Optimization under Uncertainty using Exponential Cones

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Outline

Introduction

The Key Methodology of The ECP Approach to EV Charging

Robust CARA Optimization

▶ Deterministic optimization

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 - Example: we do not know whether the coin is unbiased
- ▶ How to rank decisions under uncertainty?
 - Decision criteria

Decision-making under uncertainty

► Expected utility theory [VNM47]

$$\max_{\boldsymbol{x} \in \mathcal{X}} \mathbb{E}_{\mathbb{P}} \left[u(f(\boldsymbol{x}, \tilde{\boldsymbol{z}})) \right]$$

where the utility function $u: \mathbb{R} \to \mathbb{R}$ is increasing.

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- ▶ Risk averse: $u(\cdot)$ is concave
- ► Maxmin expected utility [GS89]

$$\max_{\boldsymbol{x} \in \mathcal{X}} \inf_{\mathbb{P} \in \mathcal{F}} \mathbb{E}_{\mathbb{P}} \left[u(f(\boldsymbol{x}, \tilde{\boldsymbol{z}})) \right]$$

Many others...

How to solve optimization problems under uncertainty?

► Stochastic Optimization

$$\max_{\boldsymbol{x} \in \mathcal{X}} \mathbb{E}_{\mathbb{P}} \left[f(\boldsymbol{x}, \tilde{\boldsymbol{z}}) \right]$$

Fact: evaluating $\mathbb{E}_{\mathbb{P}}\left[\max\{\boldsymbol{a}^{\top}\tilde{\boldsymbol{z}}-b,0\}\right]$ is #P-hard for given $\boldsymbol{a}\in\mathbb{R}^n_+$, $b\in\mathbb{R}_+$, \tilde{z}_i 's are independent uniform on [0,1].

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$$\max_{\boldsymbol{x} \in \mathcal{X}} \mathbb{E}_{\mathbb{P}} \left[f(\boldsymbol{x}, \tilde{\boldsymbol{z}}) \right]$$

▶ Random approximation: Sample Average Approximation (SAA)

$$\max_{\boldsymbol{x}\in\mathcal{X}}\frac{1}{S}\sum_{s\in[S]}f(\boldsymbol{x},\hat{\boldsymbol{z}}^s)$$

- ► General: sampling oracle
- ► Effective: statistics and optimization perspectives
- Disadvantage: curse of dimensionality

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- lackbox Deterministic approximation: bound $\mathbb{E}_{\mathbb{P}}\left[f(oldsymbol{x}, ilde{oldsymbol{z}})
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 - Ad hoc: utilize special structures of f and \mathbb{P} , e.g., moments
 - Advantages: scalability, handle decision-dependent uncertainty
 - Disadvantages: suboptimality



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$$\max_{\boldsymbol{x} \in \mathcal{X}} \mathbb{E}_{\mathbb{P}} \left[f(\boldsymbol{x}, \tilde{\boldsymbol{z}}) \right]$$

▶ Distributionally Robust Optimization (DRO)

$$\max_{\boldsymbol{x} \in \mathcal{X}} \inf_{\mathbb{P} \in \mathcal{F}} \mathbb{E}_{\mathbb{P}} \left[f(\boldsymbol{x}, \tilde{\boldsymbol{z}}) \right]$$

- Tractability depends on underlying problem structures and choices of ambiguity sets
- ▶ Mostly duality-based reformulation techniques: DRO \rightarrow RO \rightarrow convex (conic) optimization

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Why do we care tractability?

- ... can be treated as actual sources of "immunized against uncertainty" decisions only if these problems are computationally tractable; when that is not the case, these settings become more wishful thinking than actual decision-making tool.
- Robust Optimization by Ben-Tal, El Ghaoui and Nemirovski

Exponential Conic Optimization

► Exponential cone: 3-dimensional closed convex cone

$$\mathcal{K}_{\exp} := \mathsf{cl}\left\{(x_1, x_2, x_3) \mid x_1 \ge x_2 \exp(x_3/x_2), x_2 > 0\right\}$$

i.e. closure of epigraph of perspective of exponential function.

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► Exponential cone programming (ECP):

$$egin{array}{ll} \min_{m{x}} & m{c}^{ op} m{x} \ \mathrm{s.t.} & m{A}m{x} - m{b} \in \mathcal{K}_{\mathrm{exp}} imes \cdots imes \mathcal{K}_{\mathrm{exp}} \ m{F}m{x} = m{g} \end{array}$$

- ► Generalization of linear programming (LP)
- Great modeling power:
 - Exponential cone ≥ power cone ≥ second-order cone
 - Many convex constraints involving exponential or logarithm functions are \mathcal{K}_{exp} -representable, e.g.

$$t \le -x \log x \iff (1, x, t) \in \mathcal{K}_{\exp}$$

Computational advances: efficient interior point algorithm based solvers such as MOSEK

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- Motivation of using MGFs:
 - ▶ Decomposability under independence of random variables
 - Close relation to exponential utility function and relative entropy based ambiguity set
 - \blacktriangleright The log-MGFs of many random variables are $\mathcal{K}_{\mathrm{exp}}$ -representable.

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- Structure:
 - ▶ An ECP approach to electric vehicle (EV) charging management
 - ► Robust CARA Optimization
 - Extensions and future work



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A large-scale stochastic program

The EV charging scheduling problem is

$$\min_{oldsymbol{x} \in \mathcal{X}} \mathbb{E}_{\mathbb{P}}\left[c(oldsymbol{x}, \widetilde{oldsymbol{z}})
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 (EV-SP)

where

$$c(\boldsymbol{x}, \tilde{\boldsymbol{z}}) \triangleq \sum_{s \in [T]} e_s \sum_{v \in \mathcal{V}_s} x_{v,s} \tilde{z}_v + d \max_{t \in [T]} \left\{ \sum_{v \in \mathcal{V}_t} x_{v,t} \tilde{z}_v \right\}$$

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Computationally challenging for SAA due to large scale of the problem: more than 80,000 random variables and 700,000 decision variables!

