第五节 隐函数 (组) 求导

(1) 隐函数存在定理

(2) 隐函数的导数和偏导数.

方程(组)确定的隐函数(组)

$$\begin{cases} F(x, y, z) = 0 \\ G(x, y, z) = 0 \end{cases} \qquad \qquad \begin{cases} y = y(x) \\ z = z(x) \end{cases}$$

$$F(x, y, z) \longrightarrow z = f(x, y)$$

$$\begin{cases} F(x, y, u, v) = 0 \\ G(x, y, u, v) = 0 \end{cases} \qquad \begin{cases} u = u(x, y) \\ v = v(x, y) \end{cases}$$

5.1 一个方程所确定的隐函数及其导数

定理1 设函数F(x,y)在点 $P(x_0,y_0)$ 的某一邻域内满足

- ① 具有连续的偏导数 $F'_{x}(x,y)$, $F'_{y}(x,y)$, 一个 ① 具有连续的偏 自变量 ② $F(x_0, y_0) = 0;$

 - (3) $F_{v}'(x_{0}, y_{0}) \neq 0$

则方程 F(x, y) = 0 在点P 的某邻域内可唯一确定一个 单值连续函数y = f(x),满足条件 $y_0 = f(x_0)$,并有连续 导数

 $\frac{\mathrm{d}y}{\mathrm{d}x} = -\frac{F_x}{F_y} \quad (隐函数求导公式)$

注 若③换成 $F_x(x_0, y_0) \neq 0$,则确定隐函数x=x(y),在点 (x_0, y_0) 可导,且

例1 设 $x^2+y^2=1$, 求 $\frac{dy}{dx} \cdot \frac{d^2y}{dx^2}$

例1 设
$$x^2+y^2=1$$
, 求
$$\frac{dy}{dx} \cdot \frac{d^2y}{dx^2}$$

解:
$$\longrightarrow$$
 $y = f(x)$

(1)法一
$$2x + 2y \cdot \frac{dy}{dx} = 0 \Rightarrow \frac{dy}{dx} = -\frac{x}{y}$$

法二
$$F(x,y)=x^2+y^2-1$$
 $\Rightarrow \frac{dy}{dx} = -\frac{F_x}{F_y} = -\frac{2x}{2y} = -\frac{x}{y}$

(2)
$$\frac{d^2y}{dx^2} = -\frac{y - x \cdot \frac{dy}{dx}}{y^2} = -\frac{x^2 + y^2}{y^3} = -\frac{1}{y^3}$$

定理2 若函数F(x, y, z)满足:

一个方程

二个自变量

① 在点 $P(x_0,y_0,z_0)$ 的某邻域内具有连续偏导数,

②
$$F(x_0, y_0, z_0) = 0$$

(3) $F_z(x_0, y_0, z_0) \neq 0$

则方程F(x,y,z)=0在点P的某一邻域内可唯一确

定一个单值连续函数z = f(x, y),满足 $z_0 = f(x_0, y_0)$,

并有连续偏导数 $\frac{\partial z}{\partial x} = -\frac{F_x}{F_z}$, $\frac{\partial z}{\partial y} = -\frac{F_y}{F_z}$

例2 设 e^{x+y+z} - xyz = e, 求 $\frac{\partial z}{\partial x}$, $\frac{\partial z}{\partial y}$

例2 设
$$e^{x+y+z}$$
- $xyz = e$, 求 $\frac{\partial z}{\partial x}$, $\frac{\partial z}{\partial y}$

解:
$$\longrightarrow z = f(x, y)$$

法一
$$e^{x+y+z} \cdot \left(1 + \frac{\partial z}{\partial x}\right) - y\left(z + x \cdot \frac{\partial z}{\partial x}\right) = 0$$
$$\frac{\partial z}{\partial x} = \frac{yz - e^{x+y+z}}{e^{x+y+z} - xy}; \qquad \frac{\partial z}{\partial y} = \frac{xz - e^{x+y+z}}{e^{x+y+z} - xy}$$

法二
$$F(x, y, z) = e^{x+y+z}$$
 $xyz - e$. $\frac{\partial z}{\partial x} = -\frac{F_x}{F_z}$, $\frac{\partial z}{\partial y} = -\frac{F_y}{F_z}$

$$\frac{\partial z}{\partial x} = \frac{e^{x+y+z} - yz}{xy - e^{x+y+z}}; \qquad \frac{\partial z}{\partial y} = \frac{e^{x+y+z} - xz}{xy - e^{x+y+z}};$$

