Gauge and Perspective Duality

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Gauge optimization framework

• κ and ρ are closed gauge functions on \mathbb{R}^n and \mathbb{R}^m .

Definition 1 (Gauge)

A convex function $\kappa: \mathcal{X} \to \overline{\mathbb{R}} = \mathbb{R} \cup \{+\infty\}$ a gauge if it is non-negative, positive honogeneous and vanishes at the origin.

- $\sigma < \rho(b)$, otherwise x = 0 is optimal.
- Examples of gauges:
 - ▶ norm || · ||
 - ightharpoonup indicator function of convex cone $\delta_{\mathcal{K}}$

Preliminaries: polar

ullet The polar of a gauge κ defined as

$$\kappa^{\circ}(y) = \inf\{\mu > 0 \mid \langle x, y \rangle \le \mu \kappa(x), \forall x\}$$

is a closed gauge. It is the generalization of dual norm.

- $\kappa^{\circ \circ} = \operatorname{cl} \kappa = \kappa^{**}$.
- For a convex set C, its polar is

$$\mathcal{C}^{\circ} = \{ y \mid \langle x, y \rangle \le 1, \forall x \in \mathcal{C} \}$$

and its antipolar is

$$\mathcal{C}' = \{ y \mid \langle x, y \rangle \ge 1, \forall x \in \mathcal{C} \}$$

- $\operatorname{epi} \kappa^{\circ} = \{(y, -\lambda) | (y, \lambda) \in (\operatorname{epi} \kappa)^{\circ} \}$
- $\kappa^{\circ}(y) = \delta_{\mathcal{U}_{\kappa}}^{*}(y)$ where $\mathcal{U}_{\kappa} = \{x \mid \kappa(x) \leq 1\}$
- $\kappa^*(y) = \delta_{\mathcal{U}_{\kappa^\circ}}(y)$
- Hölder like inequality

$$\langle x, y \rangle \le \kappa(x) \kappa^{\circ}(y), \forall x \in \operatorname{dom} \kappa, y \in \operatorname{dom} \kappa^{\circ}$$

Preliminaries

 \bullet Representation of gauge function: the gauge of a nonempty convex set ${\cal C}$ is

$$\gamma_{\mathcal{C}}(x) = \inf\{\lambda > 0 \mid x \in \lambda \mathcal{C}\}\$$

For a gauge κ , we have

$$\kappa = \gamma_{\mathcal{U}_{\kappa}}$$

• Results to deal with case of $\sigma = 0$: let $\mathcal{H}_{\kappa} = \{x \mid \kappa(x) = 0\}$,

$$\mathcal{U}_{\kappa}^{\circ} = \mathcal{U}_{\kappa^{\circ}}, \ \mathcal{U}_{\kappa}^{\infty} = \mathcal{H}_{\kappa}, \ (\operatorname{dom} \kappa)^{\circ} = \mathcal{H}_{\kappa}, \ \mathcal{H}_{\kappa}^{\circ} = \operatorname{cl} \operatorname{dom} \kappa^{\circ}$$

• Let κ_1 and κ_2 be gauges. Then $\kappa(x_1,x_2):=\kappa_1(x_1)+\kappa_2(x_2)$ is a gauge and its polar is

$$\kappa^{\circ}(y_1, y_2) = \max\{\kappa_1^{\circ}(y_1), \kappa_2^{\circ}(y_2)\}$$

Gauge duality

Different from Lagrange dual

$$\max_{y} \quad \langle b, y \rangle - \sigma \rho^{\circ}(y)$$
s.t. $\kappa^{\circ}(A^{T}y) \leq 1$ (Ld)

Gauge dual has the form

Goal:

- Derive related duality theory (weak and strong duality)
- Derive related optimal condition (like KKT)

Deriving gauge dual: a quick intuition

$$\min_{\substack{x \in \mathcal{X} \\ \text{s.t.} \quad x \in \mathcal{C}}} \kappa(x) \tag{1}$$

$$\min_{\substack{x \in \mathcal{X} \\ \text{s.t.}}} \kappa^{\circ}(y) \\
\text{s.t.} \quad y \in \mathcal{C}'$$
(2)

Then for any $x \in \mathcal{C}, y \in \mathcal{C}'$, we have

$$\kappa(x)\kappa^{\circ}(y) \ge \langle x, y \rangle \ge 1$$

as weak duality. Hopefully we can have strong duality

$$\kappa(x)\kappa^{\circ}(y) = 1.$$

When $C = \{x \mid \rho(b - Ax) \leq \sigma\}$, we need to derive corresponding C'. It turns out (2) becomes Gd.

