

Camera ISP Overview for APQ8084/MSM8992/MSM8994/ MSM8996



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80-NM328-68 D

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Revision History

Revision	Date	Description
A	August 2014	Initial release
B	November 2014	Added MSM8992 information
C	February 2015	Added MSM8996 information
D	July 2015	Updated slide 5

Contents

- Camera System Comparison – SM8974/APQ8084/MSM8992/MSM8994/MSM8996
- ISP Block-by-Block Comparison
- Camera Updates – Block Diagram
- New and updated blocks
- Acronyms
- Questions?

Camera System Comparison

	MSM8974AB	APQ8084	MSM8992	MSM8994	MSM8996
Maximum real-time sensor input resolution	<ul style="list-style-type: none"> ISP1 – 21 MP ISP2 – 13 MP 	<ul style="list-style-type: none"> ISP1 – 21 MP ISP2 – 13 MP 	<ul style="list-style-type: none"> ISP1 – 21 MP ISP2 – 8 MP 	<ul style="list-style-type: none"> ISP1 – 28 MP ISP2 – 13 MP 	<ul style="list-style-type: none"> ISP1 – 21 MP (16:9) ISP2 – 13 MP
Maximum output sizes (constraint on width)	<ul style="list-style-type: none"> ISP1 enc – 5376 ISP1 view – 2560+10% ISP2 enc – 4288 ISP2 view – 2560+10% 	<ul style="list-style-type: none"> ISP1 enc – 5376 ISP1 view – 2560+10% ISP2 enc – 4288 ISP2 view – 2560+10% 	<ul style="list-style-type: none"> ISP1 enc – 6240 ISP1 view – 2560+10% ISP2 enc – 4288 ISP2 view – 2560+10% 	<ul style="list-style-type: none"> ISP1 enc – 6240 ISP1 view – 4608+10% ISP2 enc – 4288 ISP2 view – 2560+10% 	<ul style="list-style-type: none"> ISP1 enc – 6240 ISP1 view – 4608+10% ISP2 enc – 4288 ISP2 view – 2560+10%
VFE and CPP MHz Nominal/Turbo mode	<ul style="list-style-type: none"> VFE – 320/465 CPP – 266/400 	<ul style="list-style-type: none"> VFE – 465/600 CPP – 370/600 	<ul style="list-style-type: none"> VFE – 465/600 CPP – 465/620 	<ul style="list-style-type: none"> VFE – 465/600 CPP – 465/620 	465/600
MIPI CSI2 ports DPHY	4/4/4 or 4/4/2/1	4/4/4 or 4/4/2/1	4/4/4 or 4/4/2/1	4/4/4 or 4/4/2/1	4/4/4 or 4/4/2/1
JPEG hardware	<ul style="list-style-type: none"> 2x encoder 1x decoder 	<ul style="list-style-type: none"> 2x encoder 1x decoder 	<ul style="list-style-type: none"> 1x encoder 	<ul style="list-style-type: none"> 2x encoder 1x decoder 1xDMA 	<ul style="list-style-type: none"> 1x encoder, 1x decoder
VFE feature highlights		LSC upgrade, ABF3, Demosaic, Dual AF, CAC, LTM, Gamma	LSC upgrade, ABF3, Demosaic, Dual AF, CAC, LTM, Gamma, Green Imbalance, Pedestal, Stats Upgrades	LSC upgrade, ABF3, Demosaic, FIR+IIR Dual AF, CAC2+SNR, LTM , Gamma, Green Imbalance, Pedestal, Stats Upgrades	LSC upgrade, ABF3, BPC, Demosaic, FIR+IIR Dual AF, CAC2+SNR, LTM , Gamma, Green Imbalance, Pedestal, Stats Upgrades
CPP feature highlights		New Adaptive Spatial Filter (ASF)	3D Denoise , new ASF	3D Denoise, new ASF	3D Denoise, Low Light Chroma Denoise , new ASF
Face Detection				Hardware	Hardware

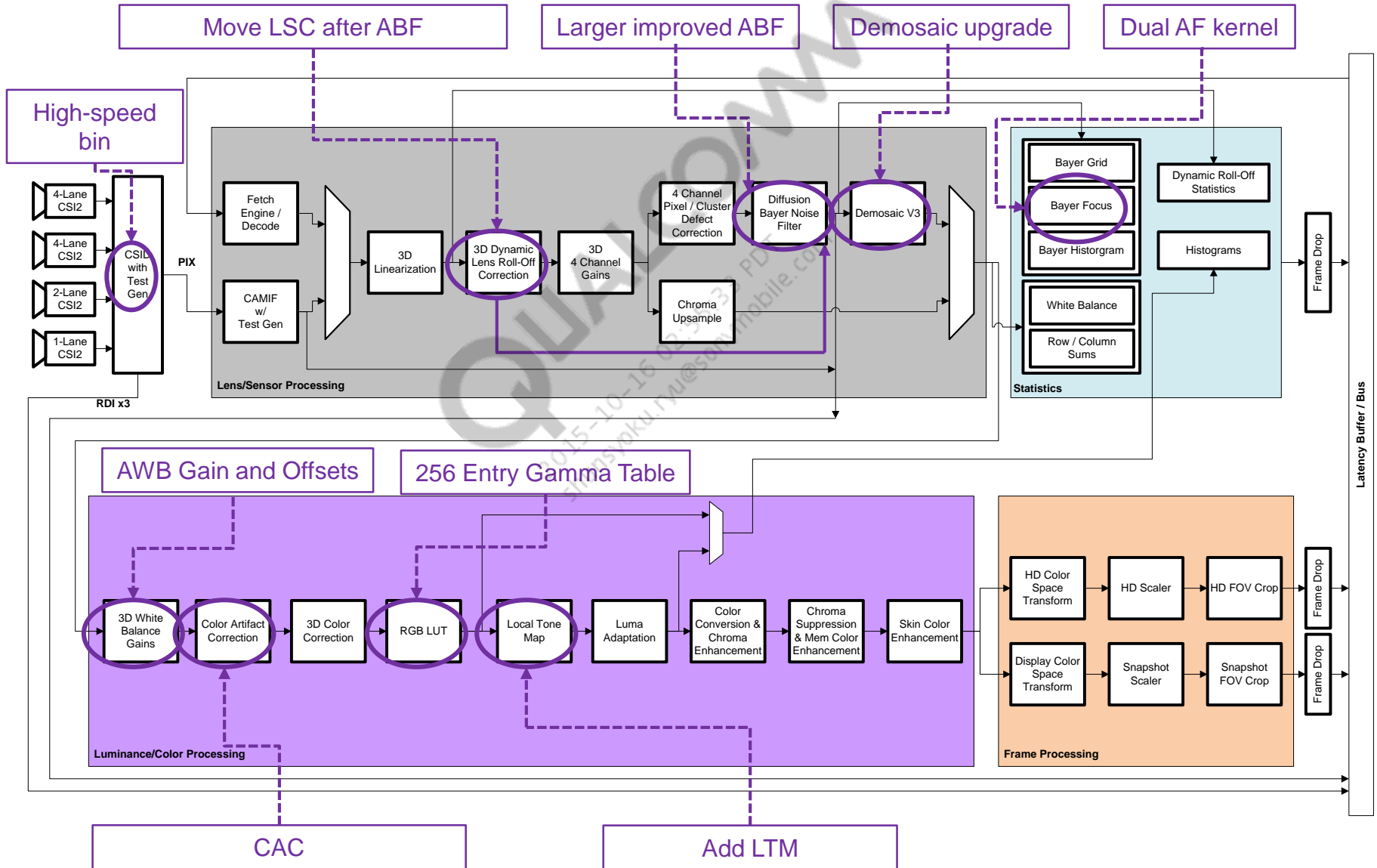
ISP Block-By-Block Comparison

ISP blocks	MSM8974	APQ8084	MSM8992	MSM8994	MSM8996
BLC, Linearization, LSC, CCM, Gamma	√	√	√	√	√
Color Enhancement blocks (ACE, SCE, MCE, CS)	√	√	√	√	√
Wavelet Noise Reduction (WNR)	√	√	√	√	Improved (sixth layer)
Defect Pixel Correction	√	√	√	√	Improved
Demosaic	Demosaic 3	Demosaic 4	Demosaic 4	Demosaic 4	Demosaic 4 Improved G-interpolation
Auto Focus (AF) Stat	Single kernel (2x5)	Dual kernel (2x11)	Dual kernel (2x11)	Dual kernel (2x11)	Dual kernel (FIR/IIR)
Adaptive Bayer Filter (ABF)	ABF2	ABF3	ABF3	ABF3	ABF3
Radial Noise Reduction (RNR)					√
ASF	ASF2.0	ASF2.2	ASF2.2	ASF2.2	ASF2.2
Local Tone Mapping (LTM)		√	√	√	√
Chromatic Aberration Correction (CAC)		CAC1	CAC1	CAC1	CAC2
Green Imbalance Correction (GIC)				√	√
Temporal (or 3D) Noise Reduction (TNR)		3DNR in VDP	TNR in CPP	TNR in CPP	TNR in CPP
Skin Noise Reduction (SNR)					√

Camera Updates – VFE Overview

MSM8974
baseline

APQ8084/
MSM8992

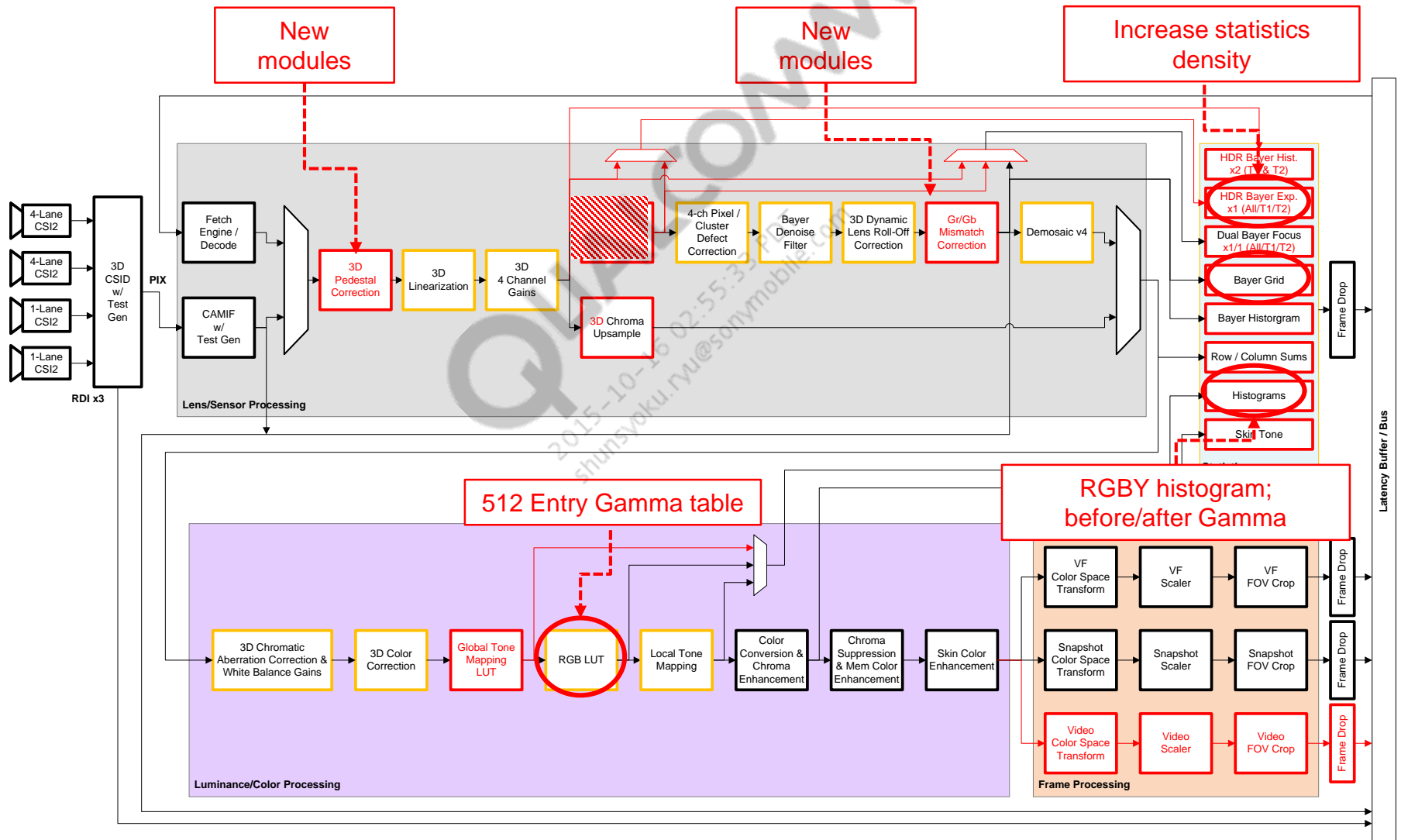


Camera Updates – VFE Overview (cont.)

MSM8974

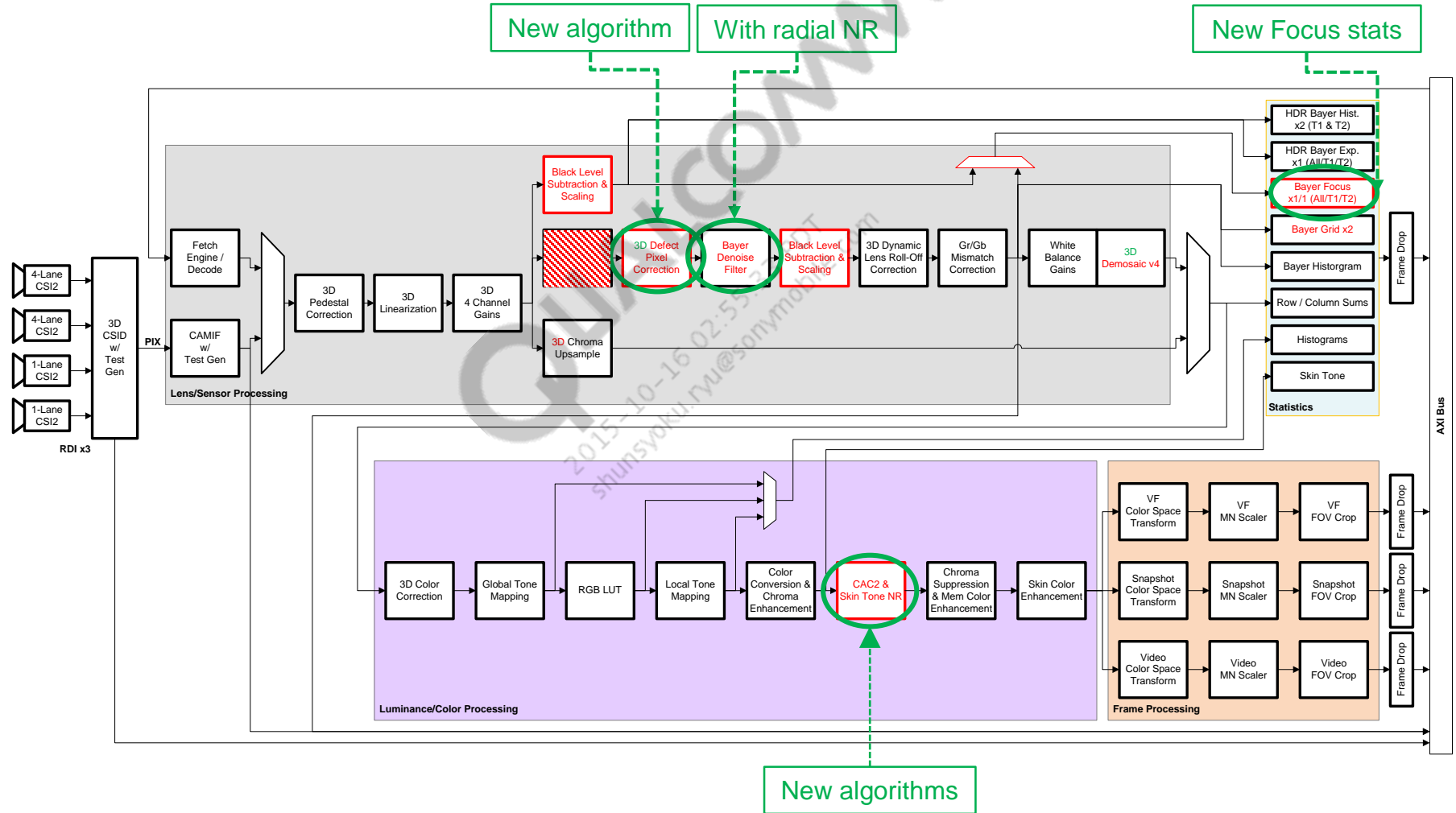
baseline

MSM8994



Camera Updates – VFE Overview (cont.)

