实验二 进程通信与内存管理

2.1 进程的软中断通信

```
#include <stdio.h>
#include <unistd.h>
#include <sys/wait.h>
#include <stdlib.h>
#include <signal.h>
int flag = 0;
pid_t pid_1 = -1, pid_2 = -1;
void inter_handler(int signal) {
        flag++;
        printf("\n%d stop test\n\n", signal);
        if (flag==1&& printf("16 stop test\n")&& printf("17 stop test\n"))
            kill(pid1, 16);
            kill(pid2, 17);
    }
void vv(){};
void waiting() {
    alarm(5);
}
int main() {
    while (pid1 == -1) pid1 = fork();
    if (pid1 > 0) {
        while (pid2 == -1) pid2 = fork();
        if (pid2 > 0) {
            signal(SIGINT, inter_handler);
            signal(SIGQUIT, inter_handler);
            signal(SIGALRM, inter_handler);
            waiting();
            wait(NULL);
            wait(NULL);
            printf("\nParent process is killed!!\n");
```

```
} else {
            signal(SIGQUIT, SIG IGN);
            signal(SIGINT, SIG IGN);
            signal(SIGALRM, SIG IGN);
            signal(17, vv);
            pause();
            printf("\nChild process2 is killed by parent!!\n");
            return 0;
        }
    } else {
        signal(SIGQUIT, SIG IGN);
        signal(SIGINT, SIG IGN);
        signal(SIGALRM, SIG_IGN);
        signal(16, vv);
        pause();
        printf("\nChild process1 is killed by parent!!\n");
        return 0;
    }
   return 0;
}
```

代码解析:

- 1. 函数 inter_handler: 当接收到 SIGINT 或 SIGQUIT 或 SIGALRM 信号时,分别向子进程1和子进程2发送16和17信号。flag用于判断是否是第一次接收到信号,如果是则向子进程发送信号,否则不发送信号。
- 2. 函数 vv: 空函数, 用于处理子进程接收到的信号。
- 3. 函数 waiting:设置5秒的定时器。5秒后向父进程发送 SIGALRM 信号。
- 4. 主函数: 创建两个子进程, 父进程调用 waiting 函数设置定时器。为父进程接收到的信号设置处理函数 inter_handler。为子进程接收到的信号设置处理函数 vv。父进程等待两个子进程结束后,输出提示信息。子进程在没接到信号前通过 pause 函数挂起,接到信号后输出提示信息。

2. 实验结果

```
chenshi@Ubuntu:~/OSlab/lab2$ ./q1
Child process2 is killed by parent!!
Child process1 is killed by parent!!
chenshi@Ubuntu:~/OSlab/lab2$ ./q1
Child process2 is killed by parent!!
Child process1 is killed by parent!!
16 stop test
Child process1 is killed by parent!!
Parent process is killed!!
```

分别验证了等待5秒和输入Ctrl+C和Ctrl+\的情况,都实现了预期的效果。

2.2 进程的管道通信

有锁情况

```
#include <unistd.h>
#include <signal.h>
#include <stdio.h>
#include <stdlib.h>
#include <sys/wait.h>

int pid1, pid2;
int main()
{
    int fd[2];
    char InPipe[8000];
```

```
char c1 = '1', c2 = '2';
pipe(fd);
while ((pid1 = fork()) == -1);
if (pid1 == 0)
{
   close(fd[0]); // 关闭读管道,子进程 1 不需要读
   lockf(fd[1], 1, 0);
   for (int i = 0; i < 2000; i++) {
       write(fd[1], &c1, 1); // 向管道写入字符 '1'
   }
   sleep(5);
   lockf(fd[1], 0, 0);
   exit(0);
}
else
{
   while ((pid2 = fork()) == -1);
   if (pid2 == 0)
   {
       close(fd[0]); // 关闭读管道, 子进程 2 不需要读
       lockf(fd[1], 1, 0);
       for (int i = 0; i < 2000; i++) {
           write(fd[1], &c2, 1); // 向管道写入字符 '2'
       }
       sleep(5);
       lockf(fd[1], 0, 0);
       exit(0);
   }
   else
   {
       close(fd[1]); // 关闭写管道, 父进程不需要写
       waitpid(pid1, NULL, 0); // 等待子进程 1 结束
       waitpid(pid2, NULL, 0); // 等待子进程 2 结束
       int count = 0;
       while (read(fd[0], &InPipe[count], 1) > 0) {
           count++;
       }
       InPipe[count] = '\0'; // 加字符串结束符
       printf("count = %d\n", count);
       printf("%s\n", InPipe);
       exit(0);
```

```
}
}
```