Assumptions on feasibility

Feasible region

$$\mathcal{F}_p := \{ u \mid \rho(b-u) \le \sigma \}, \quad , \mathcal{F}_d = \{ y \mid \langle b, y \rangle - \sigma \rho^{\circ}(y) \ge 1 \}$$

• Convention: when $\sigma = 0$, do the replacement

$$(\rho, \sigma) \to (\delta_{\mathcal{H}_{\rho}}, 1), \quad \sigma \rho^{\circ} := \delta \operatorname{cl} \operatorname{dom} \rho^{\circ} \equiv \delta_{\mathcal{H}_{\rho}}^{\circ}$$

Feasibility of Gp and Gd.

$$A^{-1}\mathcal{F}_p \cap \operatorname{dom} \kappa \neq \emptyset, \quad A^T\mathcal{F}_d \cap \operatorname{dom} \kappa^{\circ} \neq \emptyset$$

• Relatively strictly feasibility (strict: ri replaced by int)

$$A^{-1}(\operatorname{ri} \mathcal{F}_p) \cap (\operatorname{ri} \operatorname{dom} \kappa) \neq \emptyset, \quad A^T \operatorname{ri} (\mathcal{F}_d) \cap \operatorname{ri} (\operatorname{dom} \kappa^{\circ}) \neq \emptyset$$

where

$$\begin{split} \operatorname{ri} \mathcal{F}_p &= \begin{array}{l} \{u \mid b-u \in \operatorname{ri} \operatorname{dom} \rho, \rho(b-u) < \sigma\} & \text{if } \sigma > 0 \\ \{u \mid b-u \in \operatorname{ri} \mathcal{H}_\rho\} & \text{if } \sigma = 0 \end{array} \\ \operatorname{ri} \mathcal{F}_d &= \begin{array}{l} \{y \mid y \in \operatorname{ri} \operatorname{dom} \rho^\circ, \langle b, y \rangle - \sigma \rho^\circ(y) > 1\} & \text{if } \sigma > 0 \\ \{y \mid y \in \operatorname{ri} \mathcal{H}_\rho^\circ, \langle b, y \rangle > 1\} & \text{if } \sigma = 0 \end{array} \end{split}$$

General perturbation framework

Theorem 1 ([1])

Consider a proper, closed, convex perturbation function F on $\mathbb{R}^n \times \mathbb{R}^m$, let $p(u) = \inf_x F(x,u)$ and $q(v) = \inf_y F^*(v,y)$. The optimal value of primal-dual pair is p(0) and $p^{**}(0) = -q(0)$.

- (a) $p(0) \ge -q(0)$
- (b) If $0 \in \operatorname{ridom} p$, then p(0) = -q(0) and if finite, the infimal q(0) is attained with $\partial p(0) = \arg\max_y -F^*(0,y)$. If $0 \in \operatorname{ridom} q$, then p(0) = -q(0) and if finite, the infimal p(0) is attained with $\partial q(0) = \arg\min_x F(x,0)$.
- (c) The set $\arg\max_y -F^*(0,y)$ is nonempty and bounded if $0 \in \operatorname{int} \operatorname{dom} p$ and p(0) is finite. The set $\arg\min_x F(x,0)$ is nonempty and bounded if $0 \in \operatorname{int} \operatorname{dom} q$ and q(0) is finite.
- (d) Optimal solutions are characterized jointly by the conditions:

$$\begin{array}{l}
\bar{x} \in \arg\min_{x} F(x,0) \\
\bar{y} \in \arg\max_{y} -F^{*}(0,y) \\
F(\bar{x},0) = -F^{*}(0,\bar{y})
\end{array}
\right\} \iff (0,\bar{y}) \in \partial F(\bar{x},0) \iff (\bar{x},0) \in \partial F^{*}(0,\bar{y})$$

A perturbation for gauge duality

Consider the primal and dual value functions

$$v_{p}(u) = \inf_{\mu>0,x} \{\mu \mid \rho(b - Ax + \mu u) \leq \sigma, \kappa(x) \leq \mu\}$$

$$(\lambda := 1/\mu, w := x/\mu)$$

$$= \inf_{\lambda>0,w} \{1/\lambda \mid \rho(b\lambda - Aw + u) \leq \sigma\lambda, \kappa(w) \leq 1\}$$

$$v_{d}(t,\theta) = \inf_{y} \{\kappa^{\circ}(A^{T}y + t) \mid \langle b, y \rangle - \sigma\rho^{\circ}(y) \geq 1 + \theta\}$$
(3)