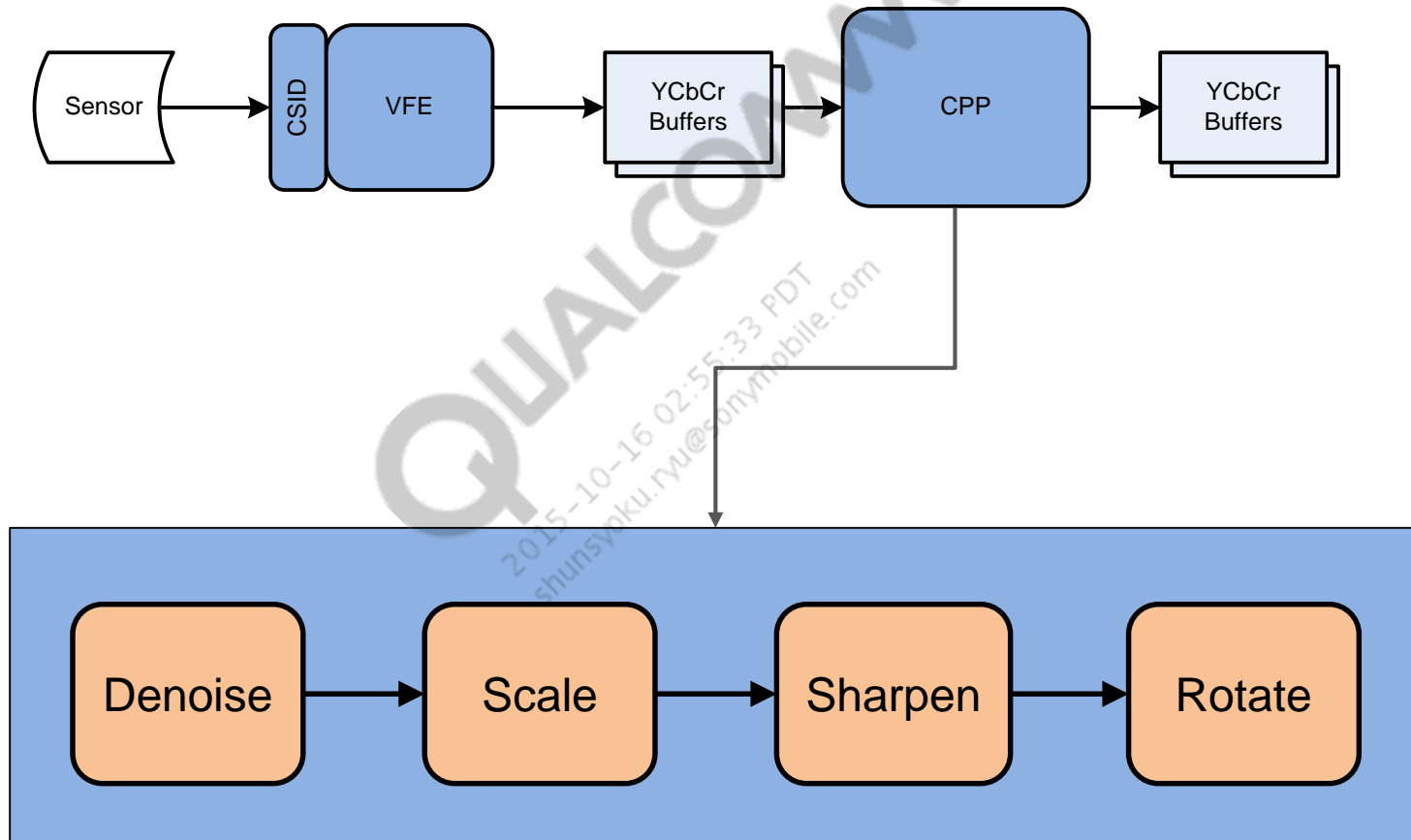
MSM8974
baseline



Camera Updates – MSM8974 CPP

MSM8974
baseline

MSM8996

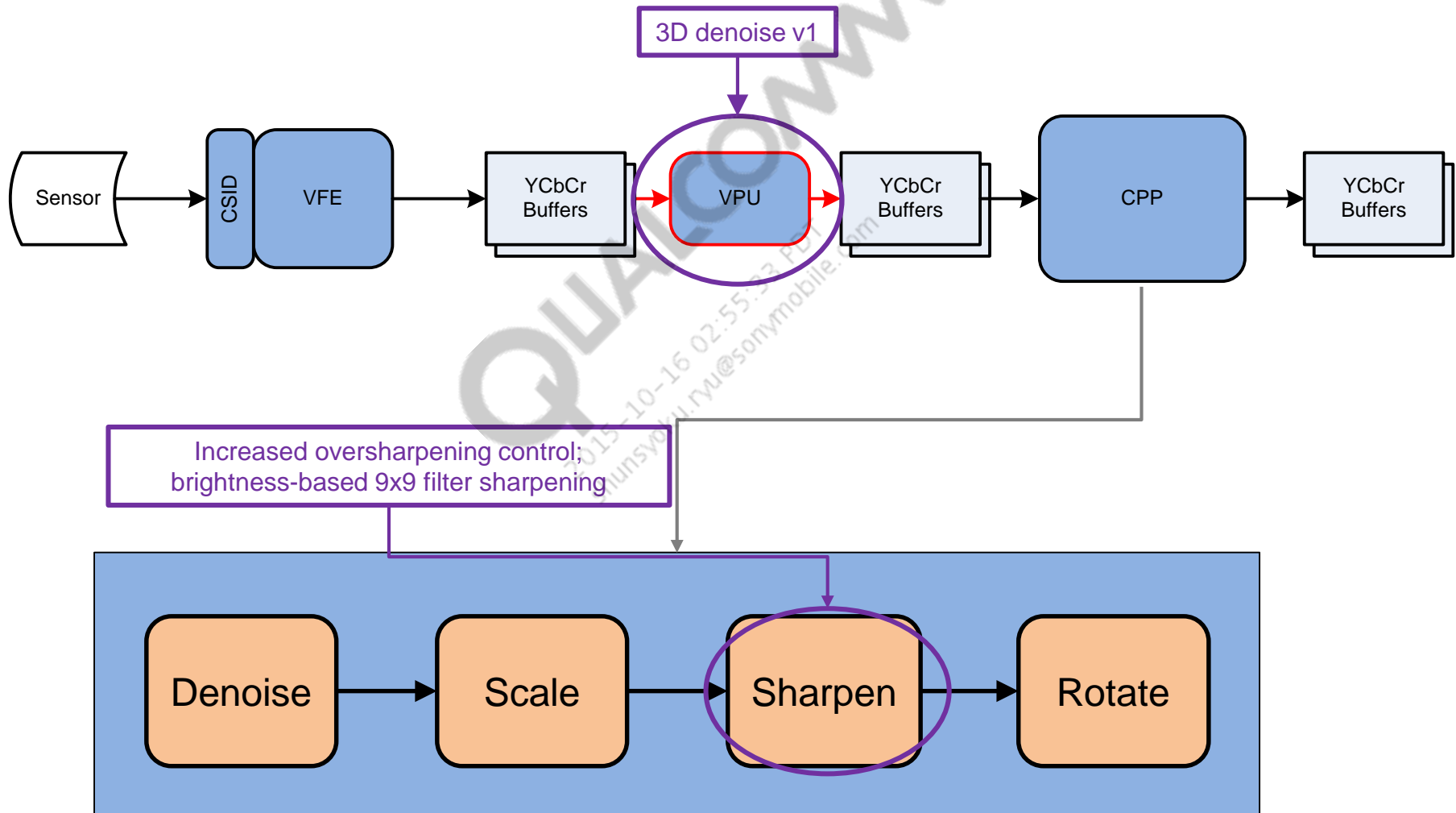


CPP core – 2D denoising, scaling, sharpening, rotation

Camera Updates – APQ8084 CPP/VPU

MSM8974
baseline

APQ8084



CPP core – 2D denoising, scaling, sharpening, rotation

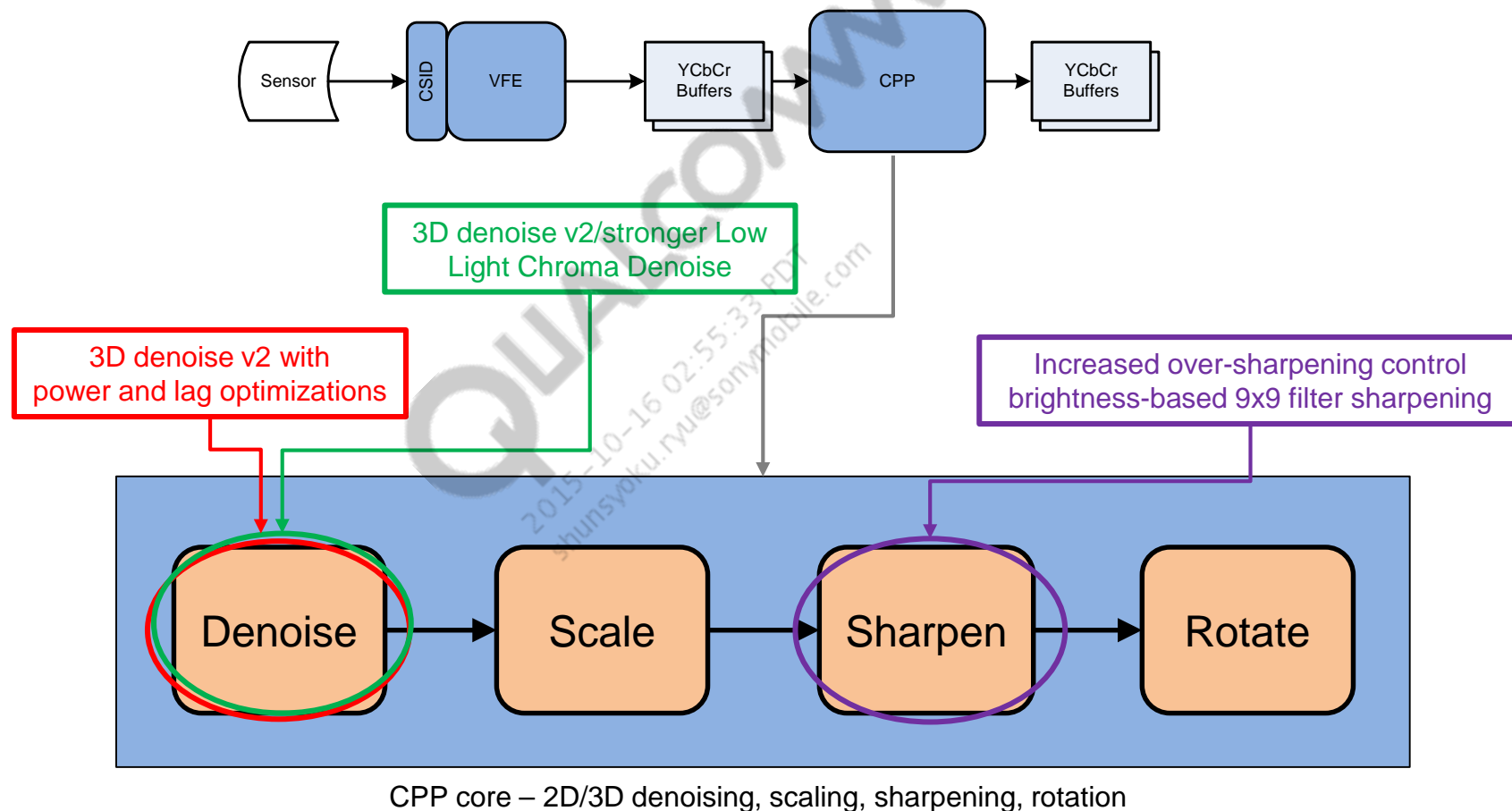
Camera Updates – MSM8992/MSM8994/MSM8996 CPP

MSM8974
baseline

MSM8992/
MSM8994

MSM8996

APQ8084



Defective Pixel and Cluster Correction



Problem – Defective Pixel and Cluster Correction

MSM8996

Problem

Defective pixel and cluster correction block corrects real defective pixel. However, unexpected color artifact can be caused by correcting normal pixels due to false positive defective pixel and cluster detection.