例3 设 $x^2+y^2+z^2-4z=0$, 求 $\frac{\partial^2 z}{\partial x^2}$

例3 设
$$x^2+y^2+z^2-4z=0$$
,求 $\frac{\partial^2 z}{\partial x^2}$

解: $\longrightarrow z = f(x, y)$

$$2x + 2z \cdot \frac{\partial z}{\partial x} - 4\frac{\partial z}{\partial x} = 0 \implies \frac{\partial z}{\partial x} = \frac{x}{2 - z}$$

$$\frac{\partial^2 z}{\partial x^2} = \frac{(2 - z) - x \cdot \left(-\frac{\partial z}{\partial x}\right)}{(2 - z)^2} = \frac{(2 - z)^2 + x^2}{(2 - z)^3}$$

5.2 方程组所确定的隐函数组及其导数

隐函数存在定理还可以推广到方程组的情形.通常, 两个方程可确定两个隐函数,即

$$\begin{cases} F(x, y, z) = 0 \\ G(x, y, z) = 0 \end{cases} \qquad \begin{cases} y = y(x) \\ z = z(x) \end{cases}$$

$$\begin{cases} F(x, y, u, v) = 0 \\ G(x, y, u, v) = 0 \end{cases} \qquad \begin{cases} u = u(x, y) \\ v = v(x, y) \end{cases}$$

定义 由F、G的偏导数组成的行列式

$$J = \frac{\partial(F,G)}{\partial(u,v)} = \begin{vmatrix} F_u & F_v \\ G_u & G_v \end{vmatrix}$$

称为F、G的雅可比(Jacobi)行列式.

$$\frac{\partial(F,G,H)}{\partial(x,y,z)} = \begin{vmatrix} F_x & F_y & F_z \\ G_x & G_y & G_z \\ H_x & H_y & H_z \end{vmatrix}$$

- ① 在点 $M_0(x_0, y_0, z_0)$, 的某邻域内具有连续偏导数;
- ② $F(x_0, y_0, z_0) = 0$, $G(x_0, y_0, z_0) = 0$;

则方程组 $\begin{cases} F(x,y,z)=0\\ G(x,y,z)=0 \end{cases}$ 在点 \mathbf{M}_0 的某一邻域内可唯一

确定一组满足条件 $y_0 = y(x_0), z_0 = z(x_0)$ 的单值连续函数 y = y(x), z = z(x), 且有连续导数公式:

$$\frac{dy}{dx} = -\frac{1}{J} \frac{\partial (F,G)}{\partial (x,z)}$$

$$= -\frac{\begin{vmatrix} F'_x & F'_z \\ G'_x & G'_z \end{vmatrix}}{\begin{vmatrix} F'_y & F'_z \\ G'_y & G'_z \end{vmatrix}}$$

$$\frac{dz}{dx} = -\frac{1}{J} \frac{\partial (F,G)}{\partial (y,x)}$$

$$= -\frac{\begin{vmatrix} F'_y & F'_x \\ G'_y & G'_x \end{vmatrix}}{\begin{vmatrix} F'_y & F'_z \\ G'_y & G'_z \end{vmatrix}}$$

$$\begin{cases} F(x, y, z) = 0 \\ G(x, y, z) = 0 \end{cases} \qquad \begin{cases} y = y(x) \\ z = z(x) \end{cases}$$

$$\begin{cases} F(x, y(x), z(x)) = 0 \\ G(x, y(x), z(x)) = 0 \end{cases} \begin{cases} F'_x + F'_y \cdot \frac{dy}{dx} + F'_z \cdot \frac{dz}{dx} = 0 \\ G'_x + G'_y \cdot \frac{dy}{dx} + G'_z \cdot \frac{dz}{dx} = 0 \end{cases}$$

$$F'_{y} \cdot \frac{dy}{dx} + F'_{z} \cdot \frac{dz}{dx} = -F'_{x}$$

$$G'_{y} \cdot \frac{dy}{dx} + G'_{z} \cdot \frac{dz}{dx} = -G'_{x}$$

$$\frac{dz}{dx} = \frac{dz}{dx} = \frac{dz}{dx$$

$$\begin{cases} F(x, y, z) = 0 \\ G(x, y, z) = 0 \end{cases} \qquad \begin{cases} y = y(x) \\ z = z(x) \end{cases}$$

$$\begin{cases} F(x, y(x), z(x)) = 0 \\ G(x, y(x), z(x)) = 0 \end{cases}$$

$$\begin{cases} F'_x + F'_y \cdot \frac{dy}{dx} + F'_z \cdot \frac{dz}{dx} = 0 \\ G'_x + G'_y \cdot \frac{dy}{dx} + G'_z \cdot \frac{dz}{dx} = 0 \end{cases}$$