Define the convex function $F(w, \lambda, u) :=$

$$-\lambda + \delta_{\operatorname{epi}\rho \times \mathcal{U}_{\kappa}} \left(W \begin{bmatrix} w \\ \lambda \\ u \end{bmatrix} \right) \text{ where } W := \begin{bmatrix} -A & b & I_{m} \\ 0 & \sigma & 0 \\ I_{n} & 0 & 0 \end{bmatrix}$$

- W is nonsingular
- $(0,0,0) \in \text{dom } F$ and F is closed and proper
- Let $p(u) := \inf_{\lambda \geq 0, w} F(w, \lambda, u)$ and $q(t, \theta) := \inf_y F^*(t, \theta, y)$, then $v_p(u) = -1/p(u)$ and given both are finite, and $v_p(u) = 0 \Longleftrightarrow p(u) = -\infty$, $p(u) = 0 \Longleftrightarrow v_p(u) = +\infty$.

A perturbation for gauge duality cont.

$$\begin{split} F^*(t,\theta,y) &= \operatorname{cl\ inf}_{z,\beta,r} \left\{ \delta^*_{\operatorname{epi}\,\rho \times \mathcal{U}_\kappa} \middle| \ W^T \left[\begin{array}{c} z \\ \beta \\ r \end{array} \right] = \left[\begin{array}{c} t \\ \theta \\ y \end{array} \right] + \left[\begin{array}{c} 0 \\ 1 \\ 0 \end{array} \right] \right\} \\ &= \delta^*_{\operatorname{epi}\,\rho} \times \mathcal{U}_\kappa \left(\begin{array}{c} \sigma^{-1}(1+\theta-\langle b,y\rangle \\ t+A^T y \end{array} \right) \\ &= \delta^*_{\operatorname{epi}\,\rho} \left(\begin{array}{c} y \\ \sigma^{-1}(1+\theta-\langle b,y\rangle \end{array} \right) + \delta^*_{\mathcal{U}_\kappa}(t+A^T y) \\ &= \delta_{\operatorname{epi}\,\rho^\circ} \left(\begin{array}{c} y \\ -\sigma^{-1}(1+\theta-\langle b,y\rangle \end{array} \right) + \kappa^\circ(t+A^T y) \end{split}$$
 Note $F^*(0,0,y) = \left\{ \begin{array}{c} \kappa^\circ(A^T y) & \text{if } \langle b,y\rangle - \sigma\rho^\circ(y) \geq 1 \\ +\infty & \text{otherwise} \end{array} \right\}$ and Gd

is $q(0,0) = \inf_{y} F^*(0,0,y)$

In summary, $-1/v_p$ and v_d plays the role of p and q in Theorem 1.

Gauge duality theorem

Theorem 2

Let $\nu_p := v(0)$ and $\nu_d := v_d(0,0)$. Then for Gp and Gd, we have

- (a) $1/\nu_p \le \nu_d$ and $1/\nu_d \le \nu_p$. If $\nu_p = 0$ (resp. $\nu_d = 0$), then Gd (resp. Gp) is infeasible.
- (b) (Weak duality) If x and y are primal and dual feasible, then

$$1 \le \nu_p \nu_d \le \kappa(x) \kappa^{\circ}(A^T y)$$

(c) If the dual(resp. primal) is feasible and the primal(resp. dual) is relatively strictly feasible, then $\nu_p \nu_d = 1$ and $Gd(resp.\ Gp)$ attains its optimal value.

Lemma 1

If the primal Gp is relatively strictly feasible, then $0 \in \operatorname{ri} \operatorname{dom} p$. if the dual Gd is relatively strictly feasible, then $0 \in \operatorname{ri} \operatorname{dom} q$. If further assume strict feasibility, the $\operatorname{ri}(\cdot)$ can be replaced by $\operatorname{int}(\cdot)$.

