(dz) \in]0, \infty[.$$

Notice that

$$\exp\left\{\frac{\lambda}{2} \|\beta(yn)\|^{2}\right\} \leqslant e^{Cy^{2}} \exp\left\{\frac{\rho}{2} \|\beta(0)\|^{2}\right\}$$
 (28)

for some $\lambda < \rho < \pi^2$, C > 0, and:

$$\mathbb{E}\left[\exp\left\{\frac{\rho}{2}\|\beta(0)\|^2\right\}\right] = \frac{1}{\sqrt{\det(I-\rho Q)}} < \infty.$$
 (29)

By (23), (24), (28), and (29), $v(e^{-2F}(e) | e(r) = y) < \infty$, and therefore $\delta_{(\varphi^F)}(r, y)$ is well defined for all $r \in]0, 1[$ and $y \ge 0$. Arguing as in the proof of Lemma 6, by the dominated convergence theorem we have for all $\varphi \in C_h(H)$ and $y \ge 0$,

$$\lim_{r \downarrow 0} \delta_{(\varphi^F)}(r, \sqrt{r(1-r)} y) = \lim_{r \uparrow 1} \delta_{(\varphi^F)}(r, \sqrt{r(1-r)} y) = \nu(\varphi^F), \tag{30}$$

and the thesis follows proceeding as in the proof of Theorem 3.

THEOREM 5. v^F is a symmetrizing measure for the processes $\{X_0(t,x): t \ge 0, x \in K_0\}$ and $\{X_0(t,x): t \ge 0, x \in K_0 \cap C_0(0,1)\}$.

Proof. Arguing as in the proof of Theorem 2, the thesis follows from Lemmas 1, 3, 4, and 7, Theorems 1 and 2, and from $v^F(K_0 \cap C_0(0, 1)) = v(K_0 \cap C_0(0, 1)) = 1$.

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