$$\begin{cases} F'_{y} \cdot \frac{dy}{dx} + F'_{z} \cdot \frac{dz}{dx} = -F'_{x} \\ G'_{y} \cdot \frac{dy}{dx} + G'_{z} \cdot \frac{dz}{dx} = -G'_{x} \end{cases} = -G'_{x} \begin{cases} \frac{dy}{dx} = \begin{vmatrix} -F'_{x} & F'_{z} \\ -G'_{x} & G'_{z} \end{vmatrix} = -\frac{\begin{vmatrix} F'_{x} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}}{\begin{vmatrix} F'_{y} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{x} & F'_{z} \\ G'_{x} & G'_{z} \end{vmatrix}}{\begin{vmatrix} F'_{y} & F'_{x} \\ G'_{y} & G'_{z} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{y} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}}{\begin{vmatrix} F'_{y} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{y} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}}{\begin{vmatrix} F'_{y} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{y} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}}{\begin{vmatrix} F'_{y} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{x} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}}{\begin{vmatrix} F'_{y} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{x} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}}{\begin{vmatrix} F'_{y} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{x} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}}{\begin{vmatrix} F'_{y} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{x} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}}{\begin{vmatrix} F'_{y} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{x} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}}{\begin{vmatrix} F'_{y} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{x} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}}{\begin{vmatrix} F'_{y} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{x} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}}{\begin{vmatrix} F'_{y} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{x} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}}{\begin{vmatrix} F'_{y} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{x} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}}{\begin{vmatrix} F'_{y} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{x} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}}{\begin{vmatrix} F'_{y} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{x} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}}{\begin{vmatrix} F'_{y} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{x} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}}{\begin{vmatrix} F'_{y} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{x} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}}{\begin{vmatrix} F'_{y} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{x} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}}{\begin{vmatrix} F'_{x} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{x} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}}{\begin{vmatrix} F'_{x} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{x} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}}{\begin{vmatrix} F'_{x} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{x} & F'_{x} \\ G'_{y} & G'_{z} \end{vmatrix}}{\begin{vmatrix} F'_{x} & F'_{y} \\ G'_{y} & G'_{z} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{x} & F'_{x} \\ G'_{y} & G'_{z} \end{vmatrix}}{\begin{vmatrix} F'$$

解:
$$= \begin{cases} y = y(x) \\ z = z(x) \end{cases}$$

法一

法二
$$\frac{dz}{dx} = -\frac{1}{J} \frac{\partial (F,G)}{\partial (y,x)}$$

$$J = \frac{\partial(F,G)}{\partial(y,z)} = \begin{vmatrix} F'_{y} & F'_{z} \\ G'_{y} & G'_{z} \end{vmatrix} = \begin{vmatrix} 2 & -3 \\ 2y & 2z \end{vmatrix} = 4z + 6y$$

$$\begin{vmatrix} F'_{y} & F'_{x} \\ G'_{y} & G'_{x} \end{vmatrix} = \begin{vmatrix} 2 & 1 \\ 2y & 2x \end{vmatrix} = 4x - 2y$$

$$\begin{vmatrix} dz \\ dx = -\frac{4x - 2y}{4z + 6y} \end{vmatrix}$$

例5 设u=F(x, y, z), z=f(x, y), $y=\sin x$, 求 $\frac{du}{dx}$

$$\begin{aligned}
\mathbf{m} &: \begin{cases}
u = F(x, y, z) \\
z = f(x, y) \\
y = \sin x
\end{aligned}
\qquad \begin{aligned}
u &= F[x, \sin x, f(x, \sin x)] \\
z &= f(x, \sin x) \\
y &= \sin x
\end{aligned}$$

$$\begin{cases}
\frac{du}{dx} &= F'_x + F'_y \cdot \frac{dy}{dx} + F'_z \cdot \frac{dz}{dx} \\
\frac{dz}{dx} &= f'_x + f'_y \cdot \frac{dy}{dx}
\end{aligned}$$

$$\frac{dy}{dx} &= \cos x$$

$$\frac{du}{dx} &= F'_x + F'_y \cdot \cos x + F'_z \cdot (f'_x + f'_y \cdot \cos x)$$

定理4. 设函数 F(x, y, u, v), G(x, y, u, v) 满足:

- ① 在点 $M_0(x_0, y_0, u_0, v_0)$ 的某一邻域内具有连续偏 导数;
- (2) $F(x_0, y_0, u_0, v_0) = 0$, $G(x_0, y_0, u_0, v_0) = 0$;