代码解析:

- 1. 在main函数开始创建了一个管道,用于父子进程之间的通信。
- 2. 创建两个子进程,子进程1向管道中写入2000个字符'1',子进程2向管道中写入2000个字符'2'。
- 3. 子进程在写入前会使用 lockf(fd[1], 1, 0); 函数对管道进行加锁, 写入后通过 lockf(fd[1], 0, 0) 解锁。这样可以保证两个子进程写入的数据不会交叉。
- 4. 父进程通过 waitpid 函数等待两个子进程结束后,从管道中读取数据并输出。

2. 实验结果

可以看到输出的 count 为4000,说明两个子进程都向管道中写入了2000个字符。输出的字符串中,字符'1'和字符'2'是分开的,说明两个子进程写入的数据没有交叉。

无锁情况

```
#include <unistd.h>
#include <signal.h>
#include <stdio.h>
#include <stdlib.h>
#include <sys/wait.h>

int pid1, pid2;

int main() {
    int fd[2];
    char InPipe[1000];
    char c1 = '1', c2 = '2';
    pipe(fd);
```

```
while ((pid1 = fork()) == -1);
   if (pid1 == 0) {
        close(fd[0]);
        for (int i = 0; i < 2000; i++) {
            write(fd[1], &c1, 1);
        }
        sleep(5);
        exit(0);
   }
    else {
       while ((pid2 = fork()) == -1);
        if (pid2 == 0) {
            close(fd[0]);
            for (int i = 0; i < 2000; i++) {
                write(fd[1], &c2, 1);
            }
            sleep(5);
            exit(0);
        }
        else {
            close(fd[1]);
            waitpid(pid1, NULL, 0);
            waitpid(pid2, NULL, 0);
            int count = 0;
            while (read(fd[0], &InPipe[count], 1) > 0) {
                count++;
            }
            InPipe[count] = '\0';
            printf("%s\n", InPipe);
            exit(0);
       }
   }
}
```

代码解析:

1. 与有锁情况相比,只是去掉了加锁和解锁的代码。

2. 实验结果

```
chenshi@chenshi—limax:/@cektor/lab25 /g2_1
chenshi@chenshi
chenshi@c
```

可以看到输出的 count 为4000, 说明两个子进程都向管道中写入了2000个字符, 没有字符写入被吞。输出的字符串中, 字符'1'和字符'2'是交叉的, 说明两个子进程写入的数据交叉了。