Without BPC



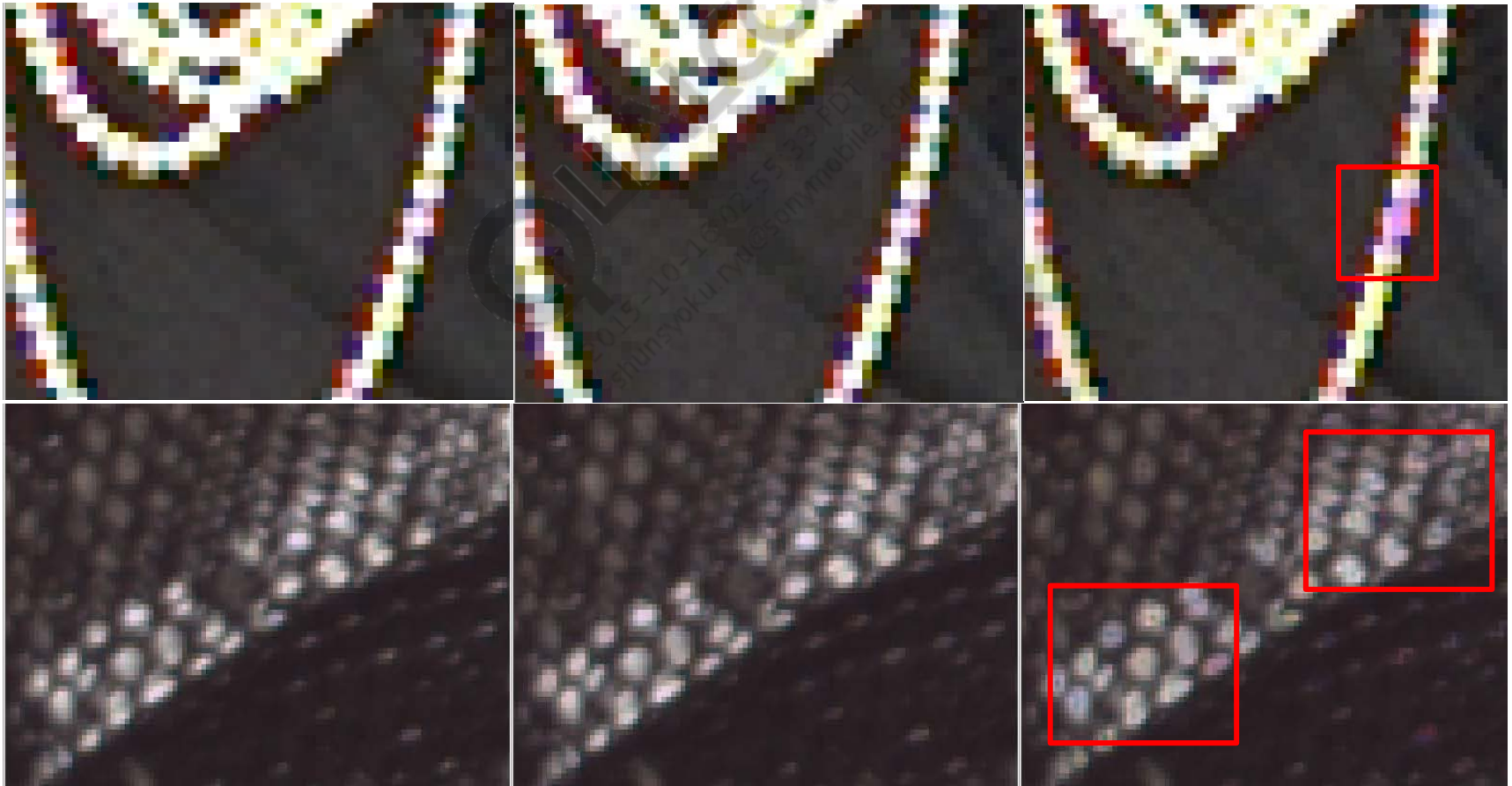
With BPC+False positive detection

Solution – Defective Pixel and Cluster Correction

MSM8996

Solution

Improve defective pixel and cluster detection algorithm; prevent color artifacts that can be caused by false positive detection



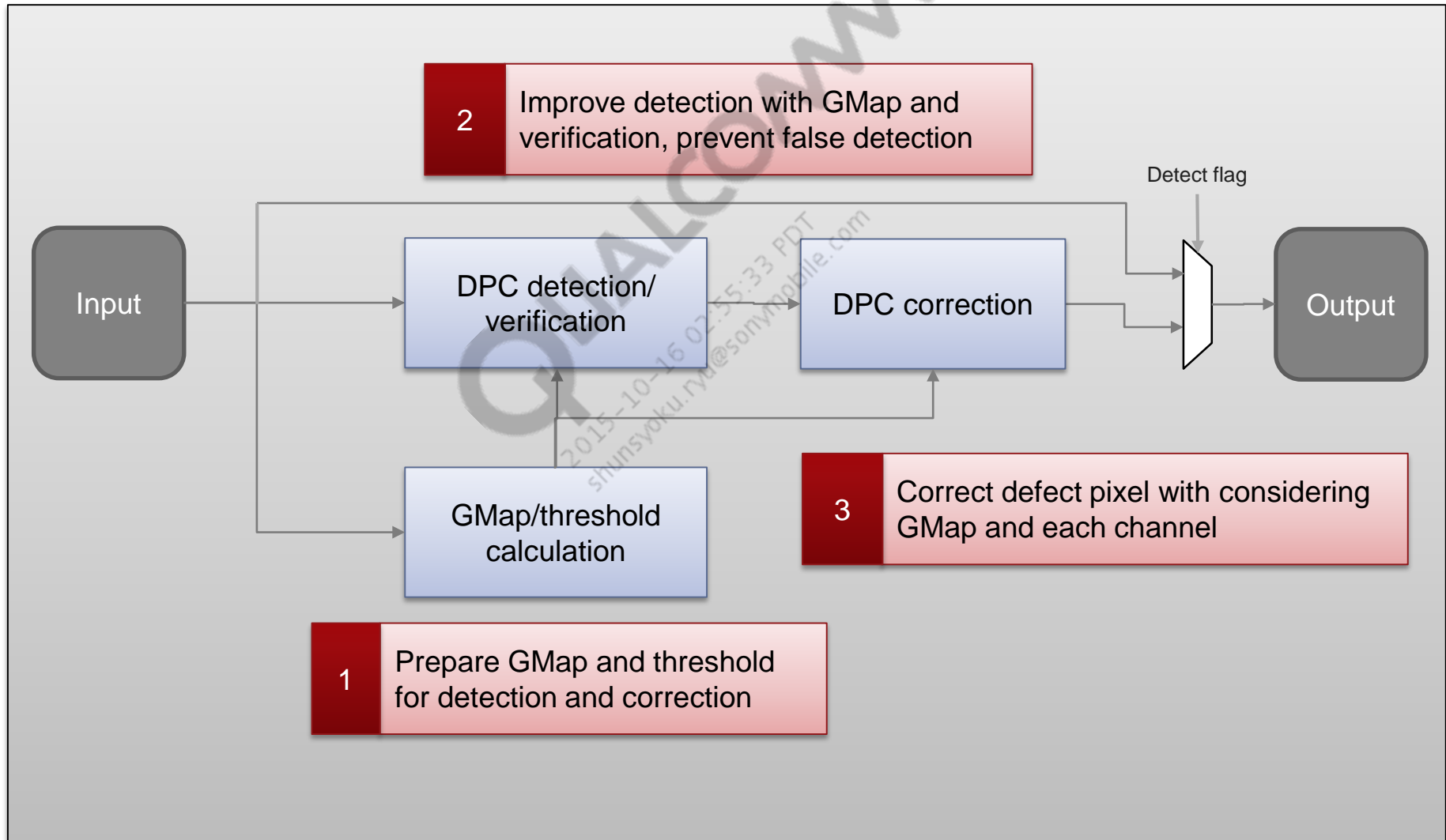
Without BPC

MSM8996

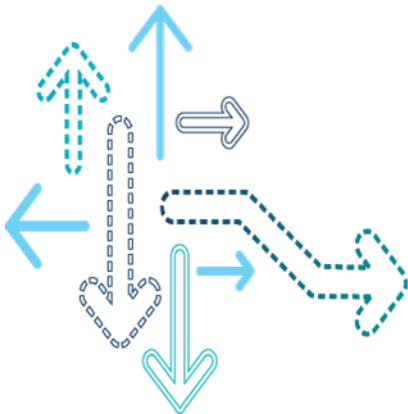
MSM8084/MSM8994/MSM8992

Block Diagram – Defective Pixel and Cluster Correction

MSM8996



Adaptive Bayer Filter, Ver 3 (ABF3)



Problem – ABF3

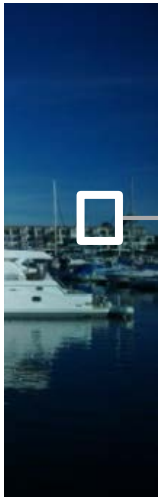
APQ8084/
MSM8992

MSM8994

MSM8996

Problem

Images captured by mobile camera sensor have a lot of noise that could be amplified by certain processing steps, making it more difficult to reduce in later phases of the imaging pipeline.



Without ABF3



With ABF3

Solution – ABF3

APQ8084/
MSM8992

MSM8994

MSM8996

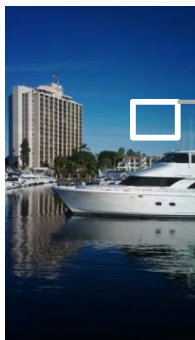
Solution

ABF3 minimizes noise in an early stage (Bayer domain) of the camera pipeline, improves performance in other modules, and reduces moderate green imbalance artifacts.