In uncapacitated case, $\tilde{z} \sim \mathbb{P}$ are independent Poisson with rate λ .

► Difficulty:

$$\sum_{s \in [T]} e_s f_s(\boldsymbol{x}, \boldsymbol{\lambda}) + d \mathbb{E}_{\mathbb{P}} \left[\max_{t \in [T]} \{ f_t(\boldsymbol{x}, \tilde{\boldsymbol{z}}) \} \right]$$

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- ► Motivation of using MGF
 - ▶ Determines non-negative random variables uniquely
 - $\blacktriangleright \ \, \text{Utilize independence:} \ \, \mathbb{E}_{\mathbb{P}}\left[e^{\sum_v\theta_v\tilde{z}_v}\right] = \prod \mathbb{E}_{\mathbb{P}}\left[e^{\theta_v\tilde{z}_v}\right]$

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▶ Bound the order statistic:

$$\mathbb{E}_{\mathbb{P}} \left[\max_{t \in [T]} \{ f_t(\boldsymbol{x}, \tilde{\boldsymbol{z}}) \} \right]$$

$$\leq \inf_{\mu > 0} \mu \log \sum_{t \in [T]} \mathbb{E}_{\mathbb{P}} \left[\exp \left(\frac{f_t(\boldsymbol{x}, \tilde{\boldsymbol{z}}) - f_t(\boldsymbol{x}, \boldsymbol{\lambda})}{\mu} \right) \right] + \max_{t \in [T]} \{ f_t(\boldsymbol{x}, \boldsymbol{\lambda}) \}$$

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Exploit stochastic independence:

$$\mu \log \mathbb{E}_{\mathbb{P}} \left[\exp \left(\frac{f_t(\boldsymbol{x}, \tilde{\boldsymbol{z}}) - f_t(\boldsymbol{x}, \boldsymbol{\lambda})}{\mu} \right) \right]$$

$$= \sum_{\boldsymbol{x} \in \mathcal{Y}} \mu \log \mathbb{E}_{\mathbb{P}} \left[\exp \left(\frac{x_{v,t} \tilde{\boldsymbol{z}}_v}{\mu} \right) \right] - f_t(\boldsymbol{x}, \boldsymbol{\lambda})$$

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▶ Exponential cone representable log-MGF of Poisson variables:

$$\mu \log \mathbb{E}_{\mathbb{P}} \left[\exp \left(\frac{x_{v,t} \tilde{z}_v}{\mu} \right) \right] = \lambda_v (\mu e^{x_{v,t}/\mu} - \mu) \text{ is } \mathcal{K}_{\exp}\text{-representable}$$

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$$\mathbb{P} \in \mathcal{F} \Rightarrow \mathbb{E}_{\mathbb{P}}\left[c(\boldsymbol{x}, \tilde{\boldsymbol{z}})\right] \leq \sup_{\mathbb{P} \in \mathcal{F}} \mathbb{E}_{\mathbb{P}}\left[c(\boldsymbol{x}, \tilde{\boldsymbol{z}})\right]$$

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▶ Support: $\mathbb{P} \in \mathcal{F}^2$

$$\mathcal{F}^2 \triangleq \left\{ \mathbb{P} \left| \begin{array}{c} & \tilde{z} \sim \mathbb{P} \\ & \mathbb{E}_{\mathbb{P}} \left[\tilde{z} \right] \leq \boldsymbol{\lambda} \\ & \mathbb{P} \left[\tilde{z} \in \mathcal{Z} \right] = 1 \end{array} \right. \right\}$$

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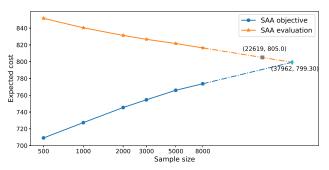
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▶ ECP-C using $\mathcal{F} = \mathcal{F}_1 \cap \mathcal{F}_2$ via infimal convolution



ECP vs SAA with different sample size

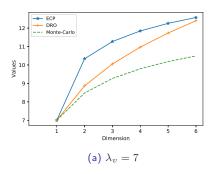
ightharpoonup Expected cost under SAA at different sample size given C=30

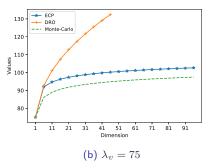


- ➤ SAA with 38,000 samples cannot be solved in 36 hours and is far from optimal upon termination
- ▶ ECP-C is near optimal: the optimality gap is at most $(805.00-773.67)/773.67\times100\%\approx4.05\%$, even 0.71% when using the extrapolation results.

ECP vs DRO with mean-covariance information

Compare the upper bounds of $\mathbb{E}_{\mathbb{P}}\left[\max_{v\in[V]}\tilde{z}_v\right]$ where $\tilde{z}_v\sim \mathsf{Poisson}(\lambda_v)$





Summary

- ▶ An ECP approach to a large-scale stochastic program
 - ▶ Bound the order statistic
 - Exploit stochastic independence
 - $\blacktriangleright~\mathcal{K}_{\mathrm{exp}}\text{-representable}$ upper bounds of log-MGF
- ► Scalability, tractability, superior performance.

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 - ▶ Risk neutral → risk averse
 - No distribution ambiguity → ambiguity averse
- ► Generalize the objective function
 - EV-SP is a very special two-stage stochastic linear program with fixed recourse:

$$f(\boldsymbol{x}, \boldsymbol{z}) = \min_{\boldsymbol{y}} \quad \boldsymbol{y}$$
s.t. $\boldsymbol{y} \ge \sum_{s \in [T]} e_s \sum_{v \in \mathcal{V}_s} x_{v,s} z_v + d \sum_{v \in \mathcal{V}_t} x_{v,t} z_v, \quad \forall t \in [T]$

The dimension of recourse variable is one.