二个方程

则方程组 $\begin{cases} F(x, y, u, v) = 0 \\ G(x, y, u, v) = 0 \end{cases}$ 在点 $M_0(x_0, y_0, u_0, v_0)$

的某一邻域内可唯一确定一组满足条件 $u_0 = u(x_0, y_0)$, $v_0 = v(x_0, y_0)$ 的单值连续函数 u = u(x, y), v = v(x, y),且有连续偏导数:

$$\frac{\partial u}{\partial x} = -\frac{1}{J} \frac{\partial (F, G)}{\partial (x, v)} = -\frac{\begin{vmatrix} F'_x & F'_v \\ G'_x & G'_v \end{vmatrix}}{\begin{vmatrix} F'_u & F'_v \\ G'_u & G'_v \end{vmatrix}},$$

$$\frac{\partial v}{\partial x} = -\frac{1}{J} \frac{\partial (F, G)}{\partial (u, x)} = -\frac{\begin{vmatrix} F_u & F_x \\ G'_u & G'_x \end{vmatrix}}{\begin{vmatrix} F'_u & F'_v \\ G'_u & G'_v \end{vmatrix}}$$

$$\frac{\partial u}{\partial y} = -\frac{1}{J} \frac{\partial (F, G)}{\partial (y, v)} = -\frac{\begin{vmatrix} F'_y & F'_v \\ G'_y & G'_v \end{vmatrix}}{\begin{vmatrix} F'_u & F'_v \\ G'_u & G'_v \end{vmatrix}},$$

$$\frac{\partial v}{\partial y} = -\frac{1}{J} \frac{\partial (F, G)}{\partial (u, y)} = -\frac{\begin{vmatrix} r_u & r_y \\ G'_u & G'_y \end{vmatrix}}{\begin{vmatrix} F'_u & F'_v \\ G'_u & G'_y \end{vmatrix}}$$

$$\begin{cases} F(x, y, u, v) = 0 \\ G(x, y, u, v) = 0 \end{cases} \qquad \begin{cases} u = u(x, y) \\ v = v(x, y) \end{cases}$$

$$\begin{cases} F(x, y, u(x, y), v(x, y)) = 0 \\ G(x, y, u(x, y), v(x, y)) = 0 \end{cases} \begin{cases} F'_x + F'_u \cdot \frac{\partial u}{\partial x} + F'_v \cdot \frac{\partial v}{\partial x} = 0 \\ G'_x + G'_u \cdot \frac{\partial u}{\partial x} + G'_z \cdot \frac{\partial v}{\partial x} = 0 \end{cases}$$

$$\frac{\partial u}{\partial x} = \frac{\begin{vmatrix} -F'_{x} & F'_{v} \\ -G'_{x} & G'_{v} \end{vmatrix}}{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{x} & F'_{v} \\ G'_{x} & G'_{v} \end{vmatrix}}{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{x} & F'_{v} \\ G'_{x} & G'_{v} \end{vmatrix}}{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{x} & F'_{v} \\ G'_{x} & G'_{v} \end{vmatrix}}{\begin{vmatrix} F'_{u} & F'_{x} \\ G'_{y} & -G'_{x} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{u} & F'_{x} \\ G'_{u} & G'_{y} \end{vmatrix}}{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}}{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}}{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}}{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}}{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}}{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}}{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}}{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}}{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}}{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}}{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}}{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}}{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}}{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}}{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}}{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}}{\begin{vmatrix} F'_{u} & F'_{v} \\ G'_{u} & G'_{v} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{u} & F'_{v} \\ F'_{u} & F'_{v} \end{vmatrix}}{\begin{vmatrix} F'_{u} & F'_{v} \\ F'_{u} & G'_{v} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{u} & F'_{v} \\ F'_{u} & G'_{v} \end{vmatrix}}{\begin{vmatrix} F'_{u} & F'_{v} \\ F'_{u} & G'_{v} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{u} & F'_{u} \\ F'_{u} & G'_{v} \end{vmatrix}}{\begin{vmatrix} F'_{u} & F'_{v} \\ F'_{u} & G'_{v} \end{vmatrix}} = -\frac{\begin{vmatrix} F'_{u} & F'_{u} \\ F'_{u} & G'_$$

$$\frac{\partial u}{\partial x} = -\frac{1}{J} \frac{\partial (F, G)}{\partial (x, v)} = -\frac{1}{|F_u|} \frac{|F_x|}{|F_u|} \frac{|F_x|}{|G_x|} \frac{|F_y|}{|G_x|} \frac{|F_x|}{|G_y|} \frac{|F_y|}{|G_y|} \frac{|F_y|}{|F_y|} \frac{|F_y|}{|F_y|}$$