Without ABF3



With ABF3

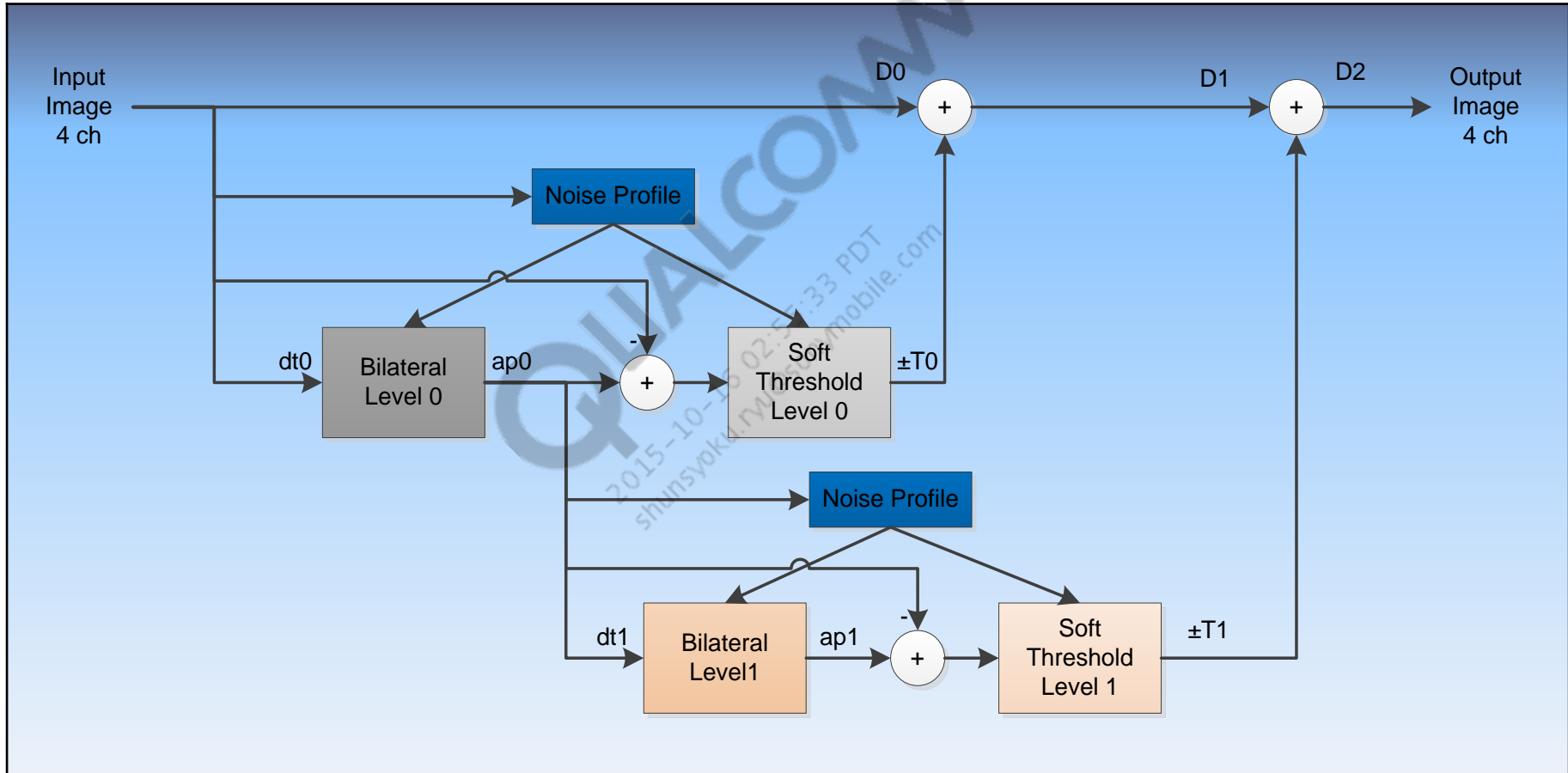


Block Diagram – ABF3

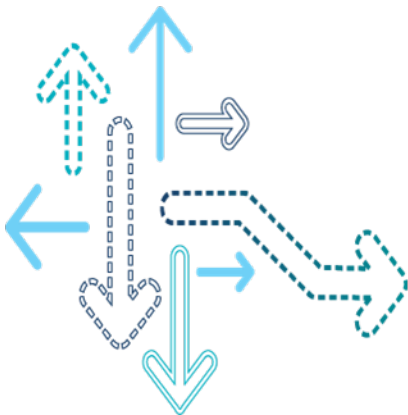
APQ8084/
MSM8992

MSM8994

MSM8996



RNR

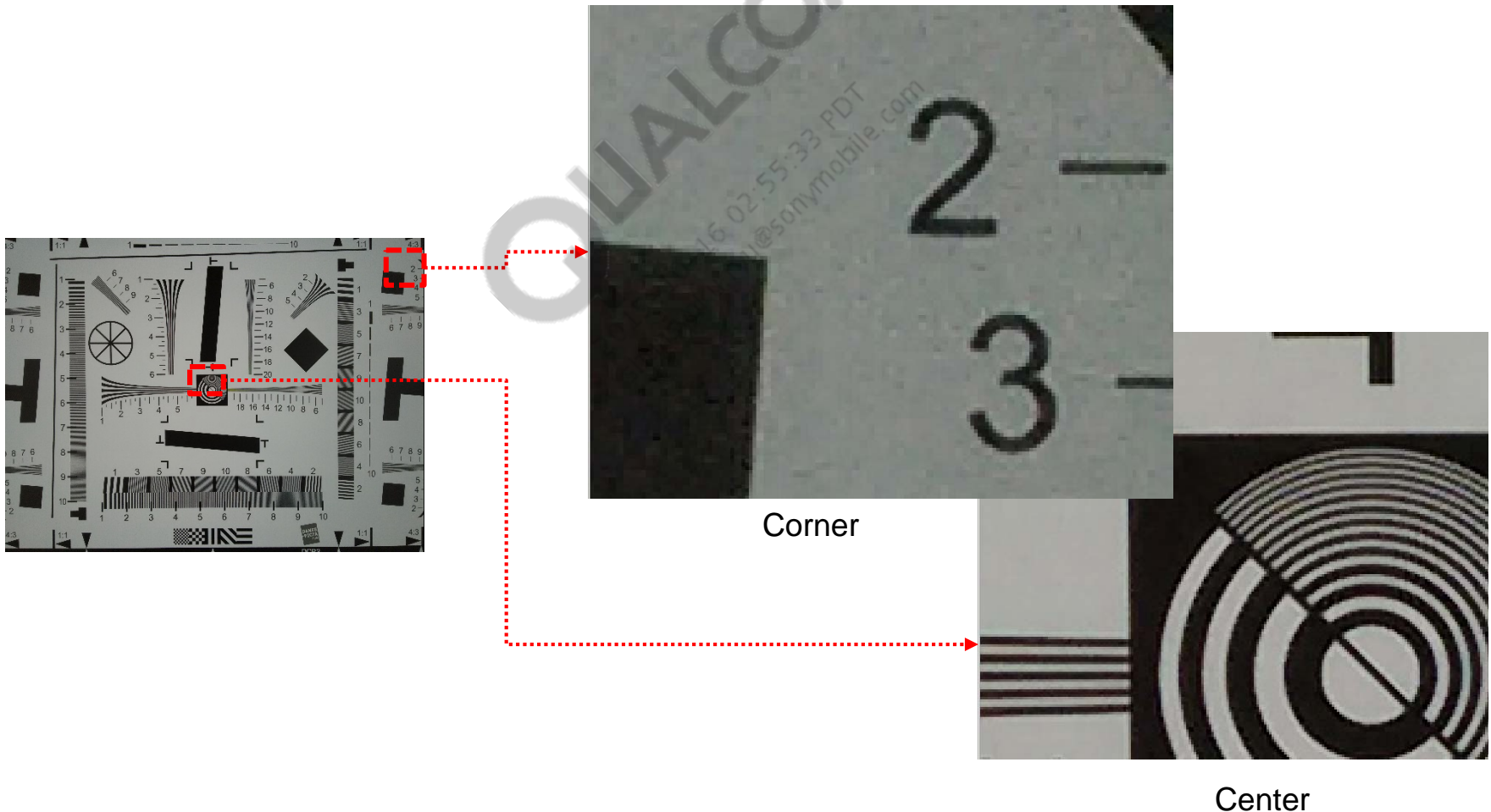


Problem – RNR

MSM8996

Problem

Noise, due to rolloff correction and other gain-related changes, is not uniformly distributed across the image. The corners of an image often suffer from increased noise.

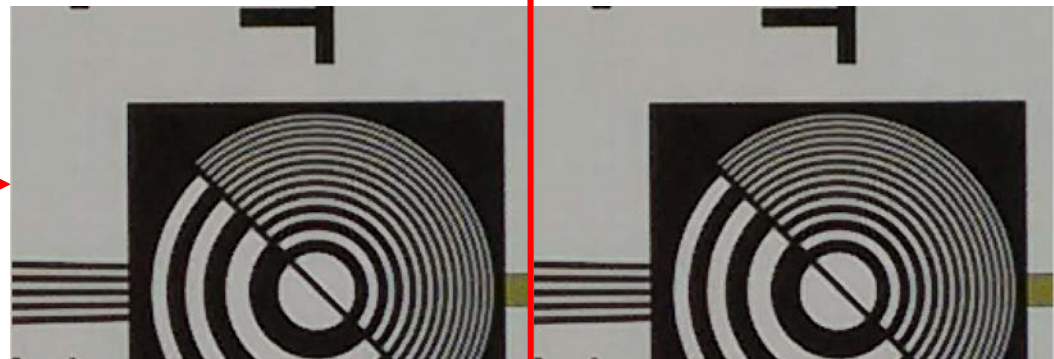
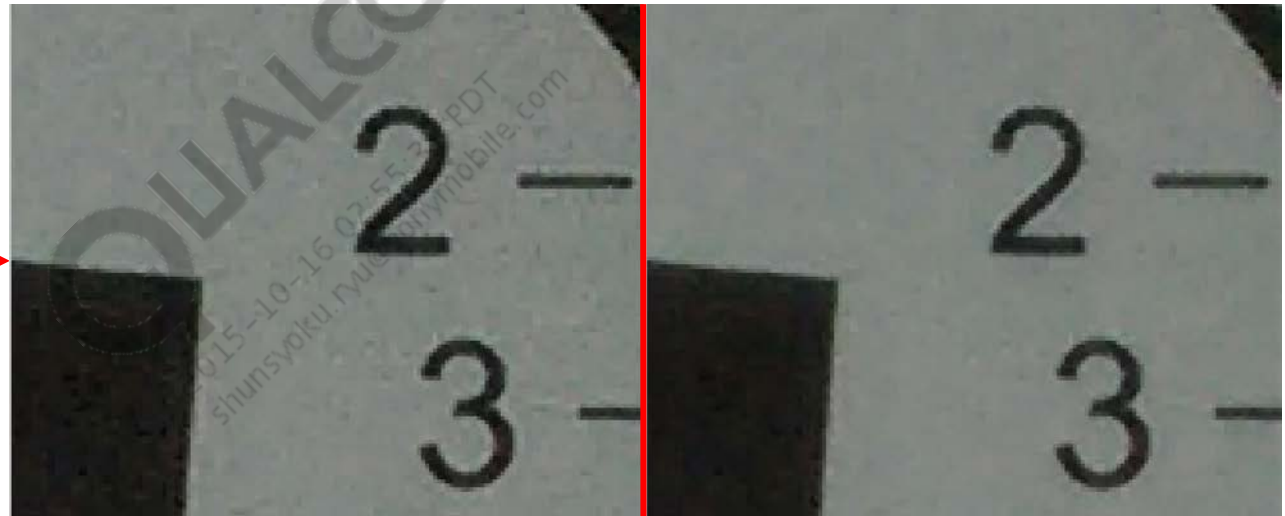
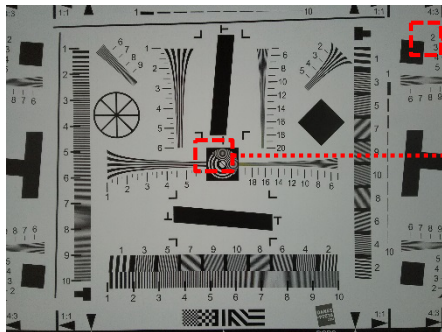


Solution – RNR

MSM8996

Solution

The purpose of RNR is to reduce nonuniformly distributed noise by applying different denoise strength radially based on the pixel position in the image. WNR is the main denoise block, while RNR is used to correct spatial nonuniformity noise issues.

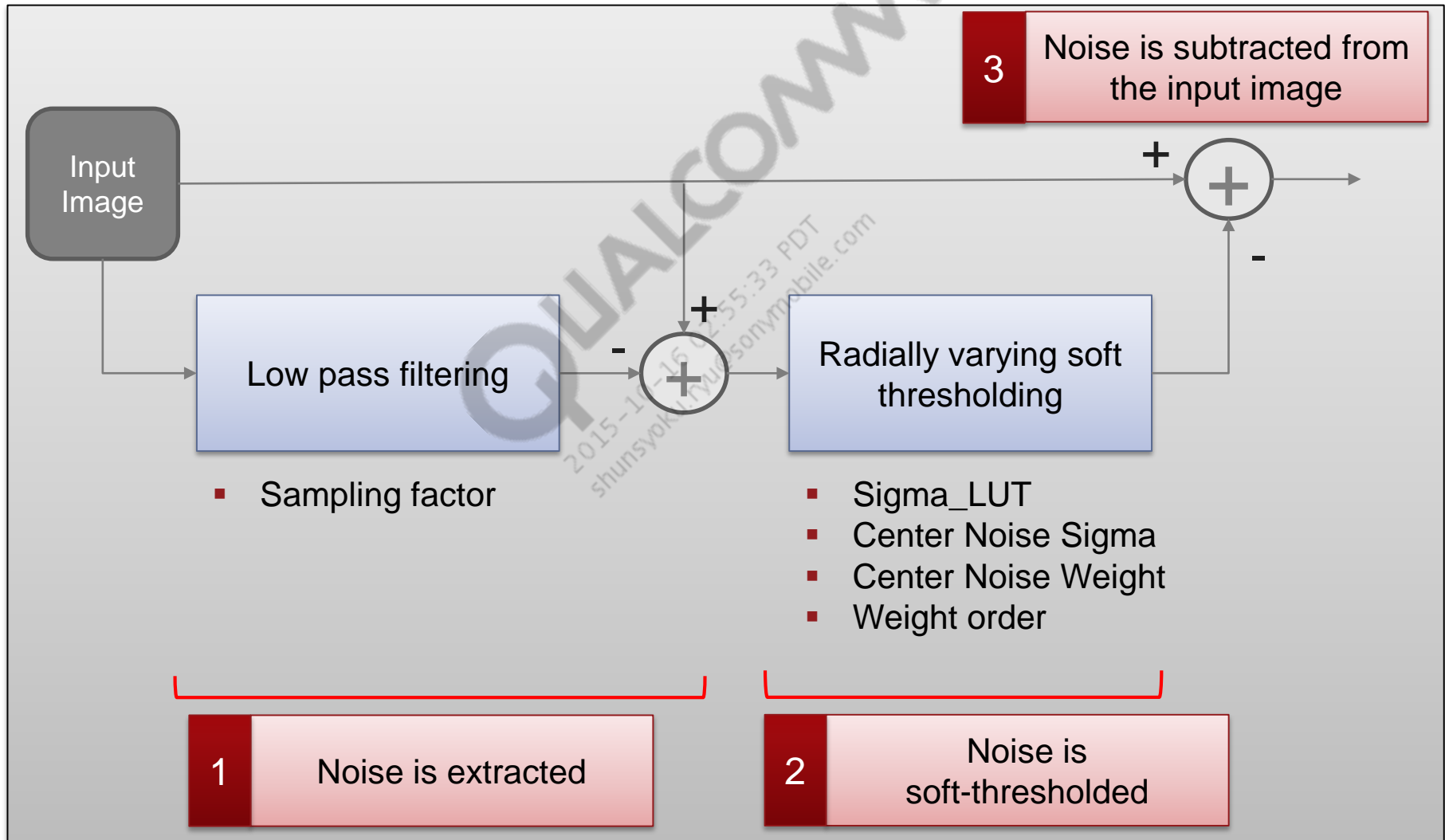


Without RNR

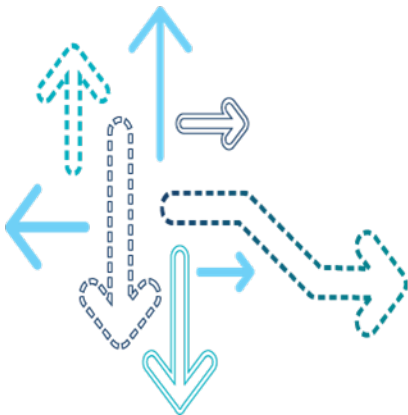
With RNR

Block Diagram – RNR

MSM8996



Demosaic



Problem – Demosaic

APQ8084/
MSM8992

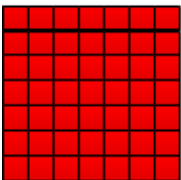
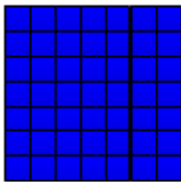
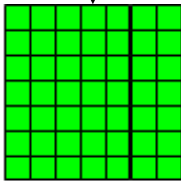
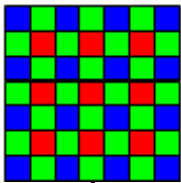
MSM8994

MSM8996

Problem

Demosaic v3 (MSM8974) recovers high-resolution details, but suffers from jagged and zipper artifacts on diagonal color and high-contrast edges.

Bayer image



Demosaic



Jaggy artifacts



Zipper artifacts



Solution – Demosaic

APQ8084/
MSM8992

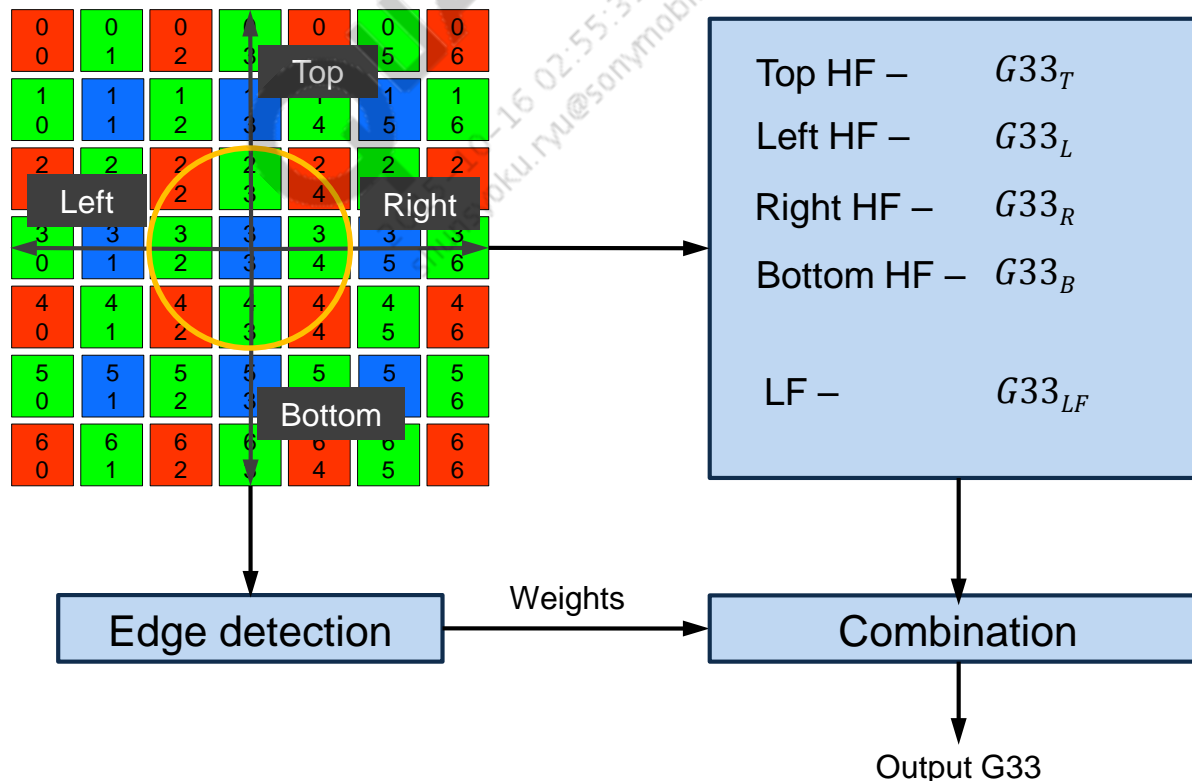
MSM8994

MSM8996

Solution

Instead of using 2-directional interpolation, Demosaic v4 (APQ8084/MSM8992/MSM8994) uses 4-directional High-Frequency (HF) interpolation combined with Low-Frequency (LF) interpolation to obtain separate estimates of color differences in four different directions. This removes jagged and zipper artifacts while preserving high resolution.