▶ Extend to two-stage and multi-stage linear optimization problems

Constant absolute risk aversion (CARA)

- ▶ Exponential utility: $u_E(v) \triangleq 1 e^{-v/\kappa} \rightarrow \text{risk aversion}$
- ▶ CARA: risk tolerance level $-u_E'/u_E'' \equiv \kappa > 0$

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 - ▶ Roughly indifferent to accepting or rejecting a gamble involving a
 - ▶ 50-50 chance of winning κ or losing $\kappa/2$
 - ▶ 75-25 chance of winning κ or losing κ

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 - ▶ 50-50 chance of winning κ or losing $\kappa/2$
 - ▶ 75-25 chance of winning κ or losing κ
- ► Tractability in economic analysis
- ▶ Popularity: about five times more commonly adopted than all other types of utility functions combined [CC95]

Robust optimization with CARA preference

A robust CARA optimization model:

$$\max_{x \in \mathcal{X}} \inf_{\mathbb{P} \in \mathcal{F}} \mathbb{C}_{\mathbb{P}}^{\kappa} [f(x, \tilde{z})]$$
 (1)

where the CARA certainty equivalent

$$\mathbb{C}_{\mathbb{P}}^{\kappa}\left[\tilde{v}\right] \triangleq u_{E}^{-1}\left(\mathbb{E}_{\mathbb{P}}\left[u_{E}(\tilde{v})\right]\right) = \begin{cases} & \text{ess inf}_{\mathbb{P}}\left[\tilde{v}\right] & \text{if } \kappa = 0 \\ \mathbb{E}_{\mathbb{P}}\left[\tilde{v}\right] & \text{if } \kappa = \infty \end{cases} \\ -\kappa\log\mathbb{E}_{\mathbb{P}}\left[\exp\left(-\frac{\tilde{v}}{\kappa}\right)\right] & \text{if } \kappa \in (0, \infty) \end{cases}$$

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Properties of $\mathbb{C}^{\kappa}_{\mathbb{P}}[\tilde{v}]$; Extend to $\mathbb{C}^{\kappa}_{\mathcal{F}}[\tilde{v}] \triangleq \inf_{\mathbb{P} \in \mathcal{F}} \mathbb{C}^{\kappa}_{\mathbb{P}}[\tilde{v}]$

- 1. $\lim_{\kappa \to \infty} \mathbb{C}^{\kappa}_{\mathbb{P}}[\tilde{v}] = \mathbb{E}_{\mathbb{P}}[\tilde{v}], \lim_{\kappa \to 0} \mathbb{C}^{\kappa}_{\mathbb{P}}[\tilde{v}] = \operatorname{ess\,inf}_{\mathbb{P}}[\tilde{v}].$
- 2. $\mathbb{C}_{\mathbb{P}}^{\kappa} [\tilde{v}]$ is increasing in $\kappa > 0$
- 3. $\mathbb{C}_{\mathbb{P}}^{\kappa} [\tilde{v}]$ is jointly concave in \tilde{v} and $\kappa > 0$.
- 4. $\mathbb{C}_{\mathbb{P}}^{\kappa} [\tilde{v} + \tilde{\nu}] = \mathbb{C}_{\mathbb{P}}^{\kappa} [\tilde{v}] + \mathbb{C}_{\mathbb{P}}^{\kappa} [\tilde{\nu}]$ if \tilde{v} , $\tilde{\nu}$ are independent.
- 5. Super-additivity: $\mathbb{C}_{\mathbb{P}}^{\kappa_1+\kappa_2}[\tilde{v}+\tilde{\nu}] \geq \mathbb{C}_{\mathbb{P}}^{\kappa_1}[\tilde{v}] + \mathbb{C}_{\mathbb{P}}^{\kappa_2}[\tilde{\nu}]$ for any $\kappa_1, \kappa_2 \in \mathbb{R}_+$.



Model of uncertainty

Independent factors with ambiguous marginals

- $\check{z} = (\tilde{z}_1, \tilde{z}_2, \cdots, \tilde{z}_{I_z})$ has independent components
- lacksquare $ilde{z}_j \sim \mathbb{P}_j \in \mathcal{F}_j \subseteq \mathcal{P}_0([\underline{z}_j, \bar{z}_j])$ where $\underline{z}_j < \bar{z}_j$
- ▶ So $\tilde{z} \sim \mathbb{P} \in \mathcal{F} \triangleq \times_{j \in [I_z]} \mathcal{F}_j \subseteq \mathcal{P}_0(\mathcal{Z})$ where $\mathcal{Z} \triangleq [\underline{z}, \bar{z}]$

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For an affine function

$$f(\boldsymbol{x}, \boldsymbol{z}) = a^{0}(\boldsymbol{x}) + \sum_{j \in [I_{*}]} a^{j}(\boldsymbol{x}) z_{j},$$

we have

$$\mathbb{C}_{\mathcal{F}}^{\kappa}\left[f(\boldsymbol{x}, \tilde{\boldsymbol{z}})\right] = a^{0}(\boldsymbol{x}) + \sum_{j \in [I_{z}]} \phi_{j}(\kappa, a^{j}(\boldsymbol{x}))$$

where the function $\phi_i:[0,\infty]\times\mathbb{R}\to\mathbb{R}$,

$$\phi_j(\kappa, \lambda) \triangleq \inf_{\mathbb{P}_i \in \mathcal{F}_j} \mathbb{C}_{\mathbb{P}}^{\kappa} \left[\lambda \tilde{z}_j \right].$$



Tractability of CARA under independence

Example 1

Let
$$\tilde{z}_i \sim \text{Unif}([0,1]), a^j(x) \equiv a_i < 0 \text{ and } a^0(x) \equiv a_0 > 0$$
, then

$$\mathbb{C}_{\mathbb{P}}^{\kappa} [f(\boldsymbol{x}, \tilde{\boldsymbol{z}})] = a_0 - \sum_{j \in [I_z]} \kappa \log \int_0^1 \exp\left(-\frac{a_j z_j}{\kappa}\right) dz_j$$
$$= a_0 - \sum_{j \in [I_z]} \kappa \log\left(\frac{\kappa - \kappa e^{-a_j/\kappa}}{a_j}\right).$$

Tractability of CARA under independence

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$$\mathbb{C}_{\mathbb{P}}^{\kappa} [f(\boldsymbol{x}, \tilde{\boldsymbol{z}})] = a_0 - \sum_{j \in [I_z]} \kappa \log \int_0^1 \exp\left(-\frac{a_j z_j}{\kappa}\right) dz_j$$
$$= a_0 - \sum_{j \in [I_z]} \kappa \log\left(\frac{\kappa - \kappa e^{-a_j/\kappa}}{a_j}\right).$$

In contrast, evaluating an expected concave piecewise linear utility such as

$$\mathbb{E}_{\mathbb{P}}\left[\min\left\{a_0 + \sum_{j \in [I_z]} a_j \tilde{z}_j, 0\right\}\right]$$

is known to be #P-hard.



