

- Graph representation
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Graph Representation

Definition: $G = (V, E)$

V = set of vertices

E = set of edges

Directed graph & Undirected graph

Two representations:

Adjacency matrix: edge test

space: $O(n^2)$, bad for sparse graph

Adjacency list: fast to traverse neighbors of a vertex

space: $O(n + m)$

How to choose efficient representation:

The type of operation

Space complexity

BFS

```

BFS(G, S) {
    Queue q;
    visited[1...n];
    q.enqueue(S);
    visited[S] = T;
    while (!q.isEmpty()) {
        v = q.dequeue();

        // do operation for different applications

        for (p in neighbor(v)) {
            if (!visited[p]) {
                q.enqueue(p);
                visited[p] = T;
            }
        }
    }
}

```

Time: $O(n + m)$

Space: $O(n + m)$

In this case it's better to use adjacency list, since we need to traverse all the neighbors of each vertex

```

BFS_ALL(G) {
    visited[1...n];
    for (s = 1...n) {
        if (!visited[s]) {
            BFS(G, s, visited);
        }
    }
}

```

Time: $O(n + m)$

NOTE: Pay attention to this time complexity.

DFS

```

DFS(G, S, visited) {
    visited[S] = T;

    // processing vertex S

    for (v in neighbor(S)) {
        if (!visited[v]) {
            DFS(G, v, visited);
        }
    }
}

```

Time: $O(n + m)$

Application

Cycle Detectoin

input: directed $G = (V, E)$

output: True if there is a cycle in the graph, false otherwise

Thought process: Obviously, dfs should be used. But basic dfs is not enough to solve the problem.

There is a cycle when during one bfs process, the neighbor of current vertex is visited but not finished (finished means dfs all neighbor).

Use $color[1...n]$ to replace $visited[1...n]$.

$color[u] = N$, not visited

$color[u] = V$, visited but not finished

$color[u] = F$, visited and finished

```

DFS(G, S) {
    color[S] = V;
    for (p in neighbor(S)) {
        if (color[p] = N) {
            DFS(G, p);
        } else if (color[p] = V) {
            exists cycle;
        }
    }
    color[S] = F;
}

```

Topological Sort

The definition of **topological sort** is a linear ordering of its vertices such that for every directed edge uv from vertex u to vertex v , u comes before v in the ordering.

The purpose of this algorithm is to produce a list of vertices in topological ordering.

Approach 1: Non-DFS

The idea is, u must come before v in the ordering if there is an edge uv . Therefore, vertices without incoming edges must come before other vertices. We use an array `indegree[n]` to record the incoming edges of every vertex.

```
// O(n+m)
for (u = 1...n) {
    for (v in neighbors(u)) {
        indegree[v]++;
    }
}
// O(n)
for (u = 1...n) {
    if (indegree[u] == 0) {
        q.enqueue(u);
    }
}
// O(n+m)
while(!q.isEmpty()) {
    u = q.dequeue();
    // add u to the list
    for (p in neighbor(u)) {
        indegree[p]--;
        if (indegree[p] == 0) {
            q.enqueue(p);
        }
    }
}
}
```

Approach 2: DFS

For edge uv from u to v , the finish time of `dfs(u)` must be later than the finish time of `dfs(v)`. Therefore, we can add the vertex to the list after its dfs process. Finally, reverse the whole list.

```
DFS(G, S, L) {  
    visited[S] = T;  
    for (u in neighbor(S)) {  
        DFS(G, u, L);  
    }  
    L.append(S);  
}
```

```
DFS_ALL(G) {  
    L = [];  
    for (s = 1...n) {  
        if (!visited[s]) {  
            DFS(G, s, L);  
        }  
    }  
    reverse(L);  
    return L;  
}
```