Proof of Theorem 2

- Proof of Lemma 1
 - ▶ Note $u \in \text{dom } p$ iff

$$(u,0,0) \in \begin{bmatrix} A & -b \\ 0 & -\sigma \\ -I & 0 \end{bmatrix} \begin{bmatrix} w \\ \lambda \end{bmatrix} + \operatorname{epi} \rho \times \mathcal{U}_{\kappa} \text{ is solvable.}$$

- Then everything is on explicit calculation of relative interior.
- Same for the dual.
- Proof of Theorem 2: use Theorem 1.
 - ▶ $p(0) \ge -q(0)$ implies (a).
 - ▶ Both p(0) and q(0) are finite given primal and dual feasibility, then (a) implies (b).
 - ▶ Lemma 1 implies $0 \in ri dom p$. By part (b) of Theorem 1, strong duality holds. Same for the dual.

Gauge multipliers and sensitivity

Theorem 3

For gauge primal-dual pair Gp and Gd, we have

(a) If the primal is relatively strictly feasible and the dual is feasible, then the set of optimal solutions for the dual is nonempty and coincides with

$$\partial p(0) = \partial (-1/v_p)(0)$$

If it is further assumed that the primal is strictly feasible, then the set of optimal solutions to the dual is bounded.

(b) If the dual is relatively strictly feasible and the primal is feasible, then the set of optimal solutions for the primal is nonempty with solutions $x^* = w^*/\lambda^*$ where

$$(w^*, \lambda^*) \in \partial v_d(0,0)$$
 and $\lambda^* > 0$

If it is further assumed that the dual is strictly feasible, then the set of optimal solutions to the primal is bounded.

Gauge optimality conditions

Theorem 4

Suppose both problems of the gauge dual pair Gp and Gd are relatively strictly feasible, and the pair (x^*, y^*) is primal-dual feasible. Then (x^*, y^*) is primal-dual optimal if and only if it satisfies the conditions:

$$\begin{array}{ll} \textit{(a)} & \rho(b-Ax^*) = \sigma \text{ or } \rho^{\circ}(y^*) = 0 & \textit{(primal activity)} \\ \textit{(b)} & \langle b, y^* \rangle - \sigma \rho^{\circ}(y^*) = 1 & \textit{(dual activity)} \\ \textit{(c)} & \langle x^*, A^Ty^* \rangle = \kappa(x^*)\kappa^{\circ}(A^Ty^*) & \textit{(objective alignment)} \\ \textit{(d)} & \langle b-Ax^*, y^* \rangle = \sigma \rho^{\circ}(y^*) & \textit{(constraint alignment)} \end{array}$$

Proof of Theorem 4

"if": note that by

$$\kappa(x^*)\kappa^{\circ}(A^Ty^*) \stackrel{(c)}{=} \langle x^*, A^Ty^* \rangle \stackrel{(b),(d)}{=} 1$$

strong duality holds, (x^*, y^*) is optimal.

- "only if": W.l.o.g. assume $\sigma > 0$ ($\sigma = 0$ can be done with the replacement).
 - ▶ If (x^*, y^*) is optimal, since $\kappa^{\circ}(A^Ty)$ and $\langle b, y \rangle \sigma \rho^{\circ}(y)$ in Gd are positive homogeneous, (b) must hold by optimality of y^* .
 - Note $\kappa(x^*)$ and $\kappa^{\circ}(A^Ty^*)$ are nonzero and finite. Next we will use part (d) in Theorem 1 to prove the remaining parts.
 - Let $\lambda^*:=1/\kappa(x^*)$ and $w^*:=\lambda^*x^*$, we have $\kappa(w^*)=1$. By Theorem 1 (d), $(0,0,y^*)\in\partial F(w^*,\lambda^*,0)$. Since the primal is relatively strictly feasible, we have

$$\partial F(w, \lambda, 0) = \begin{bmatrix} 0 \\ -1 \\ 0 \end{bmatrix} + W^T \mathcal{N}_{\text{epi } \rho \times \mathcal{U}_{\kappa}} \left(\begin{bmatrix} -Aw + b\lambda \\ \sigma \lambda \\ w \end{bmatrix} \right)$$

Proof of Theorem 4 cont.