Take G33 interpolation for example



Sample Image – Demosaic

APQ8084/
MSM8992

MSM8994

MSM8996

Demosaic

Demosaic v4 removes jagged/zipper artifacts and improves edge continuity along diagonal color and high contrast edges.

Jagged edges



Zipper artifacts



Demosaic v3

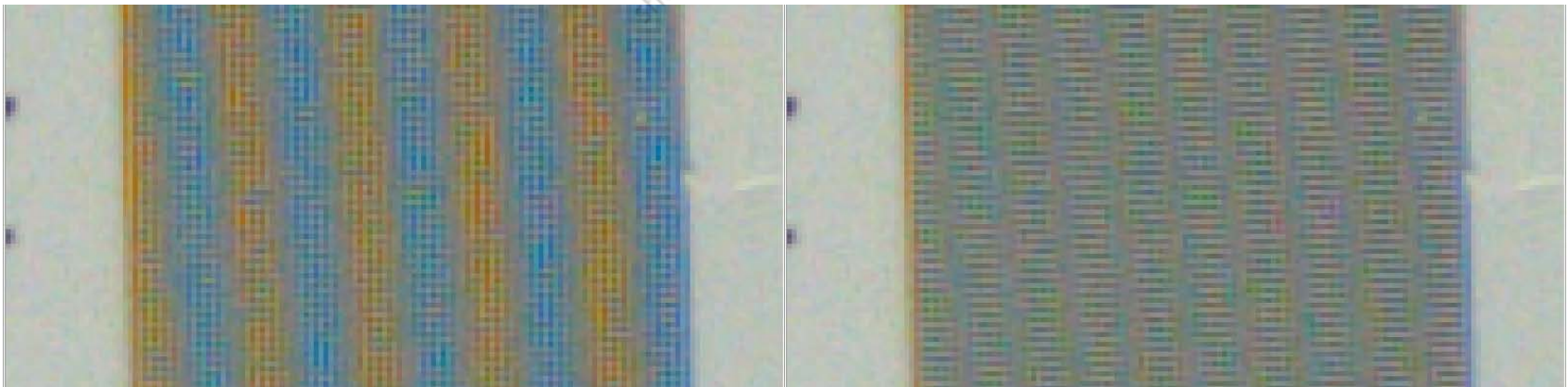
Demosaic v4

Sample Image – Demosaic (cont.)

MSM8996

Demosaic

MSM8996 chipset has improved green channel interpolation on top of Demosaic v4.



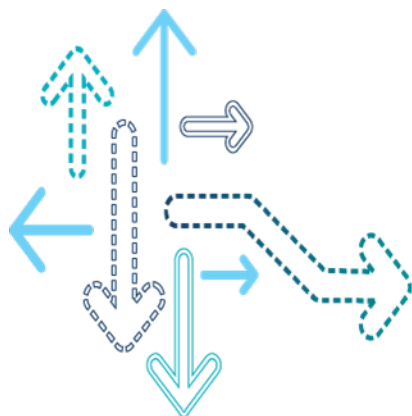
APQ8084/MSM8992/MSM8994

MSM8996

MSM8996



ASF



Problem – ASF

MSM8992/
MSM8994

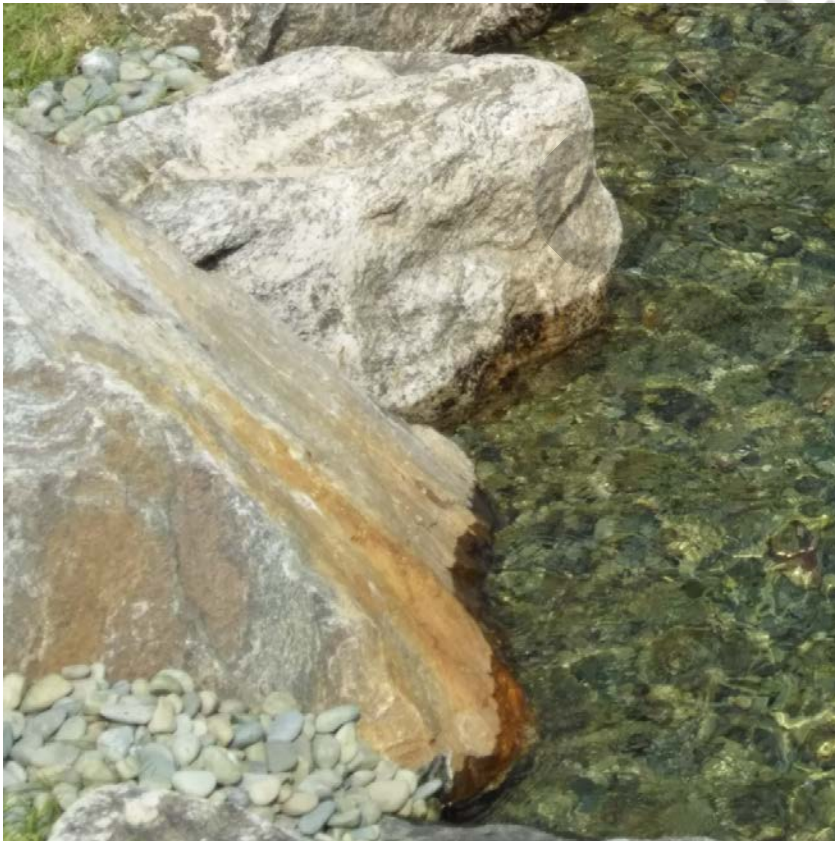
APQ8084

MSM8996

Problem

Images look blurry and lack enough contrast/details after WNR.

After WNR



With ASF



Solution

Comparison between MSM8974 and MSM8994/MSM8992/APQ8084 – The key benefit of MSM8994/MSM8992/APQ8084 ASF over MSM8974 ASF is that MSM8994/MSM8992/APQ8084ASF can apply accurate enhancement based on local intensity with more angular resolution for sharpening.



MSM8974



MSM8994/MSM8992/APQ8084

Sample Image – ASF

MSM8992/
MSM8994
MSM8996

APQ8084

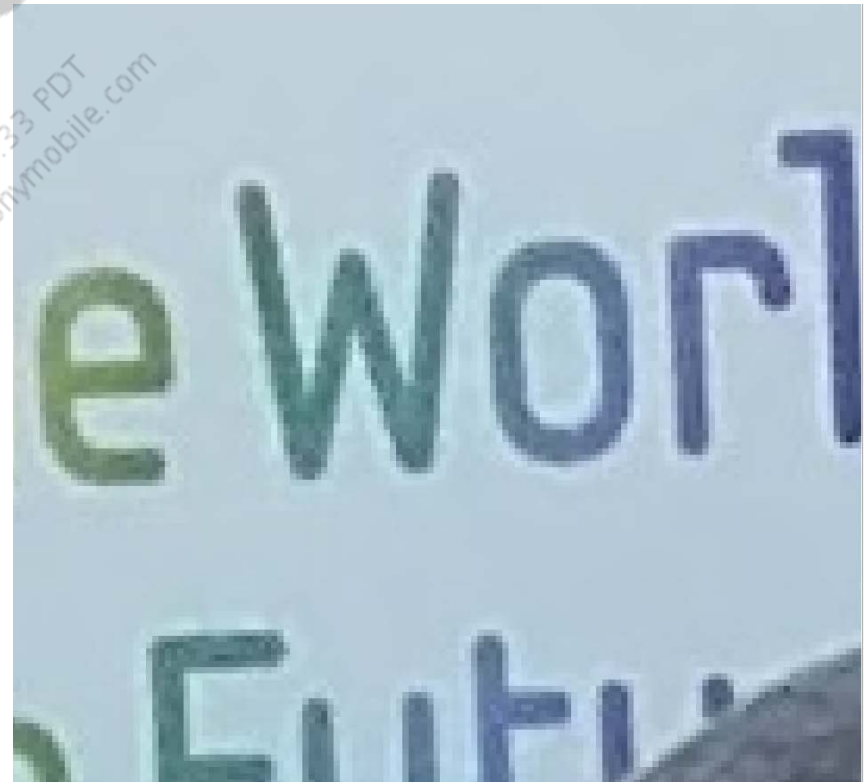
ASF

Comparison between directional and symmetric sharpening

Edges are cleaner with less artifacts



4-directional and symmetric sharpening

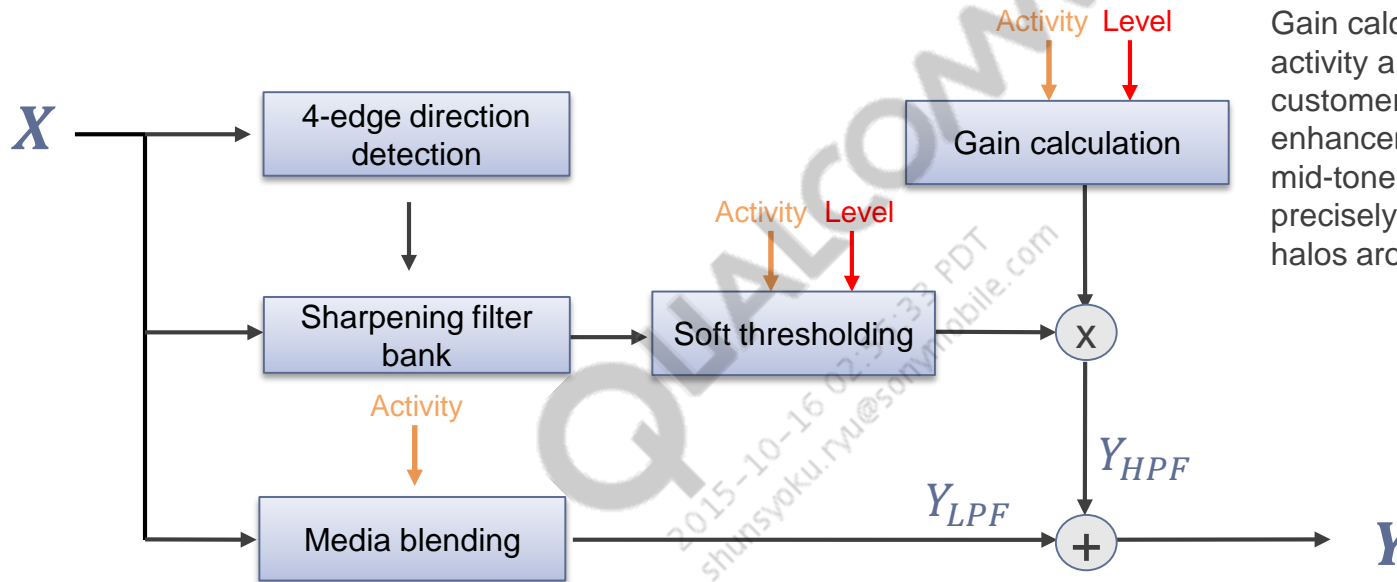


Symmetric sharpening

Block Diagram – ASF

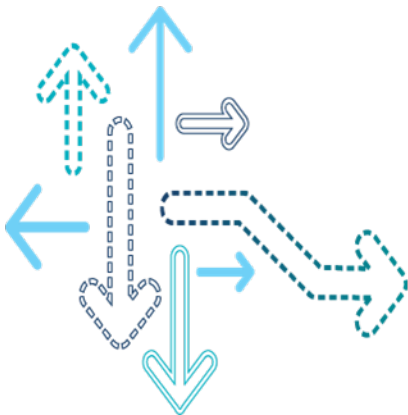
MSM8992/
MSM8994
MSM8996

APQ8084

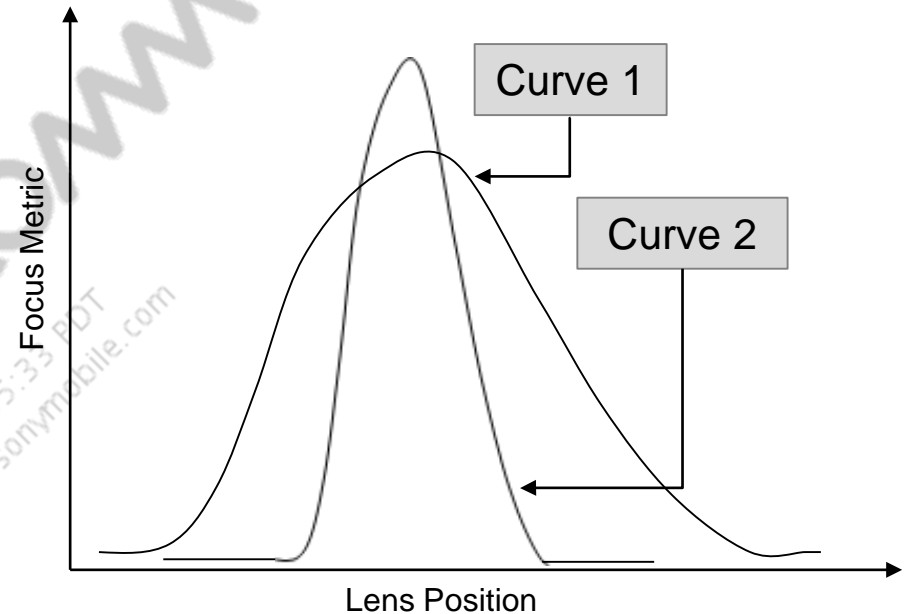


Activity – Measure of local patch variance/business
Level – Approximation of local brightness level

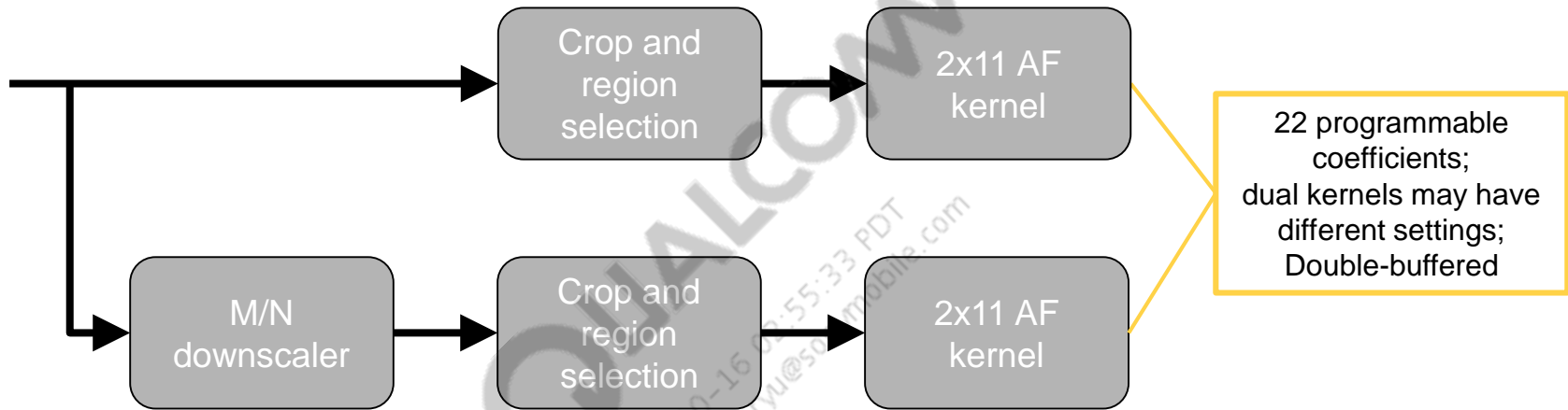
New AF Statistic



- Dual kernels and larger kernels will improve AF performance
 - Dual kernel
 - Kernel1 provides metrics based on larger regions of the image; this provides a smooth and robust measure for driving the direction of the actuator.
 - Kernel2 provides metrics based on fine detail; this gives good accuracy for achieving the peak focus position.
 - Together the two kernels allow for a fast and accurate focus search.
 - Larger kernels
 - Larger AF kernels allow for better frequency response in handling large resolution sensors.