2.3 内存的分配与回收

```
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#define PROCESS_NAME_LEN 32 /*进程名长度 */
#define MIN SLICE 10 /* 最小碎片的大小 */
#define DEFAULT MEM SIZE 1024 /* 内存大小 */
#define DEFAULT MEM START 0 /* 起始位置 */
/* 内存分配算法 */
#define MA FF 1
#define MA_BF 2
#define MA_WF 3
int mem_size = DEFAULT_MEM_SIZE; /* 内存大小 */
int ma_algorithm = MA_FF;  /* 当前分配算法 */
static int pid = 0;  /* 初始 pid */
                             /* 设置内存大小标志 */
int flag = 0;
/* (1) 主要功能 */
1 - Set memory size (default = 1024)
2 - Select memory allocation algorithm
3 - New process
4 - Terminate a process
5 - Display memory usage
0 - Exit
/*(2) 主要数据结构 */
/* 1) 内存空闲分区的描述 */
/* 描述每一个空闲块的数据结构*/
struct free_block_type
```

```
int size;
   int start addr;
   struct free block type *next;
};
/* 指向内存中空闲块链表的首指针 */
struct free_block_type*free_block;
/*2) 描述已分配的内存块 */
/* 每个进程分配到的内存块的描述*/
struct allocated block
{
   int pid;
   int size;
   int start_addr;
   char process_name[PROCESS_NAME_LEN];
   struct allocated_block *next;
};
/* 进程分配内存块链表的首指针 */
struct allocated block*allocated block head = NULL;
/*初始化空闲块,默认为一块,可以指定大小及起始地址*/
struct free_block_type *init_free_block(int mem_size)
{
   struct free_block_type*fb;
   fb = (struct free_block_type *)malloc(sizeof(struct free_block_type));
   if (fb == NULL)
   {
       printf("No mem\n");
       return NULL;
   }
   fb->size = mem_size;
   fb->start_addr = DEFAULT_MEM_START;
   fb->next = NULL;
   return fb;
}
/*显示菜单*/
void display_menu()
{
   printf("\n");
   printf("1 - Set memory size (default=%d)\n", DEFAULT_MEM_SIZE);
   printf("2 - Select memory allocation algorithm\n");
   printf("3 - New process\n");
   printf("4 - Terminate a process\n");
   printf("5 - Display memory usage\n");
   printf("0 - Exit\n");
```

```
/*设置内存的大小*/
int set mem size()
   int size;
   if (flag != 0)
   { // 防止重复设置
       printf("Cannot set memory size again\n");
       return 0;
   }
   printf("Total memory size =");
   scanf("%d", &size);
   char input;
   while ((input = getchar()) != '\n' && input != EOF)
       // 读入一个字符后清空缓存区,避免\n被读入或者一次输入多个字符
   }
   if (size > 0)
   {
       mem_size = size;
       free_block->size = mem_size;
   }
   flag = 1;
   return 1;
}
// 所有的排序算法都采用插入排序,只需要修改比较的条件即可
/*按 FF 算法重新整理内存空闲块链表*/
void rearrange_FF()
{
   if (free_block == NULL)
       return;
   struct free_block_type *current,*next, *temp;
   current = free_block;
   struct free_block_type*new_head = (struct free_block_type
*)malloc(sizeof(struct free_block_type)); // 头结点dummy
   new_head->next = NULL;
   new_head->size = 0;
   new_head->start_addr = -1;
   while (current != NULL)
   {
       next = current->next;
       temp = new_head;
       while (temp->next != NULL)
```

```
if (temp->next->start_addr > current->start_addr)
            {
                break;
            temp = temp->next;
        }
        current->next = temp->next;
        temp->next = current;
        current = next;
    }
    free_block = new_head->next;
    free(new_head);
}
/*按 BF 算法重新整理内存空闲块链表*/
void rearrange_BF()
{
    if (free_block == NULL)
        return;
    struct free_block_type *current,*next, *temp;
    current = free_block;
    struct free_block_type*new_head = (struct free_block_type
*)malloc(sizeof(struct free_block_type));
    new_head->next = NULL;
    new_head->size = 0;
    new_head->start_addr = -1;
    while (current != NULL)
        next = current->next;
        temp = new_head;
        while (temp->next != NULL)
            if (temp->next->size > current->size)
            {
                break;
            temp = temp->next;
        }
        current->next = temp->next;
        temp->next = current;
        current = next;
    free_block = new_head->next;
    free(new_head);
}
```

```
/*按 WF 算法重新整理内存空闲块链表*/
void rearrange WF()
    if (free_block == NULL)
       return;
    struct free_block_type *current,*next, *temp;
    current = free_block;
    struct free_block_type*new_head = (struct free_block_type
*)malloc(sizeof(struct free_block_type));
    new_head->next = NULL;
    new_head->size = 10000000;
    new_head->start_addr = -1;
    while (current != NULL)
    {
       next = current->next;
       temp = new_head;
       while (temp->next != NULL)
        {
           if (temp->next->size < current->size)