"only if" (cont.):

$$\mathcal{N}_{\mathrm{epi}\,\rho\times\mathcal{U}_{\kappa}}\left(\left[\begin{array}{c}-Aw+b\lambda\\\sigma\lambda\\w\end{array}\right]\right)=\mathcal{N}_{\mathrm{epi}\,\rho}\left(\left[\begin{array}{c}-Aw+b\lambda\\\sigma\lambda\end{array}\right]\right)\times\mathcal{N}_{\mathcal{U}_{\kappa}}\left(w\right)$$

▶ If $\rho(\lambda^*b - Aw^*) = \lambda^*\sigma$ ((a) holds), we have

$$\mathcal{N}_{\text{epi}\,\rho}\left(\left[\begin{array}{c} -Aw^* + b\lambda^* \\ \sigma\lambda^* \end{array}\right]\right) = \text{cone}\left(\partial\rho(b\lambda^* - Aw^*)\right) \times \{-1\}$$

and $\mathcal{N}_{\mathcal{U}_{\cdot\cdot}}(w^*) = \{v \mid \kappa^{\circ}(v) \leq \langle v, w^* \rangle \}$. Hence

$$\partial F(w^*, \lambda^*, 0) = \left\{ \begin{bmatrix} v - \mu A^T z \\ \mu(\langle b, z \rangle - \sigma) - 1 \\ \mu z \end{bmatrix} \middle| \begin{array}{l} \mu \ge 0, \\ z \in \partial \rho(b\lambda^* - Aw^*), \\ v \in \mathcal{N}_{\mathcal{U}_{\kappa}}(w^*) \end{array} \right\}$$

We know there exists $\mu^*>0$, $z^*\in\partial\rho(b\lambda^*-Aw^*)$ and $y^*=\mu^*z^*$ such that $v^*=A^Ty^*$, $\mu^*(\langle b,z^*\rangle-\sigma)=1$ and $\kappa^\circ(v^*)\leq\langle v^*,w^*\rangle$

Proof of Theorem 4 cont.

- "only if" (cont.):
 - - \triangleright Eliminate v^* , there exists

$$\left\{ \begin{array}{l} \mu^* > 0, z^* \in \partial \rho(b\lambda^* - Aw^*), y^* = \mu^*z^* \\ (\langle b, y^* \rangle - \sigma \mu^*) = 1 \\ \kappa(w^*) \kappa^{\circ}(A^Ty^*) \leq \langle A^Ty^*, w^* \rangle \end{array} \right.$$

Hence (c) holds.

Note

$$\left\{ \begin{array}{l} y^* \in \mu^* \partial \rho(b\lambda^* - Aw^*) \\ \partial \rho(u) = \arg \max_y \{ \langle u, y \rangle | \rho^{\circ}(y) \leq 1 \} \end{array} \right.$$

we have $\rho(b\lambda^* - Aw^*) = \langle b\lambda^* - Aw^*, y^*/\mu^* \rangle \ge 0$.

If $\rho(b\lambda^* - Aw^*) > 0$, then $\rho^{\circ}(y^*/\mu^*) = 1$, we have

$$\rho^{\circ}(y^*/\mu^*)\lambda^*\sigma = \rho^{\circ}(y^*/\mu^*)\rho(b\lambda^* - Aw^*) = \langle b\lambda^* - Aw^*, y^*/\mu^* \rangle,$$

hence (d) holds.

 $If \rho(b\lambda^* - Aw^*) = 0, then$

$$0 = \rho^{\circ}(y^*)\rho(b\lambda^* - Aw^*) \ge \langle b\lambda^* - Aw^*, y^* \rangle \ge 0.$$

Hence $\rho^{\circ}(y^*)\lambda^*\sigma = \langle b\lambda^* - Aw^*, y^* \rangle$ and (d) holds.

Proof of Theorem 4 cont.

- "only if" (cont.):
 - ▶ If $\rho(\lambda^*b Aw^*) < \lambda^*\sigma$, then

$$\mathcal{N}_{\mathrm{epi}\,\rho}\left(\left[\begin{array}{c} -Aw^* + b\lambda^* \\ \sigma\lambda^* \end{array}\right]\right) = \mathcal{N}_{\mathrm{dom}\,\rho}\left(-Aw^* + b\lambda^*\right) \times \{0\}$$

Hence

$$\partial F(w^*, \lambda^*, 0) = \left\{ \begin{bmatrix} v - A^T z \\ \langle b, z \rangle - 1 \\ z \end{bmatrix} \middle| \begin{array}{l} z \in \mathcal{N}_{\operatorname{dom} \rho} \left(-Aw^* + b\lambda^* \right), \\ v \in \mathcal{N}_{\mathcal{U}_{\kappa}} \left(w^* \right) \end{array} \right\}$$