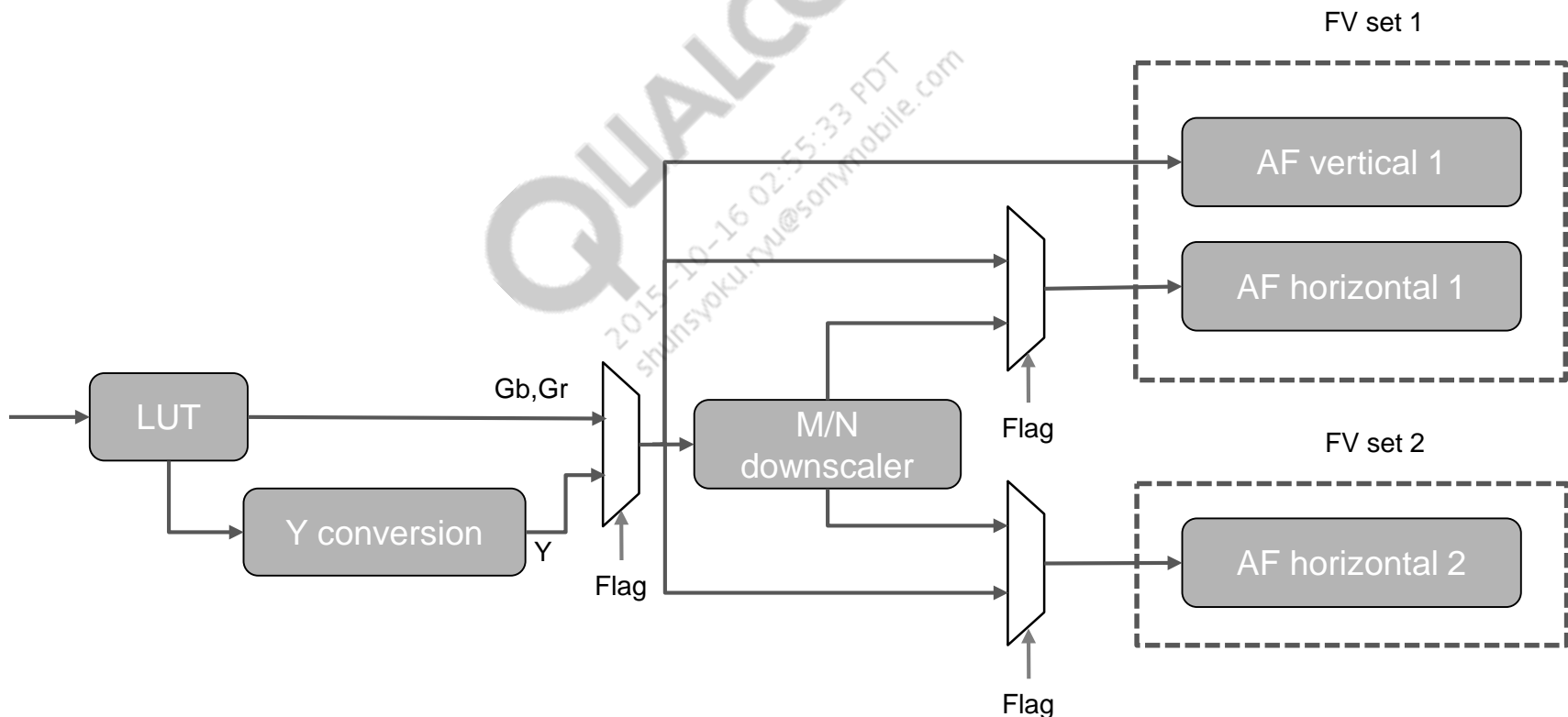


- Architecture – Add one set of Bayer focus filter with a downscaler.

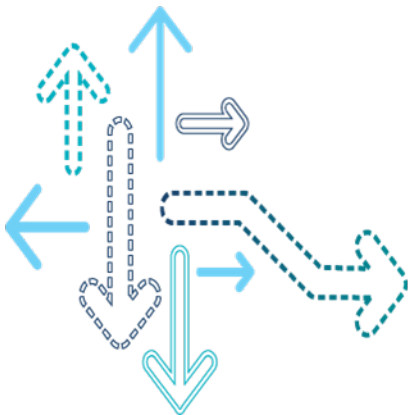


- Region of interest is divided into a grid with **up to 18x14 regions**
- Calculation of sharpness metric for R, B, Gr, Gb channels in each region

- FIR and IIR filters in horizontal and vertical focus engines
 - FV_H – 13-tap FIR+Fourth order IIR; FV_V – 5-tap FIR+Second order IIR
- Dual scales of horizontal focus engines

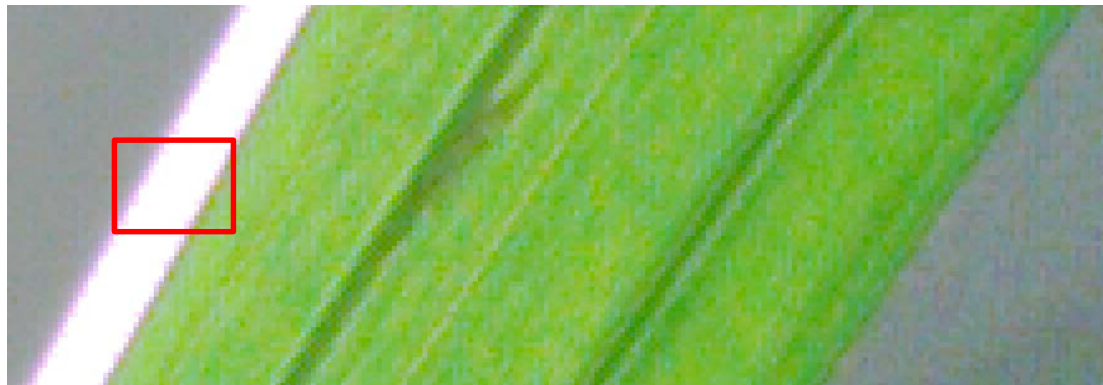
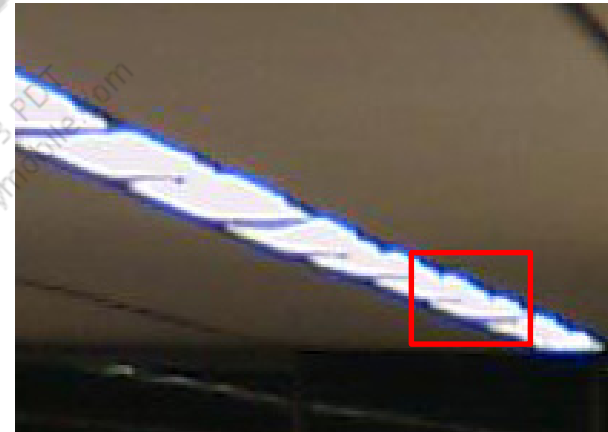


CAC Ver 1 and Ver 2



Problem

Chromatic aberration produces undesirable colors that may appear at light and dark boundaries in an image, which negatively impacts the image quality.



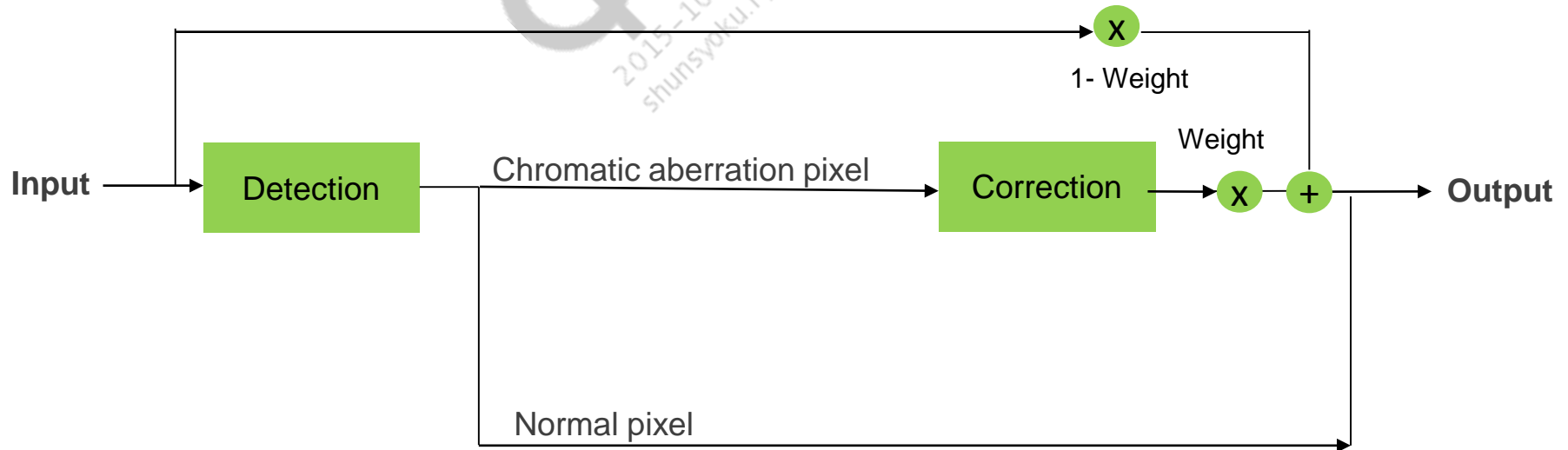
Solution

Detection – Pixels must meet the following conditions:

- An Edge Pixel
- Beside a saturated region
- Neighbor's luminance monotonically changing
- Inside a color range
- Not among color range from its neighbors

Correction – Use weighted average between:

- (*Max* of its neighbors) *and* (original chromatic value), or
- (*Min* of its neighbors) *and* (original chromatic value)



Sample Image – CAC Ver 1

APQ8084/
MSM8992

MSM8994

CAC

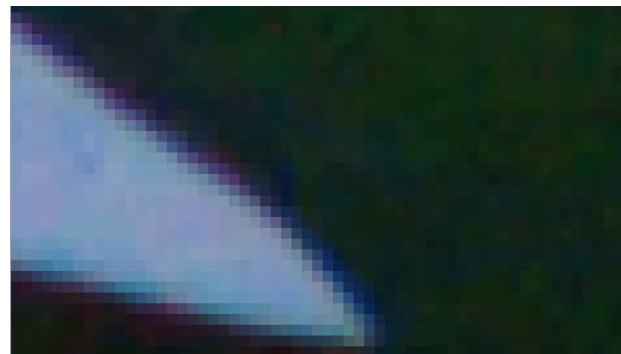
Can remove chromatic aberration successfully



CAC off



CAC on



CAC off



CAC on

Problem – CAC Ver 2

MSM8996

Problem

Chromatic aberration produces undesirable colors that may appear at light and dark boundaries or spot in an image, which negatively impacts the image quality.



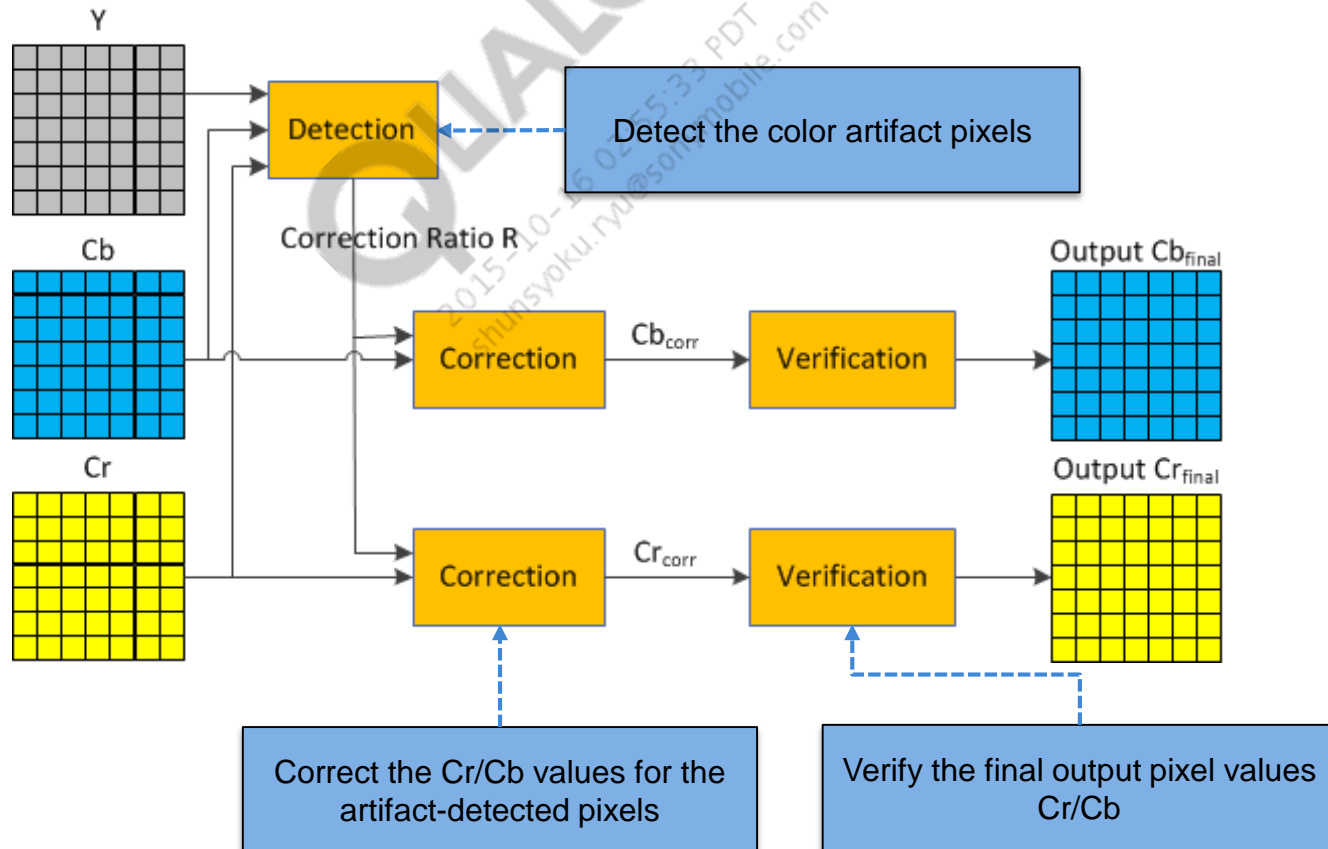
Solution

Detection – Pixels must meet the following conditions:

- Color spot or within Y saturation threshold
- Inside a color saturation range

Correction:

- Using 5x3 median filter with direction
- Correcting CbCr and clamping range



Sample Image – CAC Ver 2

MSM8996

CAC

Can remove false color on edge and color spot successfully

CA on Edge



Color Spot

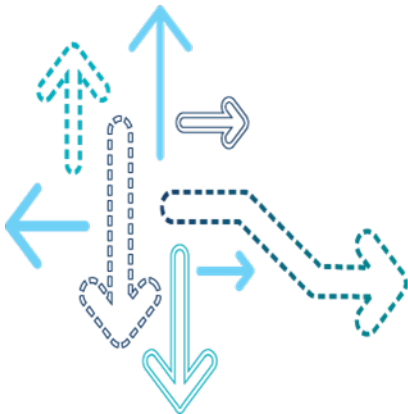


CAC off

CAC Ver 1

CAC Ver 2

SNR

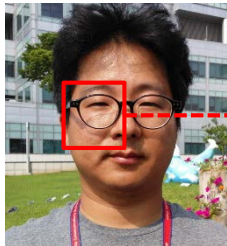


Problem – SNR

MSM8996

Problem

Natural scenes usually require strong sharpening for better visual quality. However, sharpening block generates unpleasing artifacts for skin-tone regions when applying strong enhancement.