$$\frac{\partial u}{\partial y} = -\frac{1}{J} \frac{\partial (F, G)}{\partial (y, v)} = -\frac{1}{\begin{vmatrix} F_u & F_v \\ G_u & G_v \end{vmatrix}} \begin{vmatrix} F_y & F_v \\ G_y & G_v \end{vmatrix}$$

$$\frac{\partial v}{\partial x} = -\frac{1}{J} \frac{\partial (F, G)}{\partial (u, x)} = -\frac{1}{\begin{vmatrix} F_u & F_v \\ G_u & G_v \end{vmatrix}} \begin{vmatrix} F_u & F_x \\ G_u & G_x \end{vmatrix}$$

$$\frac{\partial v}{\partial y} = -\frac{1}{J} \frac{\partial (F, G)}{\partial (u, y)} = -\frac{1}{\begin{vmatrix} F_u & F_v \\ G_u & G_v \end{vmatrix}} \begin{vmatrix} F_u & F_y \\ G_u & G_v \end{vmatrix}$$

 $\begin{cases} xu - yv = 0 \\ yu + xv = 1 \end{cases} \Rightarrow \frac{\partial u}{\partial x} \cdot \frac{\partial u}{\partial y}, \frac{\partial v}{\partial x} \cdot \frac{\partial v}{\partial y} \quad \begin{cases} u = u(x, y) \\ v = v(x, y) \end{cases}$

$$\begin{cases} u = u(x, y) \\ v = v(x, y) \end{cases}$$

$$\begin{cases} xu - yv = 0 \\ yu + xv = 1 \end{cases} \not \Rightarrow \frac{\partial u}{\partial x} \cdot \frac{\partial u}{\partial y}, \frac{\partial v}{\partial x} \cdot \frac{\partial v}{\partial y} \quad \begin{cases} u = u(x, y) \\ v = v(x, y) \end{cases}$$

$$\begin{cases} u = u(x, y) \\ v = v(x, y) \end{cases}$$

法一
$$\begin{cases} x \frac{\partial u}{\partial x} - y \frac{\partial v}{\partial x} = -u \\ y \frac{\partial u}{\partial x} + x \frac{\partial v}{\partial x} = -v \\ D = \begin{vmatrix} x & -y \\ y & x \end{vmatrix} = x^2 + y^2$$

$$D = \begin{vmatrix} x & -y \\ y & x \end{vmatrix} = x^2 + y^2$$

$$D = \begin{vmatrix} x & -y \\ y & x \end{vmatrix} = x^2 + y^2$$

$$D_{1} = \begin{vmatrix} y & x \\ -u & -y \\ -v & x \end{vmatrix} = -xu - vy \qquad D_{1} = \begin{vmatrix} v & -y \\ -u & x \end{vmatrix} = vx - yu$$

$$D_2 = \begin{vmatrix} x & -u \\ y & -v \end{vmatrix} = -xv + uy \qquad D_2 = \begin{vmatrix} x & v \\ v & -u \end{vmatrix} = -xu - vy$$

$$\begin{cases} x \frac{\partial u}{\partial x} - y \frac{\partial v}{\partial x} = -u & \begin{cases} x \frac{\partial u}{\partial y} - y \frac{\partial v}{\partial y} = v \\ y \frac{\partial u}{\partial x} + x \frac{\partial v}{\partial x} = -v & \begin{cases} y \frac{\partial u}{\partial y} + x \frac{\partial v}{\partial y} = -u \\ y \frac{\partial u}{\partial y} + x \frac{\partial v}{\partial y} = -u \end{cases} \end{cases}$$

$$D = \begin{vmatrix} x & -y \\ y & x \end{vmatrix} = x^2 + y^2$$

$$D_1 = \begin{vmatrix} -u & -y \\ y & x \end{vmatrix} = -xu - vy$$

$$D_1 = \begin{vmatrix} v & -y \\ y & x \end{vmatrix} = vx - y^2$$

$$D_2 = \begin{vmatrix} x & v \\ y & -u \end{vmatrix} = -xu - vy$$

例6
$$\begin{cases} xu - yv = 0 \\ yu + xv = 1 \end{cases} \Rightarrow \frac{\partial u}{\partial x} \cdot \frac{\partial u}{\partial y}, \frac{\partial v}{\partial x} \cdot \frac{\partial v}{\partial y}$$