So we have

$$\begin{cases} y^* \in \mathcal{N}_{\mathrm{dom}\,\rho}\left(-Aw^* + b\lambda^*\right) & \Longrightarrow y^* \in (\mathrm{dom}\,\rho)^\circ \\ & \Longrightarrow \rho^\circ(y^*) = 0 \\ & \Longrightarrow (a) \text{ holds} \\ v^* = A^Ty^* \in \mathcal{N}_{\mathcal{U}_\kappa}\left(w^*\right) & \Longrightarrow (c) \text{ holds} \\ \langle b, y^* \rangle = 1 \end{cases}$$

and

$$\begin{array}{l} \langle b - Ax^*, y^* \rangle \stackrel{(c),(b)}{=} 1 + \sigma \rho^{\circ}(y^*) - \kappa(x^*) \kappa^{\circ}(A^Ty^*) \stackrel{s.d.}{=} \sigma \rho^{\circ}(y^*) \\ \Longrightarrow (d) \text{ holds} \end{array}$$

Recover primal solution from the dual

Corollary 1

Suppose that the primal-dual pair Gp and Gd are each relatively strictly feasible. If y^* is optimal for Gd, then for any primal feasible x the following conditions are equivalent:

- (a) x is optimal for Gp.
- (b) $\langle x, A^T y^* \rangle = \kappa(x) \kappa^{\circ} (A^T y^*)$ and $b Ax \in \partial (\sigma \rho^{\circ})(y^*)$
- (c) $A^Ty^* \in \kappa^\circ(A^Ty^*)\partial\kappa(x)$ and $b-Ax \in \partial(\sigma\rho^\circ)(y^*)$

where by convention, $\sigma \rho^{\circ} = \delta_{\operatorname{cl}\operatorname{dom}\rho^{\circ}}$ when $\sigma = 0$.

Example

Example 1

Consider basis pursuit denoising:

$$\min_{x} \{ \|x\|_1 \mid \|b - Ax\|_2 \le \sigma \} \tag{4}$$

$$\min_{y} \{ \|A^{T}y\|_{\infty} \mid \langle b, y \rangle - \sigma \|y\|_{2} \ge 1 \}$$
 (5)

After solving the dual, we have $z^* = A^T y^*$. Set $I(z) = \{i \mid |z_i| = ||z||_{\infty}$. By Corollary 1 part (b),

$$\langle x, z^* \rangle = ||x||_1 ||z^*||_{\infty}$$

 $b - Ax = \sigma(y^* / ||y^*||_2)$

Hence $x_i = 0$ for all $i \notin I(z^*)$ and $\operatorname{sign}(x_i) = \operatorname{sign}(z_i^*)$ for all $i \in I(z^*)$. To recover primal solution, we can solve

$$\min_{x} \{ \|b - Ax - \sigma(y^* / \|y^*\|_2) \|_2^2 \mid x_i = 0, \forall i \notin I(z^*) \}$$

The relationship between Lagrange and gauge multipliers

Theorem 5

Suppose that the gauge dual Gd is relatively strictly feasible and the primal Gp is feasible. Let Lp denote the Lagrange dual of Gd, and let ν_L denote its optimal value. Then

 z^* is optimal for Lp \iff $z^*/
u_L$ is optimal for Gp

Proof sketch:

- Perturbation function for Lagrange duality: $h(xy) = \inf_{x \in \mathbb{R}^n} \left\{ \frac{1}{2} \left(\frac{1}{2} A T x + \frac{1}{2} x \right) + \frac{1}{2} \right\}$
 - $h(w) = \inf_{y} \{ \kappa^{\circ} (A^{T} y + w) + \delta_{\langle b, \cdot \rangle \sigma \rho^{\circ} (\cdot) \geq 1} \}$
- Relate $\partial h(0)$ and $\partial v_d(0,0)$ by

$$\partial v_d(0,0) = \{(z, -h^*(z)) \mid z \in \partial h(0)\}$$

• Note $0 = \langle 0, z \rangle = h^*(z) + h(0) = h^*(z) + \nu_L$, so

$$\partial v_d(0,0) = \partial h(0) \times \{\nu_L\}$$

Extension to perspective duality

Given $f: \mathbb{R}^n \to \overline{\mathbb{R}}_+$ and $g: \mathbb{R}^m \to \overline{\mathbb{R}}_+$ closed, convex.

$$\min_{x} f(x)
\text{s.t.} g(b - Ax) \le \sigma$$
(Np)

$$\begin{aligned} & \min_{y,\alpha,\mu} & & f^{\sharp}(A^Ty,\alpha) \\ & \text{s.t.} & & \langle b,y \rangle - \sigma g^{\sharp}(y,\mu) \geq 1 - (\alpha + \mu) \end{aligned} \tag{Nd}$$

where $f^{\sharp} := (f^{\pi})^{\circ}$ and f^{π} is the perspective function of f, i.e.,

$$f^{\pi}(x,\lambda) = \begin{cases} \lambda f(x/\lambda) & \text{if } \lambda > 0 \\ f^{\infty}(x) & \text{if } \lambda = 0 \\ +\infty & \text{if } \lambda < 0 \end{cases}$$