Tractability of CARA under independence

Example 2

Consider a simple mean-support ambiguity set:

$$\mathcal{G} = \left\{ \mathbb{P} \in \mathcal{P}_0(\mathbb{R}^{I_z}) \left| \begin{array}{l} \tilde{\boldsymbol{z}} \sim \mathbb{P} \\ \mathbb{E}_{\mathbb{P}}\left[\tilde{\boldsymbol{z}}\right] = \boldsymbol{\mu} \\ \mathbb{P}\left[\tilde{\boldsymbol{z}} \in \left[\underline{\boldsymbol{z}}, \bar{\boldsymbol{z}}\right]\right] = 1 \end{array} \right\}.$$

Note that evaluating $\mathbb{C}^\kappa_\mathcal{G}\left[m{a}^ op ilde{m{z}}
ight]$ requires

$$\sup_{\mathbb{P} \in \mathcal{G}} \mathbb{E}_{\mathbb{P}} \left[\exp \left(-\frac{\boldsymbol{a}^{\top} \tilde{\boldsymbol{z}}}{\kappa} \right) \right] = \inf_{\alpha, \boldsymbol{\beta}} \quad \alpha + \boldsymbol{\beta}^{\top} \boldsymbol{\mu}$$
s.t. $\alpha \ge \sup_{\boldsymbol{z} \in [\boldsymbol{z}, \tilde{\boldsymbol{z}}]} \exp \left(\frac{-\boldsymbol{a}^{\top} \boldsymbol{z}}{\kappa} \right) - \boldsymbol{\beta}^{\top} \boldsymbol{z},$

which involves a convex maximization problem.

Theorem 1

Let $g(x,\kappa) = -\kappa \log \sum p_i e^{-x_i/\kappa}$ with $\kappa > 0$ and $p_i > 0$ for all $i \in [I]$, then the closure of $\{(\boldsymbol{x}, \kappa, y) : y \leq g(\boldsymbol{x}, \kappa), \kappa > 0\}$ can be represented by

$$\left\{ (\boldsymbol{x}, \kappa, y) \mid \exists \boldsymbol{q} \in \mathbb{R}^{I} : \sum_{i \in [I]} p_{i}q_{i} \leq \kappa, \ (q_{i}, \kappa, y - x_{i}) \in \mathcal{K}_{\exp} \ \forall i \in [I] \right\}.$$

Theorem 1

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Recall that for an affine function,

$$\mathbb{C}^{\kappa}_{\mathcal{F}}\left[f(oldsymbol{x}, ilde{oldsymbol{z}})
ight] = a^0(oldsymbol{x}) + \sum_{j \in [I_z]} \phi_j(\kappa,a^j(oldsymbol{x})).$$

• $\phi(\kappa, \lambda) \triangleq \mathbb{C}_{\mathcal{G}}^{\kappa}[\lambda \tilde{z}]$ is \mathcal{K}_{exp} -representable for many ambiguity sets. [NS07]

Table 1 Equivalent representations of $\phi(\kappa, \lambda)$ Ambiguity set F $\phi(\kappa, \lambda)$ $\{\mathbb{P} [\tilde{z} \in [-1, 1]] = 1\}$ $-|\lambda|$ P is symmetric $-\kappa \log \left(\frac{e^{\lambda/\kappa} + e^{-\lambda/\kappa}}{2}\right)$ $\mathbb{P}[\tilde{z} \in [-1, 1]] = 1$ P is unimodal w.r.t. 0 $-\kappa \log \int_{0}^{1} e^{s|\lambda|/\kappa} ds$ $\mathbb{P}[\tilde{z} \in [-1, 1]] = 1$ P is symmetric, $\lambda - \kappa \log \int_{0}^{1} e^{-2\lambda s/\kappa} ds$ unimodal w.r.t. 0 $\mathbb{P}[\tilde{z} \in [-1,1]] = 1$ $\mathbb{E}_{\mathbb{P}}\left[\tilde{z}\right] \in \left[\mu, \overline{\mu}\right]$ $-\kappa \log$ \min $(1+\overline{\mu})e^{-\lambda/\kappa}+(1-\overline{\mu})e^{\lambda/\kappa}$ $-\kappa\log\left(\frac{\delta}{2(\mu+1)}e^{\lambda/\kappa}+\frac{\delta}{2(1-\mu)}e^{-\lambda/\kappa}+\left(1-\frac{\delta}{2(\mu+1)}-\frac{\delta}{2(1-\mu)}\right)e^{-\mu\lambda/\kappa}\right)$ $\mathbb{P}\left[\tilde{z} \in [-1, 1]\right] = 1$ $-\kappa \log$ \min $\left(\frac{(1+\mu)^2 \exp\left(\frac{-(\mu+\sigma^2)\lambda}{(1-\mu)\kappa}\right) + (\sigma^2-\mu^2) \exp(\lambda/\kappa)}{1+2\mu+\sigma^2}\right)$ $\mathbb P$ is symmetric, $-\kappa \log \left(\frac{\sigma^2(e^{\lambda/\kappa} + e^{-\lambda/\kappa})}{2} + 1 - \sigma^2 \right)$

 $\mathbb{P}[\tilde{z} \in [-1, 1]] = 1$

- $\phi(\kappa, \lambda) \triangleq \mathbb{C}_{\mathcal{G}}^{\kappa} [\lambda \tilde{z}]$ is \mathcal{K}_{exp} -representable for many ambiguity sets. [NS07]
- $\qquad \qquad \mathbb{C}^\kappa_{\mathcal{F}}\left[f(\boldsymbol{x},\tilde{\boldsymbol{z}})\right] = a^0(\boldsymbol{x}) + \sum_{j \in [I_z]} \phi_j(\kappa,a^j(\boldsymbol{x})) \text{ is } \mathcal{K}_{\exp}\text{-representable if } a^0(\boldsymbol{x}), \\ a^j(\boldsymbol{x}) \text{ are affine.}$

Concave piecewise affine functions

▶ However, in practice the payoff functions f(x, z) are usually nonlinear in z.