法二
$$\begin{cases} F(x,y,u,v) = xu - yv = 0 \\ G(x,y,u,v) = yu + xv - 1 = 0 \end{cases}$$

$$\begin{cases} u = u(x,y) \\ v = v(x,y) \end{cases}$$

$$\begin{cases} u = u(x, y) \\ v = v(x, y) \end{cases}$$

$$J = \begin{vmatrix} F_u & F_v \\ G_u & G_v \end{vmatrix} = \begin{vmatrix} x & -y \\ y & x \end{vmatrix} = x^2 + y^2$$

$$\frac{\partial u}{\partial x} = -\frac{1}{J} \frac{\partial (F,G)}{\partial (x,v)} = -\frac{\begin{vmatrix} u & -y \\ v & x \end{vmatrix}}{x^2 + y^2} = \frac{-ux - yv}{x^2 + y^2}$$

例6
$$\begin{cases} xu - yv = 0 \\ yu + xv = 1 \end{cases} \Rightarrow \frac{\partial u}{\partial x} \cdot \frac{\partial u}{\partial y}, \frac{\partial v}{\partial x} \cdot \frac{\partial v}{\partial y}$$

法二
$$\begin{cases} F(x,y,u,v) = xu - yv = 0 \\ G(x,y,u,v) = yu + xv - 1 = 0 \end{cases} \qquad \begin{cases} u = u(x,y) \\ v = v(x,y) \end{cases}$$

$$\begin{cases} u = u(x, y) \\ v = v(x, y) \end{cases}$$

$$J = \begin{vmatrix} F_u & F_v \\ G_u & G_v \end{vmatrix} = \begin{vmatrix} x & -y \\ y & x \end{vmatrix} = x^2 + y^2$$

$$\frac{\partial u}{\partial y} = -\frac{1}{J} \frac{\partial (F,G)}{\partial (y,v)} = -\frac{\begin{vmatrix} -v & -y \\ u & x \end{vmatrix}}{x^2 + y^2} = \frac{vx - yu}{x^2 + y^2}$$

例6
$$\begin{cases} xu - yv = 0 \\ yu + xv = 1 \end{cases}$$
 求 $\frac{\partial u}{\partial x} \cdot \frac{\partial u}{\partial y}, \frac{\partial v}{\partial x} \cdot \frac{\partial v}{\partial y}$

法二
$$\begin{cases} F(x,y,u,v) = xu - yv = 0 \\ G(x,y,u,v) = yu + xv - 1 = 0 \end{cases}$$

$$\begin{cases} u = u(x, y) \\ v = v(x, y) \end{cases}$$

$$J = \begin{vmatrix} F_u & F_v \\ G_u & G_v \end{vmatrix} = \begin{vmatrix} x & -y \\ y & x \end{vmatrix} = x^2 + y^2$$

$$\frac{\partial v}{\partial x} = -\frac{1}{J} \frac{\partial (F, G)}{\partial (u, x)} = -\frac{\begin{vmatrix} x & u \\ y & v \end{vmatrix}}{x^2 + y^2} = -\frac{vx - yu}{x^2 + y^2}$$

例6
$$\begin{cases} xu - yv = 0 \\ yu + xv = 1 \end{cases} \stackrel{\partial u}{\Rightarrow} \frac{\partial u}{\partial x} \cdot \frac{\partial u}{\partial y}, \frac{\partial v}{\partial x} \cdot \frac{\partial v}{\partial y}$$

法二
$$\begin{cases} F(x,y,u,v) = xu - yv = 0 \\ G(x,y,u,v) = yu + xv - 1 = 0 \end{cases}$$

$$\begin{cases} u = u(x, y) \\ v = v(x, y) \end{cases}$$

$$J = \begin{vmatrix} F_u & F_v \\ G_u & G_v \end{vmatrix} = \begin{vmatrix} x & -y \\ y & x \end{vmatrix} = x^2 + y^2$$

$$\frac{\partial v}{\partial y} = -\frac{1}{J} \frac{\partial (F, G)}{\partial (u, y)} = -\frac{\begin{vmatrix} x & -v \\ y & u \end{vmatrix}}{x^2 + y^2} = -\frac{ux + yv}{x^2 + y^2}$$

5.3 一阶全微分形式不变性的应用

利用一阶全微分形式不变性求偏导数

- 1. 将所有变量视为自变量,等式两端求全微分.
- 2. 同样适用于方程组确定的隐函数求偏导数.
- 3. 求(偏)导方法的选择.