            {
               break;
            temp = temp->next;
        }
        current->next = temp->next;
       temp->next = current;
        current = next;
    free_block = new_head->next;
   free(new_head);
}
/*按指定算法重新整理内存空闲块链表*/
void rearrange(int algorithm)
{
    switch (algorithm)
    {
    case MA_FF:
       rearrange_FF();
       break;
    case MA_BF:
       rearrange_BF();
       break;
    case MA_WF:
       rearrange_WF();
```

```
break;
   }
}
/*设置当前的分配算法 */
void set_algorithm()
{
   int algorithm;
   printf("\t1 - First Fit\n");
   printf("\t2 - Best Fit\n");
   printf("\t3 - Worst Fit\n");
   scanf("%d", &algorithm);
   char input;
   while ((input = getchar()) != '\n' && input != EOF)
   {
       // 读入一个字符后清空缓存区,避免\n被读入或者一次输入多个字符
   if (algorithm >= 1 && algorithm <= 3)</pre>
       ma algorithm = algorithm;
   /* 按指定算法重新排列空闲区链表*/
   rearrange(ma_algorithm);
}
//已分配内存空间按照起始地址排序
void sort_allocated_block(){
   struct allocated_block *current,*next, *temp;
   current = allocated_block_head;
   struct allocated_block*new_head = (struct allocated_block
*)malloc(sizeof(struct allocated_block));
   new_head->next = NULL;
   new_head->size = 0;
   new_head->start_addr = -1;
   while (current != NULL)
   {
       next = current->next;
       temp = new_head;
       while (temp->next != NULL)
       {
           if (temp->next->start_addr > current->start_addr)
           {
               break;
           temp = temp->next;
       current->next = temp->next;
       temp->next = current;
```

```
current = next;
   }
   allocated block head = new head->next;
   free(new head);
}
/*分配内存模块*/
int allocate_mem(struct allocated_block *ab)
   struct free_block_type*fbt, *pre;
   int request size = ab->size;
   fbt = pre = free_block;
   if (free_block == NULL)
   {
      return -1;
   }
   // 根据当前算法在空闲分区链表中搜索合适的空闲分区进行分配
   // 分配时需要考虑多种情况,如分割、合并、内存紧缩等
   // 1. 找到可满足空闲分区且分配后剩余空间足够大,则分割
   // 2. 找到可满足空闲分区且但分配后剩余空间比较小,则一起分配
   // 3. 找不可满足需要的空闲分区但空闲分区之和能满足需要,则采用内存紧缩技术,
   // 进行空闲分区的合并, 然后再分配
   // 4. 在成功分配内存后,应保持空闲分区按照相应算法有序
   // 5. 分配成功则返回 1, 否则返回 -1
   // 请自行补充实现...
   // 找到第一个满足要求的空闲分区
   while (fbt != NULL)
   {
      if (fbt->size >= request_size)
      {
         break;
      pre = fbt;
      fbt = fbt->next;
   }
   // 没找到,则合并空闲分区后再找
   if (fbt == NULL)
   {
      int rest = 0;
      fbt = free_block;
      while (fbt != NULL) {
         rest += fbt->size;
         fbt = fbt->next;
```

```
if(rest < request_size) {</pre>
        return -1;
   }else {
        sort_allocated_block();
        struct allocated_block* abt=allocated_block_head;
        int prev=0;
        while(abt!=NULL){
            abt->start_addr=prev;
            prev=prev+abt->size;
            abt=abt->next;
        }
        //释放所有空闲分区
        fbt = free_block->next;
        while (fbt != NULL)
        {
            pre = fbt;
            fbt = fbt->next;
            free(pre);
        }
        free_block->size = mem_size-prev;
        free_block->start_addr = prev;
        free_block->next = NULL;
   }
   fbt = free_block;
}
// 找到了,分配
if (fbt->size - request_size > MIN_SLICE)
{
   ab->start_addr = fbt->start_addr;
   ab->size = request_size;
   fbt->start_addr += request_size;
   fbt->size -= request_size;
}
else
{
   ab->start_addr = fbt->start_addr;
   ab->size = fbt->size;
   if (fbt == free_block)
       free_block = fbt->next;
    }
   else
    {
        pre->next = fbt->next;
```

```
free(fbt);
   }
   return 1;
}
/*创建新的进程,主要是获取内存的申请数量*/
int new_process()
{
   struct allocated_block *ab;
   int size;
   int ret;
   ab = (struct allocated_block *)malloc(sizeof(struct allocated_block));
   if (!ab)
       exit(-5);
   ab->next = NULL;
   pid++;
   sprintf(ab->process_name, "PROCESS-%02d", pid);
   ab->pid = pid;
   printf("Memory for %s:", ab->process_name);
   scanf("%d", &size);
   char input;
   while ((input = getchar()) != '\n' && input != EOF)
   {
       // 读入一个字符后清空缓存区,避免\n被读入或者一次输入多个字符
   if (size > 0)
       ab->size = size;
   ret = allocate_mem(ab); /* 从空闲区分配内存, ret==1 表示分配 ok*/
   /* 如果此时 allocated_block_head 尚未赋值,则赋值 */
   if ((ret == 1) && (allocated_block_head == NULL))
       allocated_block_head = ab;
       return 1;
   /* 分配成功,将该已分配块的描述插入已分配链表 */
   else if (ret == 1)