Concave piecewise affine functions

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- ► Consider a concave piecewise affine payoff function

$$f(oldsymbol{x},oldsymbol{z}) = \min_{i \in \mathcal{I}} \left\{ a_i^0(oldsymbol{x}) + \sum_{j \in [I_z]} a_i^j(oldsymbol{x}) z_j
ight\}.$$

lacktriangledown Recall evaluating $\mathbb{C}^\kappa_{\mathbb{P}}[f(x, ilde{z})]$ under known distribution can be $\# \mathrm{P-hard}.$

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- ▶ However, in practice the payoff functions f(x,z) are usually nonlinear in z.
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- ▶ Recall evaluating $\mathbb{C}^{\kappa}_{\mathbb{P}}\left[f(x,\tilde{z})\right]$ under known distribution can be #P-hard.
- ► Tractable approximations are needed.

Let
$$\alpha_i = a_i^0(\boldsymbol{x})$$
, $\beta_i^j = a_i^j(\boldsymbol{x})$,

$$\mathbb{C}_{\mathcal{F}}^{\kappa} \left[\min_{i \in \mathcal{I}} \left\{ \alpha_i + \boldsymbol{\beta}_i^{\top} \tilde{\boldsymbol{z}} \right\} \right]$$
$$= \mathbb{C}_{\mathcal{F}}^{\kappa} \left[\boldsymbol{\gamma}^{\top} \tilde{\boldsymbol{z}} + \min_{i \in \mathcal{I}} \{ \alpha_i + (\boldsymbol{\beta}_i - \boldsymbol{\gamma})^{\top} \tilde{\boldsymbol{z}} \} \right]$$

$$\mathbb{C}_{\mathcal{F}}^{\kappa} \left[\min_{i \in \mathcal{I}} \left\{ \alpha_{i} + \boldsymbol{\beta}_{i}^{\top} \tilde{\boldsymbol{z}} \right\} \right] \\
= \mathbb{C}_{\mathcal{F}}^{\kappa} \left[\boldsymbol{\gamma}^{\top} \tilde{\boldsymbol{z}} + \min_{i \in \mathcal{I}} \left\{ \alpha_{i} + (\boldsymbol{\beta}_{i} - \boldsymbol{\gamma})^{\top} \tilde{\boldsymbol{z}} \right\} \right] \\
\geq \sup_{\kappa_{0} + \kappa_{1} = \kappa, \kappa \geq 0} \mathbb{C}_{\mathcal{F}}^{\kappa_{0}} \left[\boldsymbol{\gamma}^{\top} \tilde{\boldsymbol{z}} \right] + \mathbb{C}_{\mathcal{F}}^{\kappa_{1}} \left[\min_{i \in \mathcal{I}} \left\{ \alpha_{i} + (\boldsymbol{\beta}_{i} - \boldsymbol{\gamma})^{\top} \tilde{\boldsymbol{z}} \right\} \right] \\
(\text{Super-additivity of } \mathbb{C}_{\mathcal{F}}^{\kappa} \left[\tilde{\boldsymbol{v}} \right] \text{ w.r.t. } (\tilde{\boldsymbol{v}}, \kappa) \text{ with } \kappa \geq 0)$$

$$\mathbb{C}_{\mathcal{F}}^{\kappa} \left[\min_{i \in \mathcal{I}} \left\{ \alpha_{i} + \boldsymbol{\beta}_{i}^{\top} \tilde{\boldsymbol{z}} \right\} \right] \\
= \mathbb{C}_{\mathcal{F}}^{\kappa} \left[\boldsymbol{\gamma}^{\top} \tilde{\boldsymbol{z}} + \min_{i \in \mathcal{I}} \{ \alpha_{i} + (\boldsymbol{\beta}_{i} - \boldsymbol{\gamma})^{\top} \tilde{\boldsymbol{z}} \} \right] \\
\geq \sup_{\kappa_{0} + \kappa_{1} = \kappa, \kappa \geq \mathbf{0}} \mathbb{C}_{\mathcal{F}}^{\kappa_{0}} \left[\boldsymbol{\gamma}^{\top} \tilde{\boldsymbol{z}} \right] + \mathbb{C}_{\mathcal{F}}^{\kappa_{1}} \left[\min_{i \in \mathcal{I}} \{ \alpha_{i} + (\boldsymbol{\beta}_{i} - \boldsymbol{\gamma})^{\top} \tilde{\boldsymbol{z}} \} \right] \\
= \sup_{\kappa_{0} + \kappa_{1} = \kappa, \kappa \geq \mathbf{0}} \mathbb{C}_{\mathcal{F}}^{\kappa_{0}} \left[\boldsymbol{\gamma}^{\top} \tilde{\boldsymbol{z}} \right] - \kappa_{1} \log \sup_{\mathbb{P} \in \mathcal{F}} \mathbb{E}_{\mathbb{P}} \left[\exp \left(\frac{\max_{i \in \mathcal{I}} \{ -\alpha_{i} - (\boldsymbol{\beta}_{i} - \boldsymbol{\gamma})^{\top} \tilde{\boldsymbol{z}} \} }{\kappa_{1}} \right) \right]$$