 $\begin{cases} xu - yv = 0 \\ yu + xv = 1 \end{cases} \Rightarrow \frac{\partial u}{\partial x} \cdot \frac{\partial u}{\partial y}, \frac{\partial v}{\partial x} \cdot \frac{\partial v}{\partial y} \quad \begin{cases} u = u(x, y) \\ v = v(x, y) \end{cases}$

法三

$$\begin{cases} xdu + udx - ydv - vdy = 0 \\ ydu + udy + xdv + vdx = 0 \end{cases} \Rightarrow \begin{cases} xdu - ydv = -udx + vdy \\ ydu + xdv = -udy - vdx \end{cases}$$

$$D = \begin{vmatrix} x & -y \\ y & x \end{vmatrix} = x^2 + y^2$$

$$D_{1} = \begin{vmatrix} -udx + vdy & -y \\ -udy - vdx & x \end{vmatrix} \quad D_{2} = \begin{vmatrix} x & -udx + vdy \\ y & -udy - vdx \end{vmatrix} \implies \begin{cases} \frac{dv}{du} = 0 \end{cases}$$

例7.设由方程组
$$\begin{cases} x=-u^2+v+z\\ y=u+vz \end{cases}$$
 确定了隐函数
$$u=u(x,y,z), v=v(x,y,z), 求它们的偏导数.$$

例7.设由方程组
$$\begin{cases} x = -u^2 + v + z \\ y = u + vz \end{cases}$$
 确定了隐函数

u = u(x, y, z), v = v(x, y, z), 求它们的偏导数.

$$\begin{cases} dx = -2udu + dv + dz \\ dy = du + zdv + vdz \end{cases} \Rightarrow \begin{cases} du = \\ dv = \end{cases}$$

$$\begin{cases} 2udu - dv = dz - dx \\ du + zdv = -vdz + dy \end{cases} \Rightarrow D = \begin{vmatrix} 2u & -1 \\ 1 & z \end{vmatrix} = 2uz + 1$$

$$\begin{cases} du = \begin{vmatrix} dz - dx & -1 \\ -vdz + dy & z \end{vmatrix} \\ 2uz + 1 \end{cases} = \frac{-zdx + dy + (z - v)dz}{2uz + 1}$$

$$dv = \begin{vmatrix} 2u & dz - dx \\ 1 & -vdz + dy \end{vmatrix} = \frac{dx + 2udy - (2uv + 1)dz}{2uz + 1}$$

例7.设由方程组
$$\begin{cases} x = -u^2 + v + z \\ y = u + vz \end{cases}$$
 确定了隐函数

u = u(x, y, z), v = v(x, y, z), 求它们的偏导数.

$$\int du = \frac{-zdx + dy + (z - v)dz}{2uz + 1} = \frac{-z}{2uz + 1}dx + \frac{1}{2uz + 1}dy + \frac{(z - v)}{2uz + 1}dz$$
$$dv = \frac{dx + 2udy - (2uv + 1)dz}{2uz + 1} = \frac{1}{2uz + 1}dx + \frac{2u}{2uz + 1}dy - \frac{2uv + 1}{2uz + 1}dz$$

$$\frac{\partial u}{\partial x} = \frac{-z}{2uz+1} \qquad \frac{\partial u}{\partial y} = \frac{1}{2uz+1} \qquad \frac{\partial u}{\partial z} = \frac{(z-v)}{2uz+1} dz$$

$$\frac{\partial v}{\partial x} = \frac{1}{2uz+1} \qquad \frac{\partial v}{\partial y} = \frac{2u}{2uz+1} dy \qquad \frac{\partial v}{\partial z} = -\frac{2uv+1}{2uz+1} dz$$

内容小结

隐函数(组)求导方法

由方程(组)个数及未知量个数确定几个几元

方法1. 利用复合函数求导法则直接计算;

方法2. 利用微分形式不变性;

方法3.代公式

练习1. 设F(x,y)具有连续偏导数,已知方程 $F(\frac{x}{z},\frac{y}{z})=0$, 求 dz.

解法1 利用偏导数公式. 设 z = f(x, y) 是由方程 $F(\frac{x}{z}, \frac{y}{z}) = 0$ 确定的隐函数,则

$$\frac{\partial z}{\partial x} = -\frac{F_1' \cdot \frac{1}{z}}{F_1' \cdot (-\frac{x}{z^2}) + F_2' \cdot (-\frac{y}{z^2})} = \frac{z F_1'}{x F_1' + y F_2'}$$

$$\frac{\partial z}{\partial y} = -\frac{F_2' \cdot \frac{1}{z}}{F_1' \cdot (-\frac{x}{z^2}) + F_2' \cdot (-\frac{y}{z^2})} = \frac{z F_2'}{x F_1' + y F_2'}$$

故
$$dz = \frac{\partial z}{\partial x} dx + \frac{\partial z}{\partial y} dy = \frac{z}{x F_1' + y F_2'} (F_1' dx + F_2' dy)$$

练习1. 设F(x,y)具有连续偏导数,已知方程 $F(\frac{x}{z},\frac{y}{z})=0$, 求 dz.