Solution – SNR

MSM8996

Solution

Applying denoise to Y channel of pixels that is detected as skin tone
soft threshold based on probability of skin tone pixels



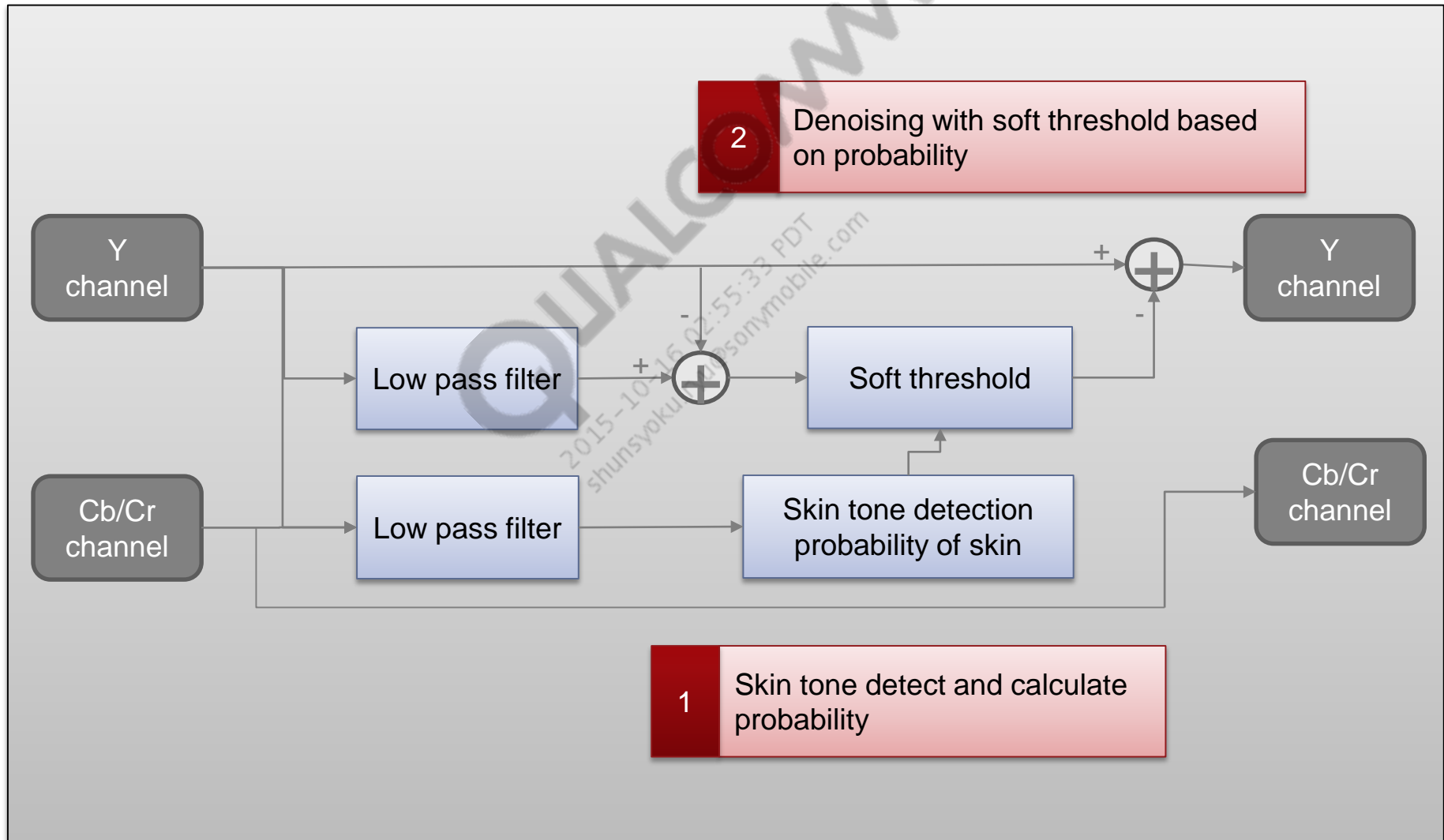
Without SNR



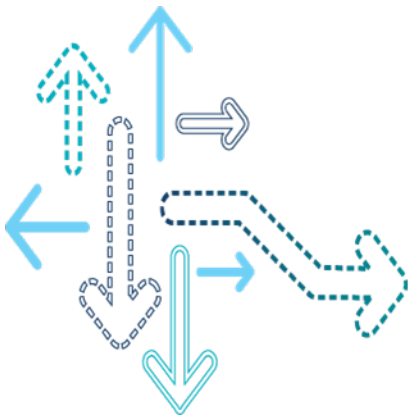
With SNR

Block Diagram – SNR

MSM8996



LTM



Problem

Natural scenes typically have a wide dynamic range. Images captured by a camera system have a lot of information that is not easily visible or obvious on display devices. Two tone mapping approaches can be used to bring obscured details in dark or bright regions to a more visible data range. The following two approaches can be used:

- **Global Tone Mapping** – Adjusts all pixels based on their values
- **LTM** – Examines each pixel's neighborhood and decides whether the pixel needs lightening or not

Although GTM can lighten area regions, it reduces contrast in normal and bright regions. As a result, the image may look flattened.

Problem

Typical camera imaging pipe cannot handle this wide dynamic range very well

Very bright area

Very dark area
Difficult to discern the details in the dark area



LTM

LTM is designed to illuminate dark areas while keeping other tone regions untouched. Also, highlight can be suppressed in order to avoid light saturation.



Original image

GTM

Normal light areas are also modified by GTM and result in either contrast loss or tone change.

LTM

With LTM, dark areas are lightened while other areas are not touched.

Sample Image – LTM

MSM8994

MSM8996

APQ8084/
MSM8992

Original



LTM



Highlight tone details
are preserved

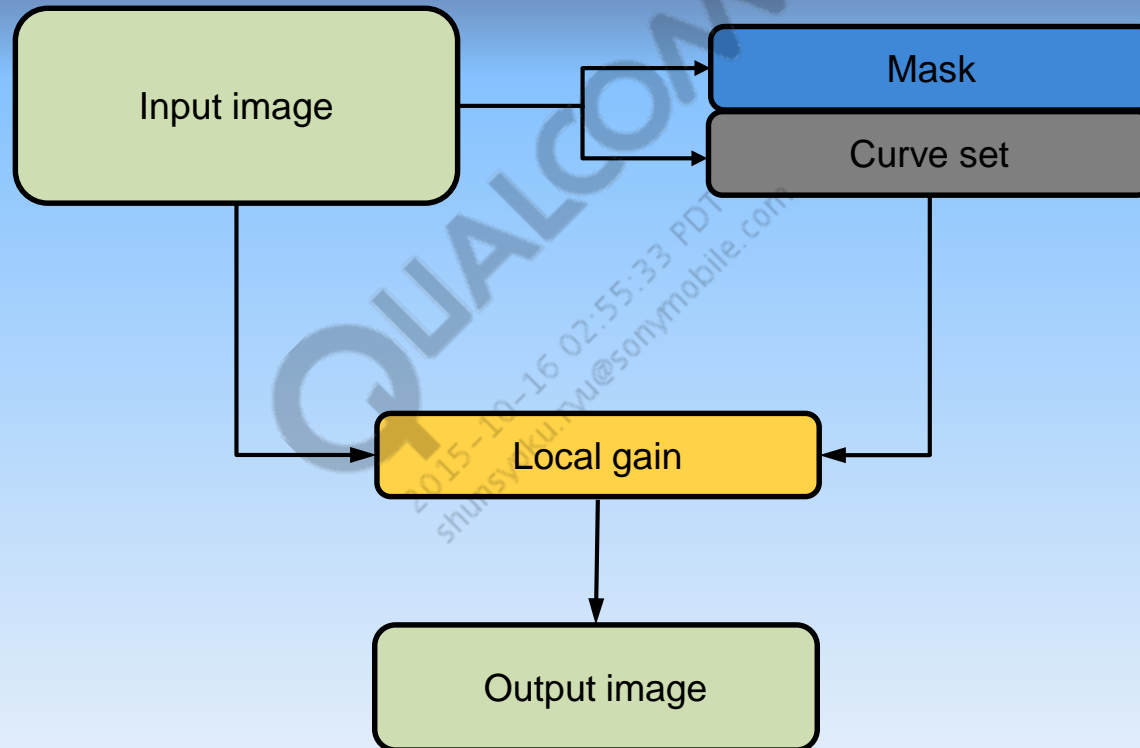
Dark details are more
visible with LTM

Block Diagram – LTM

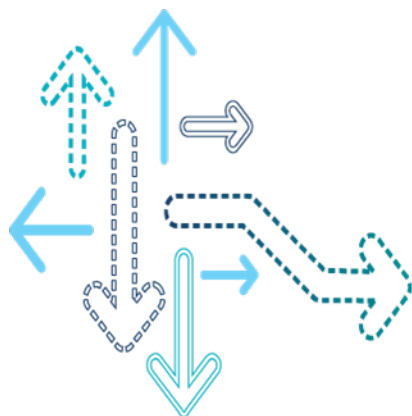
MSM8994

APQ8084/
MSM8992

MSM8996



GIC



Problem – GIC

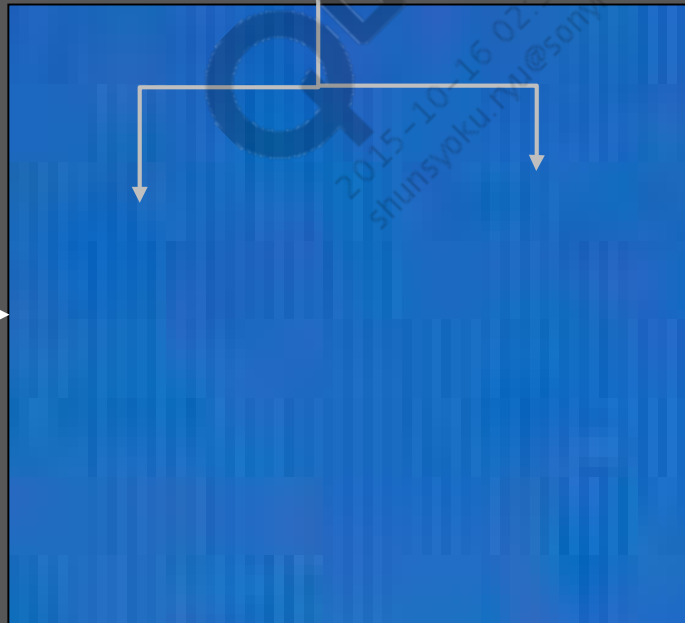
MSM8994

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Problem

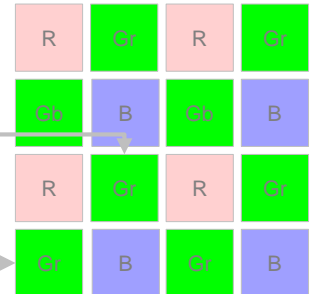
Some sensors have a significant imbalance between Gb and Gr channels. Those artifacts may not be fully corrected by the noise reduction block in the Bayer domain ABF in MSM8994.

Vertical bands are visible due to the imbalance between the Gr and Gb channel in the Bayer domain.



Sensor without Gr/Gb imbalance

Same sensitivities of Gr/Gb channels



Sensor showing Gr/Gb imbalance

Different sensitivities of Gr/Gb channels

Gr/Gb imbalance artifact



Solution

GIC removes the banding artifacts caused by the different sensor sensitivities between Gr and Gb channels.

Bayer noise reduction – Off
Green Imbalance Correction – Off

Noise observed
without Bayer noise reduction



Bayer noise reduction – On
Green Imbalance Correction – Off

Banding artifact is noticeable
even with Bayer noise reduction



Bayer noise reduction – On
Green Imbalance Correction – On

GIC removes the banding artifact



Sample Image – GIC

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GIC

GIC is designed to remove strong green imbalance artifacts.