   {
       ab->next = allocated_block_head;
       allocated_block_head = ab;
       return 2;
   }
   else if (ret == -1)
       /* 分配不成功 */
```

```
printf("Allocation fail\n");
       free(ab);
       return -1;
   return 3;
}
/*根据pid查找内存块*/
struct allocated_block *find_process(int pid)
{
   struct allocated_block*ab = allocated_block_head;
   while (ab != NULL)
       if (ab->pid == pid)
          break;
       ab = ab->next;
   }
   return ab;
}
/*将 ab 所表示的已分配区归还,并进行可能的合并*/
int free_mem(struct allocated_block *ab)
{
   int algorithm = ma_algorithm;
   struct free_block_type*fbt, *pre,*work;
   // 进行可能的合并,基本策略如下
   // 1. 将新释放的结点插入到空闲分区队列末尾
   // 2. 对空闲链表按照地址有序排列
   // 3. 检查并合并相邻的空闲分区
   // 4. 将空闲链表重新按照当前算法排序
   // 请自行补充...
   // 头插法
   work = (struct free_block_type *)malloc(sizeof(struct free_block_type));
   if (work == NULL)
   {
       return -1;
   }
   work->start_addr = ab->start_addr;
   work->size = ab->size;
   work->next = free_block;
   free_block = work;
   rearrange_FF(free_block);
```

```
fbt = free_block;
   while (fbt->next != NULL)
       if (fbt->start addr + fbt->size == fbt->next->start addr)
           struct free_block_type *temp = fbt->next;
           fbt->size += fbt->next->size;
           fbt->next = fbt->next->next;
           free(temp);
       }
       else
       {
           fbt = fbt->next;
       }
   rearrange(ma_algorithm);
   return 1;
}
/*释放 ab 数据结构节点*/
int dispose(struct allocated_block *free_ab)
{
   struct allocated_block*pre, *ab;
   if (free_ab == allocated_block_head)
   { /* 如果要释放第一个节点 */
       allocated_block_head = allocated_block_head->next;
       free(free_ab);
       return 1;
   }
   pre = allocated_block_head;
   ab = allocated_block_head->next;
   while (ab != free_ab)
   {
       pre = ab;
       ab = ab->next;
   pre->next = ab->next;
   free(ab);
   return 2;
}
/*删除进程,归还分配的存储空间,并删除描述该进程内存分配的节点*/
void kill_process()
   struct allocated_block *ab;
```

```
int pid;
   printf("Kill Process, pid=");
   scanf("%d", &pid);
   char input;
   while ((input = getchar()) != '\n' && input != EOF)
      // 读入一个字符后清空缓存区,避免\n被读入或者一次输入多个字符
   }
   ab = find_process(pid);
   if (ab != NULL)
   {
      free mem(ab); /* 释放 ab 所表示的分配区 */
      dispose(ab); /* 释放 ab 数据结构节点 */
   }
}
/*显示当前内存的使用情况,包括空闲区的情况和已经分配的情况*/
int display_mem_usage()
{
   struct free_block_type *fbt = free_block;
   struct allocated_block*ab = allocated_block_head;
   printf("-----
                 -----\n");
   /* 显示空闲区 */
   printf("Free Memory:\n");
   printf("%20s %20s\n", "start_addr", "size");
   while (fbt != NULL)
   {
      printf("%20d %20d\n", fbt->start_addr, fbt->size);
      fbt = fbt->next;
   }
   /* 显示已分配区 */
   printf("\nUsed Memory:\n");
   printf("%10s %20s %10s %10s\n", "PID", "ProcessName", "start_addr",
"size");
   while (ab != NULL)
   {
      printf("%10d %20s %10d %10d\n", ab->pid, ab->process_name, ab-
>start_addr, ab->size);
      ab = ab->next;
   printf("-----\n");
}
/*退出,释放所有链表*/
```

```
void do_exit()
   struct free_block_type *fbt = free_block;
   struct allocated_block*ab = allocated_block_head;
   while (fbt != NULL)
       free_block = fbt->next;
       free(fbt);
       fbt = free_block;
   }
   while (ab != NULL)
       allocated_block_head = ab->next;
       free(ab);
       ab = allocated_block_head;
   }
}
void tab(char choice)
{
}
int main()
   char choice, input;
   pid = 0;
   free_block = init_free_block(mem_size); // 初始化空闲区
   while (1)
   {
       display_menu(); // 显示菜单
       choice = getchar();
       while ((input = getchar()) != '\n' && input != EOF)
       {
           // 读入一个字符后清空缓存区,避免\n被读入或者一次输入多个字符
       switch (choice)
       {
       case '1':
           set_mem_size();
           break; // 设置内存大小
       case '2':
           set_algorithm();
           flag = 1;
           break; // 设置算法
       case '3':
```

```
new process();
           flag = 1;
           break; // 创建新进程
       case '4':
           kill_process();
           flag = 1;
           break; // 删除进程
       case '5':
           display_mem_usage();
           flag = 1;
           break; // 显示内存使用
       case '0':
           do_exit();
           exit(0);
           /*释放链表并退出*/
       default:
           break:
       }
   }
   return 0;
}
```