$$\mathbb{C}_{\mathcal{F}}^{\kappa} \left[\min_{i \in \mathcal{I}} \left\{ \alpha_{i} + \boldsymbol{\beta}_{i}^{\top} \tilde{\boldsymbol{z}} \right\} \right] \\
= \mathbb{C}_{\mathcal{F}}^{\kappa} \left[\boldsymbol{\gamma}^{\top} \tilde{\boldsymbol{z}} + \min_{i \in \mathcal{I}} \{ \alpha_{i} + (\boldsymbol{\beta}_{i} - \boldsymbol{\gamma})^{\top} \tilde{\boldsymbol{z}} \} \right] \\
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(\text{Bound max by sum})$$

$$\mathbb{C}_{\mathcal{F}}^{\kappa} \left[\min_{i \in \mathcal{I}} \left\{ \alpha_{i} + \boldsymbol{\beta}_{i}^{\top} \tilde{\boldsymbol{z}} \right\} \right] \\
= \mathbb{C}_{\mathcal{F}}^{\kappa} \left[\boldsymbol{\gamma}^{\top} \tilde{\boldsymbol{z}} + \min_{i \in \mathcal{I}} \left\{ \alpha_{i} + (\boldsymbol{\beta}_{i} - \boldsymbol{\gamma})^{\top} \tilde{\boldsymbol{z}} \right\} \right] \\
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ECP approximations

All in all, $\mathbb{C}^{\kappa}_{\mathcal{F}}\left[f(\boldsymbol{x}, \tilde{\boldsymbol{z}})\right]$ has an ECP lower bound

$$\begin{split} \Lambda(\kappa, \boldsymbol{x}) &\triangleq \max r_0 + \rho \\ \text{s.t.} \quad \kappa_0 + \kappa_1 &= \kappa \\ &\sum_{i \in \mathcal{I}} q_i \leq \kappa_1 \\ &(q_i, \kappa_1, \rho - r_i) \in \mathcal{K}_{\text{exp}} \quad \forall i \in \mathcal{I} \\ &\sum_{j \in [I_z]} \phi_j(\kappa_0, \gamma^j) \geq r_0 \\ &\alpha_i + \sum_{j \in [I_z]} \phi_j(\kappa_1, \beta_i^j - \gamma^j) \geq r_i \quad \forall i \in \mathcal{I} \\ &\boldsymbol{\gamma} \in \mathbb{R}^{I_z}, \boldsymbol{r} \in \mathbb{R}^{1+N}, \boldsymbol{\kappa} \in \mathbb{R}^2_+, \rho \in \mathbb{R}, \boldsymbol{q} \in \mathbb{R}^N \end{split}$$

if $a_i^0(\boldsymbol{x})$ and $a_i^j(\boldsymbol{x})$ are affine.

Properties of the approximation

Theorem 2

For any $x \in \mathcal{X}$, $\Lambda(\kappa, x)$ is nondecreasing in $\kappa \in [0, \infty]$ and satisfies $\Lambda(\kappa, x) \geq \inf_{\mathbf{z} \in \mathcal{Z}} f(\mathbf{x}, \mathbf{z})$. Moreover, $\mathbb{C}^{\kappa}_{\mathcal{F}}[f(\mathbf{x}, \tilde{\mathbf{z}})] = \Lambda(\kappa, x)$ if there exists some $i^* \in \mathcal{I}$ such that

$$a_{i^*}^0(\boldsymbol{x}) + \sum_{j \in [I_z]} a_{i^*}^j(\boldsymbol{x}) z_j \le a_i^0(\boldsymbol{x}) + \sum_{j \in [I_z]} a_i^j(\boldsymbol{x}) z_j \qquad \forall \boldsymbol{z} \in \mathcal{Z}, i \in \mathcal{I}.$$

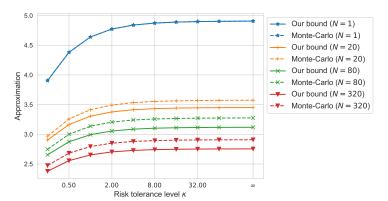
Cases of good approximation:

- ▶ Low risk tolerance κ
- ▶ Low coefficient of variations among the payoff components

Comparison with Monte-Carlo approximation

Approximate
$$\mathbb{C}^{\kappa}_{\mathbb{P}}\left[\min_{i\in[N]}\left\{oldsymbol{a}_{i}^{ op} ilde{oldsymbol{z}}\right\}
ight]$$
 where $ilde{z}_{j}\sim\mathrm{Unif}([0,1])$

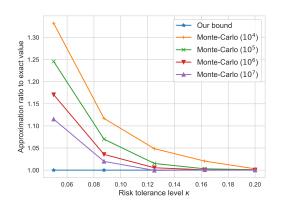
Figure: Comparison of our bound and Monte-Carlo approximation (10^6 samples) for $\kappa \geq 0.25$



Comparison with Monte-Carlo approximation

Approximate
$$\mathbb{C}_{\mathbb{P}}^{\kappa}\left[\min_{i\in[N]}\left\{\boldsymbol{a}_{i}^{\top}\tilde{\boldsymbol{z}}\right\}
ight]$$
 where $\tilde{z}_{j}\sim\mathrm{Unif}([0,1])$

Figure: Ratio of Monte-Carlo approximation to our bound for $\kappa \leq 0.2$ at N=1 where our bound is exact while Monte-Carlo is upward biased



Consider the two-stage problem with fixed recourse

$$\begin{split} f(\boldsymbol{x}, \boldsymbol{z}) = & \max_{\boldsymbol{y}} & \boldsymbol{c}^{\top} \boldsymbol{y} \\ & \text{s.t.} & \boldsymbol{b}_i^{\top} \boldsymbol{y} \leq a_i^0(\boldsymbol{x}) + \boldsymbol{a}_i^{\top}(\boldsymbol{x}) \boldsymbol{z} & \forall i \in \mathcal{I}, \\ & \boldsymbol{y} \in \mathbb{R}^{I_y} \end{split}$$

where y is the recourse decision adaptive to uncertainty realization.