Without independent GIC



Vertical Banding

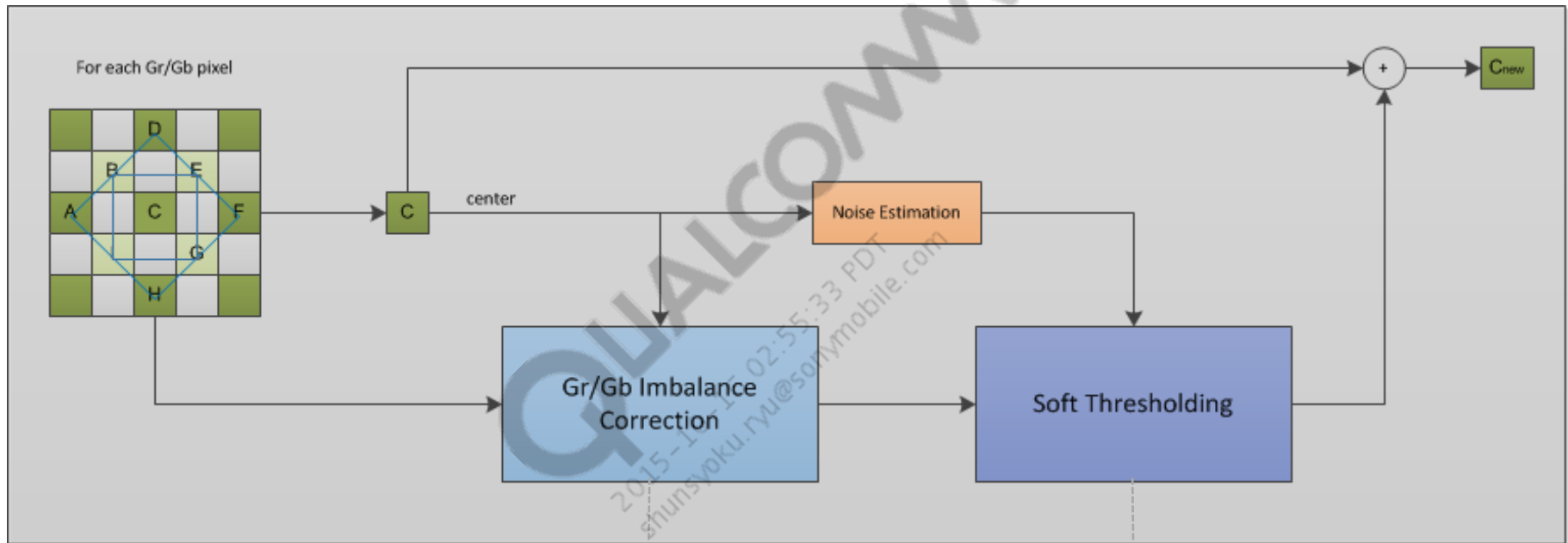
With independent GIC



Block Diagram – GIC

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Gr/Gb Imbalance Correction

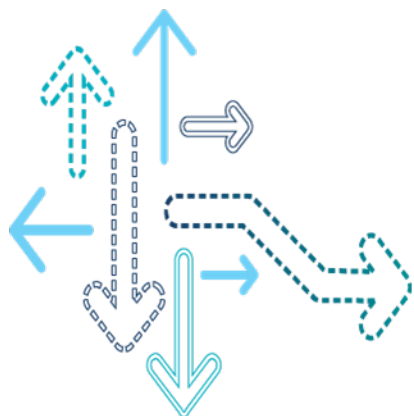
Taking the center value C and its Gr/Gb neighborhood pixel values, determine the amount of the imbalance correction. The amount of pixel value correction will be applied to the center pixel value to generate a new output C_{new}.

Soft Thresholding

Refine the amount of the imbalance correction based on the noise estimation. The noise is characterized as a function of pixel level (brightness). In APQ8084/MSM8994, the noise estimation can be shared with ABF3.

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WNR



Problem – WNR

Problem

Low frequency color noise in lowlight scene is noticeable on the image even though denoising is applied with the fourth layer WNR.



Solution – WNR

Solution

Adding fifth, sixth layer to WNR for reducing low frequency noise

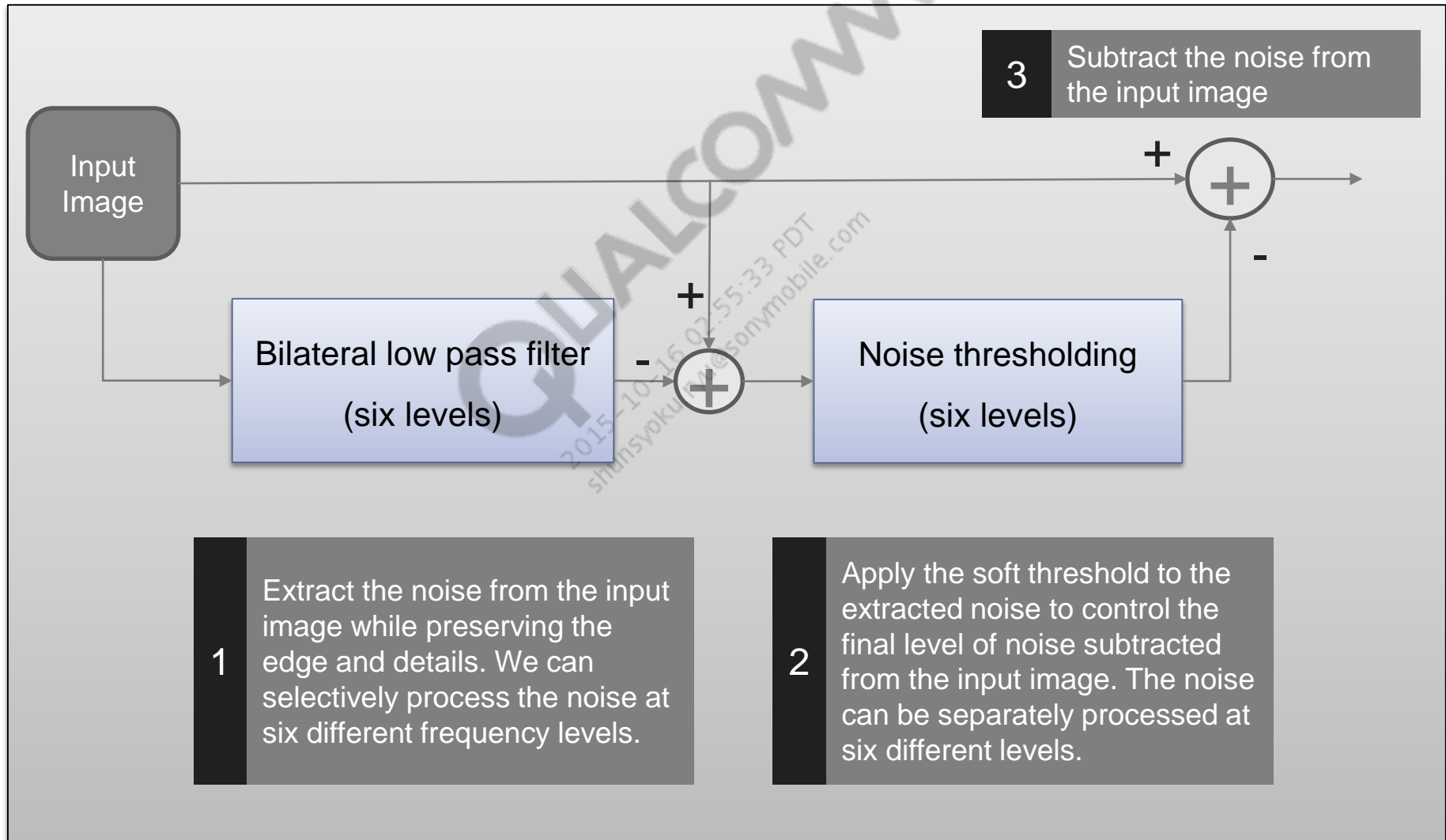


Fourth layer WNR
MSM8974/APQ8084/MSM8994/MSM8992

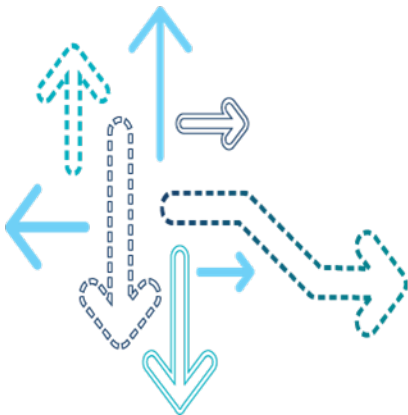


Sixth layer WNR
MSM8996

Block Diagram – WNR



TNR



Problem – TNR

MSM8992/
MSM8994

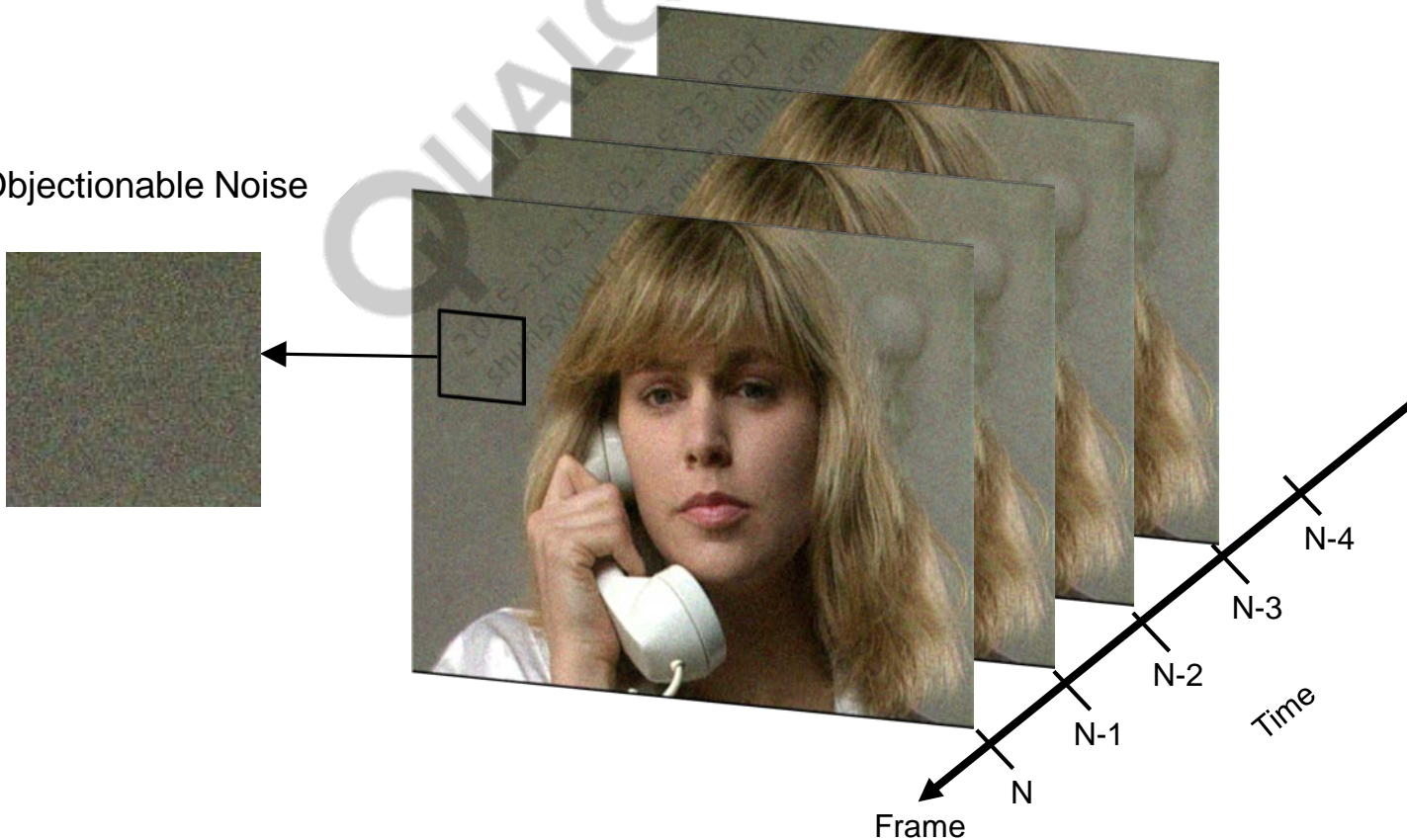
APQ8084

MSM8996

Problem

In the video (camera preview or video recorded from camera), noise is not efficiently reduced by using only the spatial noise reduction block, e.g., WNR in CPP.

Objectionable Noise



Solution – TNR

MSM8992/
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APQ8084

MSM8996

Solution

TNR block efficiently reduces the temporal noise by appropriately processing the current and previous frames.

TNR uses the previous frames to reduce the noise in the current frame



Sample Video – TNR

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TNR Off



TNR On

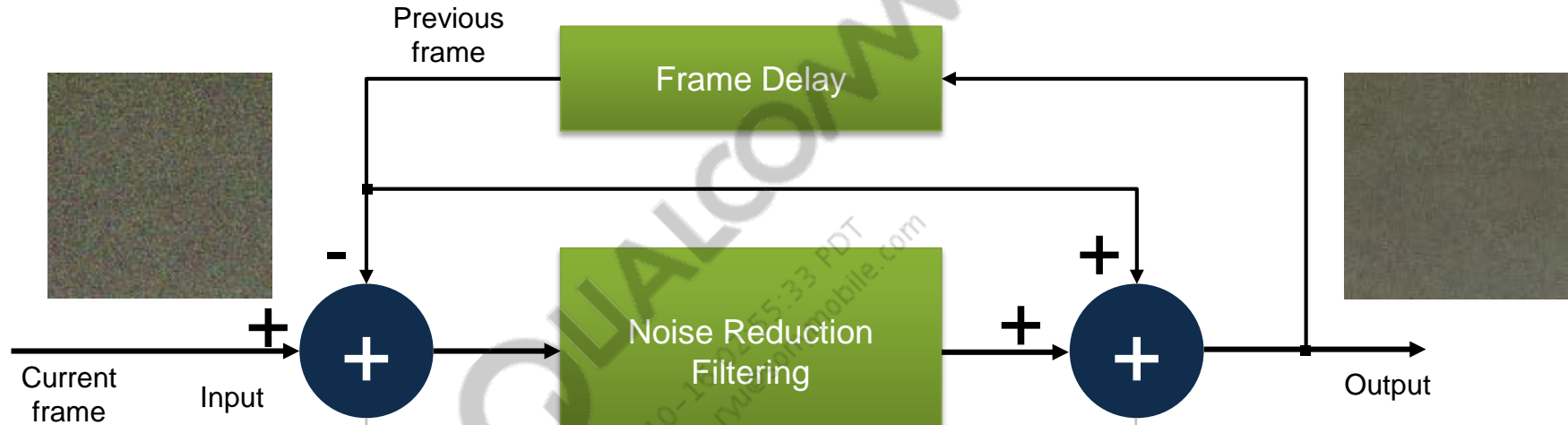


Block Diagram – TNR

MSM8992/
MSM8994

APQ8084

MSM8996



1

Generate the image between the current and previous frames.

2

Reduce the noise.

3

Add the previous frame image to the noise reduced image to generate the final output.

Acronyms

Acronyms	
Term	Definition
ABF3	Adaptive Bayer Filter, Ver 3
ABF	Adaptive Bayer Filter
ASF	Adaptive Spatial Filter
AF	Auto Focus
CAC	Chromatic Aberration Correction
GIC	Green Imbalance Correction
HF	High-Frequency
LTM	Local Tone Mapping
LF	Low-Frequency
RNR	Radial Noise Reduction
SNR	Skin Noise Reduction
TNR	Temporal Noise Reduction
WNR	Wavelet Noise Reduction

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Questions?

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