解法2 微分法. 对方程两边求微分:

$$F(\frac{x}{z}, \frac{y}{z}) = 0 \qquad F_{1}' \cdot d(\frac{x}{z}) + F_{2}' \cdot d(\frac{y}{z}) = 0$$

$$F_{1}' \cdot (\frac{z dx - x dz}{z^{2}}) + F_{2}' \cdot (\frac{z dy - y dz}{z^{2}}) = 0$$

$$\frac{xF_{1}' + yF_{2}'}{z^{2}} dz = \frac{F_{1}' dx + F_{2}' dy}{z}$$

$$dz = \frac{z}{xF_{1}' + yF_{2}'} (F_{1}' dx + F_{2}' dy)$$

练习2. 设
$$z = f(x + y + z, xyz)$$
, 求 $\frac{\partial z}{\partial x}$, $\frac{\partial x}{\partial z}$, $\frac{\partial x}{\partial z}$.

•
$$\frac{\partial z}{\partial x} = f_1' \cdot (1 + \frac{\partial z}{\partial x}) + f_2' \cdot (yz + xy \frac{\partial z}{\partial x})$$

$$\Longrightarrow \frac{\partial z}{\partial x} = \frac{f_1' + yzf_2'}{1 - f_1' - xyf_2'}$$

•
$$1 = f_1' \cdot \left(\frac{\partial x}{\partial z} + 1\right) + f_2' \cdot \left(yz\frac{\partial x}{\partial z} + xy\right)$$

$$\Longrightarrow \frac{\partial x}{\partial z} = \frac{1 - f_1' - xyf_2'}{f_1' + yzf_2'}$$

•
$$0 = f_1' \cdot \left(\frac{\partial x}{\partial y} + 1\right) + f_2' \cdot \left(yz\frac{\partial x}{\partial y} + xz\right)$$

$$\Longrightarrow \frac{\partial x}{\partial y} = -\frac{f_1' + xzf_2'}{f_1' + yzf_2'}$$

解法2. 利用全微分形式不变性同时求出各偏导数.

$$z = f(x + y + z, xyz)$$

 $dz = f_1' \cdot (dx + dy + dz) + f_2' (yz dx + xz dy + xy dz)$

解出 dx:

$$dx : dx = \frac{-(f_1' + xzf_2')dy + (1 - f_1' - xyf_2')dz}{f_1' + yzf_2'}$$

由dy,dz的系数即可得 $\frac{\partial x}{\partial y}$, $\frac{\partial x}{\partial z}$.

练习3. 设 y = y(x), z = z(x) 是由方程 z = x f(x + y) 和 F(x,y,z) = 0 所确定的函数, 求 $\frac{\mathrm{d} z}{\mathrm{d} x}$.

解法1 分别在各方程两端对 x 求导, 得

$$\begin{cases} z' = f + x \cdot f' \cdot (1 + y') \\ F_x + F_y \cdot y' + F_z \cdot z' = 0 \end{cases} \qquad \begin{cases} -xf' \cdot y' + z' = f + xf' \\ F_y \cdot y' + F_z \cdot z' = -F_x \end{cases}$$

$$\therefore \frac{\mathrm{d}z}{\mathrm{d}x} = \frac{\begin{vmatrix} -xf' & f+xf' \\ F_y & -F_x \end{vmatrix}}{\begin{vmatrix} -xf' & 1 \\ F_y & F_z \end{vmatrix}} = \frac{(f+xf')F_y - xf' \cdot F_x}{F_y + xf' \cdot F_z}$$
$$(F_y + xf' \cdot F_z \neq 0)$$

解法2 微分法.

$$z = x f(x + y), F(x, y, z) = 0$$

对各方程两边分别求微分:

$$\begin{cases} dz = f dx + xf' \cdot (dx + dy) \\ F_1' dx + F_2' dy + F_3' dz = 0 \end{cases}$$

化简得

$$\begin{cases} (f + xf') dx + x f' dy - dz = 0 \\ F'_1 dx + F'_2 dy + F'_3 dz = 0 \end{cases}$$

消去dy可得 $\frac{dz}{dx}$.