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► Assume no here-and-now variable in objective w.l.o.g.

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- Assume no here-and-now variable in objective w.l.o.g.
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 eq 0$ w.l.o.g.
- ► Assume inequality constraints only w.l.o.g.

Note: Generalize the concave piecewise affine payoff function where $I_y=1,\ c=1,$ and $b_i=1,\ i\in\mathcal{I}.$

► A multi-deflected linear decision rule (MLDR)

$$\hat{m{y}}(m{z}) riangleq ar{m{y}}(m{z}) + \sum_{\ell \in [m]} m{y}_*^\ell \left(\max_{i \in \mathcal{I}_\ell^o} \left\{ rac{h_i(m{x}, ar{m{y}}(m{z}), m{z})}{\|m{b}_i\|}
ight\}
ight)^+.$$

where

$$egin{aligned} ar{m{y}}(m{z}) & riangleq m{y}^0 + m{Y}m{z} \ h_i(m{x},m{y},m{z}) & riangleq m{b}_i^ op m{y} - a_i^0(m{x}) - m{a}_i^ op(m{x})m{z} & orall i \in \mathcal{I}. \end{aligned}$$

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ight\}
ight)^+.$$

where y_*^{ℓ} and \mathcal{I}_{ℓ}^o are chosen as follows:

Solve for each $i \in \mathcal{I}$,

$$\begin{aligned} \max_{\boldsymbol{y} \in \mathbb{R}^{I_{\boldsymbol{y}}}} & & \boldsymbol{c}^{\top} \boldsymbol{y} \\ & & \boldsymbol{b}_{k}^{\top} \boldsymbol{y} \leq 0 \\ & & & \boldsymbol{b}_{i}^{\top} \boldsymbol{y} = -\|\boldsymbol{b}_{i}\| \end{aligned}$$

and denote \boldsymbol{y}_*^i as its optimal solution if feasible.

▶ Partition feasible index set

$$\mathcal{I}^o = \bigcup_{\ell \in [m]} \mathcal{I}^o_\ell$$

such that $m{y}_*^{i_1} = m{y}_*^{i_2}$ if and only if i_1 and i_2 are in the same \mathcal{I}_ℓ^o .

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- \blacktriangleright Can replicate optimal decision rule under complete recourse with $I_y=1$

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ight\}
ight)^+.$$

- ▶ Better than previous deflected LDR in [CSSZ08]
- \blacktriangleright Can replicate optimal decision rule under complete recourse with $I_y=1$
- ▶ Obtain ECP lower bound based on approximation for concave piecewise affine functions.

A multi-period consumption model

Given $\boldsymbol{\xi}_t \triangleq (\boldsymbol{z}_1,...,\boldsymbol{z}_t)$,

$$\begin{aligned} \max_{\substack{\boldsymbol{x} \in \mathcal{X}, \\ \boldsymbol{y}_1, \dots, \boldsymbol{y}_T}} & \quad \mathbb{C}_{\mathcal{F}}^{\kappa, \boldsymbol{\theta}} \left[\boldsymbol{c}_1^{\top} \boldsymbol{y}_1(\tilde{\boldsymbol{\xi}}_1), \dots, \boldsymbol{c}_T^{\top} \boldsymbol{y}_T(\tilde{\boldsymbol{\xi}}_T) \right] \\ \text{s.t.} & \quad \sum_{\tau \in [t]} \boldsymbol{b}_{t, i, \tau}^{\top} \boldsymbol{y}_{\tau}(\boldsymbol{\xi}_{\tau}) \leq a_{t, i}^{0}(\boldsymbol{x}) + \boldsymbol{a}_{t, i}^{\top}(\boldsymbol{x}) \boldsymbol{\xi}_t & \forall t \in [T], \ i \in \mathcal{I}_t, \ \boldsymbol{z} \in \mathcal{Z} \\ \boldsymbol{y}_t \in \mathcal{R}^{I_{\boldsymbol{\xi}_t}, I_{\boldsymbol{y}_t}} & \forall t \in [T]. \end{aligned}$$

where the multi-period ambiguity-averse CARA certainty equivalent

$$\mathbb{C}_{\mathcal{F}}^{\kappa,\boldsymbol{\theta}}\left[\tilde{\boldsymbol{v}}\right] \triangleq \left\{ \begin{array}{ll} \min\limits_{t \in [T]: \theta_{t} > 0} \left\{ \inf\limits_{\mathbb{P} \in \mathcal{F}} \operatorname{ess\,inf}_{\mathbb{P}}\left[\tilde{v}_{t}\right] \right\} & \text{if } \kappa = 0 \\ \sum\limits_{t \in [T]} \theta_{t} \inf\limits_{\mathbb{P} \in \mathcal{F}} \mathbb{E}_{\mathbb{P}}\left[\tilde{v}_{t}\right] & \text{if } \kappa = \infty \\ -\kappa \log \left(\sum\limits_{t \in [T]} \theta_{t} \sup\limits_{\mathbb{P} \in \mathcal{F}} \mathbb{E}_{\mathbb{P}}\left[\exp\left(-\frac{\tilde{v}_{t}}{\kappa}\right) \right] \right) & \text{if } \kappa \in (0, \infty). \end{array} \right.$$

A multi-period consumption model

Given $\boldsymbol{\xi}_t \triangleq (\boldsymbol{z}_1,...,\boldsymbol{z}_t)$,

where the multi-period ambiguity-averse CARA certainty equivalent

$$\mathbb{C}_{\mathcal{F}}^{\kappa,\boldsymbol{\theta}}\left[\tilde{\boldsymbol{v}}\right] \triangleq \left\{ \begin{array}{ll} \min\limits_{t \in [T]:\theta_{t}>0} \left\{\inf\limits_{\mathbb{P} \in \mathcal{F}} \operatorname{ess}\inf_{\mathbb{P}}\left[\tilde{v}_{t}\right]\right\} & \text{if } \kappa = 0 \\ \sum\limits_{t \in [T]} \theta_{t}\inf\limits_{\mathbb{P} \in \mathcal{F}} \mathbb{E}_{\mathbb{P}}\left[\tilde{v}_{t}\right] & \text{if } \kappa = \infty \\ -\kappa\log\left(\sum\limits_{t \in [T]} \theta_{t}\sup\limits_{\mathbb{P} \in \mathcal{F}} \mathbb{E}_{\mathbb{P}}\left[\exp\left(-\frac{\tilde{v}_{t}}{\kappa}\right)\right]\right) & \text{if } \kappa \in (0,\infty). \end{array} \right.$$