- 1. 首先调整了一下代码的格式,将函数定义和实现放在了主函数前,同时发现了两个没有定义的函数 find_pid 和 do_exit ,于是将这两个函数的定义和实现补充了
- 2. FF和BF和WF算法都是使用的插入排序,只需要修改比较的条件即可,分别比较的是起始地址、空闲块大小和空闲块大小
- 3. 同时在所有的读入后加入了清空缓存区的代码,避免了回车键导致的一些重复显示问题
- 4. 代码实质上和数据结构课的链表一致,维护了两个链表,分别表示空闲块和已分配块,每次分配和回收都会对空闲块链表进行重新排序,保证了空闲块链表的有序性

2. 实验结果

1. 设置内存空间为1024, 采用Best Fit算法

```
1 - Set memory size (default=1024)
2 - Select memory allocation algorithm
3 - New process
4 - Terminate a process
5 - Display memory usage
0 - Exit
1
Total memory size =1024

1 - Set memory size (default=1024)
2 - Select memory allocation algorithm
3 - New process
4 - Terminate a process
5 - Display memory usage
0 - Exit
2

1 - First Fit
2 - Best Fit
3 - Worst Fit
```

2. 设置了五个进程,每个进程分配空间为64

```
Free Memory:
         start_addr
                                size
              320
                                  704
Used Memory:
      PID
                 ProcessName start_addr
                                           size
                  PROCESS-05 256
                                              64
                  PROCESS-04
                                              64
                   PROCESS-03
                                  128
                                              64
                   PROCESS-02
PROCESS-01
1 - Set memory size (default=1024)
2 - Select memory allocation algorithm
3 - New process
4 - Terminate a process
5 - Display memory usage
0 - Exit
```

3. 删除进程2和进程3, 展示全部进程的内存分配情况, 验证了内存回收的正确性

```
1 - Set memory size (default=1024)
2 - Select memory allocation algorithm
3 - New proces
4 - Terminate a process
5 - Display memory usage
6 - Extt
4
KILL Process, pid=2
1 - Set memory size (default=1024)
2 - Select memory allocation algorithm
3 - New process
5 - Display memory usage
6 - Extt
4
KILL Process, pid=3
1 - Set memory size (default=1024)
2 - Select memory allocation algorithm
3 - New process
5 - Display memory usage
6 - Extt
4
KILL Process, pid=3
1 - Set memory size (default=1024)
2 - Select memory allocation algorithm
3 - New proces
6 - Extt
5 - Display memory usage
6 - Extt
5 - Display memory usage
6 - Extt
5 - Display memory usage
7 - Terminate a process
6 - Display memory usage
7 - Terminate a process
8 - Display memory usage
9 - Extt
5 - Display memory usage
9 - Extt
5 - Select memory allocation algorithm
9 - New process
1 - Terminate a process
9 - Display memory usage
9 - Extt
5 - Display memory usage
9 - Extt
6 - 128
320 - 704

Used Memory:

PID ProcessRame start_addr size
5 - PROCESS-61 256 64
4 - PROCESS-61 192 64
1 - PROCESS-61 0 64
```