Examples

$$f^{\sharp}(z, -\xi) = \inf\{\mu > 0 \mid \langle z, x \rangle - \xi \lambda \leq \mu f^{\pi}(x, \lambda), \forall x, \lambda\}$$

$$= \inf\{\mu > 0 \mid \langle z, x \rangle - \xi \lambda \leq \mu \lambda f(x/\lambda), \forall x, \lambda > 0\}$$

$$= \inf\{\mu > 0 \mid \langle z, \lambda x \rangle - \xi \lambda \leq \mu \lambda f(x), \forall x, \lambda > 0\}$$

$$= \inf\{\mu > 0 \mid \langle z, x \rangle \leq \xi + \mu f(x), \forall x\}$$

Example 2

- Let f be a closed gauge, then $f^\sharp(z,\xi) = f^\circ(z) + \delta_{\mathbb{R}_-}(\xi)$
- Let $f(x) = \sum_{i=1}^n f_i(x_i)$ where each f_i is convex and nonnegative, then $f^\pi(x,\lambda) = \sum_{i=1}^n f_i^\pi(x_i,\lambda)$ and $f^\sharp(z,\xi) = \max_{i=1,\dots,n} f_i^\sharp(z_i,\xi)$

A useful characterization of perspective-polar transform

Theorem 6

For any closed proper convex function f with $0 \in \text{dom } f$, we have $f^{\pi*}(z, -\xi) = \delta_{\text{epi } f^*}(z, \xi)$. If f is also nonnegative, $f^{\sharp}(z, -\xi) = \gamma_{\text{epi } f^*}(z, \xi)$

Proof.

•

$$\begin{split} f^{\pi*}(z,-\xi) &= \sup_{x,\lambda} \{\langle z,x\rangle - \lambda \xi - f^{\pi}(x,\lambda)\} \\ &= \sup_{x,\lambda>0} \{\langle z,x\rangle - \lambda \xi - \lambda f(x/\lambda)\} \\ &= \sup_{y,\lambda>0} \lambda \{\langle z,y\rangle - \xi - f(y)\} \\ &= \delta_{\{f^*(z)<\xi\}}(z,\xi) = \delta_{\mathrm{epi}\,f^*}(z,\xi) \end{split}$$

• If f is nonnegative, then $f^\pi(x,\lambda)=f^{\pi**}=\delta^*_{\mathrm{epi}\,f^*}(x,-\lambda)$, then $f^\sharp(z,-\xi)=f^{\pi\circ}(z,-\xi)=\delta^{*\circ}_{\mathrm{epi}\,f^*}(z,\xi)=\gamma_{\mathrm{epi}\,f^*}(z,\xi)$ since $\mathrm{epi}\,f^*$ contains the origin.

Derive perspective dual via lifting

Np is equivalent to the gauge problem:

where $\rho(z,\mu,\tau) := g^\pi(z,\tau) + \delta_{\{0\}}(\mu).$ Its gauge dual is

$$\min_{y,\alpha,\mu} f^{\pi \circ} \left(\begin{bmatrix} A^T & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} y \\ \alpha \\ \mu \end{bmatrix} \right)
\text{s.t.} \quad \langle (y,\alpha,\mu), (b,1,1) \rangle - \sigma \rho^{\circ}(y,\alpha,\mu) \ge 1$$
(7)

where
$$\rho^{\circ}(y,\alpha,\mu) = \max\{g^{\pi \circ}(y,\mu),\delta^{\circ}_{\{0\}}(\alpha)\} = g^{\sharp}(y,\mu)$$

Perspective duality

Theorem 7

Let ν_p and ν_d be the optimal value of Np and Nd, we have

- (a) $1/\nu_p \le \nu_d$ and $1/\nu_d \le \nu_p$. If $\nu_p = 0$ (resp. $\nu_d = 0$), then Nd (resp. Np) is infeasible.
- (b) (Weak duality) If x and (y, α, μ) are primal and dual feasible, then

$$1 \le \nu_p \nu_d \le f(x) f^{\sharp}(A^T y, \alpha)$$

- (c) If the dual(resp. primal) is feasible and the primal(resp. dual) is relatively strictly feasible, then $\nu_p \nu_d = 1$ and Nd(resp. Np) attains its optimal value.
 - Proof is based on Theorem 2.
 - Note Np(resp. Nd) is relatively strictly feasible iff the lifted formulation (6)(resp. (7)) is relatively strictly feasible.