➤ Multi-period MLDR ⇒ Tractable ECP approximation



- ▶ Initial inventory x_1 , wealth w_1
- ▶ In each period t = 1, ..., T,

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 - Inventory update:

$$x_{t+1} = y_t - \tilde{z}_t$$

A consumption model [CSSLS07]:

- ▶ Initial inventory x_1 , wealth w_1
- ln each period t = 1, ..., T,
 - ▶ Order up to $y_t \ge x_t$ with ordering cost $c_t(y_t x_t)$
 - ▶ Uncertain demand \tilde{z}_t realizes, obtain profit subtracting holding and backlogging cost $p_t\tilde{z}_t h(y_t \tilde{z}_t)^+ b(\tilde{z}_t y_t)^+$
 - ▶ Determine consumption level f_t and obtain utility $1 e^{-f_t/\kappa}$
 - Inventory update:

$$x_{t+1} = y_t - \tilde{z}_t$$

Wealth update:

$$w_{t+1} = (w_t + q_t - f_t)(1 + \beta)$$

where the income

$$q_t = p_t \tilde{z}_t - h(y_t - \tilde{z}_t)^+ - b(\tilde{z}_t - y_t)^+ - c_t(y_t - \tilde{z}_t)$$

ightharpoonup Assume $w_{T+1}=0$.



$$\begin{aligned} \max_{\boldsymbol{x},\boldsymbol{y},\boldsymbol{f},\boldsymbol{w},\boldsymbol{q}} \quad \mathbb{E}_{\mathbb{P}} \left[\sum_{t \in [T]} \theta_t (1 - e^{-f_t(\tilde{\boldsymbol{\xi}}_t)/\kappa}) \right] \\ \text{s.t.} \quad f_t(\tilde{\boldsymbol{\xi}}_t) = w_t(\tilde{\boldsymbol{\xi}}_{t-1}) - \frac{w_{t+1}(\boldsymbol{\xi}_t)}{1 + \beta} + q_t(\tilde{\boldsymbol{\xi}}_t) & \forall t \in [T] \\ q_t(\tilde{\boldsymbol{\xi}}_t) \leq p_t \tilde{z}_t - h(y_t(\tilde{\boldsymbol{\xi}}_{t-1}) - \tilde{z}_t) - c_t(y_t(\tilde{\boldsymbol{\xi}}_{t-1}) - x_t(\tilde{\boldsymbol{\xi}}_{t-1})) & \forall t \in [T] \\ q_t(\tilde{\boldsymbol{\xi}}_t) \leq p_t \tilde{z}_t - b(\tilde{z}_t - y_t(\tilde{\boldsymbol{\xi}}_{t-1})) - c_t(y_t(\tilde{\boldsymbol{\xi}}_{t-1}) - x_t(\tilde{\boldsymbol{\xi}}_{t-1})) & \forall t \in [T] \\ y_t(\tilde{\boldsymbol{\xi}}_{t-1}) \geq x_t(\tilde{\boldsymbol{\xi}}_{t-1}) & \forall t \in [T] \\ x_{t+1}(\tilde{\boldsymbol{\xi}}_t) = y_t(\tilde{\boldsymbol{\xi}}_{t-1}) - \tilde{z}_t & \forall t \in [T-1] \\ w_{T+1}(\tilde{\boldsymbol{\xi}}_T) = 0 \end{aligned}$$

- ► Approach 1: dynamic programming (DP)
- ► Approach 2: Fourier-Motzkin elimination + multi-period MLDR

▶ Similar parameter setting as in [CSSLS07]:

$$h = 6$$
, $b = 3$, $c_t = 1$, $p_t = 8$, $\beta = 0.1$ for all $t \in [T]$

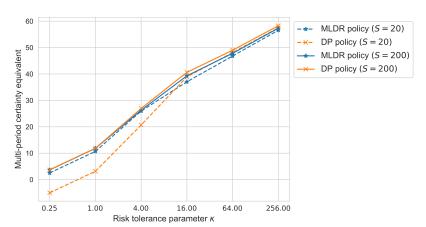
- Similar parameter setting as in [CSSLS07]: $h = 6, b = 3, c_t = 1, p_t = 8, \beta = 0.1$ for all $t \in [T]$
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- ➤ Solving the problem by (i) DP; (ii) MLDR under empirical distribution of S samples, then evaluate the solution (policy) over 10,000 samples generated from the same distribution
- ▶ The results are averaged over 50 random instances.

Figure: Multi-peirod CARA certainty equivalent under different risk tolerance parameters



Summary

► A robust decision model with CARA preference

$$\max_{\boldsymbol{x} \in \mathcal{X}} \mathbb{C}^{\kappa}_{\mathcal{F}} \left[f(\boldsymbol{x}, \tilde{\boldsymbol{z}}) \right]$$

- ► Tractable ECP approximations for a hierarchy of payoff functions:
 - ► Affine perturbations
 - Concave piecewise affine perturbations
 - ▶ Two-stage optimization with fixed recourse
- ▶ Extend to a multi-period consumption model
- ▶ Robust performance in data-driven setting when risk tolerance is low.

Extensions and future work

- ▶ Other entropy related decision criteria such as entropic value-at-risk, entropic risk measure.
- ► Faster computation for large-scale ECP (with integer constraints)
- ► Handle correlated uncertain factors in robust CARA optimization
- ► Stronger probability bound of functions of (partially) independent random variables



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- My family

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