4. 采用worst fit算法,分配一块空间为64的内存,如果实现正确,起始地址应该为320,经验证,实现正确

```
1 - Set memory size (default=1024)
2 - Select memory allocation algorithm
3 - New process
4 - Terminate a process
5 - Display memory usage
6 - Exit
2 - Best Fit
3 - Worst Fit
3 - Worst Fit
3 - Worst Fit
3 - Select memory size (default=1024)
2 - Select memory size (default=1024)
3 - Select memory allocation algorithm
3 - New process
4 - Terminate a process
5 - Display memory usage
6 - Exit
3 - Wemory size (default=1024)
2 - Select memory allocation algorithm
3 - New process
4 - Terminate a process
5 - Display memory usage
6 - Exit
5 - Company size (default=1024)
5 - Exit memory allocation algorithm
5 - New process
6 - Display memory usage
7 - Exit memory allocation algorithm
8 - New process
9 - Exit
5 - Free Memory:
8 - Select memory allocation algorithm
9 - Exit
1 - Exit memory allocation algorithm
9 - Exit memory allocation algorithm
1 - Reverse memory allocation algorithm
1 - Reverse memory allocation algorithm
1 - Select memory allocation algorithm
2 - Select memory allocation algorithm
3 - New process
6 - Display memory usage
8 - Exit
9 - Exit
9
```

5. 采用Best Fit算法,分配一块空间为64的内存,如果实现正确,起始地址应该为64,经验证,实现正确

```
2 - Select memory allocation algorithm
3 - Now process
5 - Display memory usage
6 - Estt
2 - Best Fit
3 - Worst Fit
2 - Best Fit
3 - Worst Fit
2 - Select memory size (default=1824)
2 - Select memory allocation algorithm
3 - Now process
4 - Terminate a process
5 - Display memory usage
6 - Estt
8 - Select memory allocation algorithm
8 - Select memory allocation algorithm
9 - Select memory allocation algorithm
9 - Select memory allocation algorithm
1 - Set memory size (default=1824)
2 - Select memory allocation algorithm
9 - Select memory allocation algorithm
9 - Select memory allocation algorithm
9 - Now process
4 - Terminate a process
5 - Display memory usage
6 - Extt
8 - Select memory allocation algorithm
9 - S
```

6. 采用First Fit算法,分配一块空间为64的内存,如果实现正确,起始地址应该为128,经验证,实现正确

```
1 - Set memory size (default=1024)
2 - Select memory allocation algorithm
3 - New process
4 - Terminate a process
5 - Display memory usage
0 - Exit

1 - First Fit
2 - Best Fit
3 - Worst Fit

1 - Set memory size (default=1024)
2 - Select memory allocation algorithm
3 - New process
5 - Display memory usage
0 - Exit
3 - Morst Fit
3 - Terminate a process
5 - Display memory usage
0 - Exit
3 - Select memory allocation algorithm
3 - New process
4 - Terminate a process
5 - Display memory usage
0 - Exit
5 - Display memory usage
0 - Exit
6 - Display memory usage
0 - Exit
5 - Display memory usage
0 - Exit
6 - DOCESS-08 - 0128 - 64
8 - POCESS-08 - 028 - 64
9 - POCESS-08 - 220 - 64
9 - POCESS-08 - 220
```

7. 验证内存紧缩的正确性,设置内存为1000,分配五个进程各占用200,释放进程1,3

```
Free Memory:
          start_addr
                                      size
                                       200
                 400
Used Memory:
       PID
                    ProcessName start_addr
                                                  size
                     PROCESS-05
                                                   200
                     PROCESS-04
                                        600
                                                    200
                     PROCESS-02
                                        200
                                                    200
```

再新建进程6,分配300内存,会触发内存紧缩,释放所有空闲块,重新分配内存

```
1 - Set memory size (default=1024)
2 - Select memory allocation algorithm
3 - New process
5 - Display memory usage
Free Memory:
         start_addr
                                   size
               900
                                    100
Used Memory:
      PID
                   ProcessName start_addr
                    PROCESS-06 600
                                                300
                    PROCESS-02
                                                200
                    PROCESS-04
                                     200
                                                200
                    PROCESS-05
                                     400
                                                200
```