Perspective optimality conditions

Theorem 8

Suppose both problems of the perspective dual pair Np and Nd are relatively strictly feasible, and the pair $(x^*, y^*, \alpha^*, \mu^*)$ is primal-dual feasible. Then $(x^*, y^*, \alpha^*, \mu^*)$ is primal-dual optimal if and only if it satisfies the conditions:

$$\begin{array}{ll} \textit{(a)} & g(b-Ax^*) = \sigma \text{ or } g^\sharp(y^*,\mu^*) = 0 & \textit{(primal activity)} \\ \textit{(b)} & \langle b,y^* \rangle - \sigma g^\sharp(y^*,\mu^*) = 1 - (\alpha^* + \mu^*) & \textit{(dual activity)} \\ \textit{(c)} & \langle x^*,A^Ty^* \rangle + \alpha^* = f(x^*)f^\sharp(A^Ty^*,\alpha^*) & \textit{(objective alignment)} \\ \textit{(d)} & \langle b-Ax^*,y^* \rangle + \mu^* = \sigma g^\sharp(y^*,\mu^*) & \textit{(constraint alignment)} \end{array}$$

Proof directly from Theorem 4.

Examples

Piecewise linear-quadratic constraints

$$g(y) = \sup_{u \in \mathcal{U}} \{ \langle u, y \rangle - \frac{1}{2} \|Lu\|_2^2 \}, \quad \mathcal{U} := \{ u \in \mathbb{R}^\ell \mid Wu \leq w \} \ni 0$$

with conjugate

$$g^*(y) = \delta_{\mathcal{U}}(y) + \frac{1}{2} ||Ly||^2$$

Hence

$$\begin{split} g^{\sharp}(y,\mu) &= \gamma_{\mathrm{epi}\,g^{*}}(y,-\mu) \\ &= \inf\{\lambda > 0 \mid (y,-\mu) \in \lambda \mathrm{epi}\,g^{*}\} \\ &= \inf\{\lambda > 0 \mid y \in \lambda \mathcal{U}, \frac{1}{2}\|Ly\|^{2} \leq -\mu\lambda\} \\ &= \delta_{\mathbb{R}_{-}}(\mu) + \max\{\gamma_{\mathcal{U}}(y), -\frac{1}{2\mu}\|Ly\|^{2}\} \\ &= \delta_{\mathbb{R}_{-}}(\mu) + \max\{\max_{i=1,\dots,k}\{W_{i}^{T}y/w_{i}\}, -\frac{1}{2\mu}\|Ly\|^{2}\} \end{split}$$

Examples cont.

If f is a closed gauge, then the perspective dual of $\min_x \{f(x) \mid g(b-Ax) \leq \sigma\}$ is

$$\min_{y,\mu,\xi} f^{\circ}(A^{T}y)$$
s.t. $\langle b, y \rangle + \mu - \sigma \xi = 1$

$$Wy \leq \xi w$$

$$-\frac{1}{2\mu} ||Ly||^{2} \leq \xi, \mu \leq 0, \xi \geq 0 \left(\Leftrightarrow \left\| \begin{bmatrix} 2Ly \\ \xi + 2\mu \end{bmatrix} \right\|_{2} \leq \xi - 2\mu \right)$$

• Sparse robust regression with Huber misfit: $f = \|\cdot\|_1$, $\mathcal{U} = \{u \mid \|u\|_{\infty} \leq 1\}$ and $L = \sqrt{\eta}I$, the dual becomes

$$\begin{aligned} \min_{y,\mu,\xi} & f^{\circ}(A^T y) \\ \text{s.t.} & \langle b, y \rangle + \mu - \sigma \xi = 1 \\ & \|y\|_{\infty} \leq \xi \\ & - \frac{\eta}{2\mu} \|Ly\|^2 \leq \xi, \mu \leq 0, \xi \geq 0 \end{aligned}$$

Conclusion

- Gauge duality under perturbation framework
- Extension to perspective duality
- Problems
 - Identify problem classes for which gauge duality is computationally advantageous
 - Primal-dual algorithm based on gauge duality
 - ► Comparison with Lagrange duality

